Math 342W / 650.4 Spring 2024 Midterm Examination One

Professor Adam Kapelner Thursday, March 14

Full Name				
	Full Name			

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$ ule{signature}$	date	
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Instructions

This exam is 110 minutes and closed-book. You are allowed **two** pages (front and back) of a "cheat sheet." You may use a graphing calculator of your choice. Please read the questions carefully. If the question reads "compute," this means the solution will be a number otherwise you can leave the answer in *any* widely accepted mathematical notation which could be resolved to an exact or approximate number with the use of a computer. I advise you to skip problems marked "[Extra Credit]" until you have finished the other questions on the exam, then loop back and plug in all the holes. I also advise you to use pencil. The exam is 100 points total plus extra credit. Partial credit will be granted for incomplete answers on most of the questions. Box in your final answers. Good luck!

Problem 1 This question is about modeling in general. "Look both ways before you cross the street" is typical advice. We will attempt to understand this advice from a modeling point of view. There is one feature in this model and one response. Let the response be and feature be:

 $y_i := \mathbb{1}_{\text{during street crossing } i, \text{ the person gets hit by a car}}$

 $x_i := \mathbb{1}_{\text{during street crossing } i}$, the person looks down the street in both directions and does not see any cars coming

- [2 pt / 2 pts] What is the unit in this modeling scenario?
- [1 pt / 3 pts] What is the data type of x? (1 word)
- [4 pt / 7 pts] "Look both ways before you cross the street" implies the following model:

$$g(x) =$$

• [3 pt / 10 pts] Describe a scenario where $y \neq g(x)$.

• [3 pt / 13 pts] Why is this model "wrong but useful"?

• [2 pt / 15 pts] Is g a mathematical model? Yes / no

Problem 2 Consider the following R code from the class demos and labs. The numbers on the right are line numbers that will be referred to later. They are not part of the code.

```
> y = MASS::Boston$medv
   > var(y)
2
   [1] 84.58672
   > X = as.matrix(cbind(1, MASS::Boston[, 1 : 13]))
   > n = nrow(X)
   > n
6
   [1] 506
   > Xt = t(X)
   > XtX = Xt %*% X
   > XtXinv = solve(XtX)
10
   > XtXinvXt = XtXinv %*% Xt
   > b = XtXinvXt %*% y
12
   > H = X %*% XtXinvXt
13
   > I_minus_H = diag(n) - H
14
   > yhat = H %*% y
15
   > e = I_minus_H %*% y
16
   > var(e)
17
             [,1]
18
   [1,] 21.93819
19
```

- [2 pt / 17 pts] What is returned by R when evaluating length(b)?
- [2 pt / 19 pts] What is returned by R when evaluating ncol(XtX)?
- [2 pt / 21 pts] What is returned by R when evaluating ncol(H)?
- [2 pt / 23 pts] What is returned by R when evaluating Matrix::rankMatrix(I_minus_H)?
- [3 pt / 26 pts] Compute SST to the nearest two decimals.
- [3 pt / 29 pts] Compute SSE to the nearest two decimals.

Now consider the following scenario: we add random predictors to the design matrix X one-by-one and run the code above for each updated design matrix X.

- [3 pt / 32 pts] What is the maximum number of random predictors that can be added before the code throws an error and halts?
- [2 pt / 34 pts] If you add too many random predictors, which line number does the code throw this error and halt?
- [5 pt / 39 pts] Graph the expected R^2 by number of predictors from 1 to the maximum number that can be considered before OLS fails. Label the x-axis "number of predictors"; label the y-axis " R^2 ". Graph it to scale. Be sure to mark critical points along both axes.

Now consider that 10% of the data was left out in a test set.

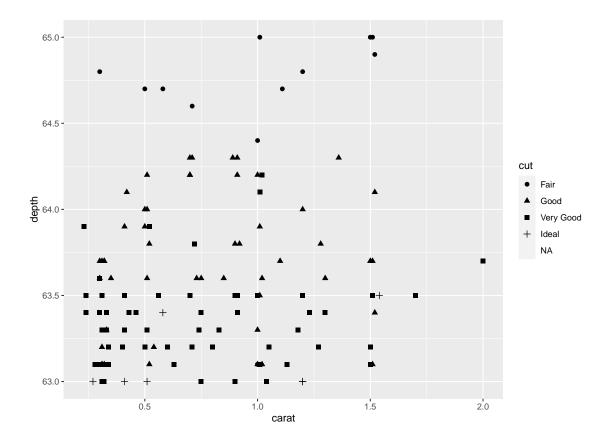
• [2 pt / 41 pts] What is the value of K?

• [6 pt / 47 pts] Graph expected $oosR^2$ by number of predictors from 1 to the maximum number that can be considered before OLS fails. Label the x-axis "number of predictors"; label the y-axis " R^2 ". Graph it to scale. Be sure to mark critical points along both axes.

