

Block parity check

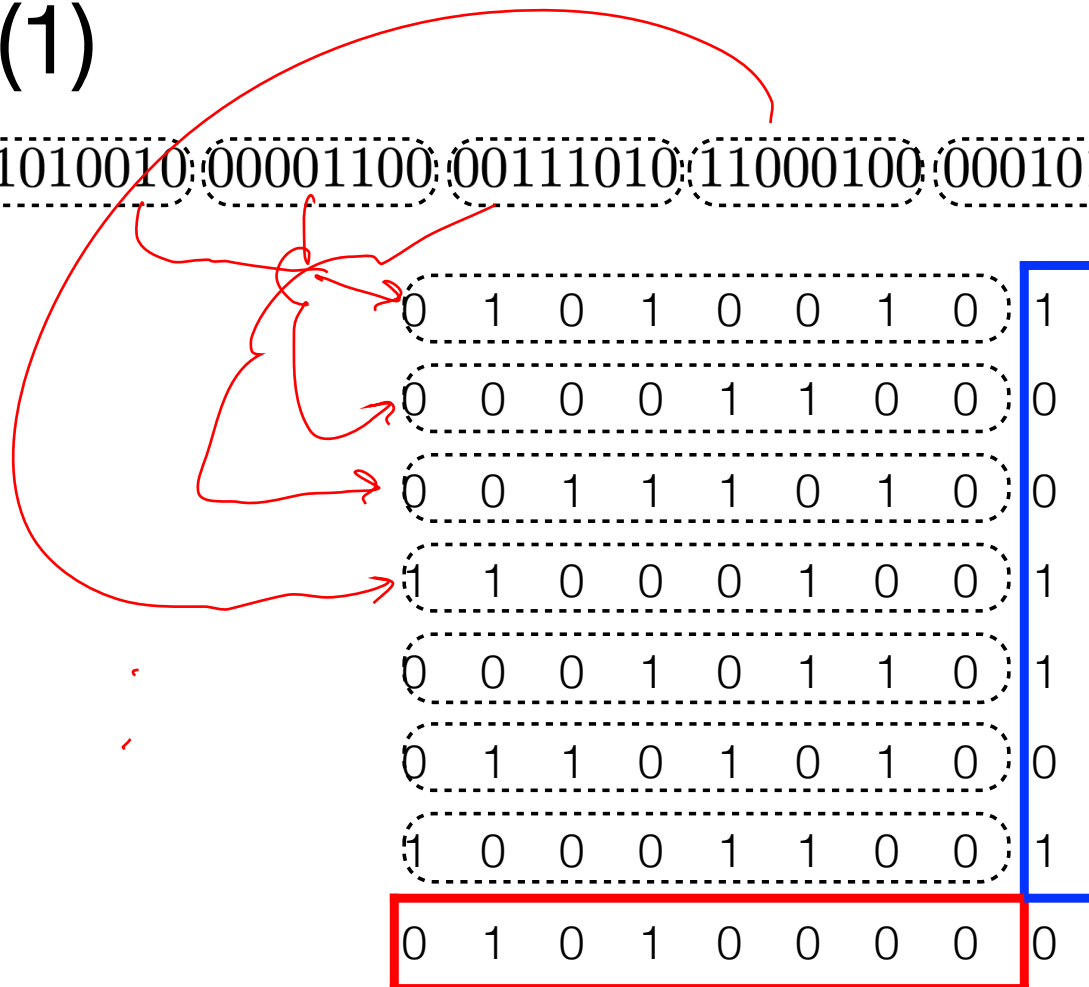
- To reveal burst errors (in the same block), one can break down the bit sequence into words and organize them into a matrix

k words, N bit/word, $k \times N$ matrix

- Parity bits are calculated on both rows and columns
- A *burst* of less length than the number of columns can be revealed → *the error is all in a row of the matrix.*
- Lower efficiency, higher effectiveness
- Alternative: *interleaving*

Example (1)

$m =$ 01010010 00001100 00111010 11000100 00010110 01101010 10001100



$$k = 7$$

$$N = 8$$

$x = m$ 1001101 01010000

Example (2)

