$$\oint_{X} (\vec{t}) := \mathbb{E} \left[e^{i\vec{t}\cdot\vec{X}} \right]$$
Consider a vector rv X with dimension n. Consider the following operation:
$$\oint_{X} \left(\begin{vmatrix} \vec{t} & \vec{t} & \vec{t} & \vec{t} \\ \vec{t} & \vec{t} & \vec{t} \end{vmatrix} \right) := \mathbb{E} \left[e^{i\vec{t}\cdot\vec{X}} \right] = \mathbb{E} \left[e^{i\vec{t}\cdot\vec{X}} \right] = \oint_{X_{1}} (\vec{t}) \Rightarrow X_{1} \cdot \hat{f}_{X_{2}} \cdot \hat{f$$

The bottom line is we can use multivariate chf's to immediately get marginal distributions. X ~ N(ñ, S)

$$\overrightarrow{X} \sim \mathcal{N}(\overrightarrow{R}, \overrightarrow{\Sigma}) \Rightarrow \Phi_{\overrightarrow{X}} \begin{pmatrix} c \\ c \\ c \\ c \end{pmatrix} = e^{i \cdot (c \cdot n_1 - \frac{\epsilon}{2} \cdot (c \cdot n_2))} \xrightarrow{\beta_1 - \frac{\epsilon}{2} \cdot (c \cdot n_2)} \begin{bmatrix} c \\ c \\ c \\ c \end{bmatrix}$$

$$= e^{i \cdot (c \cdot n_1 - \frac{\epsilon}{2} \cdot (c \cdot n_2))} \begin{bmatrix} c \\ c \\ c \\ c \end{bmatrix}$$

$$= e^{i \cdot (c \cdot n_1 - \frac{\epsilon}{2} \cdot (c \cdot n_2))} \xrightarrow{\beta_1 - \frac{\epsilon}{2} \cdot (c \cdot n_2)} X_1 \sim \mathcal{N}(n_1, \sigma_1^c)$$

We now begin the unit on the "pure math" part of probability

Let X be a rv with non-negative support ie. Supp[X] >= 0. Let a be a constant > 0. Consider the function:

$$A(X) = A(X) \times A(X) \times A(X)$$

Let X be a rv with non-negative support ie. Supp
$$[X] >= 0$$
. Let a be a constant > 0 . Consider the function:

$$g(X) = g \prod_{X \ge g} \leq x \quad \forall x ? \quad \text{Consider two Cross:}$$

be a constant > 0. Consider the function:

$$g(X) = q \text{ } 1_{X \ge q}$$

$$I_{3} \text{ } 1_{X \ge q} \le X \text{ } X \text{ } X \text{ } Consider the function:}$$

$$X \le 1 = q \text{ } 1_{X \ge q} = 0 \text{ } C_{1} \text{ } \text{ } \text{ } C_{2} \text{ } C_{3} \text{ } C_{4} \text{ }$$

this rv has sygne (P.1. | ⇒ it's bermelli(P)

e.g X~ Exp(1)

Markov bread | Chebysha Bread | Cherroff Bound 0.5 | 0.73576 0.2 | 0.0635 | 0.09150 0.1 | 0.012 | 0.00123

The Markov inequality has tons of corollaries:

· let b=an > P(X = b) = A > P(X = an) = 1

 $P(h(X) \ge h(x)) \in \frac{E[h(X)]}{h(x)} \Rightarrow P(X \ge n) \in \frac{E[h(X)]}{h(x)}$

P(X Z N) = 4 => 1-Fx (x) = 4 => 1-Fx (x) = 4 = Fx'(x)

• Let X be any $x : x \Rightarrow |X|$ in non-negative $\Rightarrow \Re[X] = \frac{\mathbb{E}[X]}{a}$

 $\mathbb{P}(Y \geq \emptyset^2) \leq \frac{\mathbb{E}[Y]}{\mathbb{P}^2} \Rightarrow \mathbb{P}((Y - \mathbb{A})^2 \geq \mathbb{P}^2) \leq \frac{\mathbb{E}[(Y - \mathbb{A})^2]}{\mathbb{P}^2} \stackrel{\text{definion of }}{\longrightarrow} \mathbb{P}(Y^2)$

 $= P(X-M \ge A) + P(X \le M-R) \Longrightarrow \text{ second term is zero since } X$ is assued non-negative

· Let X be any rv and $Y=e^{\pm X} \Rightarrow Y$ is nonzy $\forall \pm$.

