

Lecture 20 Math 621 11/20/17

$$\vec{Z} \sim N_n(\vec{0}_n, I_n)$$

$$E(\vec{Z}) = \vec{0}_n, \quad \text{Var}(\vec{Z}) = I_n$$

$$\vec{Z} \in \mathbb{R}^n$$

$$\text{if } \vec{X} = \vec{Z} + \vec{\mu} \sim N(\vec{\mu}, I_n)$$

$$\text{if } \vec{X} = A\vec{Z}, \quad A \in \mathbb{R}^{m \times n}, \quad \mu = E(\vec{X}) = A E(\vec{Z}) = A \vec{0}_n = \vec{0}_m, \quad \Sigma = \text{Var}(\vec{X}) = AA^T \in \mathbb{R}^{m \times m}$$

Is  $\Sigma$  symmetric?

$$\Sigma = \Sigma^T = (AA^T)^T = A^T A^T = AA^T \checkmark$$

$f_{\vec{X}}(\vec{x})$ ? Note  $\vec{X} = g(\vec{Z}) = A\vec{Z}$ . Assume  $A \in \mathbb{R}^{n \times n}$  for now.

$$\vec{Z} = h(\vec{X}) = A^{-1}\vec{X}, \quad g \text{ is only 1:1 if } A \text{ is full rank.}$$

Let's do invertible change of variables like before...

$$h_1(\vec{x}), \dots, h_n(\vec{x})$$

$$f_{\vec{x}}(\vec{x}) = f_{\vec{z}}(h(\vec{x})) \mid J_h(\vec{x})$$

$$A^{-1}x$$

$$J_h = \begin{bmatrix} \frac{\partial}{\partial x_1} h_1(\vec{x}) & \dots & \frac{\partial}{\partial x_n} h_1(\vec{x}) \\ \vdots & & \vdots \\ \frac{\partial}{\partial x_1} h_n(\vec{x}) & \dots & \frac{\partial}{\partial x_n} h_n(\vec{x}) \end{bmatrix}$$

$$h(\vec{x}) = \begin{bmatrix} h_1(\vec{x}) \\ h_2(\vec{x}) \\ \vdots \\ h_n(\vec{x}) \end{bmatrix} = B \vec{x}$$

let  $B = A^{-1}$  just for horizontal simplicity

$$B = \begin{bmatrix} \vec{b}_{1\cdot} \\ \vdots \\ \vec{b}_{n\cdot} \end{bmatrix} \text{ or } [\vec{b}_{\cdot 1} \dots \vec{b}_{\cdot n}] \text{ or } \begin{bmatrix} b_{11} & \dots & b_{1n} \\ \vdots & & \vdots \\ b_{n1} & \dots & b_{nn} \end{bmatrix}$$

$$h_1(\vec{x}) = \vec{b}_{1\cdot} \vec{x} = b_{11}x_1 + \dots + b_{1n}x_n$$

$$\frac{\partial}{\partial x_1} [h_1(\vec{x})] = b_{11}$$

$$\frac{\partial}{\partial x_2} [h_1(\vec{x})] = b_{12}$$

$$\frac{\partial}{\partial x_n} [h_1(\vec{x})] = b_{1n}$$

top row of  $J_h$

$$h_2(\vec{x}) = \vec{b}_{2\cdot} \vec{x} = b_{21}x_1 + b_{22}x_2 + \dots + b_{2n}x_n$$

$$\frac{\partial}{\partial x_1} [h_2(\vec{x})] = b_{21}$$

$$J_h = \det \begin{pmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & \dots & \dots & b_{nn} \end{pmatrix} = \det(B) = \det(A^{-1})$$

Side bar... vector derivatives...

$$\frac{\partial}{\partial \vec{x}} [C \vec{x}] = C$$

Many different definitions... no time for this...

$$\Rightarrow f_{\vec{x}}(\vec{x}) = f_{\vec{z}}(A^{-1}x) \mid \det(A^{-1})$$

Recall

$$\det(A^{-1}) = \frac{1}{\det(A)}$$

$$\begin{aligned} AA^{-1} &= I \\ \det(AA^{-1}) &= \det(I) \\ \det(A)\det(A^{-1}) &= 1 \end{aligned}$$

$$= \frac{1}{(2\pi)^{n/2} |\det(A)|} e^{-\frac{1}{2} \frac{(A^{-1}\vec{x})^T (A^{-1}\vec{x})}{\vec{x}^T (A^{-1})^T A^{-1} \vec{x}}}$$

why?

$$(AB)^{-1} = B^{-1}A^{-1}$$

$$\begin{aligned} \text{since } (AB)(AB)^{-1} &= I \\ AB B^{-1} A^{-1} &= AA^{-1} = I \checkmark \end{aligned}$$

Recall:

$$\Sigma = AA^T \Rightarrow \Sigma^{-1} = (AA^T)^{-1} = (A^T)^{-1} A^{-1}$$

Does  $(A^T)^{-1} = (A^{-1})^T$ ?

