

Posterior Predictive Inference

Given
likelihood, X_1, \dots, X_n X_*
data future observation

Use ^{likelihood} ~~data~~ and prior \Rightarrow posterior dist $P(\theta | \vec{x})$

Use likelihood + posterior \Rightarrow posterior dist $P(X_* | \vec{x})$

2-sided
What if I want a range of possible values for X_* ?

$$PI_{X_*, 1-\alpha} := [Q[X_* | \vec{x}, \frac{\alpha}{2}], Q[X_* | \vec{x}, 1-\frac{\alpha}{2}]]$$

\uparrow \uparrow
 posterior \uparrow prob.
 interval

The three you're expected to know...

For $X \sim \text{Bern}(\theta)$, $\theta \sim \text{Beta}(\alpha, \beta) \Rightarrow \theta | x \sim \text{Beta}(\alpha+x, \beta+n-x)$
 $\Rightarrow X_* | x \sim \text{Bern}(\frac{\alpha+x}{\alpha+\beta+n})$

$$\Rightarrow PI_{X_*, 1-\alpha} = [\text{qbern}(\frac{\alpha}{2}, \frac{\alpha+x}{\alpha+\beta+n}, \frac{\beta+n-x}{\alpha+\beta+n}), \text{qbern}(1-\frac{\alpha}{2}, \frac{\alpha+x}{\alpha+\beta+n}, \frac{\beta+n-x}{\alpha+\beta+n})]$$

For $X_1, \dots, X_n \stackrel{iid}{\sim} \text{Poisson}(\theta)$, $\theta \sim \text{Gamma}(\alpha, \beta) \Rightarrow \theta | \vec{x} \sim \text{Gamma}(\alpha + \sum x_i, \beta + n)$
 $\Rightarrow X_* | \vec{x} \sim \text{Evgam}(\alpha + \sum x_i, \frac{\beta}{\beta + n})$

$$\Rightarrow PI_{X_*, 1-\alpha} = [\text{qvgam}(\frac{\alpha}{2}, \alpha + \sum x_i, \frac{\beta}{\beta + n}), \text{qvgam}(1-\frac{\alpha}{2}, \alpha + \sum x_i, \frac{\beta}{\beta + n})]$$

For $X_1, \dots, X_n \stackrel{iid}{\sim} N(\theta, \sigma^2)$, $\sigma^2 \propto (\sigma^2)^{-1}$ (Jeffreys) $\Rightarrow \theta, \sigma^2 | \vec{x} \sim \text{NormalGamma}(\dots)$
 $\Rightarrow X_* | \vec{x} \sim T_{n-1}(\bar{x}, \frac{n+1}{n} s^2)$

$$\Rightarrow PI_{X_*, 1-\alpha} = [\text{qtscd}(\frac{\alpha}{2}, n-1, \bar{x}, \frac{n+1}{n} s^2), \text{qtscd}(1-\frac{\alpha}{2}, n-1, \bar{x}, \frac{n+1}{n} s^2)] \quad \boxed{\text{END}}$$

Obf: $X_1, \dots, X_n \sim N(\theta, \sigma^2)$, θ, σ^2 both unknown
 $f(\theta, \sigma^2) = f(\theta)f(\sigma^2)$

Let, where $f(\theta) = N(\mu_0, \tau^2)$ indep of $f(\sigma^2) = \text{InverseGamma}(\frac{\nu_0}{2}, \frac{\nu_0 \sigma_0^2}{2})$

→ This is different from $f(\theta|\sigma^2) = N(\mu_0, \frac{\sigma^2}{\tau^2})$ which resulted in the conjugate Normal-InverseGamma distr. What happens here?

$$\begin{aligned} f(\theta, \sigma^2 | x) &\propto f(\vec{x} | \theta, \sigma^2) f(\theta) f(\sigma^2) \underbrace{\frac{1}{h\tau^2 - 2\mu_0\theta}}_{A} \underbrace{-\frac{1}{2\tau^2}\theta^2 + \frac{\mu_0}{\tau^2}\theta - \frac{\mu_0^2}{2\tau^2}}_{B} \\ &\propto (\sigma^2)^{-\frac{n}{2}} e^{-\frac{1}{2\sigma^2}((n-1)S^2 + (\vec{x} - \theta)^2)} e^{-\frac{1}{2\tau^2}(\theta - \mu_0)^2} (\sigma^2)^{-\frac{\nu_0}{2}-1} e^{-\frac{\nu_0 \sigma_0^2/2}{\sigma^2}} \\ &\propto (\sigma^2)^{-\frac{n}{2} - \frac{\nu_0}{2} - 1} e^{-\frac{(n-1)S^2/2 + (\vec{x} - \theta)^2/2 + \nu_0 \sigma_0^2/2}{\sigma^2}} e^{\underbrace{(\frac{n\vec{x}}{\sigma^2} + \frac{\mu_0}{\tau^2})\theta}_{a} - \underbrace{(\frac{n}{2\sigma^2} + \frac{1}{2\tau^2})\theta^2}_{b}} \\ &= (\sigma^2)^{-\frac{n}{2} - \frac{\nu_0}{2} - 1} e^{-\frac{A}{\sigma^2}} \sqrt{\frac{\pi}{b}} e^{\frac{a^2}{4b}} N\left(\frac{a}{2b}, \frac{1}{4b}\right) \end{aligned}$$

