

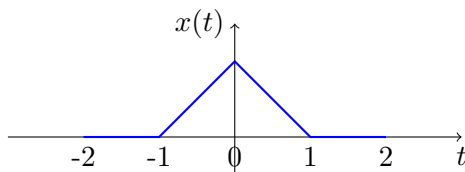
# EE1101: Signals and Systems JAN—MAY 2019

## Tutorial 1 Solutions

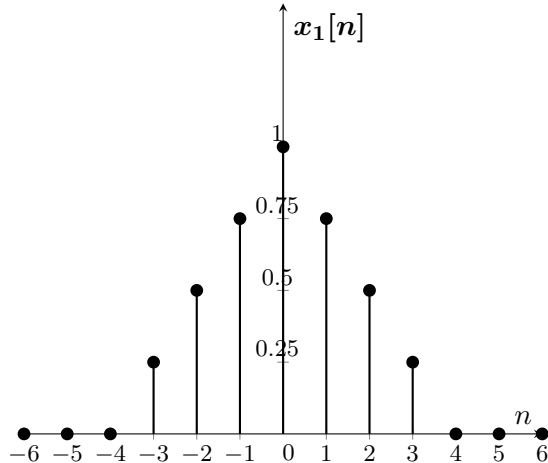
### Solution 1

$$x(t) = \begin{cases} 1 - |t| & -1 \leq t \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

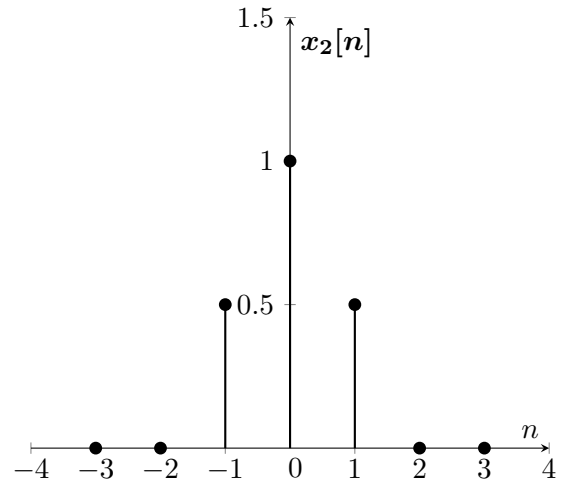
$x(t)$  is a triangular function from -1 to +1. The plot is shown below.



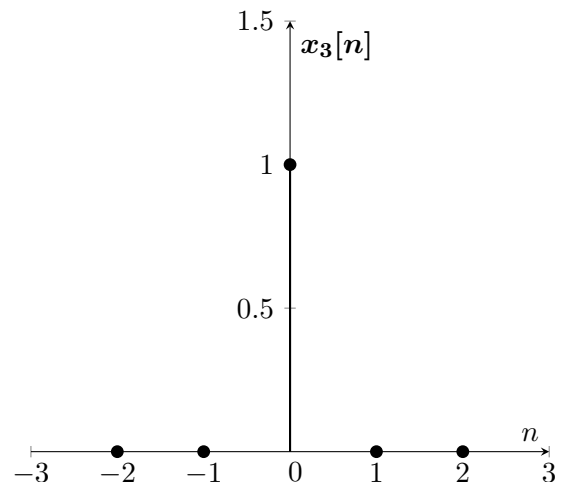
- when sampled at 0.25s,  $x(t)$  becomes a discrete sequence taking values at  $t = 0.25n$  where  $n = 0, \pm 1, \pm 2, \pm 3 \dots$ . The plot is shown below.



- when sampled at 0.5s,  $x(t)$  becomes a discrete sequence taking values at  $t = 0.5n$  where  $n = 0, \pm 1, \pm 2, \pm 3 \dots$ . The plot is shown below.

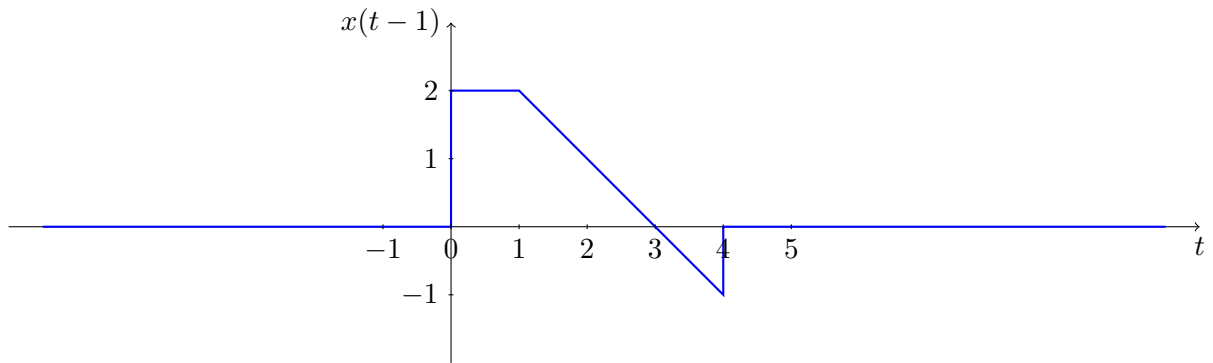


- when sampled at 1s,  $x(t)$  becomes a discrete sequence taking values at  $t = n$  where  $n = 0, \pm 1, \pm 2, \pm 3 \dots$ . The plot is shown below.

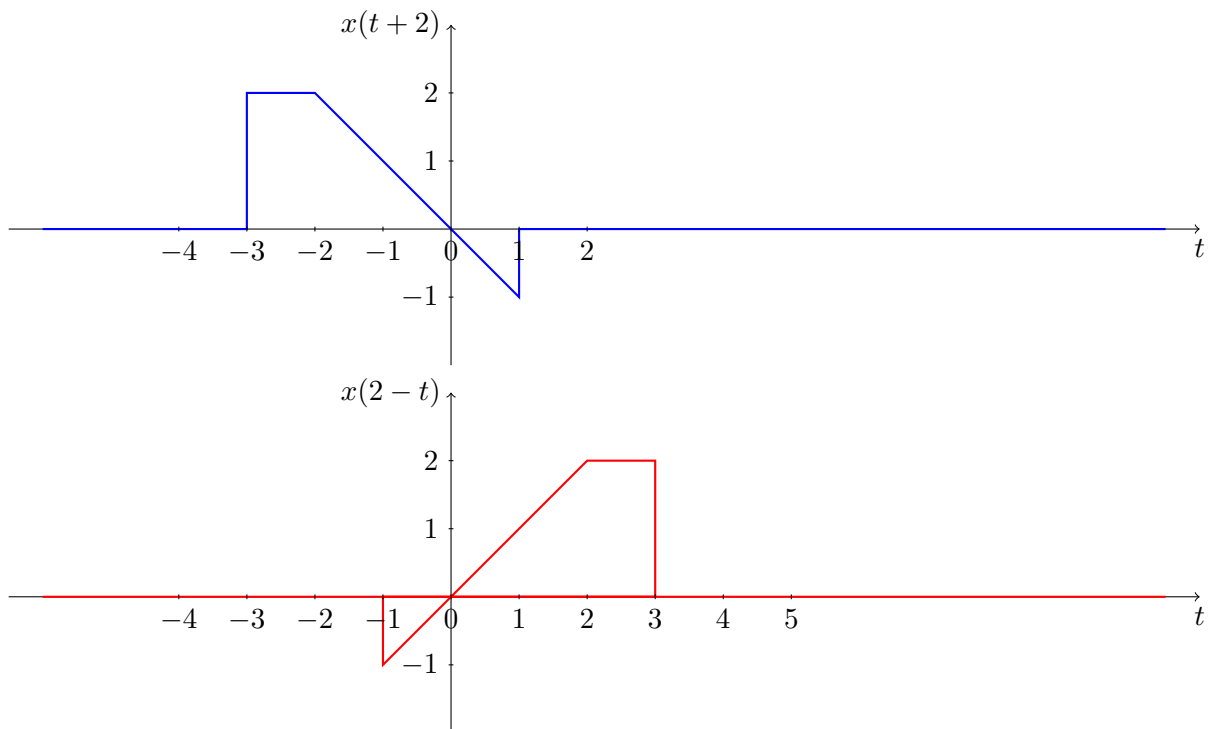


## Solution 2

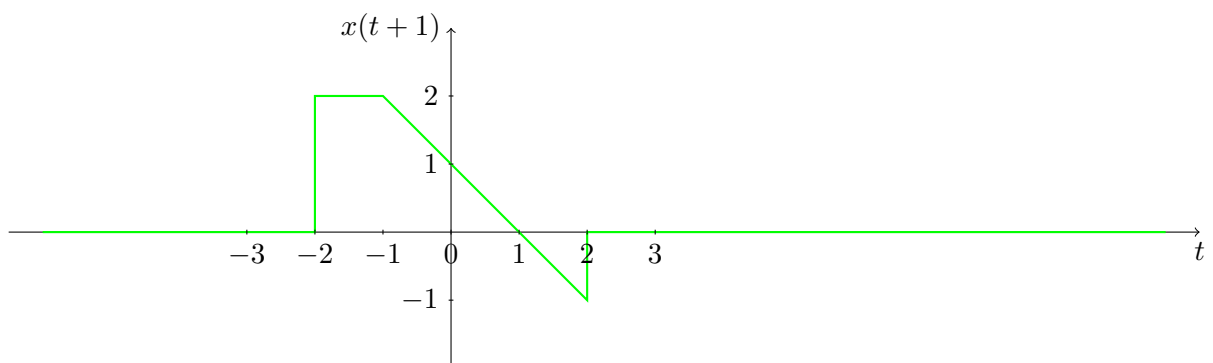
- (a)  $x(t-1)$  can be obtained by shifting  $x(t)$  right by 1 unit as shown below.

