Programming Assignment #2 Report 0516007 高誌佑

1. Implementation Details

For the basic backtrack search, I implement it with a stack. Each node contains current variables with value assigned, domain of unassigned variable, and current number of mine for the conveneience of checking the constraint of total mine number. When a node was popped, do one of the following actions:

- 1. output the solution if all variables are assigned.
- 2. failure is detected if the domain of the current unassigned variable is empty, cut the node
- 3. generate the child nodes for every value in domain, update the domains after the assigning the value of the current variable, and insert child nodes into the stack.

 (I update the domains without doing forward checking. The empty domains of some variables will only be detected when child nodes is popped in the future.)

For the forward checking, do the consistency check before insert child nodes into the stack. The child nodes will not be inserted if some failures are detected. The consistenct check includes checking whether the domains of variables can satisfy all the hints and the number of total mine.

For MRV heuristic, when a node is popped, I use a linear search for finding an unassigned variable with the fewest legal value. Then, assign this variable first.

For Degree heuristic, before the backtrack search, I calculate the number of constraint of each variable and sort the variables according to the number. Since the number of constraint will not change during the process of search, I sort the variables in the beginning rather than use a linear search every time when a node is popped.

For LCV heuristic, for both values, I use the consistency check to calculate the sum of the size of domains of the affected variables. The values with less affected domains are tried first.

My code finds **all the solutions** rather than only a legal solution, since I noticed it after I have done all the experiments and the report. As a result, the experiment results and the analysis are based on the implementation of finding all solutions.

2. Experiments results, Observations, and Interpretations

Below are some settings in all experiments:

• Machine (CPU): AMD Ryzen 7-3700X 3.6GHz

Operating System: Ubuntu 18.04

• Language: C++

• Compiler Version: gcc 7.5.0

• The execution time are the average time of five trial.

Execution Time and Expanded Nodes Comparison

This test compares the execution time and the number of expanded nodes with different board sizes, number of mines and hints. The following tables show the results. The red color means it is the fastest among basic search and three heuristics.

First, I test the board size 6x6 using the sample testcase1 given in the spec.

From the below table, we can see that the time and the expanded nodes are less than the basic backtrack search when we apply MRV and Degree heuristic. MRV tends to choose the variable with the fewest legal values, while Degree heuristic gives variables with more constraints higher priority. To a certain degree, more constraints means less selections, so both of them aim to handle variables with less selection first. In this way, it can further avoid some failures, and that is why the time and the number of expanded nodes are less.

As for LCV, it uses the consistency check to decide which value should be tried first. However, the execution time is longer than the basic search. I guess the reason is that the overhead is heavy and that I try value 0 first by default. Value 0 means the variable is not a mine, and it usually affects less domains of other variables in the game. Thus, LCV is hard to improve the performance. I also change my code that value 1 is tried first, and the execution time of LCV decreases a little, but is still longer than that of basic search.

For the forward checking, it detects the failures earlier, so it helps to reduce the execution time and the number of expanded nodes. The basic search and three heuristic all becomes faster.

• Board Size: 6 x 6, 10 mines, 16 hints

Algorithm	Time	Expanded Nodes
Basic	2.07 ms	156
MRV	1.08 ms	72
Degree	1.91 ms	139
LCV	2.61 ms	153
Basic + forward checking	1.85 ms	125
MRV + forward checking	0.94 ms	63
Degree + forward checking	1.22 ms	85
LCV + forward checking	2.49 ms	123

I also do the experiments with board size 9x9 (the testcase is randomly generated).

The results is similar to 6x6 board. The difference is that Degree heuristic performs better than MRV here. I think which one has better performance is case by case.

In addition, I experiment with more mines and hints. As the number of mines and hints grow, the number of solutions decreases. Therefore, the initial domains of all variables are limited, so failures are usually detected very early. It results in less execution time and expanded nodes.

