

$$\text{if } \left[ P(X) = \lim_{t \rightarrow \infty} \int_x \left( \prod_{i=1}^{t+1} P(x_i | x_{i-1}) \right) P(X_0 = x) dx \right] \text{ then Sampler converges}$$

Lec 21: Showing Gibbs sampling works continued

Note:  $\theta_{t,p}$   
sample #      iteration

Let:

$$P(\vec{\theta}_{t+1} | \vec{\theta}_t, X) = P(\theta_{t+1,1}, \theta_{t+1,2}, \dots, \theta_{t+1,p} | \theta_{t,1}, \theta_{t,2}, \dots, \theta_{t,p}, X)$$

\* ignoring  $X$  for convenience

$$A = P(\theta_{t+1,1} | \theta_{t,1,2}, \dots, \theta_{t,p}) \cdot P(\theta_{t+1,2} | \theta_{t+1,1}, \theta_{t,1,3}, \dots, \theta_{t,p}) \dots P(\theta_{t+1,p} | \theta_{t+1,1}, \dots, \theta_{t,p-1})$$

systematic  
p steps, sweep steps: we find  $\theta_{t+1}$  one iteration at a time using old data that is replaced by new data

So...

$$P(\vec{\theta}_{t+1} | X) = \int_{\Theta} P(\vec{\theta}_{t+1} | \vec{\theta}_t, X) P(\vec{\theta}_t | X) d\vec{\theta}$$

$$P(\theta_{t+1,1}, \theta_{t+1,2}, \dots, \theta_{t+1,p}) =$$

... converges if  $P(\vec{\theta}_{t+1}) = P(\vec{\theta}_t)$   
since new data is the same as the old data

$$= \int \dots \int P(\vec{\theta}_{t+1} | \vec{\theta}_t, X) P(\vec{\theta}_t | X) d\theta_{t,1} d\theta_{t,2} \dots d\theta_{t,p}$$

replace w/ the above expression      expandable via bayes rule

$$P(\theta_{t+1,1} | \theta_{t+1,2}, \dots, \theta_{t,p}) \cdot P(\theta_{t+1,2}, \dots, \theta_{t,p})$$

$$= \int \dots \int P(\vec{\theta}_{t+1} | \vec{\theta}_t) \cdot P(\theta_{t+1,2}, \dots, \theta_{t,p}) \cdot \left[ \int P(\theta_{t+1,1} | \theta_{t+1,2}, \dots, \theta_{t,p}) d\theta_{t+1,1} \right] d\theta_{t+1,2} \dots d\theta_{t+1,p}$$

= 1



$$= \int_{\theta_{t,3}} \int_{\theta_{t,p}} \dots \int A \cdot \int_{\theta_{t,2}} P(\theta_{t+1,1} | \theta_{t,2}, \dots, \theta_{t,p}) P(\theta_{t,2}, \dots, \theta_{t,p}) d\theta_{t,2} \dots d\theta_{t,p}$$

$A_1$   
 1st term of A  
 $B$   
 w/o the first term

$$= \int_{\theta_{t,3}} \int_{\theta_{t,p}} \dots \int (A-1) \cdot \left[ \int_{\theta_{t,2}} P(\theta_{t+1,1} | \theta_{t,2}, \dots, \theta_{t,p}) d\theta_{t,2} \right] \dots d\theta_{t,p}$$

$$= \int_{\theta_{t,3}} \int_{\theta_{t,p}} \dots \int (A-1) \cdot \left( P(\theta_{t+1,1} | \theta_{t,3}, \dots, \theta_{t,p}) \right) d\theta_{t,3} \dots d\theta_{t,p}$$

$B$  w/o 1st term:  $(B-1)$   
 Replaced by new  $t+1$  term

∴ repeat steps so that  $A_{i+1}$  term and  $(B-i+1)$ th term combine to create the new  $B$  term for next  $A$

∴ at the end:

$P(\theta_{t+1,1}, \dots, \theta_{t+p,p})$  proves the Gibbs converges since each iteration for our old data changed to our new

\* so it doesn't matter where  $\vec{\theta}_+ | X$  begins, it will eventually converge at some point such that the next sample will be identical to the previous



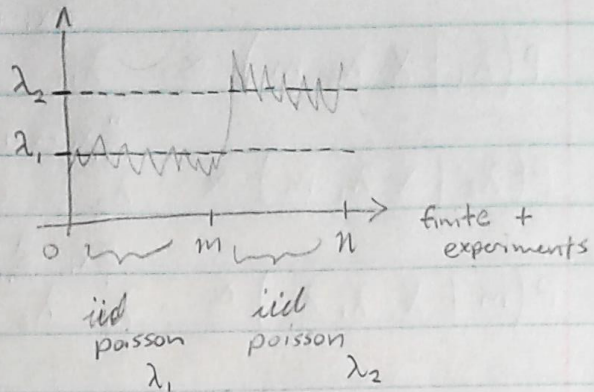
# Change Point Model

ex: two iid Poissons st.