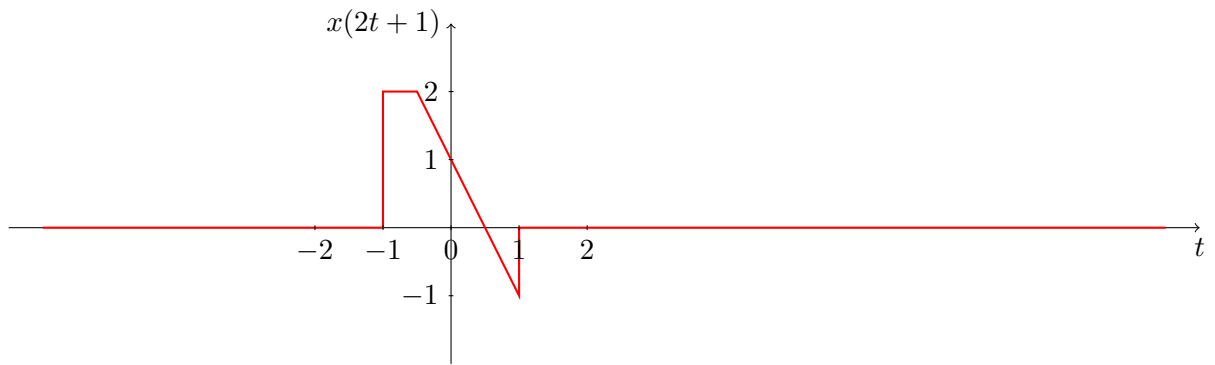


- (b)  $x(2-t) = x(-t+2)$  can be obtained by shifting  $x(t)$  left by 2 units and then reversing the time axis as shown below.

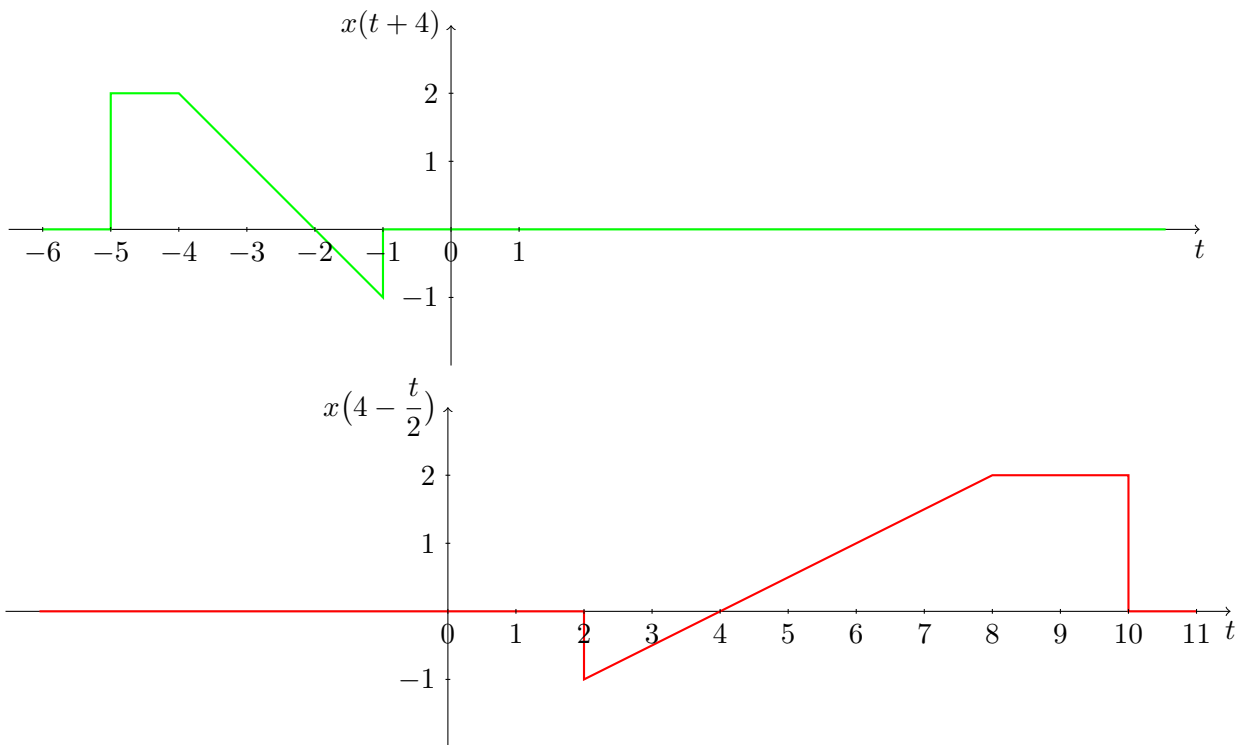


- (c)  $x(2t+1)$  can be obtained by shifting  $x(t)$  left by 1 unit and then scaling the time axis by a factor of 2 as shown below.

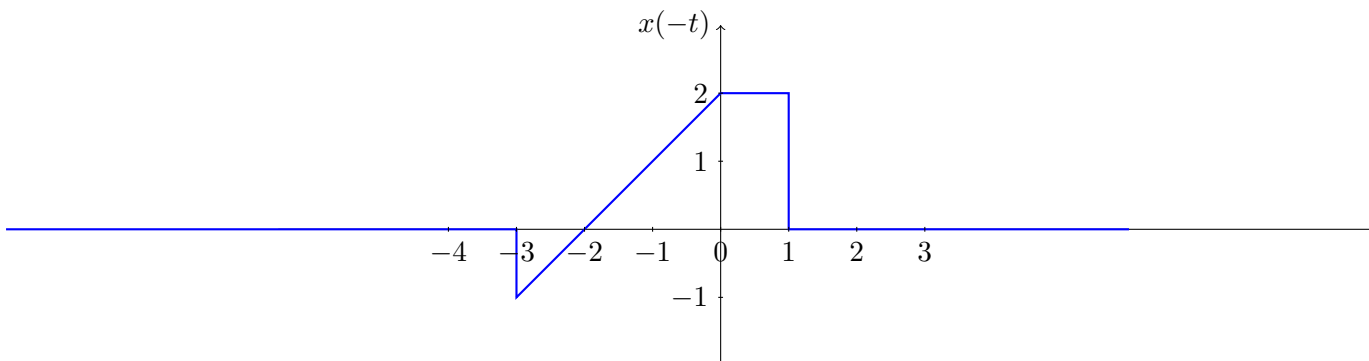


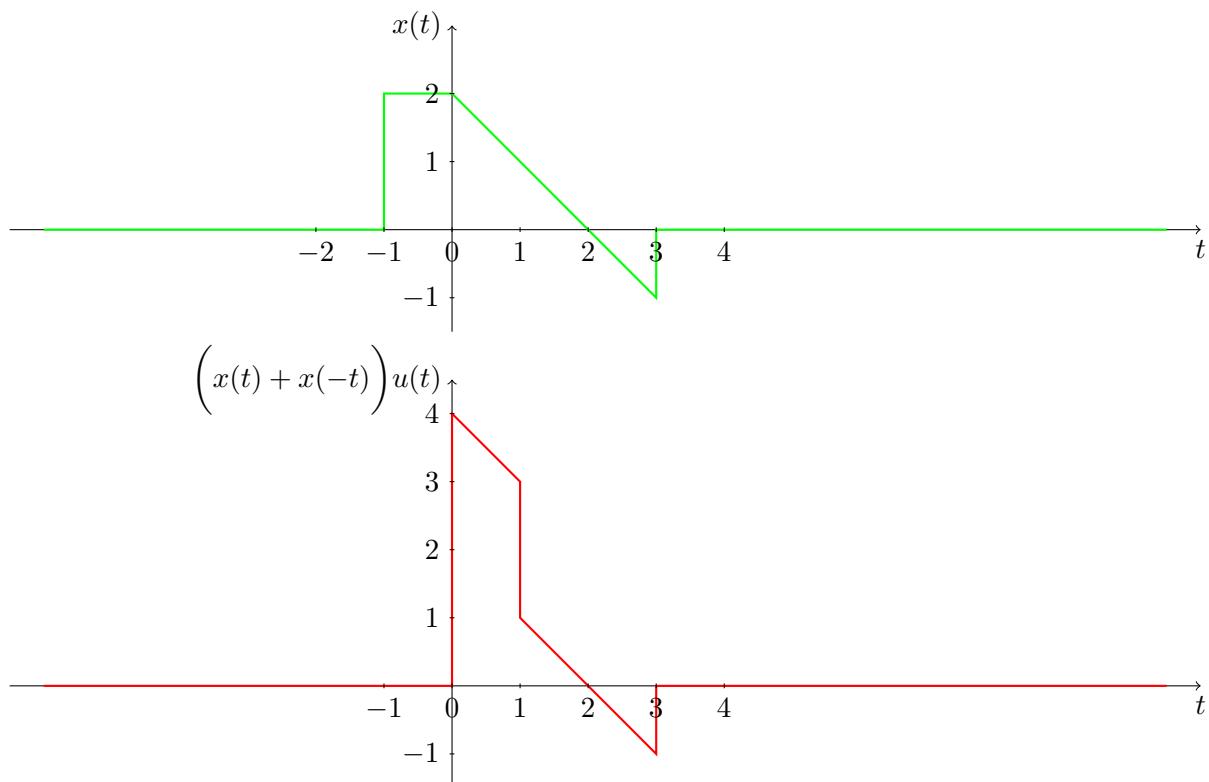


(d)  $x(4 - \frac{t}{2})$  can be plotted in a similar way as shown below.