$k(\sigma^2 | \vec{x})$

$$N\left(\frac{\frac{n\vec{x}}{\sigma^2} + \frac{\mu_0}{\tau^2}}{\frac{n}{\sigma^2} + \frac{1}{\tau^2}}, \frac{1}{\frac{n}{\sigma^2} + \frac{1}{\tau^2}}\right) = p(\theta | \vec{x}, \sigma^2)$$

$$k(\sigma^2 | \vec{x}) \propto (\sigma^2)^{-\frac{n+\nu_0}{2}-1} e^{-\frac{A}{\sigma^2}} \left(\frac{1}{2\sigma^2} + \frac{1}{\tau^2}\right)^{-\frac{1}{2}} e^{\frac{(\frac{n\vec{x}}{\sigma^2} + \frac{\mu_0}{\tau^2})^2}{4(\frac{n}{\sigma^2} + \frac{1}{\tau^2})}}$$

$$= (\sigma^2)^{-\theta_1-1} e^{-\frac{\theta_2}{\sigma^2}} \left(\frac{\theta_3}{\sigma^2} + \theta_4\right)^{-\frac{1}{2}} e^{\frac{(\frac{\theta_5}{\sigma^2} + \theta_6)^2}{4(\frac{\theta_3}{\sigma^2} + \theta_4)}}$$

Same as before...

which is not the kernel of any known distr

In fact, it has 6 params!

What can we do? We can still find $\begin{bmatrix} \hat{\theta}_{\text{true}} \\ \hat{\sigma}^2_{\text{map}} \end{bmatrix}$ Can we find $\hat{\theta}_{\text{true}}$?

If we can sample from $f(\theta, \sigma^2 | \vec{x})$, we can get samples

of $(\theta_1, \sigma_1^2), (\theta_2, \sigma_2^2), \dots, (\theta_S, \sigma_S^2)$. Then $f(\theta | \vec{x})$ is approximated by $\theta_1, \theta_2, \dots, \theta_S$ and $f(\sigma^2 | \vec{x})$ is approximated by $\sigma_1^2, \sigma_2^2, \dots, \sigma_S^2$.

You can use these samples to then approximate $\hat{\theta}_1, \hat{\theta}_2, \hat{\theta}_3, \dots$

$C(\theta, \alpha)$, $C(\theta, 1-\alpha)$ and priors for tests. How to sample?

$$f(\theta, \alpha | \vec{x}) = f(\theta | \vec{x}, \alpha) f(\alpha | \vec{x})$$

$$p(\theta | \vec{x}) \approx \frac{1}{S} \sum_{i=1}^S \mathbb{1}_{\theta_i \leq \theta_0} \quad H_0: \theta \leq \theta_0$$

① sample α from $f(\alpha | \vec{x})$

② sample θ from $f(\theta | \vec{x}, \alpha)$

③ Repeat 1-2 S times to obtain $(\theta_1, \dots, \theta_S), (\alpha_1, \dots, \alpha_S)$

How to sample $f(\alpha | \vec{x})$? Grid sample $k(\alpha | \vec{x})$ to find reasonable values.

Then build $\hat{F}(\alpha | \vec{x})$. Then sample α from $U(0,1)$ and find α s.t. $\hat{F}(\alpha | \vec{x}) \geq u$.

How to get $f(\alpha | \vec{x})$?

Do sampling above. Step

③ sample x from $N(\theta, \alpha)$

④ Repeat steps 1-3 to obtain (x_1, \dots, x_S) .

You can then estimate $E(x | \vec{x})$, $PI_{x, 1-\alpha}$, etc.

How useful is this? Right now you are just sampling to approximate $F(\alpha | \vec{x})$ from $k(\alpha | \vec{x})$. If there are many dimensions, grid search fails. Why?

dim(θ) = 10. You have 1,000,000,000 samples, that's only $\sqrt[10]{10^9} \approx 8$ points per each dimension \Rightarrow don't have good resolution.

Is there another way?

