

Metropolis - Hastings model Verification

How do we sample from this distribution?
Sample θ from posterior. Then sample X from θ .
Pick an arbitrary θ

- ① Pick $\theta \in \{\theta_1, \dots, \theta_L\}$
- ② Sample X^* from $P(X^* | \theta = \theta_e)$
- ③ Repeat steps 1-2.

Gibbs is a Markov chain.

5/11/17

Algorithm: Systematic Sweep

Gibbs Sampler

$P(\theta_1, \dots, \theta_p | X)$, the unknown posterior w/
 p parameters.

Here, all conditionals $\forall j$

$P(\theta_j | \theta_{-j})$ where

$\theta_{-j} = \{\theta_1, \dots, \theta_{j-1}, \theta_{j+1}, \dots, \theta_p\}$ are

known and can be "easily" sampled from.

Step 1: Initialize

$\theta = \langle \theta_{0,1}, \theta_{0,2}, \dots, \theta_{0,p} \rangle$

Step 2: Sample $\theta_{1,1}$ from

$P(\theta_{1,1} | \theta_2 = \theta_{0,2}, \dots, \theta_p = \theta_{0,p})$

Sample $\theta_{1,2}$ from $P(\theta_{1,2} | \theta_1 = \theta_{1,1}, \theta_3 = \theta_{0,3}, \dots, \theta_p = \theta_{0,p})$

Sample $\theta_{1,p}$ from $P(\theta_{1,p} | \theta_1 = \theta_{1,1}, \dots, \theta_{p-1} = \theta_{1,p-1})$

Step 3: Repeat step 2 until "convergence."

Proof not req'd

Consider X_0, X_1, X_2, \dots a sequence of r.v.'s. (scalar or vector).

$P(\theta_{t+1} | \theta_t)$

Arbitrary
on data
 X, \dots

Each has support X . If $P(X_{t+1} \in A | X_t = x, X_{t-1}, X_{t-2}, \dots, X_0) = P(X_{t+1} \in A | X_t = x) \quad \forall t \quad \forall A \subset X$ then the sequence is called a "discrete-time" Markov chain."

\Rightarrow The Gibbs sampler is a Markov chain. The Gibbs sampler is a form of "Markov Chain Monte Carlo" (MCMC).

$$P(X_{t+1}) = \int_X P(X_{t+1}, X_t) dx = \int_X \underbrace{P(X_{t+1} | X_t)}_{\text{transition kernel}} P(X_t) dx$$

If $P(X_{t+1}) = P(X_t)$ then this distribution is called the "invariant", "equilibrium", "stationary", "long-term", "steady-state", "limiting" dist.

$$P(X_{t+1}) = P(X_t | X_{t-1}) P(X_{t-1} | X_{t-2}) \dots P(X_1 | X_0) P(X_0)$$

$$= p(X) = \lim_{t \rightarrow \infty} \int_X \dots dx$$

$$P(\theta_{t+1} | \vec{\theta}_t) = P(\theta_{t+1} | \theta_{t+2}, \dots, \theta_{t+p}) \cdot (P(\theta_{t+2} | \theta_{t+3}, \dots, \theta_{t+p}) \cdot P(\theta_{t+3} | \theta_{t+4}, \dots, \theta_{t+p}) \cdot \dots \cdot P(\theta_{t+p-1} | \theta_{t+p}))$$

$$P(\vec{\theta}_{t+1}) = \int P(\vec{\theta}_{t+1} | \vec{\theta}_t) P(\vec{\theta}_t) d\vec{\theta}$$

$$P(\theta_{t+1}, \dots, \theta_{t+p}) = \int_{\theta_1} \int_{\theta_2} \dots \int_{\theta_p} P(\theta_{t+1}, \dots, \theta_{t+p}) d\theta_1 d\theta_2 \dots d\theta_p$$

$$= P(\theta_{t+1} | \theta_{t+2}, \dots, \theta_{t+p}) \cdot P(\theta_{t+2}, \dots, \theta_{t+p})$$

$$= \int_{\theta_2} \dots \int_{\theta_p} \text{kernel} \left[\int_{\theta_1} P(\theta_{t+1} | \theta_{t+2}, \dots, \theta_{t+p}) d\theta_1 \right] \cdot P(\theta_{t+2}, \dots, \theta_{t+p}) d\theta_2 \dots d\theta_p$$

$$\int_{\theta_3} \int_{\theta_p} \text{next of the kernel} \left[\int_{\theta_2} P(\theta_{t+1} | \theta_{t+2}, \dots, \theta_{t+p}) P(\theta_{t+2}, \dots, \theta_{t+p}) d\theta_2 \right] d\theta_3 \dots d\theta_p$$