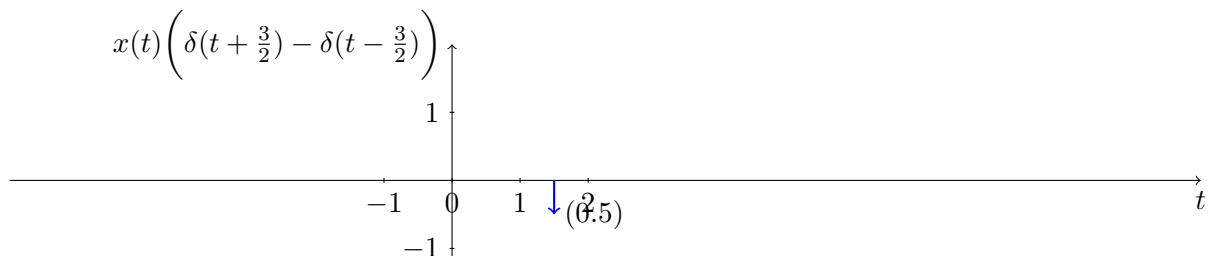


(e) The signals  $x(t)$  and  $x(-t)$  are added and the result is multiplied with  $u(t)$ , which makes the resultant signal causal.





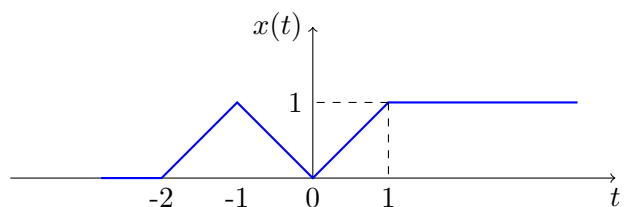
- (f) The signal  $x(t) \left( \delta(t + \frac{3}{2}) - \delta(t - \frac{3}{2}) \right)$  consists of impulse samples of the signal  $x(t)$  at  $t = \frac{3}{2}$  and  $t = -\frac{3}{2}$ .



### Solution 3

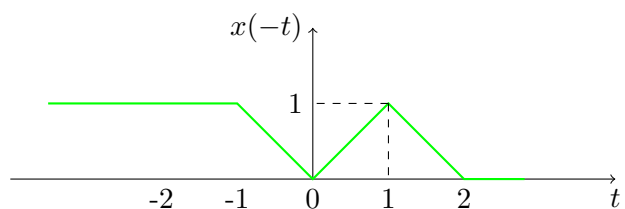
- (a) The even part of a signal  $x(t)$  can be calculated as

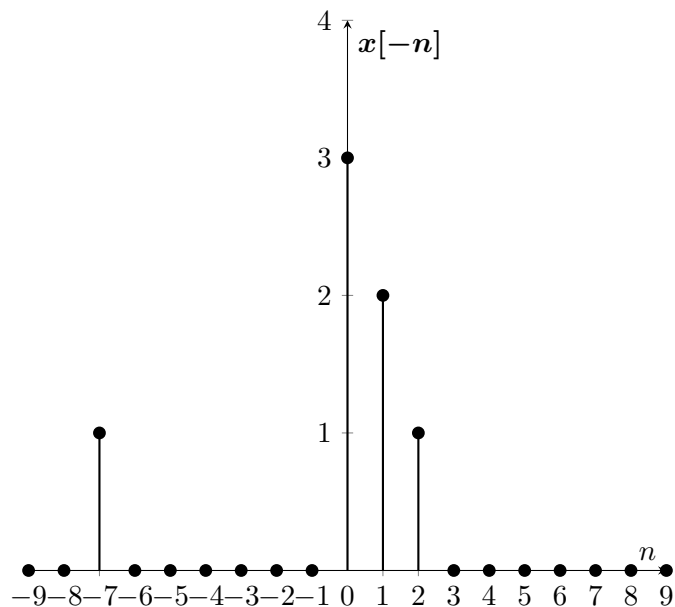
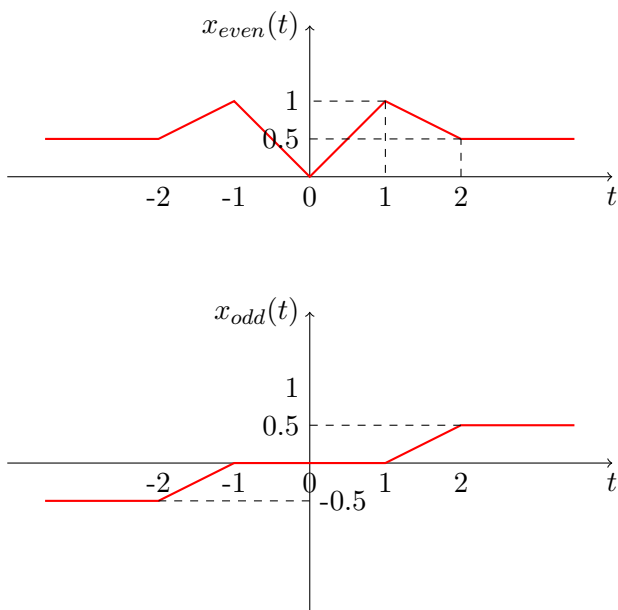
$$x_{\text{even}}(t) = \frac{x(t) + x(-t)}{2}$$



- The odd part of a signal  $x(t)$  can be calculated as

$$x_{\text{odd}}(t) = \frac{x(t) - x(-t)}{2}$$



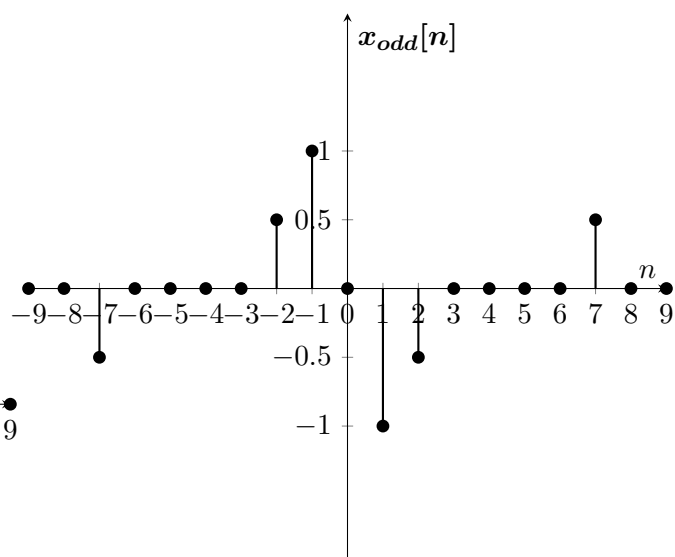
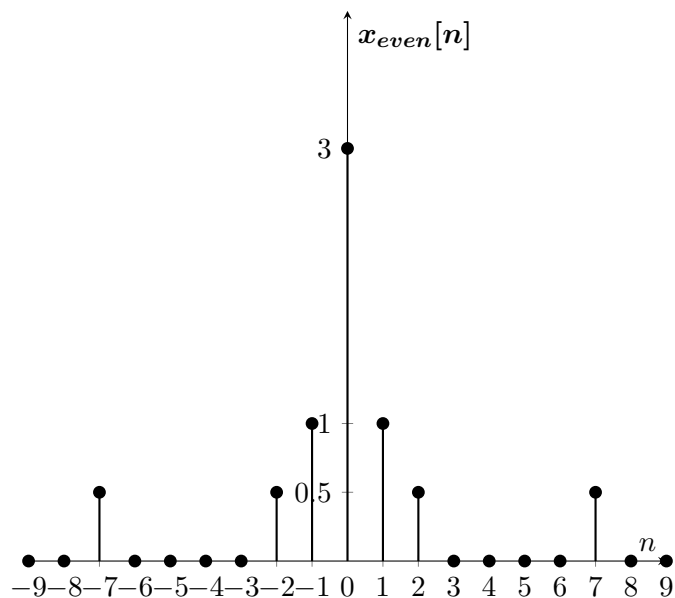
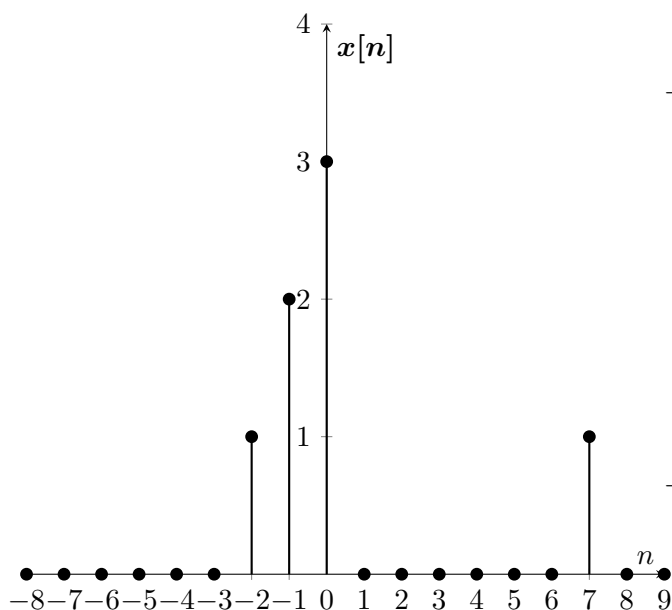