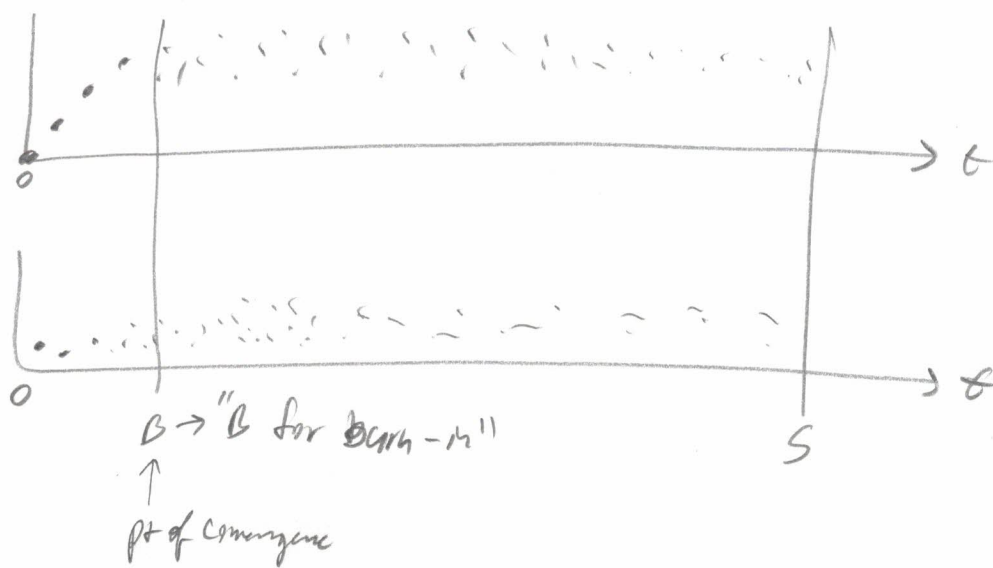
We know that

$$f(\theta | \vec{x}, \sigma) = N(\sigma_p, \sigma_p^2)$$

$$f(\sigma | \vec{x}, \theta) = \text{Invgamma}\left(\frac{y_0 + 1}{2}, \frac{y_0 \sigma_0^2 + 1 \hat{\sigma}^2_{MLE}}{2}\right)$$

The symmetric sweep Gibbs Sampler approximates $f(\theta, \sigma | \vec{x})$ via

- Step 1: Begin θ_0 at an arbitrary value
 Step 2: Draw σ_1^2 from $f(\sigma | \vec{x}, \theta_0)$
 Step 3: Draw θ_1 from $f(\theta | \vec{x}, \sigma_1)$
 Step 4: Draw σ_2^2 from $f(\sigma | \vec{x}, \theta_1)$
 Step 5: Draw θ_2 from $f(\theta | \vec{x}, \sigma_2)$
 ⋮
- Repeat until "convergence" and then collect many samples.
- Note: θ_{t+1} is dependent of θ_t
- In 343, I hope we will prove this convergence using Markov Chain theory.



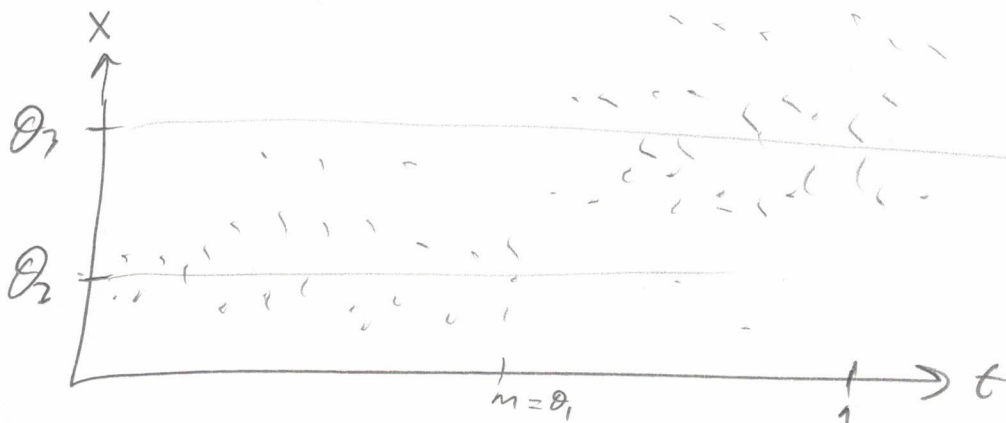
Remark but "shrinked" is only 1 of our Tackges
 Since the samples are dependent on those previously.
 Thinning by T breaks this dependence and it yields
 iid sample from $p(\vec{\theta} | \vec{x})$.

