

$$\hat{\theta}_2 = \frac{\sum X_i(1-I_i)}{\sum 1-I_i} \quad X_{mix 2}$$

let $\hat{\sigma}_1^2$

$$\frac{2}{2\sigma_1^2} [l] = - \frac{1 + \frac{1}{2} \sum I_i}{\sigma_1^2} + \frac{\sum I_i (X_i - \theta)^2}{2(\sigma_1^2)^2} = 0$$

$$\Rightarrow 1 + \frac{1}{2} \sum I_i = \frac{1}{2\sigma_1^2} \sum I_i (X_i - \theta)^2$$

$$\Rightarrow 2 + \sum I_i = \frac{1}{\sigma_1^2} \sum I_i (X_i - \theta)^2$$

$$\Rightarrow \hat{\sigma}_1^2 = \frac{\sum I_i (X_i - \theta)^2}{2 + \sum I_i}$$

Likewise, $\hat{\sigma}_2^2 = \frac{\sum (1-I_i) (X_i - \theta)^2}{2 + \sum (1-I_i)}$

\hat{p} get $\frac{2}{2p} [l] \stackrel{\text{set}}{=} 0$

$$= \frac{\sum I_i}{p} - \frac{\sum 1-I_i}{1-p} = 0$$

Use data until converges

$$\frac{\sum I_i}{p} = \frac{\sum 1-I_i}{1-p} = n - \sum I_i$$

Dirho

$$\sum I_i - p \sum I_i = pn - p \sum I_i \Rightarrow \boxed{\hat{p} = \frac{\sum I_i}{n}}$$

5/9/17

Recall $X_1, \dots, X_n | \theta, \sigma^2 \stackrel{iid}{\sim} N(\theta, \sigma^2)$

$$\theta \sim N(\mu_0, \tau^2)$$

$$\sigma^2 \sim \text{InvG}\left(\frac{n_0}{2}, \frac{n_0 \sigma_0^2}{2}\right)$$

Do not

sample from

InvGamma

$$\Rightarrow p(\theta, \sigma^2 | X) \propto N(\theta | \mu_p, \sigma_p^2) K(\sigma^2 | X)$$

Recall

$$p(\theta | \sigma^2, X) = N(\theta | \mu_p, \sigma_p^2)$$

$$p(\sigma^2 | \theta, X) = \text{InvG}\left(\frac{n_0 + n}{2}, \frac{n_0 \sigma_0^2 + n \hat{\sigma}_{MLE}^2}{2}\right)$$

Can we use these two cond. distributions to tell us about $P(\theta, \sigma^2 | X)$?

$$P(AB) = P(A|B) \cdot P(B) = P(B|A)P(A)$$

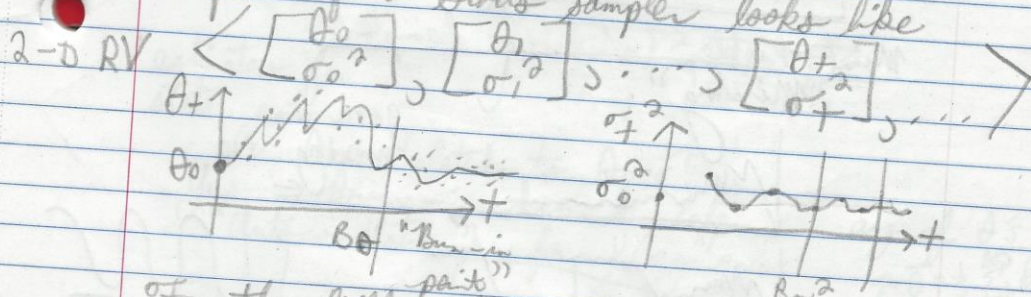
$$P(\theta, \sigma^2 | X) = \underbrace{P(\theta | \sigma^2 | X)}_{\text{cond. dist.}} \underbrace{P(\sigma^2 | X)}_{\text{cond. dist.}} = P(\sigma^2 | \theta, X) P(\theta | X)$$

What if we used an iterative algorithm?

- ① Assume an arbitrary value of θ_0
- ② Draw σ_0^2 from $P(\sigma^2 | \theta = \theta_0, X) = \text{InvG}$
- ③ Draw θ_1 from $P(\theta | \sigma^2 = \sigma_0^2, X)$
- ④ Draw σ_1^2 from $P(\sigma^2 | \theta = \theta_1, X)$
- ⑤ Repeat 2, 3 until "convergence."