(b) The even part of a signal  $x[n]$  can be calculated as

$$x_{\text{even}}[n] = \frac{x[n] + x[-n]}{2}$$

The odd part of a signal  $x[n]$  can be calculated as

$$x_{\text{odd}}[n] = \frac{x[n] - x[-n]}{2}$$



## Solution 4

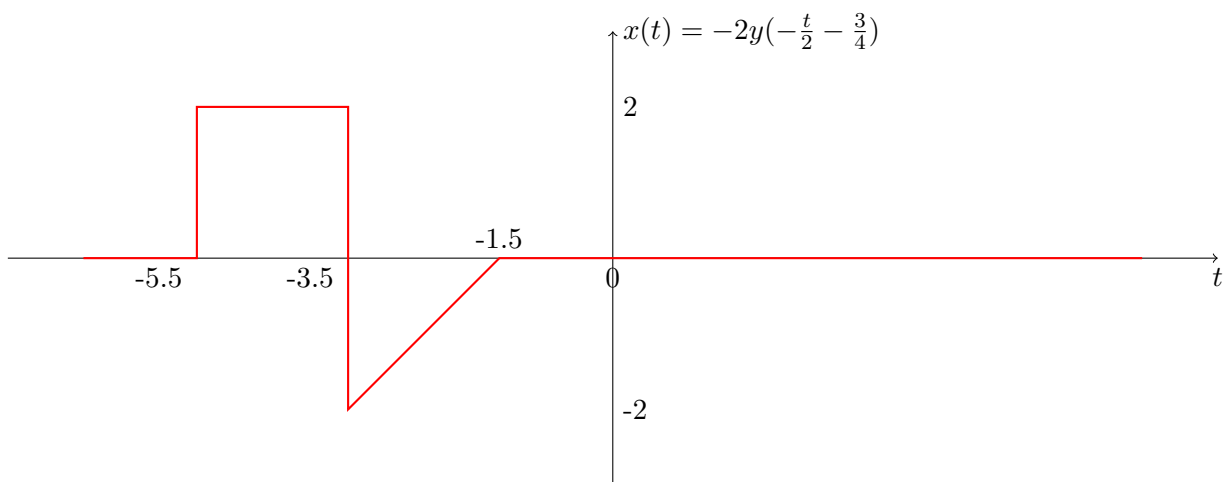
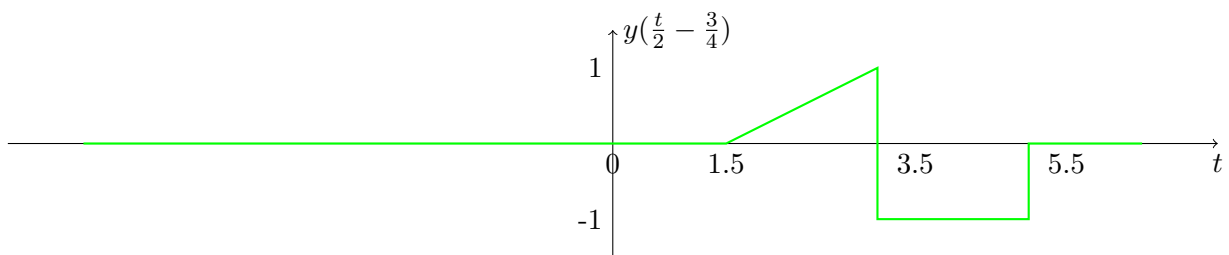
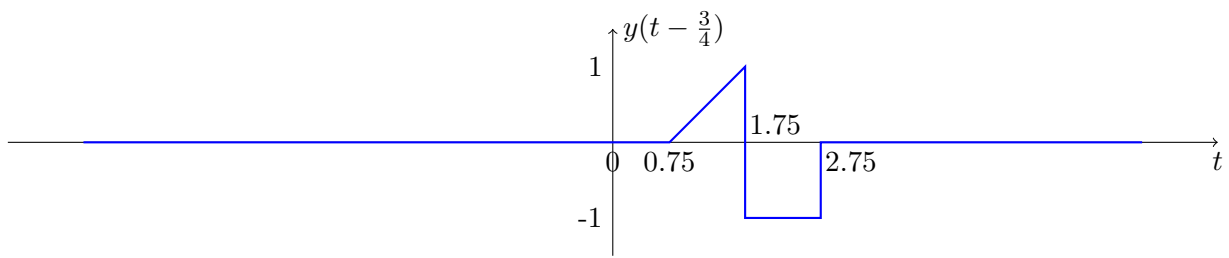
The signal  $x(t)$  can be obtained from  $y(t)$  through the change of variables as shown below

$$y(t) = \frac{-1}{2}x\left(-2t - \frac{3}{2}\right)$$

$$\text{Let } t' = -2t - \frac{3}{2}$$

$$y\left(-\frac{(t' + \frac{3}{2})}{2}\right) = \frac{1}{2}x(t')$$

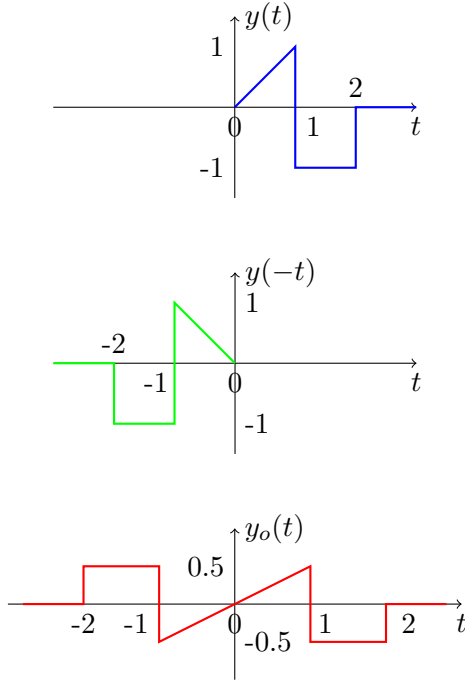
$$x(t) = -2y\left(-\frac{t}{2} - \frac{3}{4}\right)$$



For the odd portion of  $y(t)$ ,

$$y_o(t) = \frac{y(t) - y(-t)}{2}$$

$$y_o = \begin{cases} 0 & t < -2 \\ 0.5 & -2 \leq t < -1 \\ \frac{t}{2} & -1 \leq t < 1 \\ -0.5 & 1 \leq t \leq 2 \\ 0 & t > 2 \end{cases}$$



## Solution 5

For a signal expanded as  $x(t) = \sum_k A_k e^{s_k t}$  where  $A_k$  is in general complex, the complex frequency components present are the  $s_k$ 's and each  $s_k = \sigma_k + j\omega_k$

(a)  $\sin(2t) = \frac{1}{2j}(e^{2jt} - e^{-2jt})$   
the complex frequencies thus are  $j2$  and  $-j2$ .

(b)  $e^{-5t} \cos(3t) = \frac{1}{2}e^{-5t}(e^{3jt} + e^{-3jt}) = \frac{1}{2}(e^{(-5+3j)t} + e^{(-5-3j)t})$   
the complex frequencies thus are  $-5+j3$  and  $-5-j3$ .

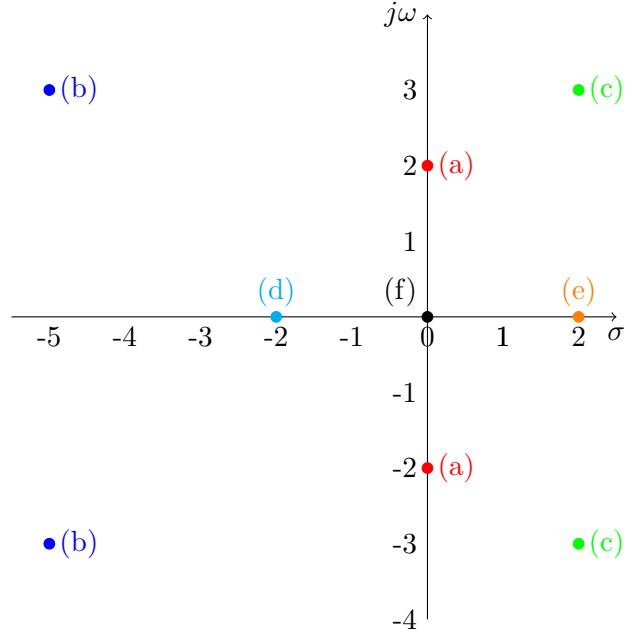
(c)  $e^{2t} \cos(3t) = \frac{1}{2}e^{2t}(e^{3jt} + e^{-3jt}) = \frac{1}{2}(e^{(2+3j)t} + e^{(2-3j)t})$   
the complex frequencies thus are  $2+j3$  and  $2-j3$ .

(d)  $e^{-2t}$   
clearly the complex frequency is  $-2$ .

(e)  $e^{2t}$   
the complex frequency is  $2$ .

(f)  $5$   
It is a DC signal, hence the frequency is  $0$ .

The complex frequencies are plotted in the complex plane below.