• Board Size: 9 x 9, 15 mines, 24 hints

Algorithm	Time	Expanded Nodes
Basic	360 ms	43649
MRV	33 ms	2439
Degree	30 ms	1684
LCV	422 ms	43620
Basic + forward checking	126 ms	12319
MRV + forward checking	20 ms	1215
Degree + forward checking	17 ms	1012
LCV + forward checking	148 ms	12268

• Board Size: 9 x 9, 22 mines, 36 hints

Algorithm	Time	Expanded Nodes
Basic	3.56 ms	196
MRV	0.87 ms	45
Degree	0.90 ms	49
LCV	4.19 ms	186
Basic + forward checking	2.34 ms	116
MRV + forward checking	0.86 ms	45
Degree + forward checking	0.87 ms	45
LCV + forward checking	2.78 ms	107

In the last, I do the experiments with board size 12x12 (the testcase is randomly generated).

The execution time and the number of expanded nodes become larger. The basic search and LCV even cannot finish in one minute. However, it still finishes quickly when there are many mines and hints. Here, we can easily realize the importance of a good heuristic in searching.

• Board Size: 12 x 12, 30 mines, 48 hints

Algorithm	Time	Expanded Nodes
Basic	> 60 s	-
MRV	5.82 s	428315
Degree	3.27 s	179619
LCV	> 60 s	-
Basic + forward checking	> 60 s	-
MRV + forward checking	1.93 s	153907
Degree + forward checking	0.81 s	56108
LCV + forward checking	> 60 s	-

• Board Size: 12 x 12, 40 mines, 64 hints

Algorithm	Time	Expanded Nodes
Basic	117 ms	9585
MRV	10 ms	413
Degree	25 s	1812
LCV	131 ms	9453
Basic + forward checking	62 ms	3959
MRV + forward checking	8 ms	323
Degree + forward checking	13 ms	551
LCV + forward checking	67 ms	3894

3. Things I have learned

It is the first time that I implement these three kinds of heuristics. It is very interesting to combine the searching with different heuristics. A good heuristic can enhance the performance very much. I indeed benefit a lot from thinking why these heuistics works. In addition, I learn the concept of forward checking. I will think about these concepts when I implement searching next time.

4. Remaining Questions and Future Investigations

In this programming assignment, the performance of LCV seems not good. I am wondering in which case that LCV will speedup a lot. In the future, I will also attemp to find a better heuristic function to further improve the performance.