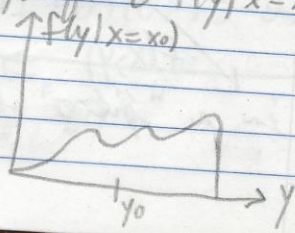
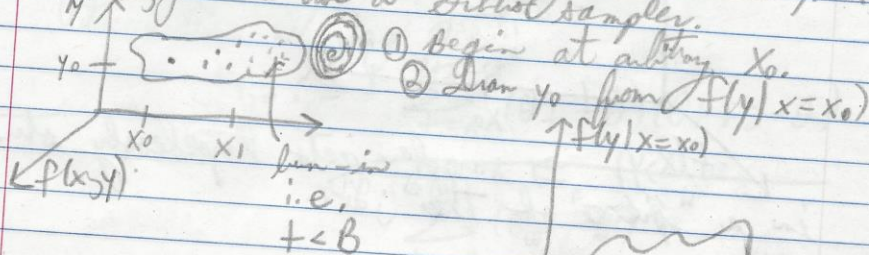
This algorithm is called "Gibbs sampling" or "the Gibbs sampler." (1980's)

Output of a Gibbs sampler looks like



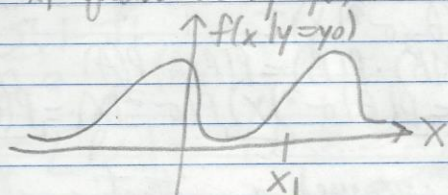
For the Gibbs chat, the burn-in is the $\max B_i$ for all θ_i 's.

For $t \geq B$, the chain $f(x, y)$ is "burn-in." If you seek $f(x, y)$ but only know $f(x|y)$ & $f(y|x)$, you can use a Gibbs sampler.



9:30-1:40
Hamiltonian Monte Carlo

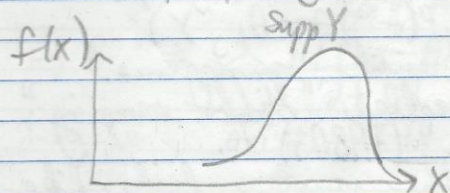
③ Draw x_1 from $f(x|y=y_0)$



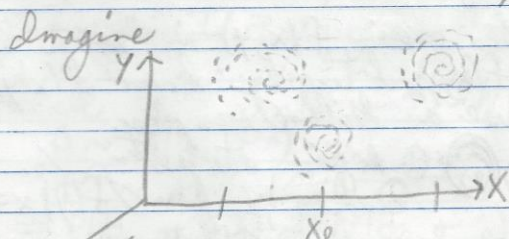
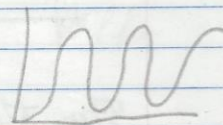
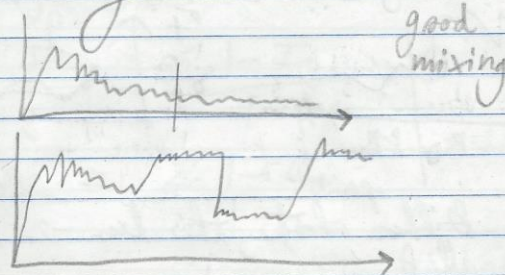
$(x_0, y_0), (x_1, y_1), \dots, (x_T, y_T)$

What if you want $f(x)$?

$$f(x) = \int f(x, y) dy$$



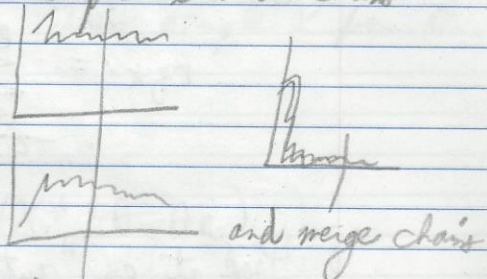
main problem w/ Gibbs sampler
"mixing"



$f(x, y) \Rightarrow$ sampler gets hopelessly stuck in a "piece" of the jdf.

a possible solution: we multiple Gibbs chains from different x_0 's.

a smaller problem (which is more fixable) is as follows. Is θ_1 related to θ_0 ? Yes.



$$\text{Cor}[X, Y] := \frac{\text{Cov}(X, Y)}{\text{SE}(X)\text{SE}(Y)} = \frac{E[(X - \mu_X)(Y - \mu_Y)]}{\sqrt{\text{Var}(X)}\sqrt{\text{Var}(Y)}}$$

$$\text{Cov}[\theta_1, \theta_0] \neq 0$$

continuous cor.

$$r := \frac{S_{xy}}{S_x S_y} = \frac{\sum (x_i - \bar{x})(y_i - \bar{y}) / (n-1)}{\sqrt{\frac{\sum (x_i - \bar{x})^2}{n-1}} \sqrt{\frac{\sum (y_i - \bar{y})^2}{n-1}}}$$

↑ ↑
estimators for
state. cov.

Is θ_{1000} related to θ_{999} ?

Yes \Rightarrow Burn-in doesn't help.

