

1 Surface Area

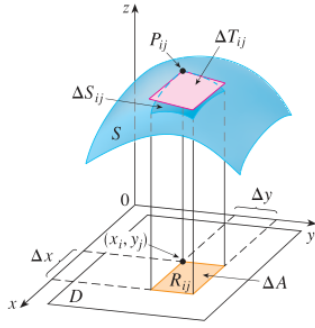


FIGURE 1

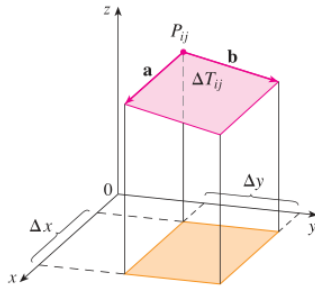


FIGURE 2

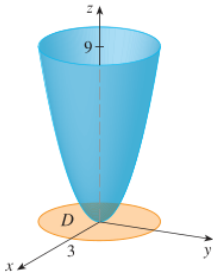


FIGURE 5

Divide into $m \times n$ square. Then $A(S) = \lim_{m,n \rightarrow \infty} \sum_{i=1}^m \sum_{j=1}^n \Delta T_{ij}$. Since $\Delta T_{ij} = |\mathbf{a} \times \mathbf{b}|$. Recall that $f_x(x_i, y_j)$ and $f_y(x_i, y_j)$ are the slopes of the tangent lines through P_{ij} .

$$\mathbf{a} = \Delta x \mathbf{i} + f_x(x_i, y_j) \Delta x \mathbf{k}$$

$$\mathbf{b} = \Delta y \mathbf{j} + f_y(x_i, y_j) \Delta y \mathbf{k}$$

$$\begin{aligned} \mathbf{a} \times \mathbf{b} &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \Delta x & 0 & f_x(x_i, y_j) \Delta x \\ 0 & \Delta y & f_y(x_i, y_j) \Delta y \end{vmatrix} \\ &= [-f_x(x_i, y_j) \mathbf{i} - f_y(x_i, y_j) \mathbf{j} + \mathbf{k}] \Delta A \end{aligned}$$

$$\Delta T_{ij} = |\mathbf{a} \times \mathbf{b}| = \sqrt{[f_x(x_i, y_j)]^2 + [f_y(x_i, y_j)]^2 + 1} \Delta A$$

Hence we have

Definition : The Area of the Surface

If f_x, f_y are continuous.

$$\begin{aligned} A(S) &= \iint_D \sqrt{[f_x(x_i, y_j)]^2 + [f_y(x_i, y_j)]^2 + 1} dA \\ &= \iint_D \sqrt{1 + \left(\frac{\partial z}{\partial x}\right)^2 + \left(\frac{\partial z}{\partial y}\right)^2} dA \end{aligned}$$

📍 **EXAMPLE.** Area of $z = x^2 + y^2$ that lies under $z = 9$.

$$\begin{aligned} A &= \iint_D \sqrt{1 + (2x)^2 + (2y)^2} dA \\ &= \iint_D \sqrt{1 + 4(x^2 + y^2)} dA \end{aligned}$$

Converting to polar coordinates, we obtain

$$\begin{aligned} A &= \int_0^{2\pi} \int_0^3 \sqrt{1 + 4r^2} r dr d\theta \\ &= \int_0^{2\pi} d\theta \int_0^3 \frac{1}{8} \sqrt{1 + 4r^2} (8r) dr \\ &= 2\pi \left(\frac{1}{8} \right) \frac{2}{3} (1 + 4r^2)^{3/2} \Big|_0^3 = \frac{\pi}{6} (37\sqrt{37} - 1) \end{aligned}$$

2 Triple Integrals

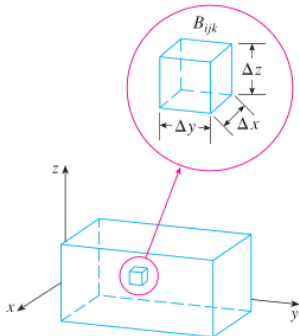
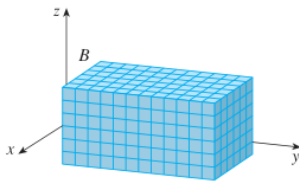


FIGURE 1

Divide into subboxes.

Definition : Triple Integrals

Let $B_{ijk} = [x_{i-1}, x_i] \times [y_{j-1}, y_j] \times [z_{k-1}, z_k]$, then

$$\iiint_B \lim_{l,m,n \rightarrow \infty} \sum_{i=1}^l \sum_{j=1}^m \sum_{k=1}^n f(x_{ijk}^*, y_{ijk}^*, z_{ijk}^*) \Delta V$$

Fubini's Theorem. $\iiint_B f(x, y, z) dV = \int_a^b \int_r^s \int_c^d f(x, y, z) dy dz dx$

Just the same, wrap E inside a box, and we got $\iiint_B F(x, y, z) dV$.