Real world example. Vol $X_1, \dots, X_{\theta_1} \stackrel{iid}{\sim} \text{Poisson}(\theta_2)$ vol of

$X_{\theta_1+1}, \dots, X_n \stackrel{iid}{\sim} \text{Poisson}(\theta_3)$

Parameter space

$$\theta_1 \in \{1, 2, \dots, n\}, \theta_2 \in (0, \infty), \theta_3 \in (0, \infty)$$



Write the log-likelihood for all three parts:

joint
prior & data
 $\rightarrow P(\theta_1, \theta_2, \theta_3) \propto 1$

$$P(\theta_1, \theta_2, \theta_3 | \vec{x}) \propto P(\vec{x} | \theta_1, \theta_2, \theta_3)$$

$$= \prod_{t=1}^{\theta_1} \frac{e^{-\theta_2} \theta_2^{x_t}}{x_t!} \prod_{t=\theta_1+1}^n \frac{e^{-\theta_3} \theta_3^{x_t}}{x_t!}$$

$$= \frac{e^{-\theta_1 \theta_2} \theta_2^{\sum_{t=1}^{\theta_1} x_t}}{\prod_{t=1}^{\theta_1} x_t!} \frac{e^{-(n-\theta_1) \theta_3} \theta_3^{\sum_{t=\theta_1+1}^n x_t}}{\prod_{t=\theta_1+1}^n x_t!}$$

$$\propto e^{-\theta_1 \theta_2} \theta_2^{\sum_{t=1}^{\theta_1} x_t} e^{-(n-\theta_1) \theta_3} \theta_3^{\sum_{t=\theta_1+1}^n x_t}$$

$$P(\theta_1 | \vec{x}, \theta_2, \theta_3) \propto e^{(\theta_1 - \theta_2) \theta_1} \theta_2^{\sum_{t=1}^{\theta_1} x_t} \theta_3^{\sum_{t=\theta_1+1}^n x_t} = k(\theta_1 | \vec{x}, \theta_2, \theta_3)$$

This is not the kernel of any known dist. Luckily good sampling is simple since $\theta_1 \in \{1, 2, \dots, n\}$

$$\Rightarrow \frac{1}{c} = \sum_{\theta_1 \in \{1, 2, \dots, n\}} k(\theta_1 | \vec{x}, \theta_2, \theta_3)$$

$$\Rightarrow p(\theta_1 | \vec{x}, \theta_2, \theta_3) = c k(\theta_1 | \vec{x}, \theta_2, \theta_3) \text{ which can then be sampled from}$$

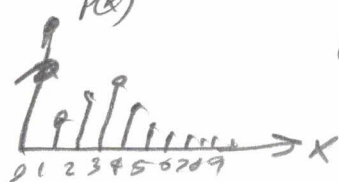
$$f(\theta_2 | \vec{x}, \theta_1, \theta_3) \propto e^{-\theta_1 \theta_2} \theta_2^{\sum_{t=1}^{\theta_1} x_t + 1 - 1} \propto \text{Gamma}\left(1 + \sum_{t=1}^{\theta_1} x_t, \theta_1\right)$$

$$f(\theta_3 | \vec{x}, \theta_1, \theta_2) \propto e^{-(n - \theta_1) \theta_3} \theta_3^{\sum_{t=\theta_1+1}^n x_t + 1 - 1} \propto \text{Gamma}\left(1 + \sum_{t=\theta_1+1}^n x_t, n - \theta_1\right)$$

Now, we go through the Gibbs Sampler... (deno)

Hurdle Model w/ Poisson count

for data



2

X_{i1}, X_{i2} iid $\begin{cases} 0 & \text{w.p. } \theta_1 \\ \text{Poisson}(\theta_2) & \text{w.p. } (1-\theta_1) \end{cases}$

i.e. a mixture data with two components

Using de Laplace prior -

$$f(\theta_1, \theta_2 | \vec{x}) \propto P(\vec{x} | \theta_1, \theta_2)$$

$$= \prod_{i=1}^n (\theta_1)^{\mathbb{1}_{X_i=0}} (1-\theta_1) \left(\frac{\theta_2^{X_i} e^{-\theta_2}}{X_i!} \right)^{\mathbb{1}_{X_i \neq 0}}$$

let $n_0 = \#X_i=0$

$$\propto \theta_1^{n_0} (1-\theta_1)^{n-n_0} \theta_2^{\sum X_i \mathbb{1}_{X_i \neq 0}} e^{-(n-n_0)\theta_2}$$

$$f(\theta_1 | \vec{x}, \theta_2) \propto \theta_1^{n_0+1-1} (1-\theta_1)^{n-n_0+1-1}$$

$\propto \text{Beta}(n_0+1, n-n_0+1)$

$$f(\theta_2 | \vec{x}, \theta_1) \propto \theta_2^{\sum X_i \mathbb{1}_{X_i \neq 0} + 1 - 1} e^{-(n-n_0)\theta_2} \propto \text{Gamma}(\sum X_i \mathbb{1}_{X_i \neq 0} + 1, n-n_0)$$