

## Survival Analysis / Reliability Analysis / Churn Modeling

$X$ , a rv, is a survival model if  $S_X \geq 0$  and no maximum.

Some brand name discrete survival models are:  
geometric, extnegbinomial, poisson

Some brand name continuous survival models are:  
gamma, lognormal, weibull\*\*, pareto, F, betaprime

$k, \lambda > 0$

Review the Weibull. Let  $Y_1, \dots, Y_n \stackrel{iid}{\sim} \text{Weibull}(k, \lambda) := \lambda k (\lambda y)^{k-1} e^{-(\lambda y)^k} \mathbb{1}_{y \geq 0}$

$$F(y) = 1 - e^{-(\lambda y)^k} \Leftrightarrow S(y) := 1 - F(y) = P(Y > y) = e^{-(\lambda y)^k}$$

$$\theta := E[Y] = \int_0^\infty y (\lambda^k (\lambda y)^{k-1} e^{-(\lambda y)^k}) dy = \lambda^k k \int_0^\infty y^k e^{-\lambda^k y^k} dy$$

$$\left\{ \begin{array}{l} \text{Let } u = \lambda^k y^k \Rightarrow y^k = \frac{u}{\lambda^k} \Rightarrow y = \frac{u^{\frac{1}{k}}}{\lambda} \Rightarrow \frac{du}{dy} = k \lambda^k y^{k-1} \Rightarrow dy = \frac{1}{k \lambda^k y^{k-1}} \\ y=0 \Rightarrow u=0, y=\infty \Rightarrow u=\infty \end{array} \right.$$

$$= \cancel{\lambda^k} \int_0^\infty \cancel{y^k} e^{-\cancel{\lambda^k} \frac{u}{\cancel{\lambda^k}}} \frac{1}{\cancel{k \lambda^k y^{k-1}}} du = \frac{1}{\lambda} \int_0^\infty u^{\frac{1}{k}+1-1} e^{-u} du = \frac{1}{\lambda} \Gamma\left(1 + \frac{1}{k}\right)$$

$$\sigma^2 := \text{Var}[Y] = \dots = \frac{1}{\lambda^2} \left( \Gamma\left(1 + \frac{2}{k}\right) + \Gamma\left(1 + \frac{1}{k}\right)^2 \right) < \infty$$

$\hat{k}^{MLE}, \hat{\lambda}^{MLE} = \text{argmax} \left\{ \ell(\lambda, k; \vec{y}) \right\}$  HW: just like the logistic rv, there's no closed-form MLE's

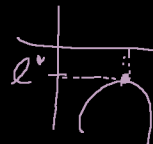
$\text{By CLT } \bar{Y} \sim N(\theta, \frac{\sigma^2}{n}) \Rightarrow \hat{\theta} = \bar{y}$  is a reasonable estimate

Invariance of the MLE thm

Let  $\vec{\theta}$  be the parameters for a rv. Let  $\vec{t} = g(\vec{\theta})$ . If  $\hat{\vec{\theta}}^{MLE}$  is the MLEs for  $\vec{\theta}$  then  $g(\hat{\vec{\theta}}^{MLE})$  will be the MLEs for  $\vec{t}$ .

Proof for if  $g$  is a 1:1 function. If not 1:1, it's true but the proof is much more involved. Assume  $Y_1, \dots, Y_n \stackrel{iid}{\sim}$

$$\sup_{\vec{t}} \left\{ \ell(\vec{t}; \vec{Y}) \right\} = \sup_{\vec{t}} \left\{ \ell(g^{-1}(\vec{t}); \vec{Y}) \right\} = \sup_{\vec{\theta}} \left\{ \ell(\vec{\theta}; \vec{Y}) \right\}$$



$$\Rightarrow \hat{\vec{\theta}}^{MLE} = \frac{1}{\hat{\lambda}^{MLE}} \Gamma\left(1 + \frac{1}{\hat{k}^{MLE}}\right)$$

This is a good estimate of "mean survival"

Unfortunately, in most situations, this is impossible to estimate since you need all the  $y_i$ 's. During your period of observation, you only have a certain amount of time to gather data, call it  $t_f$ . All  $y_i$ 's that realize past this time are... missing (which is called "right-censored" in this context).

Let  $c$  be the binary censoring variable. So you observe  $\vec{y}, \vec{c}$  as data. If  $c_i = 1$ ,  $y_i$  is missing but known that  $y_i > t_f$ . If  $c_i = 0$ , then  $y_i$  is measured as usual. How do we estimate  $\theta$ ?

$$\begin{aligned} \mathcal{L}(k, \lambda; \vec{y}, \vec{c}, t_f) &= \prod_{\{i: c_i=0\}} f(y_i; \lambda, k) \prod_{\{i: c_i=1\}} P(Y > t_f) \\ &= \prod_{\{i: c_i=0\}} k \lambda^k y_i^{k-1} e^{-\lambda^k y_i^k} \prod_{i=1}^{n_1} e^{-\lambda^k t_f^k} \end{aligned}$$

$\text{Let } n_0 = \sum \mathbb{1}_{c_i=0}, \frac{n_0}{n} = \sum \frac{\mathbb{1}_{c_i=0}}{n}$

$$\ell(k, \lambda; \vec{y}, \vec{c}, t_f) = n_0 \ln(k) + n_0 k \ln(\lambda) + (k-1) \sum_{\{i: c_i=0\}} \ln(y_i) - \lambda^k \sum_{\{i: c_i=0\}} y_i^k - n_1 \lambda^k t_f^k$$

$\ell' \stackrel{\text{def}}{=} 0$  but.....There is no closed form solution to the root of its derivative, so you need to use an optimizer.

How do you do inference? The monster MLE thm says:

$$\hat{\theta}^{MLE} \sim N\left(\theta, \frac{1}{I_n(\theta)}\right) \xrightarrow{\text{slutsky's}} \hat{\theta}^{MLE} \sim N\left(\theta, \frac{1}{I_n(\hat{\theta}^{MLE})}\right)$$

How do we get the Fisher Information? With two-dimensional parameters, the Fisher Information is a 2x2 Fisher Information matrix. And then you use the multivariate delta method. Bottom line: inference is doable.

Is there an alternative to using this censoring data? Yes, it's the EM algorithm.

Step 0: you begin with guesses for the missing  $y_i$ 's e.g.  $t_f$   
Step 1: Compute  $k$ -hat-hat-mle,  $\lambda$ -hat-hat-mle (M-step)  
Step 2: Compute better guesses for the missing  $y_i$ 's (E-step)

$E[Y_i | Y_i > t_f]$  which is the same for all  $i$ , censored.

Step 3: Repeat steps 1-2 until convergence i.e. your  $k$ ,  $\lambda$  estimates don't change too much between iterations.

Today we covered "parametric survival modeling" since we assumed the times were realized from a known distribution (in our case, the Weibull). What if we have no idea what distribution it is and we still want inference? We need nonparametric survival modeling tools.