"Autocorrelation" for "lag" one:

arg. of θ 's
 $\uparrow \theta = \frac{1}{5} \sum_{t=0}^{999} \theta_t$

$$r_{0,1} := \frac{\sum_{t=0}^{B+S-1} (\theta_t - \bar{\theta})(\theta_{t+1} - \bar{\theta})}{\sum_{t=0}^{B+S-1} (\theta_t - \bar{\theta})^2}$$

B+S is total # of iterations

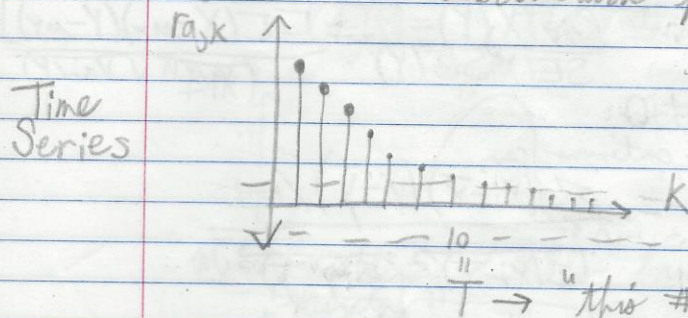
Autocorrelation w/ lag 2:

$$r_{1,2} := \frac{\sum_{t=0}^{B+S-2} (\theta_t - \bar{\theta})(\theta_{t+2} - \bar{\theta})}{\sum_{t=0}^{B+S-2} (\theta_t - \bar{\theta})^2}$$

Autocorrelation for lag k :

$$r_{g,k} = \frac{\sum_{t=B}^{B+S-K} (\theta_t - \bar{\theta})(\theta_{t+k} - \bar{\theta})}{\sum_{t=B}^{B+S} (\theta_t - \bar{\theta})^2}$$

Look at an "autocorrelation plot"



Retain T_{med} $T=0$
Thin every 10 here

Gibbs is smaller than Metropolis

independent chains \Rightarrow

$$\left\langle \begin{bmatrix} \theta_{15} \\ \theta_{25} \end{bmatrix}, \begin{bmatrix} \theta_{B+T} \\ \theta_{B+T} \end{bmatrix}, \begin{bmatrix} \theta_{B+2T} \\ \theta_{B+2T} \end{bmatrix}, \dots \right\rangle$$

burned + thinned chain

good to have ≥ 1000

length L

$$\hat{\theta}_{MSE} = E[\theta|X] \approx \bar{\theta} = \frac{1}{L} \sum_{l=1}^L \theta_l$$

$$\hat{\theta}_{MAE} = \text{Med}[\theta|X] \approx \text{order } \theta\text{'s from lowest to highest}$$

$\theta_{(1)}, \theta_{(2)}, \dots, \theta_{(L)}$
and use $\theta_{(\frac{L}{2})}$.

$$P(X^*|X) = \int_{\Theta} P(x^*|\theta) P(\theta|X) d\theta$$

FINAL

Metropolis - Hastings Model Verification

How do we sample from this distribution?
Sample θ from posterior. Then sample X from θ .
Pick an arbitrary θ

- ① Pick $\theta \in \{\theta_1, \dots, \theta_L\}$
- ② Sample X^* from $P(X^* | \theta = \theta_e)$
- ③ Repeat steps 1-2.

Gibbs is a Markov chain.

5/11/17

Algorithm: Systematic Sweep

Gibbs Sampler
 $P(\theta_1, \dots, \theta_p | X)$, the unknown posterior w/
 p parameters.
Here, all conditionals, $\forall j$

$P(\theta_j | \theta_{-j})$ where

$\theta_{-j} = \{\theta_1, \dots, \theta_{j-1}, \theta_{j+1}, \dots, \theta_p\}$ are

known and can be "easily" sampled from.

Step 1: Initialize

$\theta = \langle \theta_{0,1}, \theta_{0,2}, \dots, \theta_{0,p} \rangle$

Step 2: Sample $\theta_{1,1}$ from

$P(\theta_{1,1} | \theta_2 = \theta_{0,2}, \dots, \theta_p = \theta_{0,p})$

Sample $\theta_{1,2}$ from $P(\theta_{1,2} | \theta_1 = \theta_{1,1}, \theta_3 = \theta_{0,3}, \dots, \theta_p = \theta_{0,p})$

Sample $\theta_{1,p}$ from $P(\theta_{1,p} | \theta_1 = \theta_{1,1}, \dots, \theta_{p-1} = \theta_{1,p-1})$

Step 3: Repeat step 2 until "convergence."

Proof not req'd

Consider X_0, X_1, X_2, \dots a sequence of r.v.'s. (scalar or vector).

$P(\theta_{t+1} | \theta_t)$

Arbitrary
on data
 X, \dots