Appendix: Source code

};

```
Compile Command: g++ -g -Wall -o search main.cpp
       main.cpp
#include <bits/stdc++.h>
using namespace std;
const int MAX SIZE = 100;
int board[MAX SIZE][MAX SIZE];
char c board[MAX SIZE][MAX SIZE]; // for output solution
int constraints[MAX SIZE][MAX SIZE]; // for degree heuristic
const int dx[8] = \{-1, -1, -1, 0, 0, 1, 1, 1\};
const int dy[8] = \{-1, 0, 1, -1, 1, -1, 0, 1\};
int board size x, board size y, mine total, solution num = 0;
bool forward check;
int heuristic type;
struct Node {
  vector<vector<int>> assignments; // variables with value assigned from root to this node
  vector<vector<int>> domains;
                                   // domains of unassigned variables
  vector<pair<int, int>> unassigned;// coordinate of unassigned variables
  int current mine num; // the number of mines from root to this node
  Node () {
    assignments.resize(board size x, vector<int>(board size y, 0));
    domains.resize(board size x, vector<int>(board size y, -1));
    unassigned.clear();
    current mine num = 0;
  }
  Node (const vector<vector<int>> &assignments, const vector<vector<int>> &domains, \
         const vector<pair<int, int>> &unassigned, int current mine num)
    : assignments(assignments), domains(domains), unassigned(unassigned),\
       current mine num(current mine num) {}
};
// sort according to constraints in Degree heuristic
struct Degree cmp {
  bool operator() (pair<int, int> a, pair<int, int> b) {
    return constraints[a.first][a.second] > constraints[b.first][b.second];
```

```
bool is outside(int x, int y) {
  return x < 0 \parallel x \ge board\_size\_x \parallel y < 0 \parallel y \ge board\_size\_y;
}
void output(const vector<vector<int>> &assignments) {
  int mine num = 0;
  for (int i = 0; i < board size x; i++) {
     for (int j = 0; j < board size y; j++) {
       if (board[i][j] == -1) {
          if (assignments[i][j] == 0) c_board[i][j] = '-';
          if (assignments[i][j] == 1) c_board[i][j] = '*', mine_num++;
       else {
          c board[i][j] = char('0' + board[i][j]);
     }
  if (mine num != mine total) return;
  ++solution num;
  // cout << "Solution " << solution num << ":\n";
  // for (int i = 0; i < board size x; <math>i++) {
       for (int j = 0; j < board size y; j++) {
  //
          cout << c board[i][j] << " ";
  //
       }
  //
       cout \ll "\n";
  // }
  // cout << "====
}
void init root(Node &node) {
  // init the value assignments of variables
  for (int x = 0; x < board size x; x++) {
     for (int y = 0; y < board size y; y++) {
       if (board[x][y] == -1) {
          node.assignments[x][y] = -1;
          node.unassigned.push back(make pair(x, y));
        }
     }
  }
  // init the domains (and constraints) of variables
  memset(constraints, 0, sizeof(constraints));
  for (int x = 0; x < board size x; x++) {
     for (int y = 0; y < board size y; y++) {
```

```
if (board[x][y] != -1) continue;
       int current domain = 0b11;
       for (int i = 0; i < 8; i++) {
         int center x = x + dx[i];
         int center y = y + dy[i];
         if (is outside(center x, center y)) continue;
         if (board[center x][center y] == -1) continue;
         constraints[x][y]++;
         int mine num = 0;
         int space num = 0;
         for (int j = 0; j < 8; j++) {
            int outer x = center x + dx[j];
            int outer y = center y + dy[j];
            if (is_outside(outer_x, outer_y)) continue;
            if (board[outer x][outer y] == -1) {
              if (node.assignments[outer x][outer y] == 1) mine num++;
              if (node.assignments[outer_x][outer_y] == -1) space_num++;
            }
         }
         int mine need = board[center x][center y] - mine num;
                                     current domain &= 0b01;
         if (mine need == 0)
         else if (mine need == space num) current domain &= 0b10;
         else if (mine need \leq space num) current domain &= 0b11;
         else if (mine need > space num) current domain &= 0b00;
         if (current domain == 0b00) break;
       node.domains[x][y] = current domain;
  }
  if (heuristic type == 2) sort(node.unassigned.begin(), node.unassigned.end(), Degree cmp());
}
void backtrack search(const Node &root) {
  int num expand = 0;
  stack<Node> frontier;
  frontier.push(root);
  while (!frontier.empty()) {
```

```
Node node = frontier.top(); frontier.pop();
// successfully find a solution when all variables are assigned
if (node.unassigned.empty()) {
  output(node.assignments);
  continue;
}
num expand++;
pair<int, int> variable = node.unassigned.front();
int x = variable.first, y = variable.second;
int current domain = node.domains[x][y];
// if the domain is empty then cut the node
if (current domain == 0) continue;
vector<int> value bit{0, 1};
// LCV (only when domain is still \{0, 1\})
if (heuristic type == 3 && current domain == 0b11) {
  int domain affect[2] = \{0, 0\};
  for (int k : value bit) {
     vector<vector<int>>> assignments = node.assignments;
     vector<vector<int>>> domains = node.domains;
     vector<pair<int, int>> unassigned;
     unassigned.assign(node.unassigned.begin() + 1, node.unassigned.end());
     assignments[x][y] = k;
     bool not satisfied = false; // forward checking
     for (int i = 0; i < 8; i++) {
       int center x = x + dx[i];
