## EE1101: Signals and Systems Quiz - 2 April 5, 2018

Answer all FOUR questions clearly and concisely.

Roll. No.:\_\_\_\_

Name:\_\_\_\_\_

Instructor (Circle it): DV / KJ / SB / SU

Marks: 40

Time: 50 minutes

1. Consider a sinusoidal signal, 
$$x(t) = A \sin(\pi t)$$
  $\left\{ \mathbf{A} = \mathbf{v} \right\}$ 

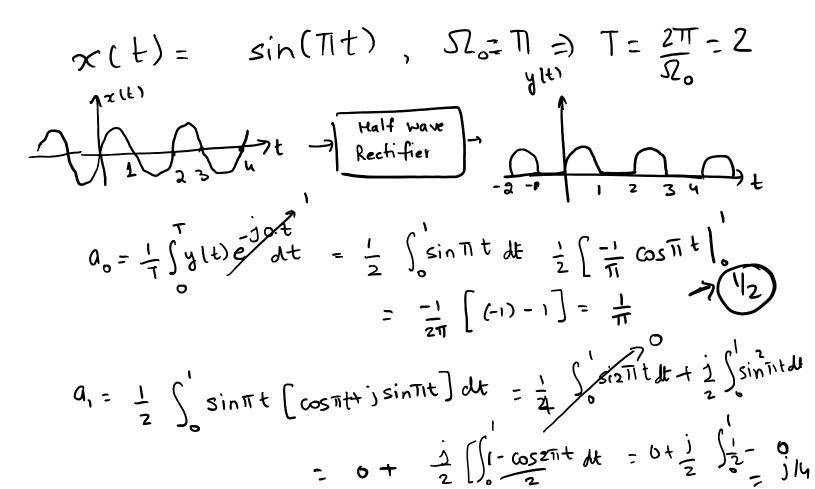
$$\underline{\mathbf{x}(t)} \qquad \left\{ \mathbf{A} = \mathbf{v} \right\}$$
Rectifier  $\mathbf{y}(t)$ 

(a) What are the exponential Fourier series coefficients of the output of half-wave rectifier, i.e. y(t) where

$$y(t) = \begin{cases} x(t) & x(t) \ge 0\\ 0 & x(t) < 0 \end{cases}$$

(Hint: Find  $a_k$  for k = 0, 1, -1 and then for k even and k odd. Use  $\cos(1\pm k)\pi = -\cos(k\pi)$ )

(b) Which F.S. coefficient of y(t) has its value as  $\frac{-j}{4}$ ? What is the frequency,  $\hat{\Omega}$  of the corresponding complex exponential? [10]



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 $a_1 = (3/4) \rightarrow 1$ 

More Work Space for Q1

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$$Q_{-1} = \frac{1}{2} \int_{0}^{1} \sin \pi t \left[ \cos \pi t - j \sin \pi t \right] = -\left( -j/4 \right) = -j/4$$

$$a_{k} = \frac{1}{2} \int_{0}^{1} \sin \pi t \left[ \cos k \pi t + j \sin k \pi t \right] dt$$

$$\int_{0}^{1} \sin (1+k) \pi t + \sin (1-k) \pi t \right] dt = -\frac{1}{4\pi} \left[ \frac{\cos (1+k) \pi t}{1+k} + \cos (1-k) \pi t \right]$$

$$=\frac{1}{2}\left(\frac{1+\cos k\pi}{\pi(1-k^2)}\right)^{2} = 0 \text{ for } k \text{ 71/1} \text{ and } k \text{ 6dd}$$

$$=\frac{1}{2}\left(\frac{1+\cos k\pi}{\pi(1-k^2)}\right)^{2} = \frac{1}{\pi(1-k^2)}, \text{ k even}$$

$$=\frac{1}{2}\int_{0}^{1}\left(\cos \left(1-k\right)\pi t\right) - \cos(1+k)\pi t\right) dt$$

$$=\frac{1}{2}\int_{0}^{1}\left(\sin \pi t\right) \left(\sin k\pi t\right) dt = \frac{1}{2}\int_{0}^{1}\left(\cos \left(1-k\right)\pi t\right) - \cos(1+k)\pi t\right) dt$$

$$\frac{1}{2} \int_{0}^{1} \left( \sin R \right) \left( \sin R \right) dt = \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos \left( 1 - k \right) \right) dt - \frac{1}{4} \int_{0}^{1} \left( \cos$$

Hence 
$$q_0 = \frac{1}{11}$$
,  $q_1 = \frac{3}{4}$ ,  $q_{-1} = -\frac{3}{14}$ 

For 
$$|k| > 1$$
  $\begin{cases} a_k = 0 & \text{if } k \text{ is odd} \\ = \frac{1}{11(1-k^2)} & \text{if } k \text{ is even} \end{cases}$ 

