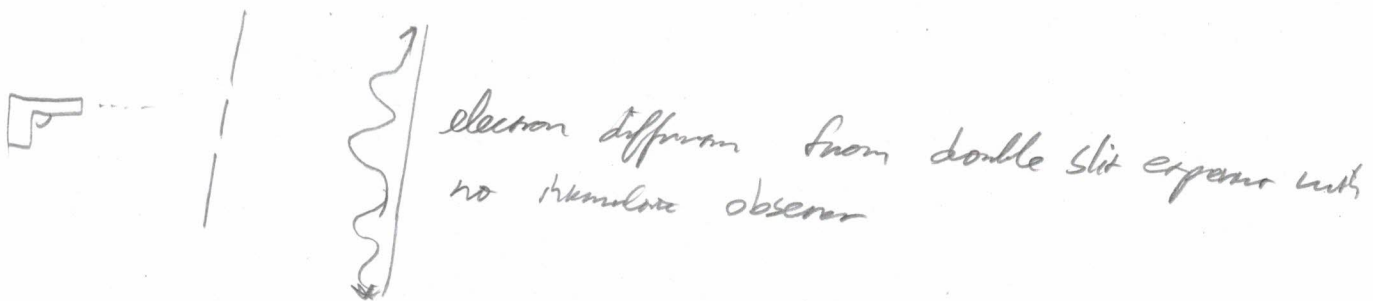


$$\underbrace{p(\theta)}_{\text{posterior}} = \frac{\underbrace{p(\tilde{x}|\theta)}_{\text{likelihood}} \underbrace{p(\theta)}_{\text{prior}}}{\underbrace{p(\tilde{x})}_{\text{prior problem}}}$$

In order to make the posterior non-degenerate, the prior must be non-degenerate

$p(\theta)$ is the dist of θ without even seeing data. This is the big pit to swallow. Frequentists scream "it's not objective"! You can't just use your own ideas. If my $p(\theta)$ differs from your $p(\theta)$, we get different answers!!!

Also is θ still considered a fixed value? One camp says yes, when $p(\theta|\tilde{x})$ just updates uncertainty in θ , the other camp says no. Different θ 's exist in quantum sense like an electron cloud around an atom.



X_1, X_2

$$\text{Obs: } \sim \text{bin}(\theta) \quad \vec{x} = (0, 1, 1)$$

2

let $\mathcal{H}_0 = \{0.5, 0.75\} \neq (0, 1)$ we will consider $(0, 1)$ later

$$P(\theta = 0.75 | \vec{x}) = \frac{P(\vec{x} | \theta = 0.75) P(\theta = 0.75)}{P(\vec{x} | \theta = 0.75) P(\theta = 0.75) + P(\vec{x} | \theta = 0.5) P(\theta = 0.5)}$$

we need $P(\theta)$ to calculate the posterior prob. Here choose...

$$P(\theta) = \begin{cases} 0.5 & \text{if } \theta = 0.75 \\ 0.5 & \text{if } \theta = 0.5 \end{cases}$$

generally...

$$P(\theta) = \frac{1}{|\mathcal{H}_0|}$$

This is called the "principle of indifference" or the "Laplace prior" (as it was his idea). This only works if

\mathcal{H}_0 is a finitely-sized set.

Now we can compute

$$P(\theta = 0.75 | \vec{x}) = \frac{P(\vec{x} | \theta = 0.75) P(\theta = 0.75)}{P(\vec{x} | \theta = 0.75) P(\theta = 0.75) + P(\vec{x} | \theta = 0.5) P(\theta = 0.5)} = \frac{0.25 \cdot 0.75^2}{0.25 \cdot 0.75^2 + 0.5^3} = 0.53 \leftarrow$$

$$P(\theta = 0.5 | \vec{x}) = \frac{P(\vec{x} | \theta = 0.5) P(\theta = 0.5)}{P(\vec{x} | \theta = 0.75) P(\theta = 0.75) + P(\vec{x} | \theta = 0.5) P(\theta = 0.5)} = \frac{0.5^3}{0.25 \cdot 0.75^2 + 0.5^3} = 0.47$$

If θ is a safe bet...

which is more likely θ ?

