

SCAD Architecture Project Paper

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1 Instruction Set Architecture

Aside from the mandatory move instruction, our Instruction Set Architecture (ISA) needs to have instructions for loading immediate values, jumping to fixed addresses and branching. An overview of those instructions is given in Figure 1.

instruction	semantics
move src, dest	Move data from an output buffer to an input buffer by sending this instruction to the corresponding functional units. Data move will asynchronous
jump address	Set pc to address.
immediate data	Place data into output buffer of control unit.
branch address	A no-op when the first data in the input buffer is a 0, jump to address otherwise. Will wait for data to arrive when there is none.

Figure 1: SCAD Architecture Instructions

2 Move Instruction Bus

2.1 2-Phase Commit

To take into account both stalls of source and destination functional units, the control unit sends move instructions in two phases, both of which are indicated by a rising edge of the "valid" flag. First, with phase low, the functional units only check whether there is space in the corresponding input and output buffers. When stalls are asserted, the control unit waits some time until retrying. When no functional unit stalls, the phase being high signals a "write".

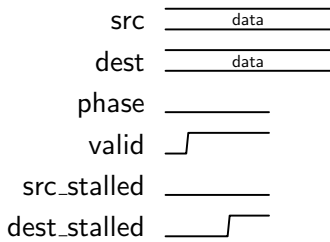


Figure 2: A timing diagram

3 Control Unit and Data Network

To keep the MIB simple, we will have the control unit send immediate values, and receive branch conditions through the data network. While broadcasting immediate values through either the MIB or a separate bus may be the faster alternative, having the control unit send them through the data network keeps the architecture cleaner.

nicer

4 Future Work

Having duplication as a separate functional unit may cause it to be a significant bottleneck. One feasible solution to this is the extension of the move instruction by an additional "non-destructive" move, where data sent is kept in the output buffer.

at least two more ideas

Appendices

A Memory Access and Branch

Basic example for memory access and branching:

```

1 // Basic function:
2 // *result = *op1 == *op2 ? 33 : 27;
3
4 // Load operands from memory
5 immediate <op1_address> // op1_address into the control unit output
6 move ctrl.o0, load.i0
7 immediate <op2_address>
8 move ctrl.o0, load.i0
9
10 // Send result destination to "store" function unit
11 immediate <result_address>
12 move ctrl.o0, store.i0
13
14 // Send parameters to compare unit
15 move load.o0, cmp.i0
16 move load.o0, cmp.i1
17
18 move cmp.o0, ctrl.i0 //move to control unit input for branch
19 branch yes // branch to yes if control unit input != 0
20 no:
21     immediate 27
22     jump both
23 yes:
24     immediate 33
25 both:
26     move ctrl.o0, store.i1 // move to data input of the store unit

```