       int center y = y + dy[i];
       if (is outside(center x, center y)) continue;
       if (board[center x][center y] == -1) continue;
       int mine num = 0, space_num = 0;
       for (int j = 0; j < 8; j++) {
          int outer x = center x + dx[i];
          int outer y = center y + dy[j];
          if (is outside(outer x, outer y)) continue;
          if (board[outer x][outer y] == -1) {
            if (assignments[outer x][outer y] == 1) mine num++;
```

```
if (assignments[outer x][outer y] == -1) space num++;
       int mine need = board[center x][center y] - mine num;
       int update domain;
       if (mine need == 0)
                                   update domain = 0b01;
       else if (mine need == space num) update domain = 0b10;
       else if (mine need < space num) update domain = 0b11;
       else if (mine need > space num) update domain = 0b00;
       for (int j = 0; j < 8; j++) {
         int outer x = center x + dx[i];
         int outer y = center y + dy[j];
         if (is outside(outer x, outer y)) continue;
         if (board[outer x][outer y] == -1 && assignments[outer x][outer y] == -1) {
            domain affect[k] += builtin popcount(domains[outer x][outer y]);
            domains[outer x][outer y] &= update domain;
            domain affect[k] -= builtin popcount(domains[outer x][outer y]);
            if (domains [outer x] [outer y] == 0) {
              not satisfied = true;
    if (not satisfied) domain affect[k] = INT MAX;
  // if value 1 is better, try value 1 first
  if (domain affect[0] > domain affect[1]) {
    swap(value bit[0], value bit[1]);
  }
}
for (int k : value bit) {
  if ((current domain & (1 << k)) == 0) continue;
  vector<vector<int>> assignments = node.assignments;
  vector<vector<int>> domains = node.domains;
  vector<pair<int, int>> unassigned;
  unassigned.assign(node.unassigned.begin() + 1, node.unassigned.end());
  int current mine num = node.current mine num + k;
  assignments[x][y] = k;
  bool not satisfied = false; // forward checking
```

```
// update the domains of other variables
for (int i = 0; i < 8; i++) {
  int center x = x + dx[i];
  int center y = y + dy[i];
  if (is outside(center x, center y)) continue;
  if (board[center x][center y] == -1) continue;
  int mine num = 0, space num = 0;
  for (int j = 0; j < 8; j++) {
     int outer x = center x + dx[j];
     int outer y = center y + dy[j];
    if (is outside(outer x, outer y)) continue;
    if (board[outer x][outer y] == -1) {
       if (assignments[outer x][outer y] == 1) mine num++;
       if (assignments outer x) outer y] == -1) space num++;
     }
  int mine need = board[center x][center y] - mine num;
  int update domain;
  if (mine need == 0)
                              update domain = 0b01;
  else if (mine need == space num) update domain = 0b10;
  else if (mine need < space num) update domain = 0b11;
  else if (mine need > space num) update domain = 0b00;
  for (int j = 0; j < 8; j++) {
     int outer x = center x + dx[i];
    int outer y = center y + dy[j];
    if (is_outside(outer_x, outer_y)) continue;
    if (board[outer x][outer y] == -1 && assignments[outer x][outer y] == -1) {
       domains[outer_x][outer_y] &= update_domain;
       if (forward check && domains[outer x][outer y] == 0) {
          not satisfied = true;
       }
  }
// return earlier if constraints will not be satisfied
if (forward check) {
  if (not satisfied) continue;
  int low bound = 0, upp bound = 0;
  for (const auto &variable : unassigned) {
     int vx = variable.first, vy = variable.second;
```

```
if (domains[vx][vy] & 0b10) upp bound++;
            if (domains[vx][vy] == 0b10) low bound++;
         // check constraint of total mine number
         if ((low bound + current mine num > mine total) ||
            (upp_bound + current_mine_num < mine_total)) continue;
       }
       // MRV
       if (heuristic type == 1) {
         int min legal value = 3, index = 0, len = unassigned.size();
         for (int i = 0; i < len; i++) {
            int vx = unassigned[i].first, vy = unassigned[i].second;
            int bits = builtin popcount(domains[vx][vy]);
            if (bits < min legal value) {
              min legal value = bits;
              index = i;
            }
         }
         if (index != 0) swap(unassigned[0], unassigned[index]);
       frontier.push(Node{assignments, domains, unassigned, current mine num});
  }
  cout << "Number of solutions: " << solution num << "\n";
  cout << "Number of expanded nodes: " << num expand << "\n";
}
int main(int argc, char **argv) {
  if (argc > 1) forward check = (atoi(argv[1]) == 1);
  if (argc > 2) heuristic type = atoi(argv[2]);
  else
            heuristic type = 0;
  cout << "forward check: " << forward check << " heuristic: " << heuristic type << "\n";
  cin >> board size x >> board size y >> mine total;
  Node root:
  for (int i = 0; i < board size x; i++) {
    for (int j = 0; j < board size y; j++) {
       cin >> board[i][j];
     }
  init root(root);
```

```
auto t1 = std::chrono::high_resolution_clock::now();
backtrack_search(root);
auto t2 = std::chrono::high_resolution_clock::now();
auto duration = std::chrono::duration_cast<std::chrono::microseconds>( t2 - t1 ).count();
cout << float(duration) / 1000.0 << " ms\n";
return 0;
}</pre>
```