But if θ is not a single value...

the coin is quantum state

Let's redo this with kernels. First of all...

$$p(\theta|\vec{x}) \propto p(\vec{x}|\theta) p(\theta) \quad \text{Why?} \quad \text{posterior is a distr in } \Theta, \text{ trying} \\ \propto k(\vec{x}|\theta) k(\theta) = k(\theta|\vec{x}) \quad \text{else belongs to } c \Rightarrow \frac{1}{p(\vec{x})} \text{ is pref}$$

$$p(\theta) = \frac{1}{2} \mathbb{1}_{\theta=.75} + \frac{1}{2} \mathbb{1}_{\theta=.5} \propto \mathbb{1}_{\theta=.75} + \mathbb{1}_{\theta=.5}$$

$$p(\vec{x}|\theta) = \theta^{\sum x_i} (1-\theta)^{n-\sum x_i}$$

$$k(\theta|\vec{x}) = \theta^{\sum x_i} (1-\theta)^{n-\sum x_i} (\mathbb{1}_{\theta=.75} + \mathbb{1}_{\theta=.5})$$

$$\sum x_i = 2, \quad \Theta = \{.5, .75\}$$

$$k(.75|\vec{x}) = .75^2 \cdot .25^4 = .141$$

$$k(.5|\vec{x}) = .5^3 = .125$$

which is more likely value of θ ? Note:

Don't need $p(\theta|\vec{x})$ to answer, just need $k(\theta|\vec{x})$!

$$\Rightarrow c = \frac{1}{\sum_{x \in \mathcal{X}} k(\theta|x)} = \frac{1}{.141 + .125} = 3.76 \Rightarrow p(.75|\vec{x}) = 3.76 \cdot .141 = .53, \quad p(.5|\vec{x}) = 3.76 \cdot .125 = .47$$

Point Estimation: provide best guess of θ

Define $\hat{\theta}_{\text{MAP}} := \underset{\theta \in \Theta}{\operatorname{argmax}} \{p(\theta|x)\} = \underset{\theta \in \Theta}{\operatorname{argmax}} \{p(x|\theta)p(\theta)\} = \underset{\theta \in \Theta}{\operatorname{argmax}} \{k(x|\theta)k(\theta)\}$

maximum
a posteriori

if $p(\theta)$ is principle of indifference
 \downarrow
 $= \underset{\theta \in \Theta}{\operatorname{argmax}} \{k(x|\theta)\}$

let's see the whole problem. $\vec{x} \in \mathcal{X}$, $\theta \in \Theta$. I'll illustrate $P(\mathcal{X}, \theta)$

$$\mathcal{X} = \left\{ \langle 0,0,0 \rangle, \langle 1,0,0 \rangle, \langle 0,1,0 \rangle, \langle 0,0,1 \rangle, \langle 1,1,0 \rangle, \langle 1,0,1 \rangle, \langle 0,1,1 \rangle, \langle 1,1,1 \rangle \right\}$$

\mathcal{X}

$\langle 1,1,1 \rangle$				$\langle 1,1,0 \rangle$	$\langle 1,0,1 \rangle$	$\langle 0,1,1 \rangle$	$\langle 0,0,1 \rangle$	$\langle 0,1,0 \rangle$	$\langle 1,0,0 \rangle$	0.75
$\langle 1,1,1 \rangle$	$\langle 1,1,0 \rangle$	$\langle 1,0,1 \rangle$	$\langle 0,1,1 \rangle$	$\langle 1,0,0 \rangle$	$\langle 0,1,0 \rangle$	$\langle 0,0,1 \rangle$	$\langle 1,0,0 \rangle$			0.5