1 0 0 1 1 0 1 0 1 0 1 0 0 0 0

The idea of interleaving
is that of mixing the
bits

Detection: possible

0	1	0	1	0	0	1	0	1
0	1	0	0	1	0	0	0	0
0	0	1	1	1	0	1	0	0
1	1	0	0	0	1	0	0	1
0	0	0	1	0	1	1	0	1
0	1	1	0	1	0	1	0	0
1	0	0	0	1	1	0	0	1
0	0	0	1	0	0	0	0	0


If the error
is in
a single row

Even
of
errors
↓
no
detection

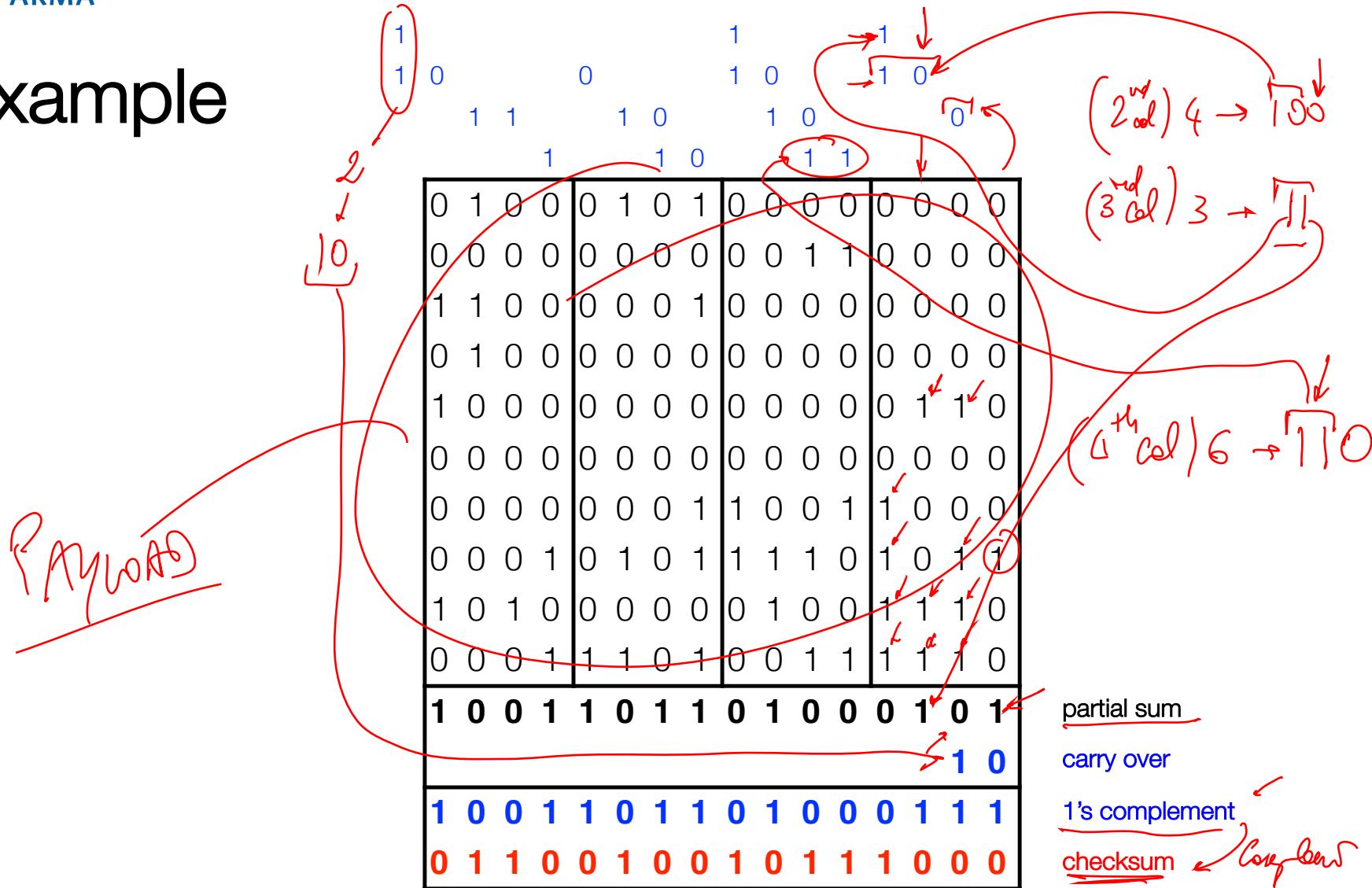
Detection: impossible

0	1	0	1	0	0	1	0	1
0	1	0	0	1	0	0	0	0
0	0	1	1	1	0	1	0	0
1	1	0	0	0	1	0	0	1
0	1	0	1	0	0	1	0	1
0	1	1	0	1	0	1	0	0
1	0	0	0	1	1	0	0	1
0	1	0	1	0	0	0	0	0

1's Complement Sum

- Same matrix organization used in block parity check
- Rows are summed together with 1-complement arithmetic
- The sum, possibly complemented, is the error detection code (checksum) 
 - The possible complement is dictated by computational complexity issues