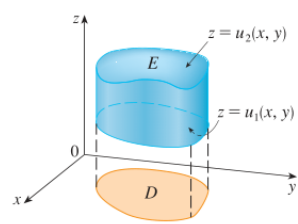


FIGURE 2
A type 1 solid region

$$E = \{(x, y, z) \mid (x, y) \in D, u_1(x, y) \leq z \leq u_2(x, y)\}$$

$$\iiint_E f(x, y, z) dV = \iint_D \left[\int_{u_1(x, y)}^{u_2(x, y)} f(x, y, z) dz \right] dA$$

Definition : 3 Types of Triple Integrals

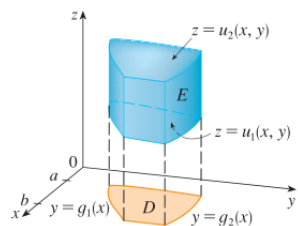


FIGURE 3
A type 1 solid region where the projection D is a type I plane region

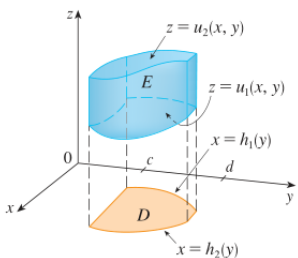


FIGURE 4
A type 1 solid region with a type II projection

■ **Type I.** D is the projection on the xy -plane.

$$E = \{(x, y, z) \mid a \leq x \leq b, g_1(x) \leq y \leq g_2(x), u_1(x, y) \leq z \leq u_2(x, y)\}$$

$$\iiint_E f(x, y, z) dV = \int_a^b \int_{g_1(x)}^{g_2(x)} \int_{u_1(x, y)}^{u_2(x, y)} f(x, y, z) dz dy dx$$

■ **Type II.** D is the projection on the yz -plane.

■ **Type III.** D is the projection on the xz -plane.

📍 **EXAMPLE.** $\iiint_E \sqrt{x^2 + z^2} dV$, where E bounded by $y = x^2 + z^2$ and $y = 4$.

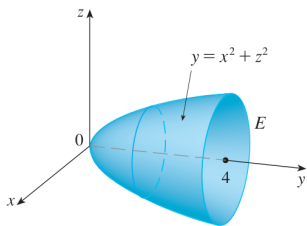


FIGURE 9
Region of integration

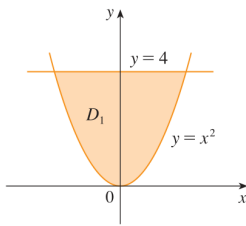


FIGURE 10
Projection onto xy -plane

$$\iint_{D_3} \left[\int_{x^2+z^2}^4 \sqrt{x^2 + z^2} dy \right] dA = \iint_{D_3} (4 - x^2 - z^2) \sqrt{x^2 + z^2} dA$$

Convert to polar coordinate in the xz -plane: $x = r \cos \theta$, $z = r \sin \theta$, which gives

$$\begin{aligned} \iiint_E \sqrt{x^2 + z^2} dV &= \iint_{D_3} (4 - x^2 - z^2) \sqrt{x^2 + z^2} dA \\ &= \int_0^{2\pi} \int_0^2 (4 - r^2) r r dr d\theta = \int_0^{2\pi} d\theta \int_0^2 (4r^2 - r^4) dr \\ &= 2\pi \left[\frac{4r^3}{3} - \frac{r^5}{5} \right]_0^2 = \frac{128\pi}{15} \end{aligned}$$

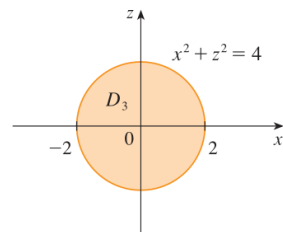


FIGURE 11
Projection onto xz -plane

3 Applications of Triple Integrals

First, begin with the special case where $f(x, y, z) = 1$ for all points in E . That would be the volume of the shape.

