

# Lec 18 MATH 393

Hazard Rate  $h(t) := \frac{f(t)}{S(t)}$  which defines a continuous survival dist.

Assume  $h(t) = h_0(t) e^{\beta_1 x_1 + \dots + \beta_p x_p} = h_0(t) e^{\vec{x} \vec{\beta}} \Rightarrow$  each change in  $x_j$  implies a multiplicative change in  $h(t)$ .

We can show

$$f(t) = h_0(t) e^{\vec{x} \vec{\beta}} e^{-\int_0^t h_0(u) du e^{\vec{x} \vec{\beta}}} \quad \text{let } t=y \text{ to match our notation from 392/393}$$

let  $y_1 < y_2 < \dots < y_n$  be unique values and order  $\vec{x}_1, \dots, \vec{x}_n$  based on that ordering into the rows of  $X$  matrix

$$\Rightarrow \mathcal{L}(\underbrace{\vec{\beta}}_{\text{unknown parameter}}, h_0; X, \vec{y}) = \prod_{i=1}^n \underbrace{h_0(y_i)}_{h_i} e^{\vec{x}_i \vec{\beta}} e^{-\int_0^{y_i} h_0(u) du e^{\vec{x}_i \vec{\beta}}}$$

add reasoning here if necessary

$$\Rightarrow \mathcal{L}(\vec{\beta}, h_1, \dots, h_n, H_1, \dots, H_n; X, \vec{y}) = \prod_{i=1}^n h_i e^{\vec{x}_i \vec{\beta}} e^{-H_i \vec{x}_i \vec{\beta}}$$

Assume:  $H_i = \int_0^{y_i} h_0(u) du \approx \underbrace{h_0(y_1)}_{\substack{\uparrow \\ \text{Similar to Riemann integral}}} + h_0(y_2) + \dots + h_0(y_i) = \sum_{l=1}^i h_0(y_l) = \sum_{l=1}^i h_l$

$$L(\vec{\beta}, \underbrace{h_1, \dots, h_n}_{\text{less nuisances}}; X, \vec{y}) = \prod_{i=1}^n h_i e^{\vec{x}_i^T \vec{\beta}} e^{-\left(\sum_{l=1}^n h_l\right) e^{\vec{x}_i^T \vec{\beta}}} \\ = \left(\prod_{i=1}^n h_i\right) e^{\sum_{i=1}^n \vec{x}_i^T \vec{\beta}} e^{-\sum_{i=1}^n \left(\sum_{l=1}^n h_l\right) e^{\vec{x}_i^T \vec{\beta}}}$$

$$\Rightarrow \ell(\vec{\beta}, h_1, \dots, h_n; X, \vec{y}) = \sum_{i=1}^n \ln(h_i) + \underbrace{\sum_{i=1}^n \vec{x}_i^T \vec{\beta}}_{\vec{1}_n^T X \vec{\beta}} - \sum_{i=1}^n e^{\vec{x}_i^T \vec{\beta}} \sum_{l=1}^n h_l$$

Let's try to find MLE for  $h_k$  where  $k \in \{1, 2, \dots, n\}$

$$\frac{\partial}{\partial h_k} [\ell] = \frac{1}{h_k} - \sum_{i=1}^n e^{\vec{x}_i^T \vec{\beta}} \sum_{l=1}^n \frac{\partial}{\partial h_k} [h_l] = \frac{1}{h_k} - \sum_{i=1}^n e^{\vec{x}_i^T \vec{\beta}} \sum_{l=1}^n \mathbb{1}_{l=k} \\ = \frac{1}{h_k} - \sum_{i=1}^n e^{\vec{x}_i^T \vec{\beta}} \mathbb{1}_{\substack{i=k \\ k \leq i}} = \frac{1}{h_k} - \sum_{i=k}^n e^{\vec{x}_i^T \vec{\beta}} \stackrel{\text{set}}{=} 0 \quad \text{to find MLE}$$

$$\Rightarrow \frac{1}{h_k} = \sum_{i=k}^n e^{\vec{x}_i^T \vec{\beta}} \Rightarrow \hat{h}_k^{\text{MLE}} = \frac{1}{\sum_{i=k}^n e^{\vec{x}_i^T \vec{\beta}}}$$

Let  $C_i := \sum_{l=1}^n \hat{h}_l^{\text{MLE}}$

$$\frac{\partial}{\partial \vec{\beta}} [\ell] = \frac{\partial}{\partial \vec{\beta}} \left[ \underbrace{\vec{1}_n^T X \vec{\beta}}_{\vec{\beta}^T X^T \vec{1}_n} \right] - \sum_{i=1}^n \frac{\partial}{\partial \vec{\beta}} \left[ e^{C_i \vec{x}_i^T \vec{\beta}} \right]$$

$$= X^T \vec{1}_n - \sum_{i=1}^n C_i \vec{x}_i^T e^{C_i \vec{x}_i^T \vec{\beta}} \stackrel{\text{set}}{=} \vec{0}_p \quad \text{and solve} \quad = e^{\vec{\beta}^T X^T \vec{1}_n}$$

(no closed form solution)

This can be approximated using an optimizer. And the Fisher Information

Matrix can be found as well!

$\Rightarrow$  Wald tests for  
single effects and  
multiple effects!