$$\vec{\theta} = \begin{cases} \lambda_1 \in (0, \infty) \\ \lambda_2 \in (0, \infty) \\ m \in \{1, 2, \dots, n\} \end{cases}$$

must change at  
some distinct pt.

all unknown



$$P(\lambda, \lambda_2, m | \underbrace{X_1, X_2, \dots, X_n}_X) \propto \underbrace{P(X | \lambda, \lambda_2, m)}_{\text{Break into parts}} \left[ P(\lambda, \lambda_2, m) \right]^*$$

Prior based on origin  
distribution of value

$\lambda_1, \lambda_2, m$  are all independent  
so  $= P(\lambda_1) \cdot P(\lambda_2) \cdot P(m)$

$$\begin{aligned} P(\lambda_1) &\sim \text{Gamma}(\alpha, \beta) \propto \lambda_1^{\alpha-1} e^{-\beta \lambda_1} \\ P(\lambda_2) &\sim \text{Gamma}(\alpha, \beta) \propto \lambda_2^{\alpha-1} e^{-\beta \lambda_2} \\ P(m) &\sim U\{1, \dots, n\} = 1/n \end{aligned} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \begin{array}{l} \text{uninformative} \\ \text{if } \alpha = 1 \\ \beta = 0 \end{array}$$

$$\underbrace{P(\lambda, \lambda_2, m | X)}_{\text{posterior}} = \left( \prod_{i=1}^m \frac{e^{-\lambda_1} \lambda_1^{x_i}}{(x_i)!} \cdot \prod_{i=m+1}^n \frac{e^{-\lambda_2} \lambda_2^{x_i}}{(x_i)!} \right) \left( \lambda_1^{\alpha-1} e^{-\beta \lambda_1} \right) \left( \lambda_2^{\alpha-1} e^{-\beta \lambda_2} \right) \left( \frac{1}{n} \right)$$

$$P(X_1, \dots, X_m | \lambda_1) \cdot P(X_{m+1}, \dots, X_n | \lambda_2) \cdot P(\lambda_1) \cdot P(\lambda_2) \cdot P(m)$$

$$\propto \left( e^{-m\lambda_1} \lambda_1^{\sum_{i=1}^m x_i} \right) \left( e^{-(n-m)\lambda_2} \lambda_2^{\sum_{i=m+1}^n x_i} \right) \left( \lambda_1^{\alpha-1} e^{-\beta \lambda_1} \right) \left( \lambda_2^{\alpha-1} e^{-\beta \lambda_2} \right) \left( \frac{1}{n} \right)$$

constant

$$k(\lambda, \lambda_2, m | X) \propto \left( e^{-(m+\beta)\lambda_1} \lambda_1^{\sum_{i=1}^m x_i + \alpha - 1} \right) \left( e^{-(n-m+\beta)\lambda_2} \lambda_2^{\sum_{i=m+1}^n x_i + \alpha - 1} \right)$$

• Kernel of posterior

• Unknown form : non conjugate

• Gibbs sample to find values

\* create conditionals

\* Create conditionals from posterior :

$$P(\lambda_1 | X, \lambda_2, m) \propto \lambda_1^{\sum_{i=1}^m X_i + \alpha - 1} e^{-(m+\beta)\lambda_1} \propto \text{Gamma}\left(\sum_{i=1}^m X_i + \alpha, m+\beta\right)$$

$$P(\lambda_2 | X, \lambda_1, m) \propto \lambda_2^{\sum_{i=m+1}^n X_i + \alpha - 1} e^{-(n-m+\beta)\lambda_2} \propto \text{Gamma}\left(\sum_{i=m+1}^n X_i + \alpha, n-m+\beta\right)$$

$$P(m | X, \lambda_1, \lambda_2) \propto \lambda_1^{\sum_{i=1}^m X_i} \lambda_2^{\sum_{i=m+1}^n X_i} e^{m(\lambda_2 - \lambda_1)} \propto K(m | \lambda_1, \lambda_2, X)$$

unknown

sample from these starting at:

$\lambda_0 = 1$	let
$\lambda_0 = 1$	$\alpha = 1$
$m_0 = \frac{n}{2}$	$\beta = 0$

Note Sampling from kernel

- Grid over support :  $\langle 1, 2, \dots, n \rangle$   
(or close)

- find  $K(\text{Grid} | X)$  for each pt.

so

$$P(m | X) = \frac{K(m | X)}{\sum_{i=1}^n K(i | X)} \quad \left. \vphantom{\frac{K(m | X)}{\sum_{i=1}^n K(i | X)}} \right\} \begin{array}{l} \text{discrete} \\ \text{sample} \end{array}$$