- Used by IP, UDP, TCP and other Internet protocols

Example



Other Codes

$\{b_i\}$
bits that
are to be
transmitted

$$b_1 \cdot n + b_2 \cdot n^2 + b_3 \cdot n^3 + \dots$$

- Polynomial codes, also called Cyclic Redundancy Check (CRC).
- The individual binary digits to be transmitted are treated as coefficients (of value "0" or "1") of a given polynomial
- The sending and receiving entities use a common polynomial, called the generator polynomial
- The parity bits and their checks are obtained from polynomial divisions in algebra modulo 2

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Error Correction

PHY layer

For example

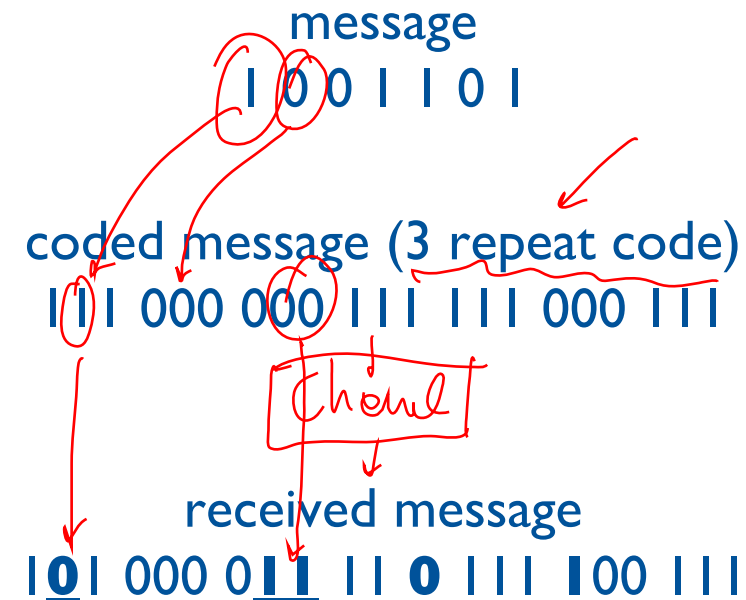
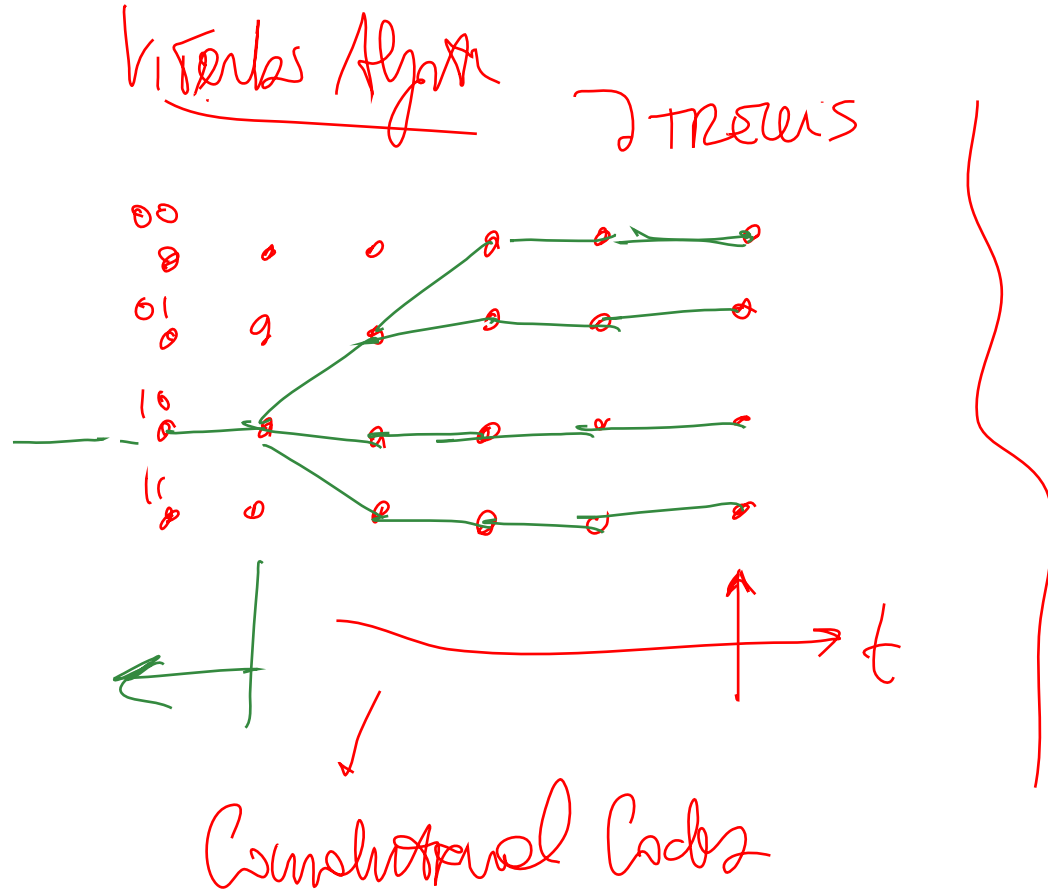
with block parity check (p68)
you can detect exactly
1 bit error