Also available to be solved for  
arbitrary subjects censored!

Causality!

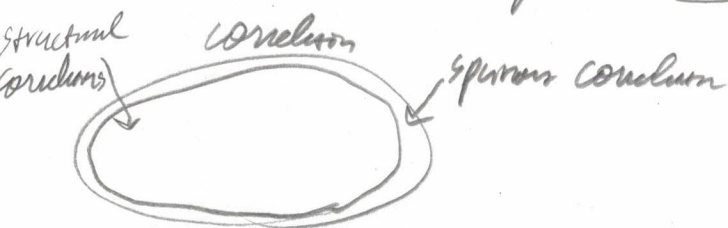
in 242

First of all, we learned, that two vectors  $\vec{x}, \vec{y} \in \mathbb{R}^n$  have a non-zero dot product. Hence

$$r := \frac{\sum (x_i - \bar{x})(y_i - \bar{y})}{\sum (x_i - \bar{x})^2 \sum (y_i - \bar{y})^2} = \frac{(\vec{x} - \bar{x} \vec{1}_n)^T (\vec{y} - \bar{y} \vec{1}_n)}{n s_x s_y}$$

Can appear significantly different than zero just by chance.

This is called a "spurious correlation". It is not a new concept. Demo In 240, we called it a Type I error!

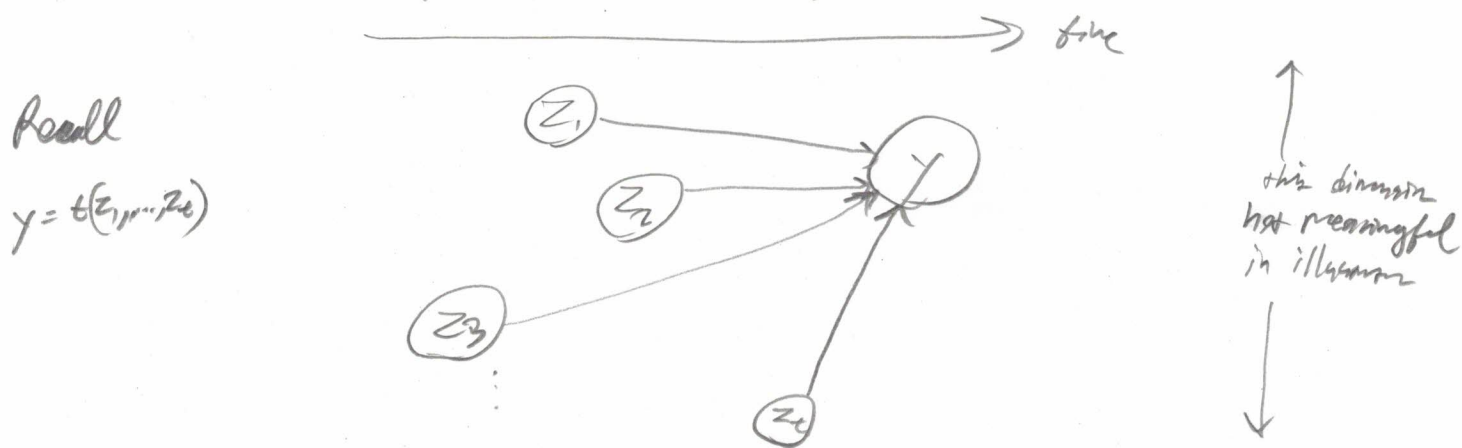


Spurious correlations are due to chance co-occurrence and disappear because syst. insign. if  $n$  gets larger!

The opposite of spurious is "structural correlation" or just "correlation"; this is based on real, probabilistic dependence. Let's visualize

this "structure". Assume causes must come before the phenomenon;

this is called the "temporal precedence assumption". Now let's draw a causal diagram, a directed acyclic graph (DAG):



Recall  
 $y = t(z_1, \dots, z_4)$

What are the arrows? The arrows mean there is a mathematical relationship between the variables connected where the end of the arrow's variable is the response. E.g.

$$y = k_{y,z_1}(z_1) + \eta_{y,z_1} \xleftarrow{\text{etc., ignorance}} \text{s.t. } \frac{\partial y}{\partial z_1} \neq 0 \text{ for at least one value of } z_1$$

$$y = k_{y,z_2}(z_2) + \eta_{y,z_2} \quad "$$

$$\vdots$$

$$y = k_{y,z_k}(z_k) + \eta_{y,z_k} \quad "$$

$$y = k_{y,z_i,z_j}(z_i,z_j) + \eta_{y,z_i,z_j} \quad \frac{\partial y}{\partial z_i} \neq 0 \text{ and } \frac{\partial y}{\partial z_j} \neq 0$$

$\vdots$   
giving contribution

$$y = t(z_1, \dots, z_k) \text{ no noise!} \quad \frac{\partial y}{\partial z_i} \neq 0 \quad \forall i$$

$\Rightarrow$  if you change values on the r.h.s. in the function, then the l.h.s. changes for some change in value(s) on the r.h.s.

This is "structural dependence" which is also "causality". Why is it causal? Because if  $z_i$  is "manipulated" by an outside force, due to the structural dependence of  $k_{y,z_i}$ .