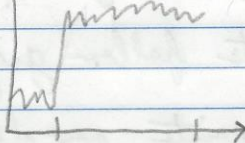
Semi-conjugate inverse gamma

$$P(\theta_{t+1}, \theta_{t+2}, \dots, \theta_{t+p}) \quad (\text{after kernel})$$

$$\int \int \dots \int_{\theta_4, \theta_p} \underbrace{P(\theta_{t+1}, \theta_{t+2}, \dots, \theta_{t+p})}_{\text{next of kernel}} \underbrace{P(\theta_{t+1}, 2 | \theta_{t+1}, \theta_{t+2}, \dots, \theta_{t+p})}_{\text{kernel}} \cdot P(\theta_{t+1}, \theta_{t+2}, \dots, \theta_{t+p}) d\theta_3 \dots d\theta_p$$

$$P(\theta_{t+1}, \theta_{t+2}, \theta_{t+3}, \dots, \theta_{t+p}) = \dots P(\theta_{t+1}, \dots, \theta_{t+p})$$

Change point model



iid Poisson(λ_1) iid Poisson(λ_2)

Parameters:

λ_1 - mean of "first process"

λ_2 - mean of second process

m - the "change point"

Priors: (good review)

$$P(\lambda_1) = \text{Gamma}(\alpha, \beta)$$

$$P(\lambda_2) = \text{Gamma}(\alpha, \beta)$$

$$P(m) = \text{Uniform}(\{0, \dots, n\}) = \frac{1}{n+1} \forall m$$

$$P(\lambda_1)P(\lambda_2)P(m)$$

$$P(\lambda_1, \lambda_2, m | X_1, \dots, X_n) \propto P(X_1, \dots, X_n | \lambda_1, \lambda_2, m) P(\lambda_1, \lambda_2, m)$$

$$\propto \left(\prod_{i=1}^m \frac{e^{-\lambda_1} \lambda_1^{x_i}}{x_i!} \right) \left(\prod_{i=m+1}^n \frac{e^{-\lambda_2} \lambda_2^{x_i}}{x_i!} \right) (\lambda_1^{\alpha-1} e^{-\beta \lambda_1}) (\lambda_2^{\alpha-1} e^{-\beta \lambda_2})$$

$$\left(\lambda_1^{\alpha-1} e^{-\beta \lambda_1} \right) \propto e^{-n \lambda_1} \lambda_1^{\sum_{i=1}^m x_i} = a \quad e^{-(n-m) \lambda_2} \lambda_2^{\sum_{i=m+1}^n x_i} = b$$

Uniform priors are good

$$= e^{-(m+\beta)\lambda_1} \lambda_1^{a+d-1} e^{-(n+m+\beta)\lambda_2} \lambda_2^{b+d-1} \text{ unknown distribution}$$

$$P(\lambda_1 | X_1, \dots, X_h, \lambda_2, m) \propto e^{-(m+\beta)\lambda_1} \lambda_1^{a+d-1} \propto \text{Gamma}(a+d, m+\beta)$$

$$P(\lambda_2 | X_1, \dots, X_h, \lambda_1, m) \propto e^{-(n+m+\beta)\lambda_2} \lambda_2^{b+d-1} \propto \text{Gamma}(b+d, n+m+\beta)$$

$$P(m | X_1, \dots, X_h, \lambda_1, \lambda_2) \propto e^{-m(\lambda_1 + \lambda_2)} \lambda_1^a \lambda_2^b \underbrace{\lambda_1^d \lambda_2^d}_{h(m)} \propto e^{-m(\lambda_1 + \lambda_2)} \lambda_1^a \lambda_2^b$$

$$\propto \frac{h(m)}{\sum_{k=0}^n h(k)} \left[\begin{array}{c} \lambda_{0,1} \\ \lambda_{0,2} \\ m_0 \end{array} \right], \left[\begin{array}{c} \lambda_{1,1} \\ \lambda_{1,2} \\ m_1 \end{array} \right], \dots$$

Burn-in line: points follow gray line
 when it burned-in
 Delete other data points; now all correlated
 bc one vector comes from other
 Take posterior and graph credible region
 Middle bar is mean ($\hat{\theta}_{MSE}$)
 CR_{0.95}: captures θ value 95% of the time