→ correct the bit!

- Forward Error Correction (FEC) techniques → ex Viterbi algorithm.
- Redundancy is used to remedy erroneous bits (if small in number)
- No acknowledgement messages of correct reception are required
 - unidirectional communication
 - there is no need for buffering of sent IUs
- Coding theory
 - added redundancy is generally greater than that used for detection alone
 - redundancy introduced to correct error is constant (fixed)

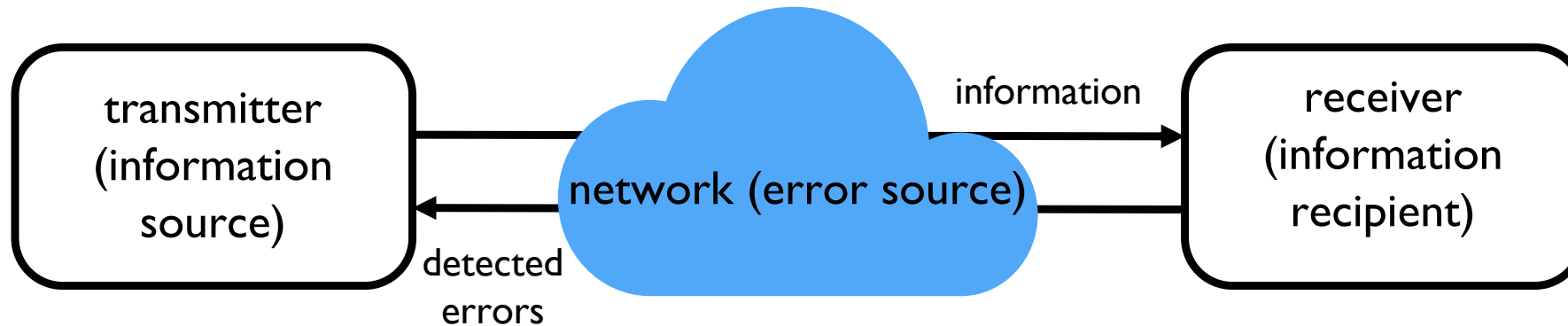
) no need to retransmit

Example: repetition code



I can correct 1 error
or detect 2

③ Error recovery *→ From Link layer (L2) up*



- Error control by automatic retransmission (Automatic Repeat Request, ARQ)
- Different mechanisms used for retransmission (error detection, acknowledgements, timers, IU identifiers)
- ARQ procedures (differ in the size of the windows)
 1. **stop and wait**: positive acknowledgement mode with reissue
 2. **sliding window, go-back-N**: variable window mode with non-selective reissue
 3. **sliding window, selective repeat**: variable window mode with selective reissue