$$P(\vec{x} = \langle 1,1,1 \rangle | \theta = .75) = .75^3 = .422$$

$$P(\vec{x} = \langle 1,1,0 \rangle | \theta = .75) = .75^2 \cdot .25 = .141$$

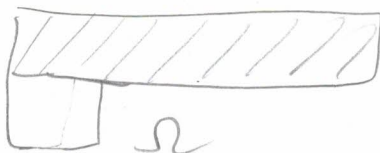
$$P(\vec{x} = \langle 1,0,0 \rangle | \theta = .75) = .75 \cdot .25^2 = .047$$

$$P(\vec{x} = \langle 0,0,0 \rangle | \theta = .75) = .25^3 = .016$$

$$P(\vec{x} = \langle 1,1,1 \rangle | \theta = .5) = .125$$

How to calculate

$$P(\theta = .75 | \vec{x} = \langle 1,1,1 \rangle)?$$



$$\frac{\{ \langle 1,1,1 \rangle, .75 \}}{\{ \langle 1,1,1 \rangle, .75 \} + \{ \langle 1,1,1 \rangle, .5 \}}$$

$\Theta_0 = \{0.5, 0.75\} \neq \Theta = (0,1)$ Not the full parameter space.
 and $\hat{\theta}_{MLE} \notin \Theta_0$! Ridiculous...

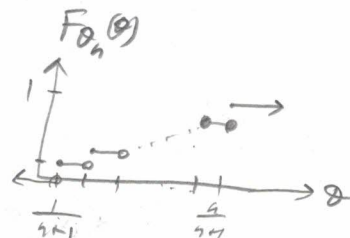
What does Laplace's Prior of Indifference look like?

Let's use our graduation of 300 to derive this...

$$\Theta_0(3) = \left\{ \frac{1}{4}, \frac{2}{4}, \frac{3}{4} \right\} \Rightarrow p_3(\theta) = U\left(\left\{ \frac{1}{4}, \frac{2}{4}, \frac{3}{4} \right\}\right)$$

$$\Theta_0(4) = \left\{ \frac{1}{5}, \frac{2}{5}, \frac{3}{5}, \frac{4}{5} \right\} \Rightarrow p_4(\theta) = U\left(\left\{ \frac{1}{5}, \frac{2}{5}, \frac{3}{5}, \frac{4}{5} \right\}\right)$$

$$\Theta_0(h) = \left\{ \frac{1}{h+1}, \frac{2}{h+1}, \dots, \frac{h}{h+1} \right\} \Rightarrow p_h(\theta) = U\left(\left\{ \frac{1}{h+1}, \frac{2}{h+1}, \dots, \frac{h}{h+1} \right\}\right)$$



$$F_{\theta_h}(\theta) = \begin{cases} 0 & \text{if } \theta < \frac{1}{h+1} \\ \frac{1}{h} [(h+1)\theta] & \text{if } \theta \in \left[\frac{1}{h+1}, \frac{h}{h+1}\right] \\ 1 & \text{if } \theta > \frac{h}{h+1} \end{cases}$$

$$h=9 \Rightarrow h+1=10$$

$$\theta = 0.05 \Rightarrow 10\theta = 0.5$$

$$\theta = .15 \Rightarrow (10\theta) \in [0.5, 1] = 1$$

$$\lim_{h \rightarrow \infty} F_{\theta_h}(\theta) = \begin{cases} 0 & \text{if } \theta < 0 \\ \theta & \text{if } \theta \in (0,1) \\ 1 & \text{if } \theta > 1 \end{cases}$$

$$\Rightarrow \theta_h \sim U(0,1)$$

Switched from discrete \rightarrow continuous

Obp: $X_1, \dots, X_n \sim \text{Bern}(\theta)$

cont.
 \downarrow

cont.
 \downarrow

$$\Rightarrow f(\theta|x) = \frac{p(x|\theta) f(\theta)}{p(x)}$$

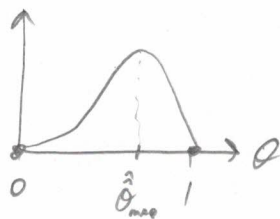
$$\propto k(x|\theta) k(\theta)$$

$$\propto \theta^{Sx_i} (1-\theta)^{n-Sx_i} \mathbb{1}_{\theta \in (0,1)}$$

$$= \theta^{Sx_i+1-1} (1-\theta)^{n-Sx_i+1-1} \mathbb{1}_{\theta \in (0,1)}$$

$$\propto \text{Beta}(Sx_i+1, n-Sx_i+1)$$

eg $\vec{x} = (1,4,0)$, $(\theta \sim U(0,1)) \Rightarrow \theta|\vec{x} \sim \text{Beta}(3,2)$



