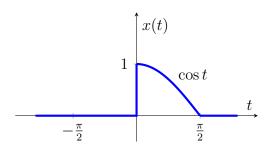
## EE1101 Signals and Systems JAN—MAY 2019 Tutorial 7, Extra Questions

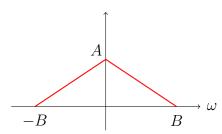
March 18, 2019

1. Find the Fourier transform of the signal x(t) shown below.



2. a) Consider a signal m(t) with its Fourier transform as shown in the figure below. The signal m(t) is multiplied by a sinusoid  $\cos(\omega t)$  to obtain the signal  $x(t) = m(t)\cos(\omega t)$ . Plot the Fourier transform of x(t). Assume  $\omega \gg B$ .

 $M(j\omega)$ 



- b) The signal x(t) is again multiplied by the same sinusoid  $\cos(\omega t)$  to get a new signal y(t). Plot the Fourier transform of y(t).
- c) The signal y(t) is passed through an ideal low pass filter with cut off frequency  $\omega_l$ . What should the range of  $\omega_l$  be so that we recover m(t) at the output of filter.

- 3. a) The impulse response of a linear time-invariant continuous time system is given by  $h(t) = e^{-2t}u(t)$ , where u(t) denotes the unit step function. Calculate the frequency response  $H(\omega)$  of this system in terms of angular frequency  $\omega$ .
  - b) Find the output of this system, to the sinusoidal input  $x(t) = 2\cos(2t)$  for all time t.
- 4. Given that x(t) has the Fourier transform X(jw), Calculate the inverse fourier transform of following functions in terms of x(t).

a) 
$$X(j(w-w_0)) + X(j(w+w_0))$$

- b) Even[X(jw)]
- 5. A signal x(t) can be expressed as the sum of even and odd components as  $x(t) = x_e(t) + x_o(t)$ .
  - a) If  $x(t) \iff X(j\omega)$ , show that for real x(t),  $x_e(t) \iff Re[X(j\omega)]$  and  $x_o(t) \iff jIm[X(j\omega)]$ .
  - b) Verify these results for  $x(t) = e^{-at}u(t)$ .
- 6. Prove that in general, the following relationships hold:

$$\frac{dx(t)}{dt} * y(t) = x(t) * \frac{dy(t)}{dt} = \frac{d(x(t) * y(t))}{dt}$$

Here \* represents convolution, and x(t), y(t) are differentiable.