3.1 Stop and Wait

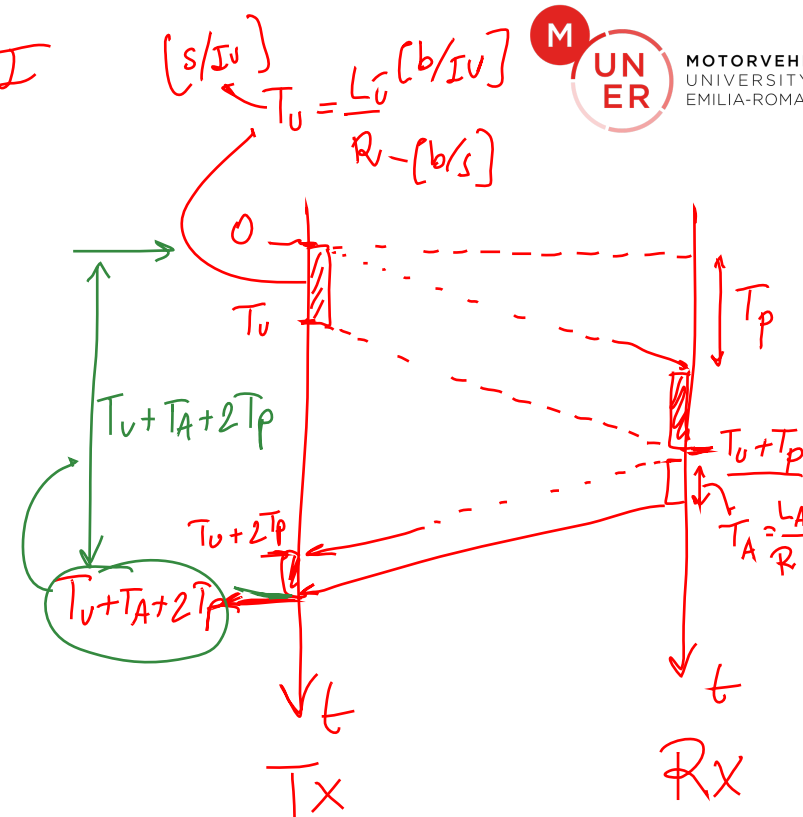
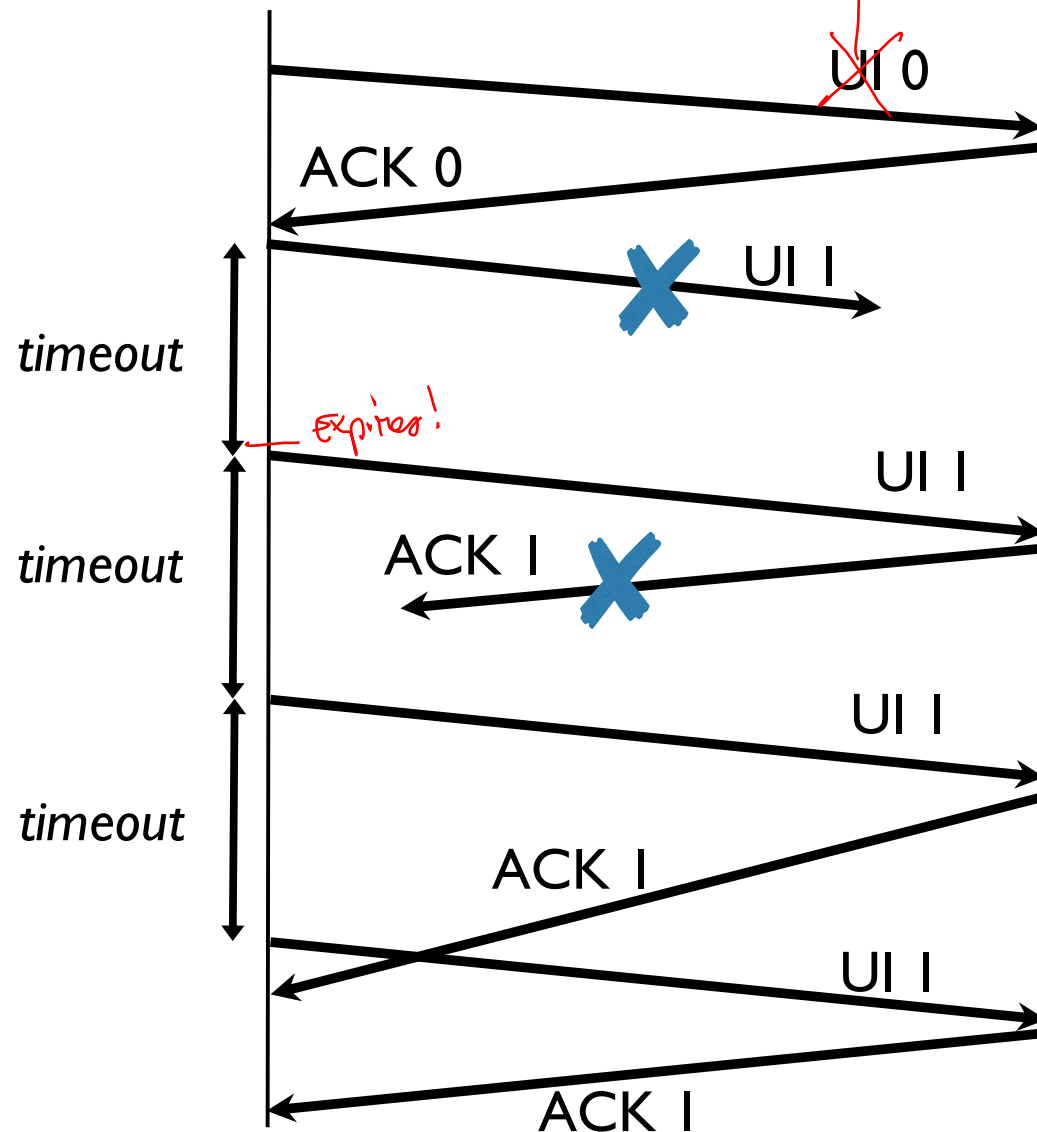
- Data IUs are sent individually
- An acknowledgement (acknowledgment, ACK) is expected before sending the next IU
 - Empty IU or with data directed in the opposite direction
 - Acknowledgements are also subject to loss/errors
- It is necessary to activate for each sent IU a retransmission timeout
 - if no ACK has been received when the timeout expires, the IU is retransmitted
 - sufficiently large but not too large
- To avoid duplication, sequence numbers (SeQuence Number, SQN) are used to identify the IUs
 - entered into the PCI with a fixed number of bits, modulo numbering
- Cumulative ACKs: the SQN following the one encountered is reported
- If the sequentiality of the IUs is maintained during the transfer (no out-of-sequence), only one bit is needed to count the SQN

(Typically)
The ACK packet is very short
much shorter than the IU.