What is $\hat{\theta}_{\text{MAP}}$ if $\theta | X \sim \text{Beta}(\alpha, \beta)$

$$\text{argmax}_{\theta \in (0,1)} \left\{ \frac{1}{\Gamma(\alpha)\Gamma(\beta)} \theta^{\alpha-1} (1-\theta)^{\beta-1} \right\} = \text{argmax}_{\theta \in (0,1)} \left\{ \theta^{\alpha-1} (1-\theta)^{\beta-1} \right\}$$

$$\frac{d}{d\theta} [\theta^{\alpha-1} (1-\theta)^{\beta-1}] = -(\beta-1) \theta^{\alpha-1} (1-\theta)^{\beta-2} + (\alpha-1) (1-\theta)^{\beta-1} \theta^{\alpha-2} \stackrel{!}{=} 0$$

$$= (1-\theta)^{\beta-2} \theta^{\alpha-2} (\alpha(1-\theta) + (\beta-1)\theta) = 0$$

$$\Rightarrow (\alpha-1)(1-\theta) = (\beta-1)\theta \Rightarrow \frac{1-\theta}{\theta} = \frac{\beta-1}{\alpha-1} \Rightarrow \frac{1}{\theta} - 1 = \frac{\beta-1}{\alpha-1} \Rightarrow \frac{1}{\theta} = \frac{\beta-1}{\alpha-1} + 1 = \frac{\beta-1 + \alpha-1}{\alpha-1}$$

$$\Rightarrow \frac{1}{\theta} = \frac{\alpha+\beta-2}{\alpha-1}$$

$$\Rightarrow \theta_{\star} = \frac{\alpha-1}{\alpha+\beta-2}$$

Second derivative test confirms $\alpha, \beta \geq 1$ for mode to exist otherwise it's min.

$$\Rightarrow \vec{X} = \langle 1, 1, 0 \rangle, \theta \sim \mathcal{U}(0,1) \Rightarrow \theta | \vec{X} \sim \text{Beta}(3, 2) \Rightarrow \hat{\theta}_{\text{MAP}} = \frac{3-1}{3+2-2} = \frac{2}{3} = \hat{\theta}_{\text{MLE}}$$

Is there another point estimate?

Consider the following prob. problem, let X be a r.v.

let $g(t) := E[(X-t)^2]$. What is $\text{argmin}\{g(t)\}$?

$$g'(t) = \frac{d}{dt} [E[X^2 - 2tX + t^2]] = \frac{d}{dt} [-2t\mu + 2t] = -2\mu + 2t \stackrel{!}{=} 0 \Rightarrow t = \mu.$$

Where are we going with this?

let $\hat{\theta}_{\text{MMSE}} := E[\theta | \vec{X}]$ which minimizes $E[(\theta - \hat{\theta})^2 | \vec{X}] = \text{MSE}[\theta | \vec{X}]$

MMSE = "min. mean sq. error"

(Risk under L^2 loss)

$$\vec{X} = \langle 1, 1, 0 \rangle, \theta \sim \mathcal{U}(0,1) \Rightarrow \hat{\theta}_{\text{MMSE}} = \frac{\alpha}{\alpha+\beta} = \frac{3}{3+2} = \frac{3}{5}$$

$$\vec{X} = \langle 0, 0, 0 \rangle, \theta \sim \mathcal{U}(0,1)$$

$$\Rightarrow \theta | X \sim \text{Beta}(1, 4) \Rightarrow \hat{\theta}_{\text{MAP}} = 0, \hat{\theta}_{\text{MMSE}} = \frac{1}{1+4} = 0.2$$

Gets around problem with MLE!!

Useful!