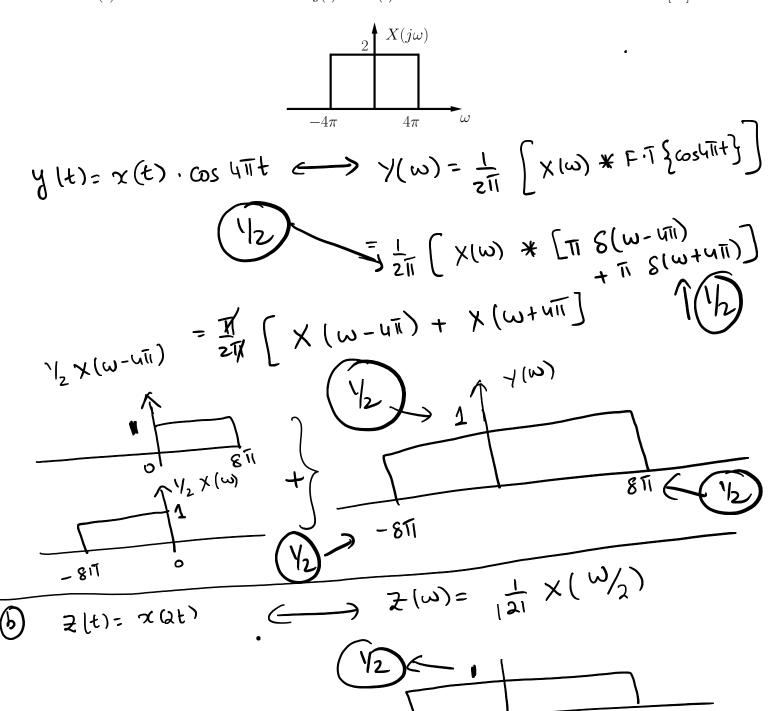
$$\alpha_1 = -i |_{V}$$
  $\Rightarrow$  feque  $k \cdot \frac{2i}{2} = 1 \cdot \frac{2\pi}{a} = \pi$  radians  $\beta_{k=1}$ 

@ Z(t)= y(t)

- 2. Let x(t) (which is real and even) have its Fourier transform,  $X(j\omega)$ , as shown in the figure below. Using Fourier transform properties:
  - (a) Plot the Fourier transform of  $y(t) = x(t)\cos(4\pi t)$ , i.e. plot  $Y(j\omega)$ . Please label properly indicating all important values.
  - (b) Plot the Fourier transform of z(t) = x(2t).
  - (c) What is the relation between y(t) and z(t)?

[10]

ВIJ



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3. Evaluate the energy of the signal, x(t), given below

$$x(t) = 8 \frac{\sin(4\pi t)}{\pi t} \cos(2\pi t)$$

$$8 \cdot \frac{1}{2\pi} \left[ \begin{array}{c} 100 \\ -4\pi \end{array} \right]$$

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$$-4 \left[ \begin{array}{c$$

Energy = 
$$\int_{-\infty}^{\infty} |\chi(k)|^2 dk = \frac{1}{2\pi} \int_{-\infty}^{\infty} |\chi(\omega)|^2 dw = \frac{1}{2\pi} \left[ \frac{4\pi \times 16 + 4\pi \times 14}{192} \right]$$
  
=  $\frac{1}{2\pi} \left[ \frac{4\pi \times 16 + 4\pi \times 14}{192} \right]$ 

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4. An LTI system has an impulse response  $h(t) = e^{-4t}u(t)$ . The input to this system is  $x(t) = \sin(4\pi t) + \cos(6\pi t + \frac{\pi}{4})$ . What is the period of x(t)? Find the exponential Fourier series representation of the corresponding output.

Idea:

Therefore F.S. B output  $y(t) = \sum_{k=-\infty}^{\infty} a_k e$  where  $\Omega_0 = a_1$   $= \dots \quad a \quad + q_1 e^{-\frac{1}{2} 2 \pi l} + a_0 + a_1 e^{\frac{1}{2} 2 \pi l} + a_2 e^{-\frac{1}{4} a_2} e^{-\frac{1}{4} a_3} e$ 

Sin 
$$\sqrt{11}t$$
  $-3\sqrt{11}t$   $-3\sqrt{11}t$   $-2\sqrt{11}t$   $-2\sqrt{11}$ 

$$= e \cdot \frac{e}{a} + e \cdot \frac{e}{a} \xrightarrow{j \in A} h(e)$$

F.s. coeff of y(t) are  $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$ Getting the ficint  $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$ Correct number  $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_1 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_2 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 = 0 \\ Q_1 = 0 \end{cases}$   $\begin{cases} Q_0 = 0 \\ Q_1 =$ 

all the rest are zero

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More Work Space for Answering Questions