4 Triple Integrals in Cylindrical Coordinates

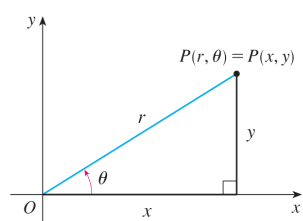


FIGURE 1

Recall the connection between polar and Cartesian coordinates:

$$x = r \cos \theta \qquad y = r \sin \theta$$
$$r^2 = x^2 + y^2 \qquad \tan \theta = \frac{y}{x}$$

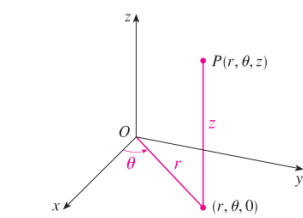


FIGURE 2
The cylindrical coordinates of a point

❖ Cylindrical Coordinates

- Represented by (r, θ, z) ,
- r, θ : polar coordinates of the **projection** of P onto the xy -plane.
 - z : the directed distance from the xy -plane to P .

$$x = r \cos \theta \qquad y = r \sin \theta \qquad z = z$$
$$r^2 = x^2 + y^2 \qquad \tan \theta = \frac{y}{x} \qquad z = z$$

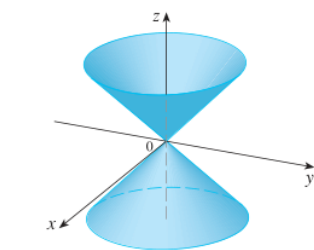
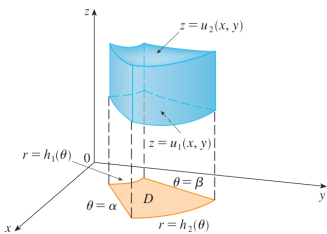


FIGURE 5
 $z = r$, a cone

This is the surface of $z = r$.

❖ Evaluating Triple Integrals with Cylindrical Coordinates



Suppose $E = \{(x, y, z) \mid (x, y) \in D, u_1(x, y) \leq z \leq u_2(x, y)\}$, and

$$D = \{(r, \theta) \mid \alpha \leq \theta \leq \beta, h_1(\theta) \leq r \leq h_2(\theta)\}$$

Definition : Triple Integrals with Cylindrical Coordinates

$$\iiint_E f(x, y, z) \, dV = \int_{\alpha}^{\beta} \int_{h_1(\theta)}^{h_2(\theta)} \int_{u_1(r \cos \theta, r \sin \theta)}^{u_2(r \cos \theta, r \sin \theta)} f(r \cos \theta, r \sin \theta, z) \, r \, dz \, dr \, d\theta$$

5 Triple Integrals in Spherical Coordinates

Definition : ❖ Spherical Coordinates

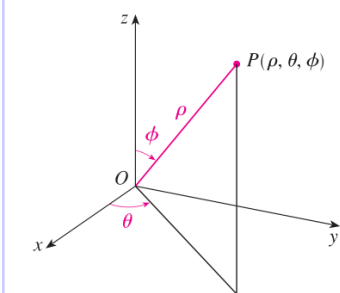


FIGURE 1
The spherical coordinates of a point

The **spherical coordinates** (ρ, θ, ϕ) of a point P :

- $\rho = |OP| \geq 0$: the distance from O to P .
- θ : the same angle as in cylindrical coordinates.
- $0 \leq \phi \leq \pi$: the angle between the positive z and OP .

Useful when there is symmetry about a point.

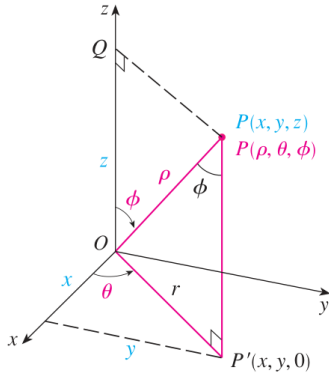


FIGURE 5

We have $z = \rho \cos \phi$ and $r = \rho \sin \phi$.

$$x = \rho \sin \phi \cos \theta \quad y = \rho \sin \phi \sin \theta \quad z = \rho \cos \phi$$

The distance formula

$$\rho^2 = x^2 + y^2 + z^2$$

Definition :  **Evaluating Triple Integrals with Spherical Coordinates**

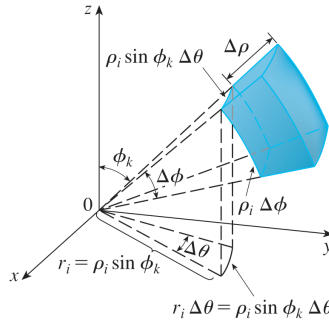


FIGURE 7

$$\begin{aligned} \iiint_E f(x, y, z) dV \\ = \int_c^d \int_\alpha^\beta \int_a^b f(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) \rho^2 \sin \phi d\rho d\theta d\phi \end{aligned}$$

where E is a **spherical wedge**

$$E = \{(\rho, \theta, \phi) \mid a \leq \rho \leq b, \alpha \leq \theta \leq \beta, c \leq \phi \leq d\}$$

where $a \geq 0$, $\beta - \alpha \leq 2\pi$, $d - c \leq \pi$.

The formula can be extended as $g_1(\theta, \phi) \leq \rho \leq g_2(\theta, \phi)$.