Problem 3 Below is the result of skimr::skim run on the dataset ggplot2::diamonds.

	Va]	lues								
Name	Хy									
Number of rows	539	940								
Number of columns	10									
Column type frequency:	:									
factor	3									
numeric	7									
Group variables	Nor	ne								
Variable type: fact										
skim-variable n-miss	sing comp	olete-rate	ordered	n-unique	top-cou	ınts		l, Ver: :	12082, Goo:	4906
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skim-variable n-miss 1 cut 2 color	sing comp 0 0	olete-rate 1 1	ordered in TRUE	n-unique † 5 : 7 (top-cou Ide: 21 G: 1129	ints 1551, Pi 92, E: 9	re: 13791 9797, F:	9542, H		
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Here is a plot of variable cut by variables carat and depth for a sample of $n_0 = 135$.

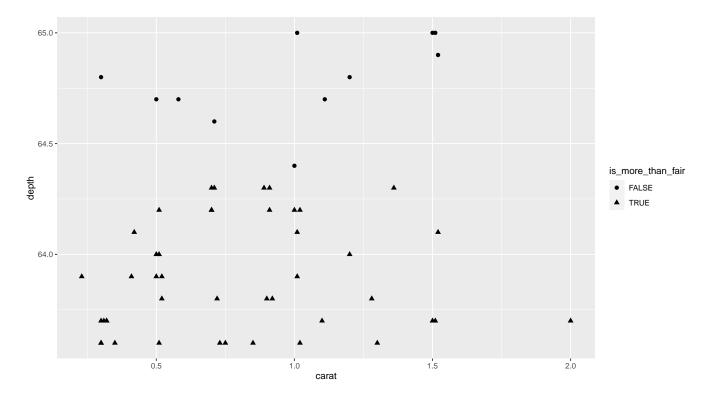


- [2 pt / 49 pts] If we wish to build a model predicting cut, a nominal categorical variable. What type of model is this called?
- [2 pt / 51 pts] Consider all algorithms we studied thus far for this type of response. Regardless of the algorithm employed to create g, what would the main source of generalization error be? Your answer must be one of the three sources of error.
- [4 pt / 55 pts] Let carat = 1.6 and depth = 63.5 and let \mathcal{A} be the 6-nearest neighbors algorithm with the Euclidean distance function. Predict y.

Consider \mathbb{D} to be only records where depth ≥ 64.5 . Employ the KNN algorithm with K=3 and the Euclidean distance function.

- [3 pt / 58 pts] What would the in-sample error be?
- [4 pt / 62 pts] Use leave-one-out cross validation (i.e. the test set consists of one record for each fold). What would the out of sample error be?

We are interested in predicting if a diamond has a cut "more than fair" in the \mathbb{D} plotted below.



• [2 pt / 64 pts] What type of model is this called?

Circle the following bullet circles which are true:

- [2 pt / 66 pts] depth and carat are likely dependent.
- \bullet [2 pt / 68 pts] depth and carat are likely associated.
- \bullet [2 pt / 70 pts] depth and is_more_than_fair are likely dependent.
- \bullet [2 pt / 72 pts] $\;$ This dataset is linearly separable.
- \bullet [2 pt / 74 pts] $\;$ If the perceptron is employed, it will converge.
- [2 pt / 76 pts] Assuming the perceptron algorithm converges, regardless of the starting position, the perceptron will converge to the same place.
- [2 pt / 78 pts] If the SVM is employed with the Vapnik objective function, the hinge error will be zero.
- [4 pt / 82 pts] The SVM and the perceptron are highly likely to exhibit similar performance for future data that is generated from the same stationary process as \mathbb{D} .

Problem 4 Assume $X \in \mathbb{R}^{n \times (p+1)}$ with p > 1 composed of random realizations from iid standard normal random variables, full rank. Let Q, R be the matrix results of the QR-decomposition procedure run on X. Let $y \in \mathbb{R}^n$ which a vector of measurements of a phenomenon of interest.

• [10 pt / 92 pts] Prove that the $\left|\left|\boldsymbol{Q}\boldsymbol{Q}^{\top}\boldsymbol{y}\right|\right|^{2}/\left|\left|\boldsymbol{y}\right|\right|^{2} \in [0,1].$

• [2 pt / 94 pts] If you were to use $\mathcal{A} = \text{OLS}$ to generate g, which of the three sources of error would be the main source of error in g?

Circle the following bullet circles which are true:

- [2 pt / 96 pts] $\exists c \neq 0$ s.t. $\boldsymbol{X}_{\cdot 1} = c \boldsymbol{Q}_{\cdot 1}$.
- [2 pt / 98 pts] $\exists c \neq 0 \text{ s.t. } X_{\cdot 2} = c Q_{\cdot 2}.$
- [2 pt / 100 pts] $\operatorname{colsp}[\mathbf{R}] = \operatorname{colsp}[\mathbf{X}].$