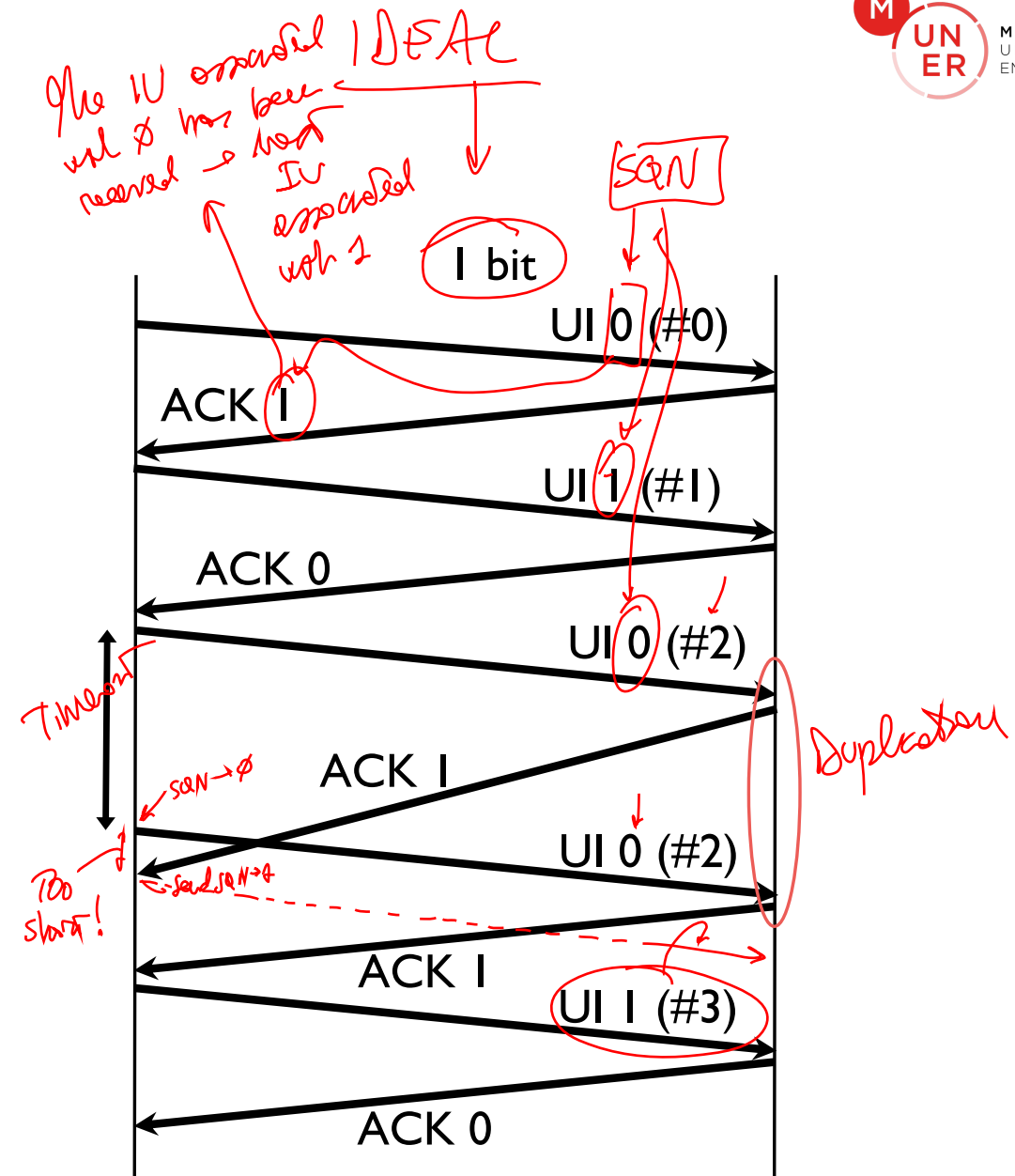
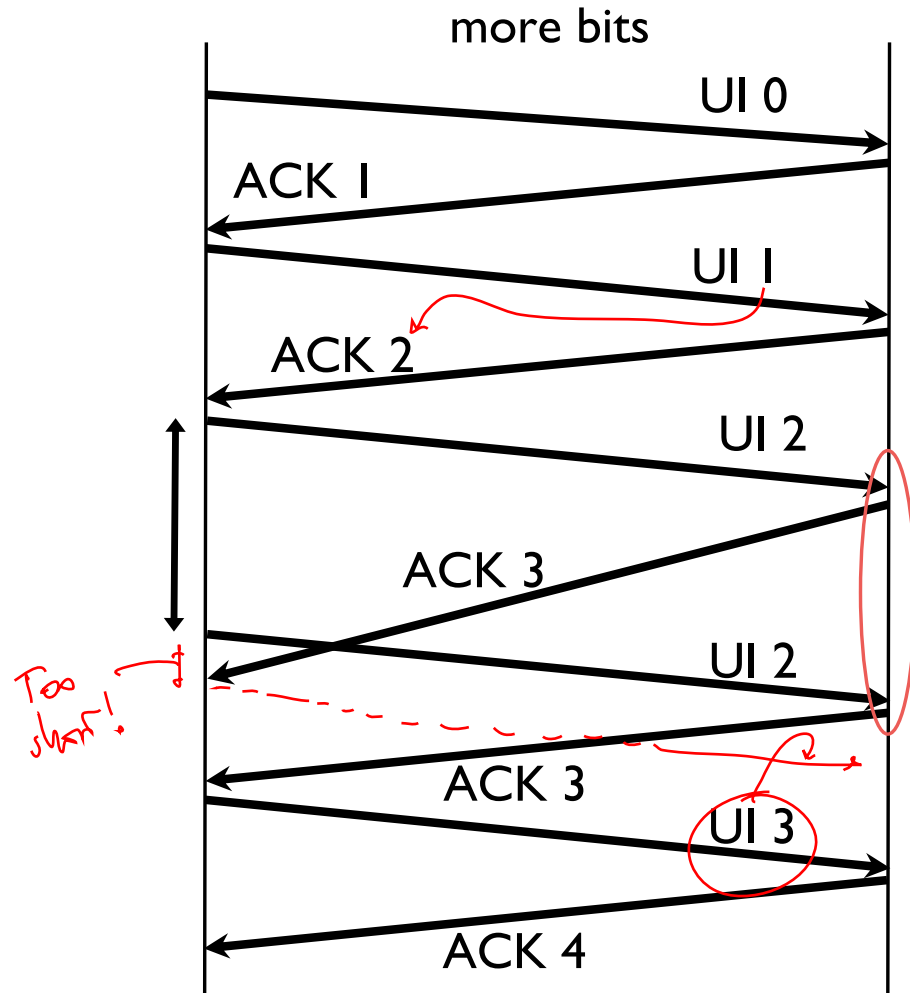
At Transport
timeout is
dynamically
updated on the
basis of
RTT
moments