6 Change of Variables in Multiple Integrals

Consider a **transformation** T from the uv -plane to the xy -plane: $x = g(u, v)$, $y = h(u, v)$.

Assume T is a C^1 **transformation** (g, h have continuous 1st-order partial derivatives).

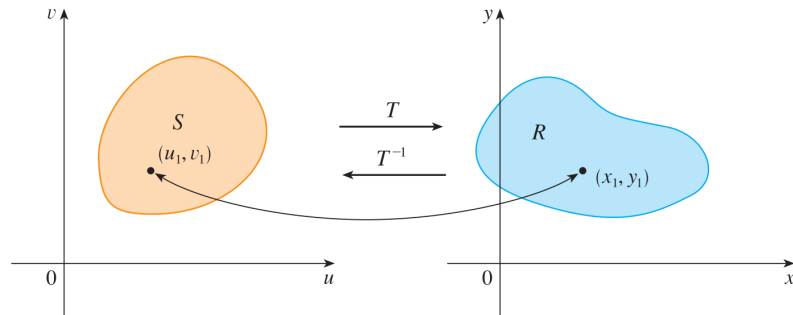


FIGURE 1

If T is **one-to-one**, the the **inverse transformation** T^{-1} exist: $u = G(x, y)$, $v = H(x, y)$.

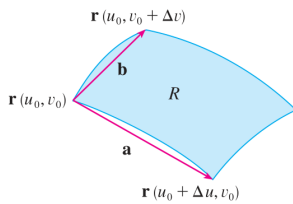


FIGURE 4

We approximate the image R by a parallelogram determined by

$$\begin{cases} \mathbf{a} &= \mathbf{r}(u_0 + \Delta u, v_0) - \mathbf{r}(u_0, v_0) \approx \Delta u \mathbf{r}_u \\ \mathbf{b} &= \mathbf{r}(u_0, v_0 + \Delta v) - \mathbf{r}(u_0, v_0) \approx \Delta v \mathbf{r}_v \\ S_R &= |(\Delta u \mathbf{r}_u) \times (\Delta v \mathbf{r}_v)| = |\mathbf{r}_u \times \mathbf{r}_v| \Delta u \Delta v \end{cases}$$

Computing the cross product

$$\mathbf{r}_u \times \mathbf{r}_v = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & 0 \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & 0 \end{vmatrix} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix} \mathbf{k} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} \mathbf{k}$$

FIGURE 5

Definition : The Jacobian

The **Jacobian** of the transformation $T: x = g(u, v), y = h(u, v)$ is

$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u}$$

Hence we got $\Delta A \approx \left| \frac{\partial(x, y)}{\partial(u, v)} \Delta u \Delta v \right|$ where the Jacobian is evaluated at (u_0, v_0) .

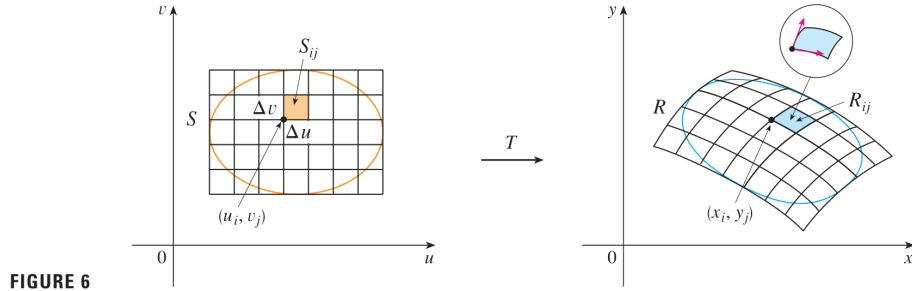


FIGURE 6

$$\begin{aligned} \iint_R f(x, y) dA &\approx \sum_{i=1}^m \sum_{j=1}^n f(x_i, y_j) \Delta A \\ &\approx \sum_{i=1}^m \sum_{j=1}^n f(g(u_i, v_i), h(u_i, v_i)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \Delta u \Delta v \end{aligned}$$

Definition : Change of Variables in a Double Integral

Suppose T is a C^1 transformation whose Jacobian is nonzero, map from uv to xy . R, S are type I, II , f is continuous.

$$\iint_R f(x, y) dA = \iint_S f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \Delta u \Delta v$$

Triple Integral

The **Jacobian** of T is the determinant

$$\begin{cases} x = g(u, v, w) \\ y = h(u, v, w) \\ z = k(u, v, w) \end{cases} \quad \frac{\partial(x, y, z)}{\partial(u, v, w)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}$$

Definition : Triple Integration in Spherical Coordinates

$$\iiint_R f(x, y, z) dV = \iiint_S f(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) \rho^2 \sin \phi d\rho d\theta d\phi$$