

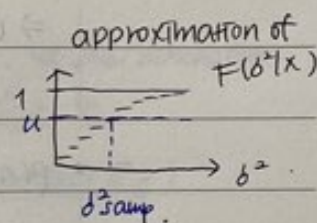
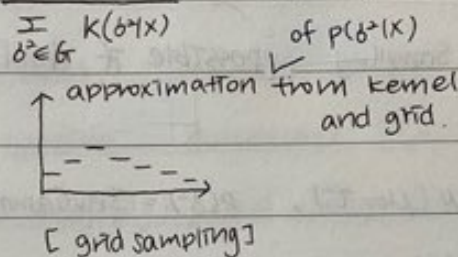
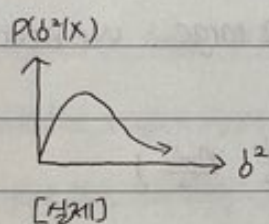
$P(\theta, \delta^2 | x) \propto P(\theta | \delta^2, x) P(\delta^2 | x)$ 2012 sheet, CHH $K(\delta^2 | x) \propto$
 $\propto P(\theta | \delta^2, x) k(\delta^2 | x)$ ← last class

$P(\delta^2 | x) = c \cdot k(\delta^2 | x)$ Drawing from $k(\delta^2 | x)$ approximately in the goal.
 produce called "grid sampling."

① Create a "grid" by picking δ^2_{\min} , δ^2_{\max} , $\Delta \rightarrow$ grid resolution.

$$G = \{\delta^2_{\min}, \delta^2_{\min} + \Delta, \delta^2_{\min} + 2\Delta, \dots, \delta^2_{\max}\}$$

② Compute $C_{\text{approx}} = \frac{1}{\sum_{\delta^2 \in G} k(\delta^2 | x)}$ " $P(\delta^2 | x) \propto C_{\text{approx}} k(\delta^2 | x)$ "



③ Compute the approximate CDF $F(\delta^2 | x) := P(\delta^2 \leq \delta^2 | x)$

$$= \sum_{\delta^2 \leq \delta^2_0 : \delta^2 \in G} C_{\text{approx}} k(\delta^2 | x)$$

④ Draw u from $U(0,1)$ via `runif(0,1)` then locate $\delta^2_{\text{samp}} := \min_{\delta^2 \in G} \{F(\delta^2 | x) \geq u\}$

Sample from the prior

① Draw δ^2_{samp} from $k(\delta^2 | x)$ via grid sampling

② Draw θ_{samp} from $P(\theta | x, \delta^2 = \delta^2_{\text{samp}})$

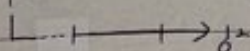
③ Return $\langle \theta_{\text{samp}}, \delta^2_{\text{samp}} \rangle$

Disadvantages of Grid sampling.

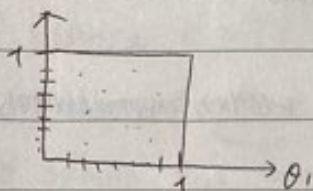
① How to pick $\theta_{\min}, \theta_{\max}, \Delta$? In one dimension, with known $\text{Supp}[\theta]$, no problem. But in many dimensions with possibly unknown $\text{Supp}[\theta]$, problems.

② $\frac{1}{N} \sum_{i=1}^N \dots$

Numerically unstable / inaccurate in the tails.



③ Curse of Dimensionality



$\Delta = 0.2$ # points in each dim = 5.

points in whole grid $5^2 = 25$.

Imagine 10^5 points in each dimension. 10 dimensions. $10^{5 \times 10} = 10^{50}$ not possible

If you want 10^5 total points $\sqrt[10]{10^5} \approx 2$ points in each dimension.

" 10^9 (billion) $\sqrt[10]{10^9} \approx 8$ points "

\Rightarrow Grid Sampling Impossible if $\dim[\theta]$ is large. We need another procedure.

• $P(\theta) = N(\mu_0, \Sigma^*)$, $P(\delta^2) = \text{InvGamma}(\frac{n_0}{2}, \frac{n_0 \delta_0^2}{2})$

$P(\theta, \delta^2(x))$ was a mess due to non-conjugacy. Technically it's

"semi-conjugate."

