

lec 6 MATH 343

Survival Analysis / Reliability Analysis

X is a ^{reliability} survival model if $S_X \geq 0$ and no maximum.

Some Brand Name
Discrete survival models: Geometric, ~~Ext~~ Neg binomial, Poisson

Some Brand Name
Continuous survival models: Gamma, LogNormal, Weibull, Pareto, F, beta prime

The Weibull is the most famous of the cont. models. Review...

Let Y_1, \dots, Y_n iid Weibull $(\lambda, k) = \lambda k (\lambda y)^{k-1} e^{-(\lambda y)^k} \mathbb{1}_{y \geq 0}$ Param space $k, \lambda > 0$

$$F_Y(y) = 1 - e^{-(\lambda y)^k} \Leftrightarrow "S(y) = e^{-(\lambda y)^k}" \text{ "survival function"}$$

$$\Rightarrow y^k = \frac{u}{\lambda^k} \Rightarrow y = \frac{u^{1/k}}{\lambda}$$

$$\text{let } u = \lambda^k y^k \Rightarrow \frac{du}{dy} = k \lambda^k y^{k-1}$$

$$\Rightarrow dy = \frac{1}{k \lambda^k y^{k-1}} du, \quad y=0 \Rightarrow u=0, \quad y=\infty \Rightarrow u=\infty$$

$$\begin{aligned} \theta := E(Y) &= \int_0^\infty y \lambda k (\lambda y)^{k-1} e^{-(\lambda y)^k} dy = k \lambda^k \int_0^\infty y^k e^{-\lambda^k y^k} dy = k \lambda^k \int_0^\infty y^k e^{-u} \frac{1}{k \lambda^k y^{k-1}} du \\ &= \frac{1}{\lambda} \int_0^\infty u^{\frac{1}{k} + 1 - 1} e^{-u} du = \frac{1}{\lambda} \Gamma\left(\frac{1}{k} + 1\right), \quad \sigma^2 = \frac{1}{\lambda^2} \left(\Gamma\left(1 + \frac{2}{k}\right) - \Gamma\left(1 + \frac{1}{k}\right)^2 \right) < \infty \end{aligned}$$

MLE's (HW)

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\Rightarrow By CLT $\bar{Y} \sim N(\theta, \frac{\sigma^2}{n})$ so the avg is the good estimator if n is large

For non-extreme quantile estimation, bootstrapping. mm works too.

But there is usually a big problem! Usually, not all the Y_1, \dots, Y_n are actually observed since observing large y_i 's actually requires waiting for them to occur. The sampling frame usually has a maximum eg. $t_f = 2 \text{ yr.}$ so all y_i 's are done

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Also... we left out the following property of MLE's in 391.

Theorem of MLE Then with parameter space \mathbb{R}^p , $p \geq 1$.

let $\vec{\theta}$ be the parameter for a r.v., let $\vec{t} = g(\vec{\theta})$.

If $\vec{\theta}_{MLE}$ is the MLE ^{for $\vec{\theta}$} , then $g(\vec{\theta}_{MLE})$ is the MLE for \vec{t} .

Proof in the case of g being 1:1 (not 1:1 is a different proof).
and X_1, \dots, X_n iid.

$$\sup_{\vec{t} \in \mathbb{R}^p} l(\vec{t}; \vec{X}) = \sup_{\vec{t} \in \mathbb{R}^p} l(g^{-1}(\vec{t}); \vec{X}) = \sup_{\vec{\theta} \in \mathbb{R}^p} l(\vec{\theta}; \vec{X})$$

This sup is attained at both $\vec{\theta}_{MLE}$ or \vec{t}_{MLE} hence they're equivalent

$$\Rightarrow \text{the MLE of the norm is } \hat{n}_{MLE} = \frac{1}{\hat{\lambda}_{MLE}} \Gamma\left(\frac{1}{\hat{\lambda}_{MLE}} + 1\right)$$

redix by t_f are missing and termed "censored".
Let c be the binary censoring variable

Eg.

y_i	c_i
0.85	0
0.71	0
?	1
0.13	0
0.60	0
?	1
\vdots	\vdots

So now the observed data is \vec{y}, \vec{c} .

How do we estimate $\mu = E[Y]$?

Let's write out the likelihood function:

$$L(k, \lambda; \vec{y}, \vec{c}, t_f) = \prod_{\{i: c_i=0\}} f(y_i; \lambda, k) \prod_{\{i: c_i=1\}} P(Y_i > t_f)$$

$$= \prod_{\{i: c_i=0\}} \lambda^k y_i^{k-1} e^{-\lambda^k y_i^k} \prod_{\{i: c_i=1\}} e^{-\lambda^k t_f^k}$$

Let $n_0 := \sum c_i = 0$
Let $n_1 := n - n_0 = \sum c_i = 1$

$$L(k, \lambda; \vec{y}, \vec{c}, t_f) = n_0 k \ln(\lambda) + n_0 \ln(k) + (k-1) \sum_{\{i: c_i=0\}} \ln(y_i) - \lambda^k \sum_{\{i: c_i=0\}} y_i^k - n_1 \lambda^k t_f^k \stackrel{\text{set } 0}{=}$$

Solving this numerically yields $\hat{\lambda}_{MLE}, \hat{k}_{MLE} \Rightarrow \hat{\mu}_{MLE} \sim N(\hat{\mu}, \hat{var})$

What is the variance? Need Fisher ^{Info} matrix (beyond scope of course)

for λ, k , then use numerical optimization. Packages in R do this for you.

Alternative: Use E-M algorithm

Hint: t_f differs for each i

Hint: don't forget to sum

Hint: E-M alg as alternative

- ① Begin with guesses for y_i s.t. $c_i=0$
- ② Compute $\hat{\lambda}_{MLE}, \hat{k}_{MLE}$ (M-step)
- ③ Compute

$E[Y_i | Y_i > t_f]$ which will be the same for all i

- ④ Repeat steps 1-2 (E-step)
- Until convergence