$$\begin{cases} AA^{-1} = I \Rightarrow (AA^{-1})^T = I^T = I \Rightarrow (A^{-1})^T A^T = I \\ (A^T)^{-1} A^T = I \end{cases}$$

by def of matrix inverse  $\Rightarrow (A^T)^{-1} = (A^{-1})^T$

symmetric?

$$\Rightarrow \Sigma^{-1} = (A^{-1})^T A^{-1} \quad \Sigma^{-1 T} = \Sigma^{-1} = \underbrace{(A^{-1})^T A^{-1}}_{= (A^{-1})^T (A^{-1})^T = (A^{-1})^T A^{-1} \checkmark}$$

$$\Rightarrow \int_{\vec{x}} (\vec{x}) = \frac{1}{(2\pi)^{n/2} |\det(A)|} e^{-\frac{1}{2} \vec{x}^T \Sigma^{-1} \vec{x}}$$

Just to get into canonical form...

Note  $|\det(\Sigma)| = |\det(AA^T)| = |\det(A) \det(A^T)| = |\det(A)|^2$

$\uparrow \quad \uparrow$   
=

$$\Rightarrow \sqrt{|\det(\Sigma)|} = |\det(A)|$$

$$\Rightarrow \int_{\vec{x}} (\vec{x}) = \frac{1}{\sqrt{(2\pi)^n |\det(\Sigma)|}} e^{-\frac{1}{2} \vec{x}^T \Sigma^{-1} \vec{x}} = N_n(\vec{0}, \Sigma)$$

If  $\vec{X} = A\vec{Z} + \vec{\mu} \sim N_n(\vec{\mu}, \Sigma) = \frac{1}{\sqrt{(2\pi)^n |\det(\Sigma)|}} e^{-\frac{1}{2} (\vec{X} - \vec{\mu})^T \Sigma^{-1} (\vec{X} - \vec{\mu})}$

If  $\vec{X} \sim N_n(\vec{\mu}, \Sigma)$ ,  $B \in \mathbb{R}^{n \times n}$ ,  $B\vec{X} \sim ?$  he can use mult. change of var's here easily...

How to prove?

Recall  $\phi_X(t) = E[e^{it^T X}]$ . What about for vector  $\vec{X}$ ?  $\phi_{\vec{X}}(\vec{t}) = E[e^{i\vec{t}^T \vec{X}}]$

This is the symbol of

$\left(\frac{x-\mu}{\sigma}\right)^2$  is the chi-squared normal i.e.

"standardized distance" sqd

This "standardized distance" sqd is called "Mahalanobis distance" sqd (1936)

by P.L. Mahalanobis (very famous Indian statistician). This is super useful!!

I used this in my thesis to measure distance between two people for a clinical trial

for ch.d.f.s  
Rules... again... Same...

$$\phi_{\vec{X}_1 + \vec{X}_2}(\vec{t}) = E[e^{i\vec{t}^T(\vec{X}_1 + \vec{X}_2)}] = E[e^{i\vec{t}^T\vec{X}_1 + i\vec{t}^T\vec{X}_2}] = E[e^{i\vec{t}^T\vec{X}_1} e^{i\vec{t}^T\vec{X}_2}] = \phi_{\vec{X}_1}(\vec{t}) \phi_{\vec{X}_2}(\vec{t})$$

if indep.

$$\phi_{A\vec{X} + \vec{c}}(\vec{t}) = E[e^{i\vec{t}^T(A\vec{X} + \vec{c})}] = E[e^{i\vec{t}^T A\vec{X} + i\vec{t}^T \vec{c}}] = e^{i\vec{t}^T \vec{c}} E[e^{i\vec{t}^T A\vec{X}}] = e^{i\vec{t}^T \vec{c}} \phi_{\vec{X}}(A^T \vec{t})$$

for appropriately scaled  $\vec{c}, A$

let  $\vec{t}' = \vec{t}^T A$   
 $\Rightarrow \vec{t} = \vec{t}'^T A^T = (A^T \vec{t}')^T = A \vec{t}'$

What is ch.d.f. for mult:  $\vec{Z} \sim N_n(\vec{0}, I_n)$

$$E[e^{i\vec{t}^T \vec{Z}}] = \int \dots \int_{\mathbb{R}^n} e^{i\vec{t}^T \vec{z}} f_{\vec{Z}}(\vec{z}) d\vec{z} = \int \dots \int_{\mathbb{R}^n} e^{i(t_1 z_1 + t_2 z_2 + \dots + t_n z_n)} \frac{1}{(\sqrt{2\pi})^n} e^{-\frac{1}{2}(z_1^2 + \dots + z_n^2)} dz_1 \dots dz_n$$

$$= \prod_{i=1}^n \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi}} e^{it_i z_i - \frac{1}{2} z_i^2} dz_i$$

we did a very similar exercise to Mult. ch.d.f. using the CLT proof

$$-\frac{1}{2} z^2 + itz = -\frac{1}{2} (z^2 - 2itz) = -\frac{1}{2} ((z - it)^2 - i^2 t^2) = -\frac{1}{2} ((z - it)^2 + t^2) = -\frac{1}{2} (z - it)^2 - \frac{t^2}{2}$$

$$\prod_{i=1}^n e^{-\frac{t_i^2}{2}} \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} (z_i - it_i)^2} dz_i = e^{-\frac{1}{2} \sum t_i^2} = e^{-\frac{1}{2} \vec{t}^T \vec{t}} = \phi_{\vec{Z}}(\vec{t})$$

