

Monday November 23rd 2020

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Lecture 20

$$\frac{\bar{X} - \mu}{\frac{s}{\sqrt{n}}} = \frac{\bar{X} - \mu}{\frac{1}{\sqrt{n}} \sqrt{s^2 \frac{n-1}{s^2}}} = \frac{\bar{X} - \mu}{\frac{s}{\sqrt{n}} \sqrt{\frac{n-1}{s^2}}} = \frac{\frac{\bar{X} - \mu}{\frac{s}{\sqrt{n}}}}{\sqrt{\frac{n-1}{s^2}}} \sim T_{n-1}$$

Due to Cochran's thm, if x_i 's are iid $N(\mu, \sigma^2) \Rightarrow \bar{X}$ and S^2 are independent and thus numerator and denominator here are independent

THE Multivariate Normal rv (MVN)

$$\vec{Z} = \begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix} \text{ s.t. } z_1, \dots, z_n \text{ iid } N(0,1), E[\vec{Z}] = \vec{0}_n, \text{Var}[\vec{Z}] = \mathbf{I}_n$$

$$\vec{Z} \sim f_{\vec{Z}}(\vec{z}) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi}} e^{-z_i^2/2} = \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} \vec{z}^T \vec{z}} = \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} \vec{z}^T \vec{z}} = N(\vec{0}, \mathbf{I})$$

$$\text{Let } \vec{\mu} \in \mathbb{R}^n, \vec{X} = \vec{Z} + \vec{\mu} = \begin{bmatrix} z_1 + \mu_1 \\ \vdots \\ z_n + \mu_n \end{bmatrix} \sim N(\vec{\mu}, \mathbf{I})$$

$$\text{Let } A = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 1 & 1 & 0 & \dots & 0 \\ 1 & 1 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & 1 & 1 & 1 & \dots & 1 \end{bmatrix}, \vec{X} = A\vec{Z} = \begin{bmatrix} z_1 \\ z_1 + z_2 \\ z_1 + z_2 + z_3 \\ \vdots \\ z_1 + z_2 + \dots + z_n \end{bmatrix} \sim N(\vec{0}, \mathbf{A})$$

$$\sigma_{1,2} = \text{Cov}[X_1, X_2] = \text{Cov}[z_1, z_1 + z_2] = \text{Cov}[z_1, z_1] + \text{Cov}[z_1, z_2] = 1 + 0 = 1$$

General rule to figure out variance-covariance matrix of a matrix A times rv vector \vec{X} ,

$$\begin{aligned}
 \text{Var}[\vec{A}\vec{x}] &= E[(\vec{A}\vec{x})(\vec{A}\vec{x})^T] - E[\vec{A}\vec{x}]E[\vec{A}\vec{x}]^T \\
 &= E[\vec{A}\vec{x}\vec{x}^T\vec{A}^T] - E[\vec{A}\vec{x}]E[\vec{A}\vec{x}]^T \\
 &= \vec{A}E[\vec{x}\vec{x}^T]\vec{A}^T - \vec{A}E[\vec{x}](\vec{A}E[\vec{x}])^T \\
 &= \vec{A}E[\vec{x}\vec{x}^T]\vec{A}^T - \vec{A}E[\vec{x}]E[\vec{x}]^T\vec{A}^T \\
 &= \vec{A}(E[\vec{x}\vec{x}^T] - E[\vec{x}]E[\vec{x}]^T)\vec{A}^T \\
 &= \vec{A}\Sigma\vec{A}^T
 \end{aligned}$$

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$$\vec{x} = \vec{A}\vec{z} + \vec{u} \sim N(\vec{u}, \vec{A}\vec{A}^T) = \int_{\vec{z}} \delta(\vec{z})$$

|| $\vec{z} = \vec{A}^{-1}(\vec{x} - \vec{u}) = h(\vec{x})$ In order for g to be 1:1, the matrix \vec{A} must be invertible.

$$\vec{z} = \vec{B}\vec{x} - \vec{B}\vec{u} \Rightarrow h(\vec{x}) = \vec{b}_1 \cdot \vec{x} - \vec{b}_1 \cdot \vec{u}$$

$$\int_{\vec{z}} \det \begin{bmatrix} \partial h_1 / \partial x_1 & \dots & \partial h_1 / \partial x_n \\ \vdots & & \vdots \\ \partial h_n / \partial x_1 & \dots & \partial h_n / \partial x_n \end{bmatrix} = \det \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \dots & b_{nn} \end{bmatrix} \det[\vec{A}^{-1}]$$