## Solution 6

The power of signal  $x(t)$  can be calculated as

$$P_x = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{t=-T/2}^{T/2} |x(t)|^2 dt$$

For a periodic signal with period  $T$  this may be just computed over a time period as:

$$P_x = \frac{1}{T} \int_{t=0}^T |x(t)|^2 dt$$

and the RMS value is the square-root of  $P_x$

(a) For the signal  $x(t) = \sum_{k=m}^n D_k e^{j\omega_k t}$  (periodic with period  $T$ ), the power can be calculated as

$$\begin{aligned} P_x &= \frac{1}{T} \int_{t=-T/2}^{T/2} x(t) x^*(t) dt \quad (\because |x(t)|^2 = x(t) x^*(t)) \\ &= \frac{1}{T} \int_{t=-T/2}^{T/2} \sum_{k=1}^n D_k e^{j\omega_k t} \sum_{l=1}^n D_l^* e^{-j\omega_l t} dt \\ &= \frac{1}{T} \int_{t=-T/2}^{T/2} \sum_{k=1}^n D_k D_k^* e^{j(\omega_k - \omega_k)t} dt \\ &\quad + \frac{1}{T} \sum_{k=1}^n \sum_{l=1; k \neq l}^n D_k D_l^* \int_{t=-T/2}^{T/2} e^{j(\omega_k - \omega_l)t} dt \\ &= \frac{1}{T} * T \sum_{k=1}^n D_k D_k^* \\ &\quad + \frac{1}{T} \sum_{k=1}^n \sum_{l=1; k \neq l}^n D_k D_l^* \int_{t=-T/2}^{T/2} e^{j(\omega_k - \omega_l)t} dt \\ &= \sum_{k=1}^n |D_k|^2 \quad (\because \int_{t=-T/2}^{T/2} e^{j(\omega_k - \omega_l)t} dt = 0) \end{aligned}$$

The frequencies are distinct and hence the sinusoids are orthogonal and when you integrate  $e^{j(\omega_k - \omega_l)t}$  over the period T gives you zero.

(b) (a)  $x(t) = 10\cos(5t)\cos(10t)$

$$\begin{aligned} x(t) &= 2.5(e^{j5t} + e^{-j5t})(e^{j10t} + e^{-j10t}) \\ &= 2.5(e^{j15t} + e^{-j5t} + e^{j5t} + e^{-j15t}) \end{aligned}$$

From the above expression, power can be calculated as:

$$P_x = 2.5^2 \times 4 = 25$$

(b)  $x(t) = 10\cos(100t + \frac{\pi}{3}) + 5\sin(100t + \frac{\pi}{6})$

$$\begin{aligned} x(t) &= 5(e^{j(100t + \frac{\pi}{3})} + e^{-j(100t + \frac{\pi}{3})}) \\ &\quad - 2.5j(e^{j(100t + \frac{\pi}{6})} - e^{-j(100t + \frac{\pi}{6})}) \\ &= 5(e^{j(100t + \frac{\pi}{3})} + e^{-j(100t + \frac{\pi}{3})}) \\ &\quad + 2.5(e^{j(100t + \frac{\pi}{6} - \frac{\pi}{2})} - e^{-j(100t + \frac{\pi}{6} + \frac{\pi}{2})}) \\ &= (5e^{j\frac{\pi}{3}} + 2.5e^{-j\frac{\pi}{3}})e^{j100t} \\ &\quad + (5e^{-j\frac{\pi}{3}} + 2.5e^{j\frac{\pi}{3}})e^{-j100t} \end{aligned}$$

Power:

$$\begin{aligned} P_x &= 2|5e^{j\frac{\pi}{3}} + 2.5e^{-j\frac{\pi}{3}}|^2 \\ &= 2 \times \frac{75}{4} \\ &= 37.5 \end{aligned}$$

## Solution 7

Any signal  $x(at + b)$  can be obtained from  $x(t)$  in 2 ways

(i) First shifting, then scaling

Find  $x(t + b)$  first then replace  $t$  with  $at$  to obtain  $x(at + b)$

(ii) First scaling, then shifting

$x(at + b) = x(a(t + b/a))$  Find  $x(at)$  first then shift left/right depending on the sign of  $b/a$  to obtain  $x(at + b)$

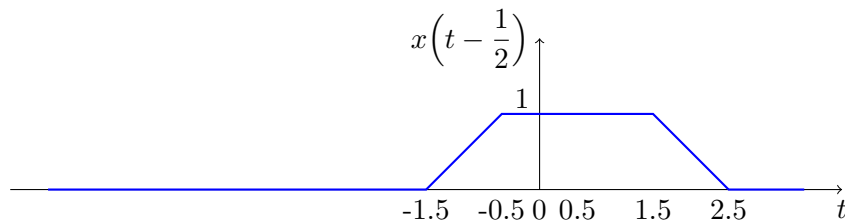
We shall follow the first method.

(a)  $y(t) = 3x\left(-\frac{1}{2}(t + 1)\right)$

$$y(t) = 3x\left(-\frac{1}{2}t - \frac{1}{2}\right)$$

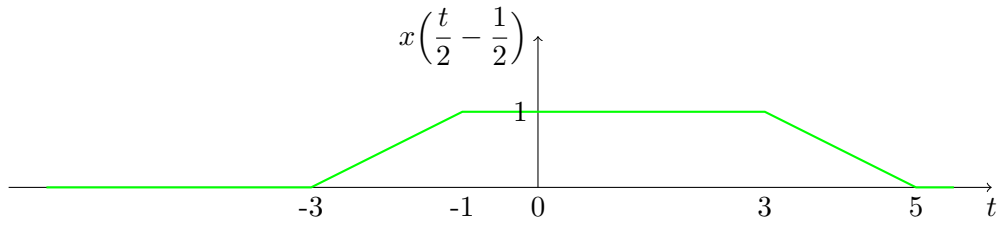
First we will find  $x\left(t - \frac{1}{2}\right)$

Here  $a = -1/2, b = 1/2$ . Since  $b$  is positive, we should delay the signal or shift it towards right

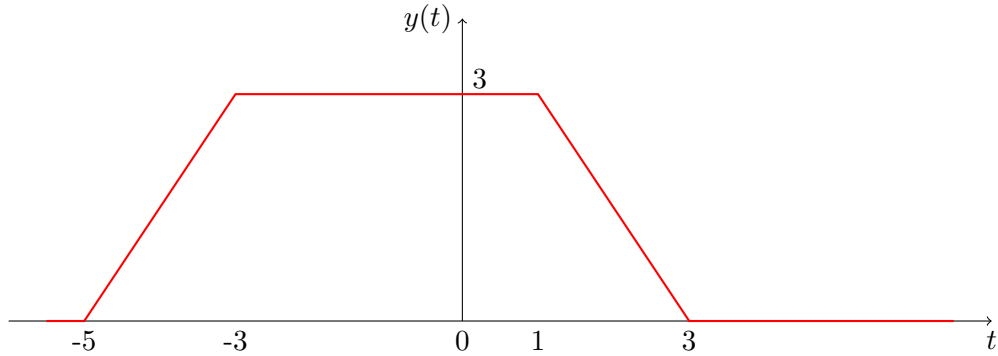


Now replace  $t$  with  $-\frac{1}{2}t$  in the above plot and redraw. Since  $a = -1/2$ , it is a combination of scaling and reflection. We will do scaling with  $1/2$  first and then take the reflection about y-axis. Since  $a = -1/2 < 1$ , we should expand the signal.





Now take the reflection about y-axis to get  $x\left(-\frac{t}{2} - \frac{1}{2}\right)$ . Finally multiply the amplitude by 3 units to obtain  $y(t)$



- (b) The energy of a signal  $x(t)$  can be calculated as Hence, Energy of  $y(t)$

$$E_x = \int_{t=-\infty}^{\infty} |x(t)|^2 dt$$

$$\begin{aligned} E_y &= \int_{-5}^{-3} |y_1(t)|^2 dt + \int_{-3}^1 |y_2(t)|^2 dt + \int_1^3 |y_3(t)|^2 dt \\ &= \int_{-5}^{-3} \left| \frac{3}{2}(t+5) \right|^2 dt + \int_{-3}^1 |3|^2 dt + \int_1^3 \left| -\frac{3}{2}(t-1) \right|^2 dt \\ &= \frac{9}{4} \left| \frac{(t+5)^3}{3} \right|_{-5}^{-3} + |9t|_{-3}^1 + \frac{9}{4} \left| \frac{(t-3)^3}{3} \right|_1^3 \\ &= \frac{9}{4} \times \frac{8}{3} + 9 \times 4 + \frac{9}{4} \times \frac{8}{3} \\ &= 48 \end{aligned}$$

The signal  $y(t)$  can be expressed as  $y(t) = y_1(t) + y_2(t) + y_3(t)$  where