$\Rightarrow P(\theta | x, \delta^2) = N(\frac{\frac{n_0 \mu_0}{2} + \frac{1}{2}}{\frac{n_0}{2} + \frac{1}{2}}, \frac{1}{\frac{n_0}{2} + \frac{1}{2}})$ & $P(\delta^2 | x, \theta) = \text{InvGamma}(\frac{n_0 + n}{2}, \frac{n_0 \delta_0^2 + n \delta^2}{2})$

Imagine the following sampling:

① Let $\theta_0 = 0$ and $\delta_0^2 = 1$.

calc.
using θ_0

①a Draw δ_1^2 from $\text{rinvgamma}(\frac{n_0 + n}{2}, \frac{n_0 \delta_0^2 + n \delta^2}{2})$

①b Draw θ_1 from $\text{rnorm}(\frac{n_0 \mu_0}{2} + \frac{1}{2}, \frac{1}{\frac{n_0}{2} + \frac{1}{2}})$

②a Draw δ_2^2 from $\text{rinvgamma}(\frac{n_0 + n}{2}, \frac{n_0 \delta_0^2 + n \delta^2}{2})$

②b Draw θ_2 from $\text{rnorm}(\frac{n_0 \mu_0}{2} + \frac{1}{2}, \frac{1}{\frac{n_0}{2} + \frac{1}{2}})$

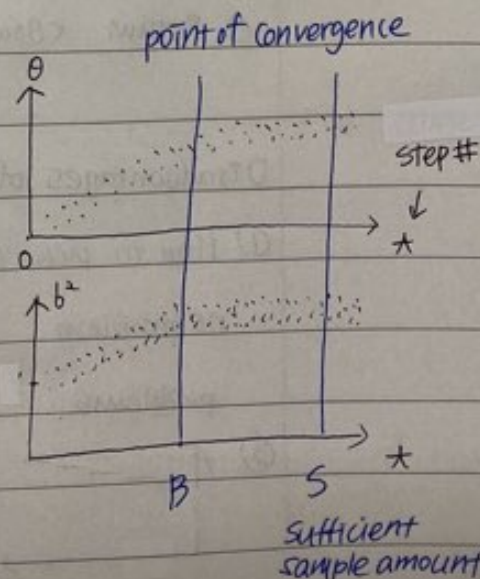
⋮

repeat until "convergence"

$\langle \theta_0 \rangle$ step 1 step 2
 $\langle \delta_0^2 \rangle$ $\langle \theta_1 \rangle$ $\langle \delta_1^2 \rangle$ $\langle \theta_2 \rangle$ $\langle \delta_2^2 \rangle$...

"B" is called the "burn-in"

need some time
to get the point
(operating right)



sufficient
sample amount

go through all order

go through all p dimension.

NO.

Systematic Sweep Gibbs Sampler for $\vec{\theta} = [\theta_1, \theta_2, \dots, \theta_p]$

① Initialize $\vec{\theta}_0 = [\theta_{0,1}, \theta_{0,2}, \dots, \theta_{0,p}]$

①a Sample $\theta_{1,1}$ from $P(\theta_1 | \theta_2 = \theta_{0,2}, \theta_3 = \theta_{0,3}, \dots, \theta_p = \theta_{0,p}, X)$

①b Sample $\theta_{1,2}$ from $P(\theta_2 | \theta_1 = \theta_{1,1}, \theta_3 = \theta_{0,3}, \dots, \theta_p = \theta_{0,p}, X)$

①p Sample $\theta_{1,p}$ from $P(\theta_p | \theta_1 = \theta_{1,1}, \theta_2 = \theta_{1,2}, \dots, \theta_{p-1} = \theta_{1,p-1}, X)$

② Record $[\theta_{1,1}, \dots, \theta_{1,p}]$

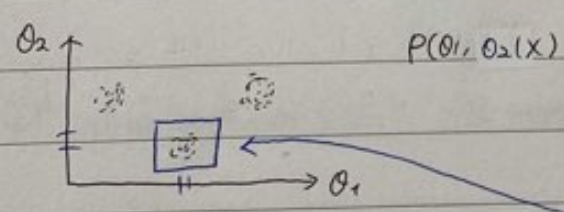
③ Repeat Step 1,2 S times.

Reminder: you need all conditional distribution $P(\theta_j | \vec{\theta}_{-j}^s)$ ^{all other dimension.} $\forall j$.

(If you are missing some $P(\theta_j | \vec{\theta}_{-j}^s)$, you'll always have $\kappa(\theta_j | \vec{\theta}_{-j}^s)$ and step 1,2 could be a grid sample step.

Problems with the Gibbs Sampler

① It's possible to not reveal while posterior



If this is your true posterior, the Gibbs Sampler will only find one pocket. eg.

problem gets worse if p large.