IMPOSSIBLE!

Example



Example with SQN



Stop and wait: performance (1)

No error

- Total time required to send an IU and receive feedback

$$T_1 = T_U + T_A + 2T_p \quad \text{See p. 76}$$

- Maximum degree of channel utilization

$$\rho_0 = \frac{T_U}{T_1} = \frac{T_U}{T_U + T_A + 2T_p}$$

$$\frac{T_U}{T_U + 2T_p} = \frac{1}{1 + 2T_p/T_U} = \begin{cases} \frac{1}{2 + 2T_p/T_U} & \text{se } T_U = T_A \\ \frac{1}{2T_p/T_U + 1} & \text{se } T_U \gg T_A \\ 0 & \text{se } T_p \gg T_U \end{cases}$$

se $T_U = T_A$

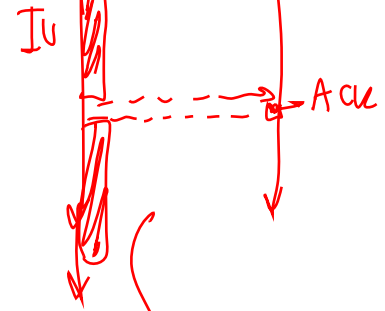
se $T_U \gg T_A$

se $T_p \gg T_U$

If $T_p \ll T_U$,
then $\rho_0 \approx 1$

Very common!

Result is too large!
2 packets to send!



With errors

- Average number of
Successful TXs

$$P\{\text{# of } 1\text{'s} = 1\} = 1 - p$$

$$P\{\text{# of } 1\text{'s} = 2\} = p(1-p)$$

$$P\{\text{# of } 1\text{'s} = 3\} = p^2(1-p)$$

$$\vdots$$

$$P\{\text{# of } 1\text{'s} = k\} = p^{k-1}(1-p)$$

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