$$y_1(t) = \frac{3}{2}(t+5), -5 \leq t \leq -3$$

$$y_2(t) = 3, -3 \leq t \leq 1$$

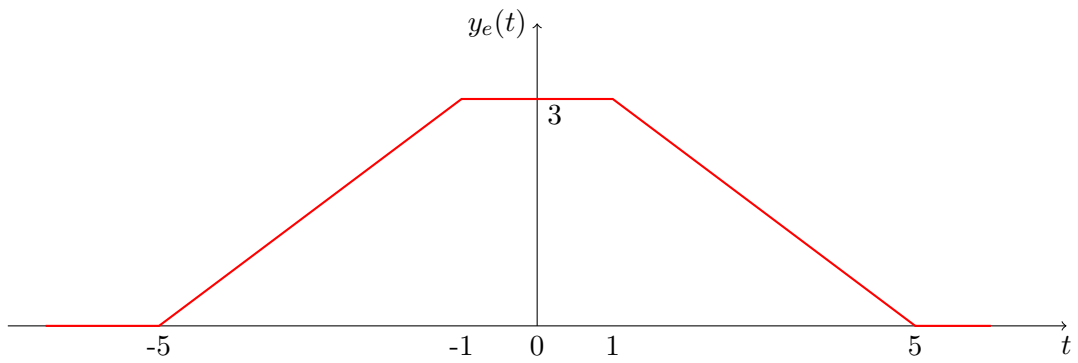
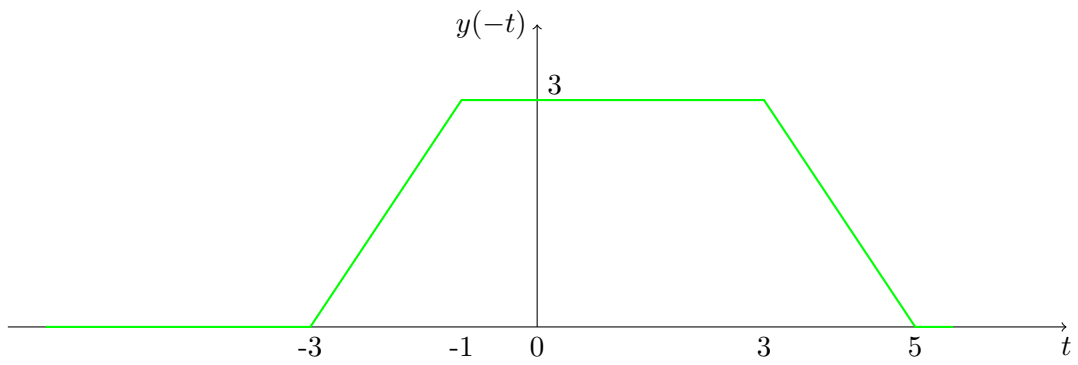
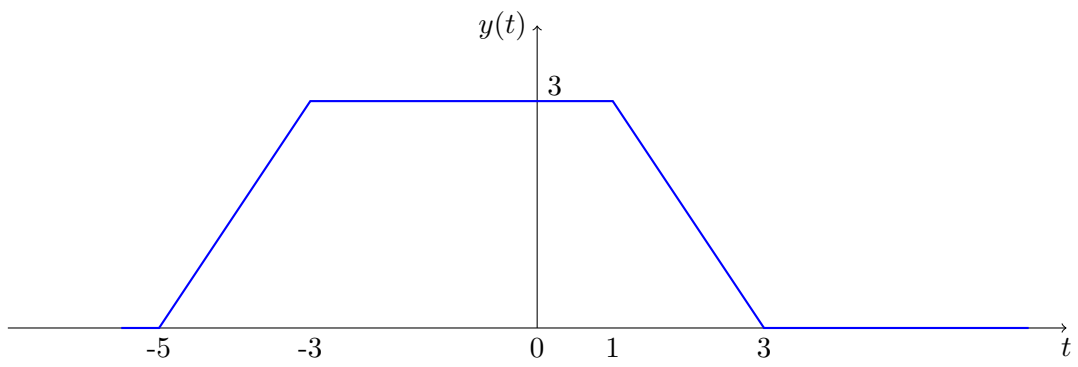
$$y_3(t) = -\frac{3}{2}(t-3), 1 \leq t \leq 3$$

The power of a signal  $x(t)$  can be calculated as

$$P_x = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt$$

Since the given signal is of finite duration and has finite energy, it is an energy signal. Hence the power is 0.

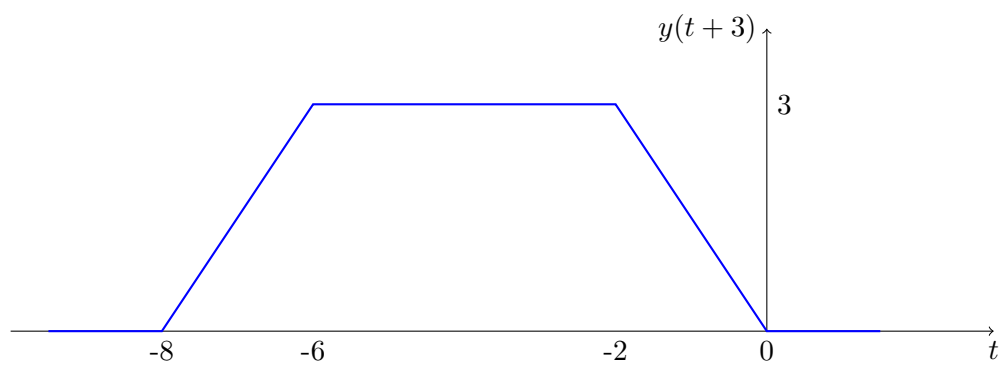
- (c) Even portion of any signal  $y(t)$  is found by  $y_e(t) = \frac{y(t) + y(-t)}{2}$   
 $y(-t)$  is the reflection of  $y(t)$  about y-axis. We will plot  $y(-t)$  now.

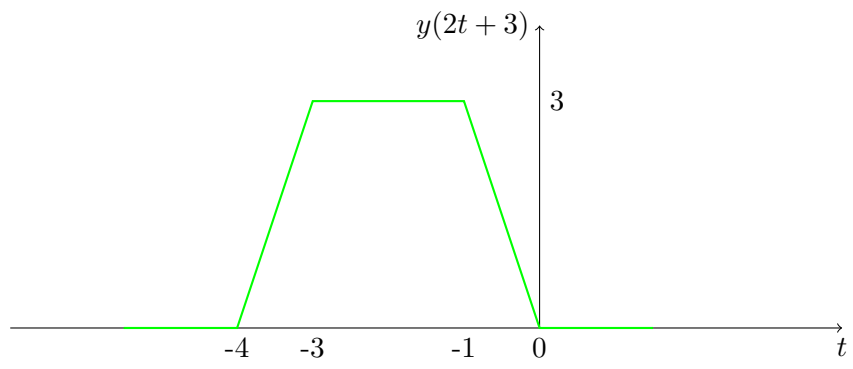


(d)

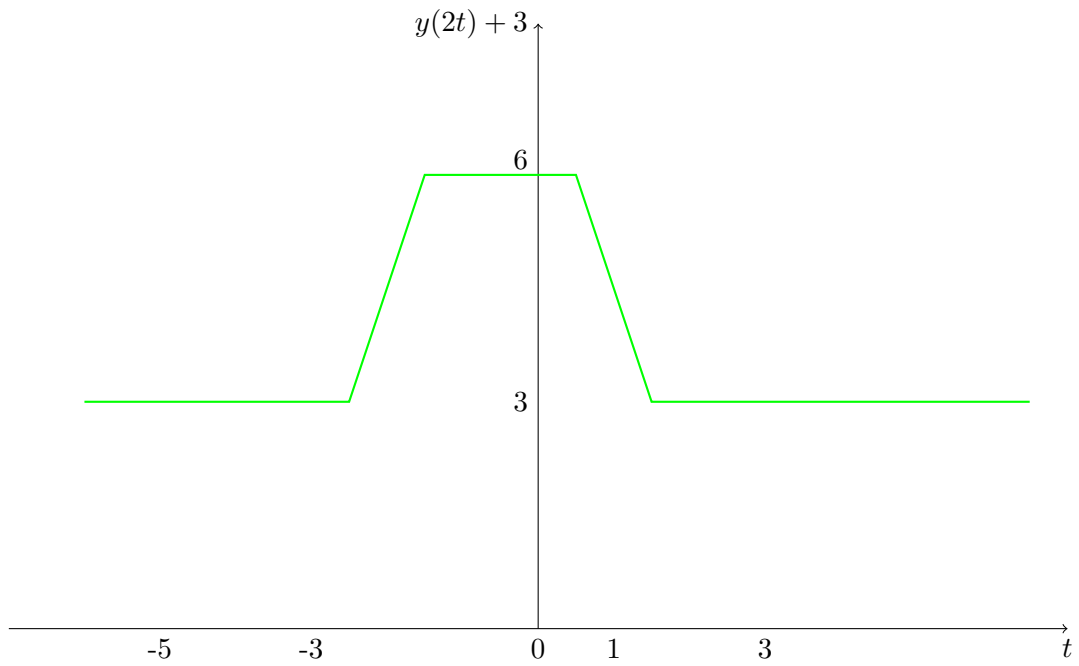
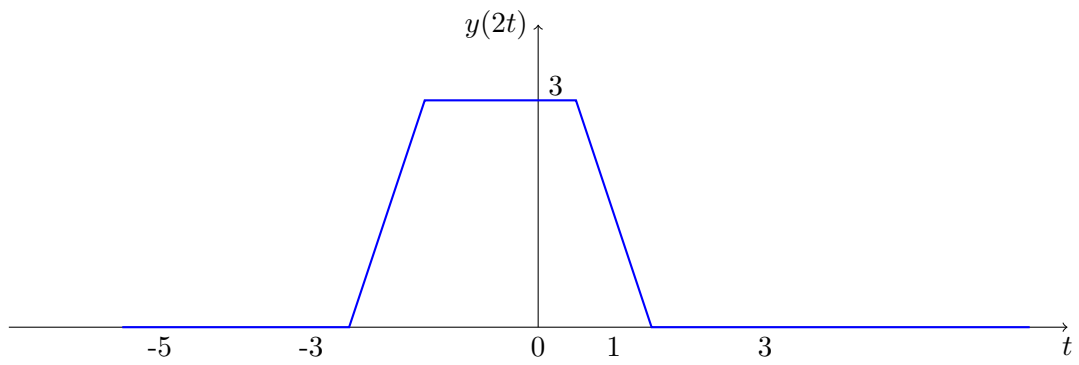
$$a = 2, b = 3$$