PDF for  $N(it_i, 1)$

Note: there is no normal centered at "it". Thus this integral needs to be proved to be 1 some other way. To do so requires complex analysis and Cauchy's theorem. See [https://www.dsprelated.com/freebooks/sasp/Gaussian\\_Integral\\_Complex\\_Offset.html](https://www.dsprelated.com/freebooks/sasp/Gaussian_Integral_Complex_Offset.html) for a proof.

$A \in \mathbb{R}^{m \times n}$   
 if  $X = A\vec{Z} + \vec{m}$   
 $\Rightarrow X \sim N_n(\vec{m}, \Sigma)$

$$\phi_X(\vec{t}) = e^{i\vec{t}^T \vec{m}} \phi_{\vec{Z}}(A^T \vec{t}) = e^{i\vec{t}^T \vec{m}} e^{-\frac{1}{2} \vec{t}^T A A^T \vec{t}} = e^{i\vec{t}^T \vec{m} - \frac{1}{2} \vec{t}^T \Sigma \vec{t}}$$

s.t.  $\Sigma = A A^T$

$\vec{Y} = B\vec{X}$  How is  $Y \sim$ ?  $\phi_Y(\vec{t}) = \phi_X(B^T \vec{t}) = e^{i\vec{t}^T B \vec{m} - \frac{1}{2} \vec{t}^T B \Sigma B^T \vec{t}} \Rightarrow Y \sim N_m(B \vec{m}, B \Sigma B^T)$   
 $B \in \mathbb{R}^{m \times n}$  with  $n \geq m$  necessary

Let's do another...  $\vec{z} \sim N_n(\vec{0}, I_n)$

Now  $X = B\vec{z} + \vec{c}$

$$\phi_X(\vec{x}) = e^{i\vec{x}^T \vec{z}} \phi_Z(B^T \vec{z}) = e^{i\vec{x}^T \vec{z} - \frac{1}{2} \vec{z}^T B B^T \vec{z}}$$

where  $B \in \mathbb{R}^{n \times n}$   
 $\uparrow$   
 dimension  $\neq n$   
 necessarily

but  $\Sigma$  must be full rank!

$$\Rightarrow X \sim N_n(\vec{c}, \Sigma)$$

$$\Sigma = B B^T$$

Given  $\vec{X}$  how do we simulate back to  $\vec{z}$ ?

$$X = AZ + \mu \Rightarrow X - \mu = AZ \Rightarrow A^{-1}(X - \mu) = Z$$

You can only get back if  $A$  is invertible!

$$Z = A^{-1}X - A^{-1}\mu$$

Why? Imagine  $A = \vec{1}$ ,  $\vec{c} = \vec{0}$

$$\vec{z}^T \vec{z} = \sum_{i=1}^n z_i^2 \sim \chi_n^2$$

$$X = \sum z_i \sim N(0, n\sigma^2)$$

$X \in \mathbb{R}^1 \Rightarrow$  we may or know what all  $n$   $z_i$ 's would be! Makes sense...

$$\Rightarrow (A^{-1}(X - \vec{\mu}))^T (A^{-1}(X - \vec{\mu})) = \vec{z}^T \vec{z} \sim \chi_n^2$$

$$(\vec{X}^T - \vec{\mu}^T) (A^{-1})^T A^{-1} (\vec{X} - \vec{\mu})$$

$$\underbrace{(A^{-1})^T A^{-1}}_{\Sigma^{-1}}$$

$$\Rightarrow (\vec{X} - \vec{\mu})^T \Sigma^{-1} (\vec{X} - \vec{\mu}) \sim \chi_n^2$$

Dist. of Mahalanobis distance squared  
 Standardizing and squaring! "Sphering"

$$X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2) \Rightarrow \vec{X} \sim N_n(n\vec{1}, \sigma^2 I_n)$$

$$\Sigma = \sigma^2 I = A A^T \Rightarrow A = \sigma I$$

$$\vec{X} = \sigma I \vec{z} + \vec{\mu} = \sigma \vec{z} + \vec{\mu} \quad \text{See as Gaussian case!}$$

See as before...

$$(\vec{X} - \vec{\mu})^T \frac{1}{\sigma^2} (\vec{X} - \vec{\mu}) \sim \chi_n^2$$

$$= \frac{1}{\sigma^2} (\vec{X} - \vec{\mu})^T (\vec{X} - \vec{\mu})$$

$$\frac{1}{\sigma^2} \sum (X_i - \mu)^2 \sim \chi_n^2$$