Note: $\vec{A}\vec{A}^{-1} = \vec{I} \Rightarrow \det[\vec{A}\vec{A}^{-1}] = 1 \Rightarrow \det[\vec{A}]\det[\vec{A}^{-1}] = 1$

$$\int_{\vec{z}} \delta(\vec{z}) = \int_{\vec{z}} \delta(h(\vec{x})) |\det \vec{J}| = \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} (A(\vec{x} - \vec{u}))^T (A^{-1}(\vec{x} - \vec{u}))} \frac{1}{|\det(\vec{A})|}$$

$$= \frac{1}{\sqrt{(2\pi)^n \det(A)^2}} e^{-\frac{1}{2} (\vec{x} - \vec{\mu})^T (A^T)^T A^{-1} (\vec{x} - \vec{\mu})} = \frac{1}{\sqrt{(2\pi)^n \det[\Sigma]^2}} \quad (3)$$

$$\det[\Sigma] = \det[AA^T] = \det(A^T) \det[A] = \det[A]^2$$

$$= \frac{1}{\sqrt{(2\pi)^n \det[\Sigma]}} e^{-\frac{1}{2} (\vec{x} - \vec{\mu})^T \Sigma^{-1} (\vec{x} - \vec{\mu})} = f_{\vec{x}}(\vec{x}) = N_n(\vec{\mu}, \Sigma)$$

Does this work if A is $m \times n$? The Answer is no, -- but we will solve that another way.

Multivariate chf

$$\phi_{\vec{x}}(\vec{t}) := E[e^{i\vec{t}^T \vec{x}}] = E[e^{i(t_1 x_1 + \dots + t_n x_n)}] = E\left[e^{i t_1 x_1} e^{i t_2 x_2} \dots e^{i t_n x_n}\right]$$

if x_1, \dots, x_n inde

$$= E[e^{i t_1 x_1}] E[e^{i t_2 x_2}] \dots E[e^{i t_n x_n}] = \phi_{x_1}(t_1) \phi_{x_2}(t_2) \dots \phi_{x_n}(t_n)$$

$$(16) \phi_{\vec{x}}(\vec{0}) = 1 \quad (17) = \text{Yes!}$$

$$(2) \vec{y} = A\vec{x} + \vec{b} \Rightarrow \phi_{\vec{y}}(\vec{t}) = E[e^{i\vec{t}^T (A\vec{x} + \vec{b})}] = E\left[e^{i\vec{t}^T A\vec{x}} e^{i\vec{t}^T \vec{b}}\right]$$

$$= e^{i\vec{t}^T \vec{b}} \phi_{\vec{x}}(\vec{t}') = e^{i\vec{t}^T \vec{b}} \phi_{\vec{x}}(A^T \vec{t})$$

Let's find the chf of the standard normal $\vec{z} \sim N_n(\vec{0}, I)$

$$\phi_{\vec{z}}(\vec{t}) = \prod_{i=1}^n \phi_{z_i}(t_i) = \prod_{i=1}^n e^{-t_i^2/2} = e^{-\frac{1}{2} \vec{t}^T \vec{t}}$$

$$\vec{x} = A\vec{z} + \vec{\mu} \sim N(\vec{\mu}, \Sigma), \quad \phi_{\vec{x}}(\vec{t}) \stackrel{(1)}{=} e^{i\vec{t}^T \vec{\mu}} \phi_{\vec{z}}(A^T \vec{t}) \stackrel{(2)}{=} e^{i\vec{t}^T \vec{\mu}} e^{-\frac{1}{2} (A^T \vec{t})^T A^T \vec{t}}$$

$$= e^{i\vec{t}^T \vec{\mu}} e^{-\frac{1}{2} \vec{t}^T \Sigma \vec{t}}$$

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$$\vec{x} \sim N(\vec{\mu}, \Sigma), \vec{y} = A\vec{x} + \vec{c}, \quad B \in \mathbb{R}^{m \times n}, \vec{c} \in \mathbb{R}^m$$

$$\begin{aligned} \text{Ch. (1)} & \stackrel{(B)}{=} \vec{y}^T \vec{c} \stackrel{(1)}{=} (B^T \vec{x})^T \vec{\mu} - \frac{1}{2} (\vec{y}^T \vec{c})^T \Sigma (B^T \vec{c}) \\ & \stackrel{(2)}{=} \vec{y}^T (B\vec{\mu} + \vec{c}) - \frac{1}{2} \vec{y}^T \Sigma B^T \vec{c} \stackrel{(3)}{=} \vec{y} \sim N_m(B\vec{\mu} + \vec{c}, B \Sigma B^T) \end{aligned}$$

$$\vec{x} \sim N_n(\vec{\mu}, \Sigma), (\vec{x} - \vec{\mu})^T \Sigma^{-1} (\vec{x} - \vec{\mu}) \sim ?$$

Assume: $AA^T = I$

$$\begin{aligned} (AA^T)^{-1} &= (A^T)^T A^{-1} \nearrow (\vec{x} - \vec{\mu})^T (A^T)^T A^{-1} (\vec{x} - \vec{\mu}) \\ &= (A^{-1} (\vec{x} - \vec{\mu}))^T (A^{-1} (\vec{x} - \vec{\mu})) \end{aligned}$$

$$\vec{z} \sim N_n(\vec{0}, I) \quad \Rightarrow \quad \vec{z}^T \vec{z} \sim \chi_n^2 \text{ Mahalanobis Distance (1932)}$$