$$y(at + b) = y(2t + 3)$$

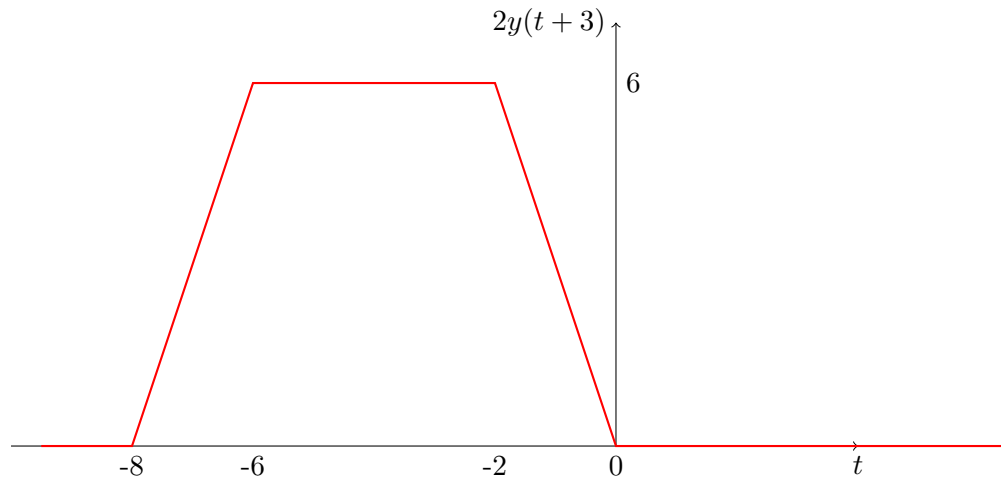




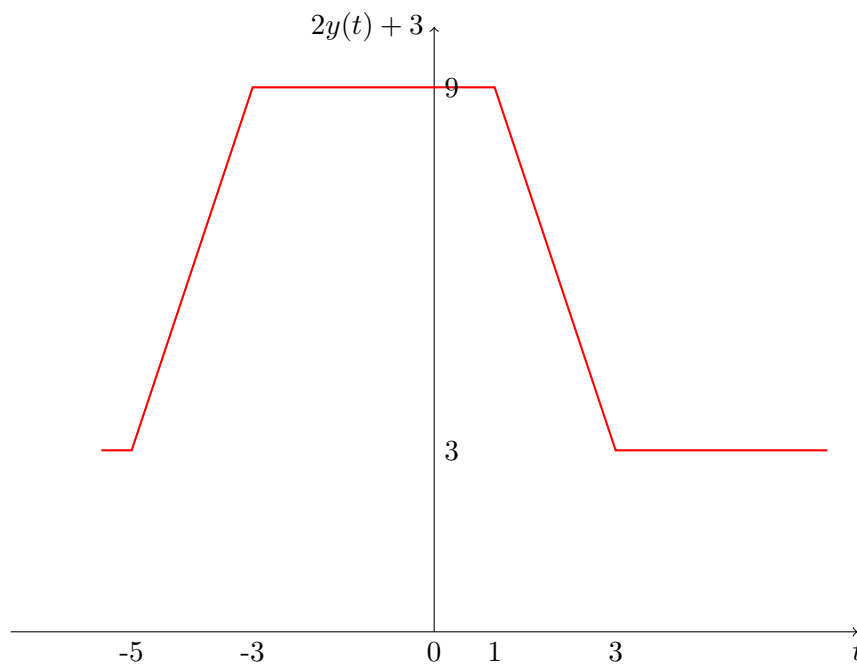
$y(2t) + 3$  is adding a dc value of 3 to  $y(2t)$



$$2y(t+3)$$



$2y(t) + 3$  is adding a dc of 3 to  $y(t)$



## Solution 8

The energy of signal  $x(t)$  can be calculated as

$$E_x = \int_{t=-\infty}^{\infty} |x(t)|^2 dt$$

$$\begin{aligned} E_1 &= \int_{t=-\infty}^{\infty} |(-x(t))|^2 dt \\ &= \int_{t=-\infty}^{\infty} |x(t)|^2 dt \\ &= E_x \end{aligned}$$

(a) (i) The energy of signal  $-x(t)$  can be calculated as

(ii) The energy of signal  $x(-t)$  can be calculated as

$$E_2 = \int_{t=-\infty}^{\infty} |x(-t)|^2 dt$$

$$\text{Let } \tau = -t \Rightarrow d\tau = -dt$$

$$\begin{aligned} \Rightarrow E_2 &= - \int_{\tau=\infty}^{-\infty} |x(\tau)|^2 d\tau \\ &= \int_{\tau=-\infty}^{\infty} |x(\tau)|^2 d\tau \\ &= E_x \end{aligned}$$

$$E_2 = \int_{t=-\infty}^{\infty} |x(at - b)|^2 dt$$

$$\text{Case 1: } a > 0 \Rightarrow a = |a|$$

$$\text{Let } \tau = at - b = |a|t - b$$

$$\Rightarrow d\tau = |a| dt$$

$$\begin{aligned} \Rightarrow E_2 &= \frac{1}{|a|} \int_{\tau=-\infty}^{\infty} |x(\tau)|^2 d\tau \\ &= \frac{E_x}{|a|} \end{aligned}$$

(iii) The energy of signal  $x(t - T)$  can be calculated as

$$E_3 = \int_{t=-\infty}^{\infty} |x(t - T)|^2 dt$$

$$\text{Let } \tau = t - T \Rightarrow d\tau = dt$$

$$\begin{aligned} \Rightarrow E_3 &= \int_{\tau=-\infty-T}^{\infty+T} |x(\tau)|^2 d\tau \\ &= \int_{\tau=-\infty}^{\infty} |x(\tau)|^2 d\tau \\ &= E_x \end{aligned}$$

$$\text{Case 2: } a < 0 \Rightarrow a = -|a|$$

$$\text{Let } \tau = at - b = -|a|t - b$$

$$\Rightarrow d\tau = -|a| dt$$

$$\begin{aligned} \Rightarrow E_2 &= -\frac{1}{|a|} \int_{\tau=\infty}^{-\infty} |x(\tau)|^2 d\tau \\ &= \frac{1}{|a|} \int_{\tau=-\infty}^{\infty} |x(\tau)|^2 d\tau \\ &= \frac{E_x}{|a|} \end{aligned}$$

## Solution 9

(b) (i) The energy of signal  $x(at)$  can be calculated as

$$E_1 = \int_{t=-\infty}^{\infty} |x(at)|^2 dt$$

$$\text{Case 1: } a > 0 \Rightarrow a = |a|$$

$$\text{Let } \tau = at = |a|t \Rightarrow d\tau = |a| dt$$

$$\begin{aligned} \Rightarrow E_1 &= \frac{1}{|a|} \int_{\tau=-\infty}^{\infty} |x(\tau)|^2 d\tau \\ &= \frac{E_x}{|a|} \end{aligned}$$

$$\text{Case 2: } a < 0 \Rightarrow a = -|a|$$

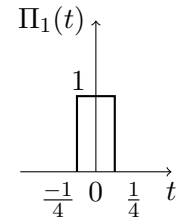
$$\text{Let } \tau = at = -|a|t \Rightarrow d\tau = -|a| dt$$

$$\begin{aligned} \Rightarrow E_1 &= -\frac{1}{|a|} \int_{\tau=\infty}^{-\infty} |x(\tau)|^2 d\tau \\ &= \frac{1}{|a|} \int_{\tau=-\infty}^{\infty} |x(\tau)|^2 d\tau \\ &= \frac{E_x}{|a|} \end{aligned}$$

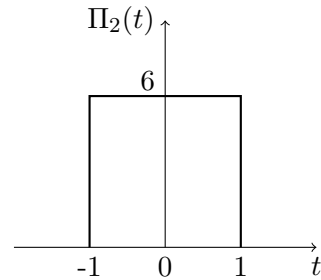
The energy of signal  $\Pi(t)$  can be calculated as

$$E_{\Pi} = \int_{t=-\infty}^{\infty} |\Pi(t)|^2 dt$$

$$\begin{aligned} \text{(a) } \Pi_1(t) &= \Pi(2t) \\ E_{\Pi_1} &= 0.5 \end{aligned}$$

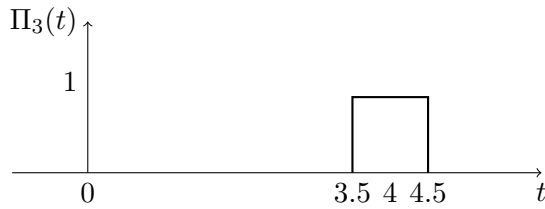


$$\begin{aligned} \text{(b) } \Pi_2(t) &= 6\Pi(0.5t) \\ E_{\Pi_2} &= 72 \end{aligned}$$

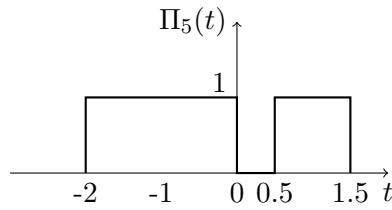


(ii) The energy of signal  $x(at - b)$  can be calculated as

$$\begin{aligned} \text{(c) } \Pi_3(t) &= \Pi(t - 4) \\ E_{\Pi_3} &= 1 \end{aligned}$$

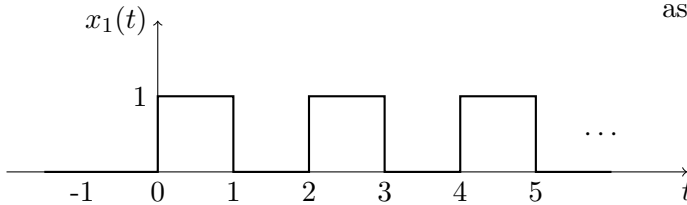


(d)  $\Pi_5(t) = \Pi\left(\frac{t+1}{2}\right) + \Pi(t-1)$   
 $E_{\Pi_5} = 3$



## Solution 10

- (a) The binary signal  $x_1(t)$  can be plotted as shown below:



### Energy of the signal

The energy of signal  $x_1(t)$  can be evaluated as:

$$\begin{aligned} E_1 &= \int_{t=-\infty}^{\infty} |x_1(t)|^2 dt \\ &= \int_{t=0}^{\infty} |x_1(t)|^2 dt \quad (\because x_1(t) = 0, t < 0) \\ &= \int_{t=0}^1 1 \cdot dt + \int_{t=1}^2 0 \cdot dt + \int_{t=2}^3 1 \cdot dt + \int_{t=3}^4 0 \cdot dt + \dots \\ &= 1 + 0 + 1 + 0 + \dots \\ &= \infty. \end{aligned}$$

### Power of the signal

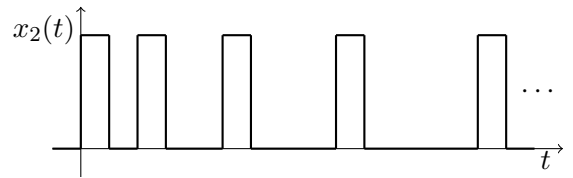
The power of the signal  $x_1(t)$  can be evaluated as:

$$\begin{aligned} P_1 &= \lim_{T \rightarrow \infty} \frac{\int_{t=-T}^T |x_1(t)|^2 dt}{2T} \\ &= \lim_{T \rightarrow \infty} \frac{1}{2} \frac{\int_{t=0}^T |x_1(t)|^2 dt}{T} \end{aligned}$$

Consider  $N$  pulses. The time elapsed would then be  $T = 2N$ .

$$\begin{aligned} \therefore P_1 &= \lim_{N \rightarrow \infty} \frac{1}{2} \frac{N}{2N} \\ &= \frac{1}{4} \end{aligned}$$

- (b) The binary signal  $x_2(t)$  can be plotted as shown below:



### Energy of the signal

The energy of signal  $x_2(t)$  can be calculated as follows:

$$\begin{aligned} E_2 &= \int_{t=0}^{\infty} |x_2(t)|^2 dt \\ &= \int_{t=0}^1 1 \cdot dt + \int_{t=1}^2 0 \cdot dt \\ &\quad + \int_{t=2}^3 1 \cdot dt + \int_{t=3}^4 0 \cdot dt + \dots \\ &= 1 + 0 + 1 + 0 + \dots \infty \\ &= \infty \end{aligned}$$

### Power of the signal

The power of signal  $x_2(t)$  can be calculated as follows:

$$\begin{aligned} P_2 &= \lim_{T \rightarrow \infty} \frac{\int_{t=-T}^T |x_2(t)|^2 dt}{2T} \\ &= \lim_{T \rightarrow \infty} \frac{1}{2} \frac{\int_{t=0}^T |x_2(t)|^2 dt}{T} \end{aligned}$$

Consider  $N$  pulses. The time elapsed would then be  $T = N + (1 + 2 + 3 + \dots + N)$ , i.e.

$$T = N + \frac{N(N+1)}{2} \quad (e)$$

$$\begin{aligned} \therefore P_2 &= \lim_{N \rightarrow \infty} \frac{1}{2} \frac{N}{N + \frac{N(N+1)}{2}} \\ &= \lim_{N \rightarrow \infty} \frac{1}{2} \frac{N}{\frac{N(N+3)}{2}} \\ &= \lim_{N \rightarrow \infty} \frac{1}{N+3} \\ &= 0 \end{aligned}$$

(f)

$$\begin{aligned} x(t) &= A \sin(4\pi t + \pi) \\ \omega &= \frac{2\pi}{T} = 4\pi \\ T &= 0.5 \end{aligned}$$

$$\text{Corresponding power is } P = \frac{A^2}{2}.$$

## Solution 11

A continuous time signal  $x(t)$  is periodic if and only if  $x(t) = x(t+T)$ .

Power of the periodic signal can be evaluated as:

$$P = \frac{1}{T} \int_T |x(t)|^2 dt$$

- (a) All continuous time sinusoidal and complex exponential are periodic.

$$\begin{aligned} x(t) &= \cos(\pi t) \\ \omega &= \frac{2\pi}{T} = \pi \\ T &= 2 \end{aligned}$$

Corresponding power is  $P = 0.5$ .

(b)

$$\begin{aligned} x(t) &= A \sin(10t) \\ \omega &= \frac{2\pi}{T} = 10 \\ T &= \frac{0.2}{\pi} \end{aligned}$$

Corresponding power is  $P = \frac{A^2}{2}$ .

(c)

$$\begin{aligned} x(t) &= \sin(\sqrt{3}\pi t) \\ \omega &= \frac{2\pi}{T} = \sqrt{3}\pi \\ T &= \frac{2}{\sqrt{3}} \end{aligned}$$

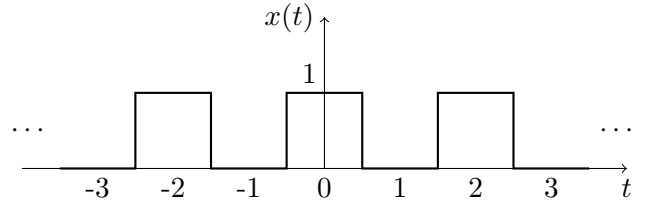
Corresponding power is  $P = 0.5$ .

(d)

$$\begin{aligned} x(t) &= e^{jt} \\ \omega &= 1 \\ T &= 2\pi \end{aligned}$$

Corresponding power is  $P = 1$ .

$$\begin{aligned} x(t) &= \sum_{n=-\infty}^{\infty} \Pi(t-2n) \\ &= \dots + \Pi(t+4) + \Pi(t+2) + \Pi(t) \\ &\quad + \Pi(t-2) + \Pi(t-4) + \dots \end{aligned}$$



From the figure, it can be observed that  $T = 2$ .

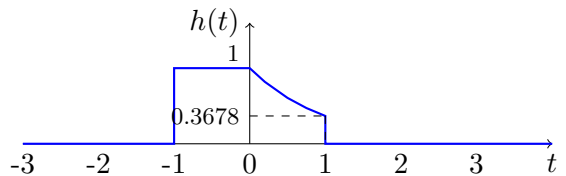
Corresponding power is  $P = 0.5$ .

## Solution 12

(a)

$$h(t) = \exp(-tu(t))$$

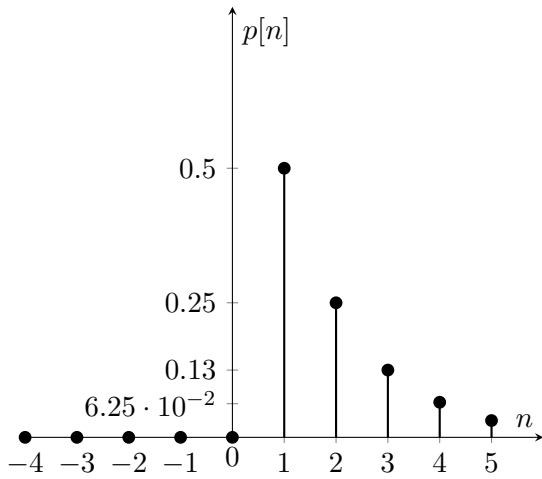
The power of exponential is zero till  $t \leq 0$ . So,  $h(t)$  is 1 till  $t \leq 0$ . For  $t > 0$ ,  $h(t)$  is an exponentially decaying signal. The plot of  $h(t)$  is shown below.



(b)

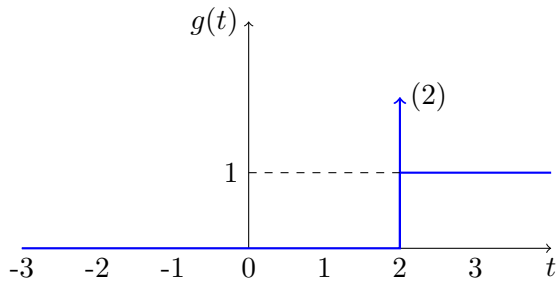
$$p[n] = \frac{1}{2} u[n-1]$$

$p[n]$  is a discrete time sequence which is zero for  $n \leq 0$  and is an exponentially decaying sequence for  $n \geq 1$ . The plot is shown below.



(c)

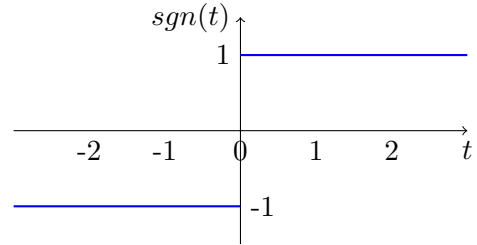
$$\begin{aligned}
 g(t) &= \frac{d}{dt}(u(t-2)r(t)) \\
 &= r(t) \frac{d}{dt}(u(t-2)) + u(t-2) \frac{dr(t)}{dt} \\
 &= r(t)\delta(t-2) + u(t-2)u(t) \\
 &= r(2)\delta(t-2) + u(t-2) \\
 &= 2\delta(t-2) + u(t-2)
 \end{aligned}$$



(d)

$$f(t) = \text{sgn}(e^{-2t} \sin \pi t)$$

The function  $\text{sgn}(t)$  can be plotted as shown below:



$e^{-2t} \sin \pi t$  oscillates with a period of  $T = 2$ . Hence the signal  $f(t)$  can be plotted as shown below:

