

Modal Logic

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1 Basic Concepts

1.1 Relational Structures

Definition 1.1. A relational structure \mathfrak{F} is a tuple, where the first component is a non-empty set W called *universe*, and remaining components are relations on W . We assume there is at least one relation on W .

In the following 2 definitions, we assume W be a non-empty set and R a binary relation on W .

Definition 1.2. $R^+ := \bigcap \{R' \mid R' \text{ is a transitive binary relation on } W \text{ and } R \subseteq R'\}$, is called the *transitive closure* of R .

Definition 1.3. $R^* := \bigcap \{R' \mid R' \text{ is a reflexive transitive binary relation on } W \text{ and } R \subseteq R'\}$, is called the *reflexive transitive closure* of R .

Note that transitive closure of a binary relation has nice *finite steps* property, see Exercise 1.1.3.

Definition 1.4. A tree \mathfrak{T} is a structural structure (T, S) where:

- (i) T , the set of nodes, contains a unique $r \in T$ (root), such that $\forall t \in T \exists! r.t$.
- (ii) For every $t \neq r$, there is a unique $t' \in T$, such that $St't$
- (iii) $\forall t \neg S^+tt$, so S is *acyclic*.

Question 1.1. Why we define tree like that?

1.2 Modal Languages

Definition 1.5. Basic modal language:

-A set of proposition letters(or proposition symbols or propositional variables) Φ , whose elements are usually denoted p, q, r , and so on.

-A unary modal operator \Diamond .

Then the well-formed *formulas* ϕ of the basic modal language are given by the rule:

$$\phi ::= p \mid \perp \mid \neg\phi \mid \psi \vee \phi \mid \Diamond\phi,$$

where p ranges over elements of Φ .

There is also a dual operator \Box which is defined by $\Box\phi := \neg\Diamond\neg\phi$.

Moreover, we can define conjunction, implication, bi-implication, and the constant true as usual:

$$\phi \wedge \psi := \neg(\neg\phi \vee \neg\psi),$$

$$\phi \rightarrow \psi := \neg\phi \vee \psi,$$

$$\phi \leftrightarrow \psi := (\phi \rightarrow \psi) \wedge (\psi \rightarrow \phi), \text{ and}$$

$$\top := \neg\perp.$$

The following 3 definitions generalize the concept of basic modal language.

Definition 1.6. A *modal similarity type* is a pair $\tau = (O, \rho)$ where O is a non-empty set, and ρ is a function $O \rightarrow \mathbb{N}$. The elements of O are called *modal operators*; we use $\Delta, \Delta_0, \Delta_1, \dots$, to denote elements of O . The function ρ assigns to each operator $\Delta \in O$ a finite *arity* indicating the number of arguments Δ can be applied to.

So we often refer to *unary* triangles as *diamonds*, and denote them by \Diamond_a or $\langle a \rangle$, where a is taken from some index set.

Definition 1.7. A *modal language* $ML(\tau, \Phi)$, with modal similarity type $\tau = (O, \rho)$ and a set of proposition letters Φ . The well-formed formulas are given by the rule:

$$\phi ::= p \mid \perp \mid \neg\phi \mid \phi_1 \vee \phi_2 \mid \Delta(\phi_1, \dots, \phi_{\rho(\Delta)}),$$

where p ranges over elements of Φ .

Definition 1.8. Dual operators for non-nullary triangles. For each $\Delta \in O$ the dual ∇ is defined as $\nabla(\phi_0, \dots, \phi_n) = \neg\Delta(\neg\phi_0, \dots, \neg\phi_n)$. The dual of a triangle of arity at least 2 is called a *nabla*. A *box*(unary triangle-down) is written \Box_a or $[a]$.

Definition 1.9. A *substitution* is a map $\sigma : \Phi \rightarrow Form(\tau, \Phi)$ (formulas).

Then a substitution σ induces a map $(\cdot)^\sigma : Form(\tau, \Phi) \rightarrow Form(\tau, \Phi)$, which can be recursively defined as follows:

$$\perp^\sigma = \perp,$$

$$p^\sigma = \sigma(p),$$

$$(\neg\psi)^\sigma = \neg\psi^\sigma,$$

$$(\psi \vee \theta)^\sigma = \psi^\sigma \vee \theta^\sigma,$$

$$(\Delta(\psi_1, \dots, \psi_n))^\sigma = \Delta(\psi_1^\sigma, \dots, \psi_n^\sigma)$$