 $\stackrel{\text{if too}}{\Rightarrow} P(X \ge 1) \le e^{-t} M_{X}(t) \quad \forall_{t>0} \stackrel{\text{too}}{\Rightarrow} P(X \le 1) \le e^{-t} M_{X}(t)$

Since this works for all t and we are looking for the "best" i.e. the lowest upper bound, then just optimize over t:

 $\Rightarrow P(X \ge a) \le \min_{t>0} \frac{1}{3} e^{-ta} M_{X^{(k)}}$ AND $P(X \le a) \le \min_{t<0} \frac{1}{3} e^{-ta} M_{X^{(k)}}$

 $P(X \ge a) \le \min_{t \ge 0} \{ e^{-t1} M_X(t) \} = \min_{t \ge 0} \{ e^{-t4} \frac{1}{1-t} \} \text{ if } t < 1$

 $= \min_{\substack{\ell \in \{0,1\} \\ \ell \in \{0,1\} }} \left\{ \frac{e^{-t1}}{1-t} \right\} = \frac{e^{-\left(\frac{1}{1}\right) \cdot n}}{1-\left(1-\frac{1}{n}\right)} = \frac{e^{n+1}}{\frac{1}{n}} = \frac{ne}{e^n}$

 $h'(t) = \frac{(-t)(-t)e^{-t\eta} - (e^{-t\eta})(-1)}{(-t)^2} = \frac{1}{(-t)^2} = \frac{e^{-t\eta}(1(t-1)+1)}{(-t)^2} = e^{-t\eta}(1(t-1)+1)$

 $\Rightarrow (-1) = 0 \Rightarrow t_* = \frac{1}{9} = 1 - \frac{1}{9} \in (0,1)$

otherwise the mgf doesn't exist!!!!

⇒ P(Yzc) ≤ E(Y) ⇒ P(exxzc) ≤ E(exx) ← myf

 $\Rightarrow \Re(e^{t \times z} e^{t \cdot t}) \leq e^{-t \cdot t} M_{\chi}(t)$

 $\Rightarrow \Re(t \times z + n) \leq e^{-t \cdot n} M_{\chi}(s)$

= 1-p= fx (p) = Fx (r) = fp e.g. Med(X) = Zu

· Let h(s) be a monotonically increasing function (so it's 1:1).

P(X zn) = 1- Fx(1) = e-7

$$= e^{i t \cdot \mathbf{A}_1 - \frac{t}{2} \left(t \cdot \mathbf{a} \cdot \mathbf{a} \cdot \mathbf{c} \right)} \begin{bmatrix} \mathbf{a}_1 \\ \mathbf{a}_2 \\ \vdots \\ \mathbf{a}_n \end{bmatrix} = e^{i t \cdot \mathbf{A}_1 - \frac{t}{2} \cdot \mathbf{a}_1^{\mathbf{a}_2} / 2} \Longrightarrow X_1 \sim \mathcal{N}(\mathbf{A}_1, \mathbf{a}_2)$$
We now begin the unit on the "pure math" part of probability eginning with famous inequalities.

$$\overrightarrow{X} \sim \mathcal{N}(\overrightarrow{A}, \Sigma) \Rightarrow \Phi_{\overrightarrow{X}}\left(\begin{bmatrix} c \\ c \\ c \end{bmatrix}\right) = e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot) \overrightarrow{A} \cdot - \frac{1}{2}(\underbrace{k} \cdot \cdot \cdot \cdot \cdot \cdot) \cdot \Sigma} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot) \cdot A} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot) \cdot A} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot) \cdot A} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot) \cdot A} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot) \cdot A} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot) \cdot A} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot) \cdot A} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot) \cdot A} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot) \cdot A} \begin{bmatrix} c \\ c \\ c \\ c \end{bmatrix} \begin{bmatrix} c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot \cdot) \cdot A} \begin{bmatrix} c \\ c \\ c \\ c \end{bmatrix} \begin{bmatrix} c \\ c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot \cdot) \cdot A} \begin{bmatrix} c \\ c \\ c \\ c \end{bmatrix} \begin{bmatrix} c \\ c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot \cdot \cdot) \cdot A} \begin{bmatrix} c \\ c \\ c \\ c \end{bmatrix} \begin{bmatrix} c \\ c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot \cdot \cdot \cdot) \cdot A} \begin{bmatrix} c \\ c \\ c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot A)} \begin{bmatrix} c \\ c \\ c \\ c \\ c \\ c \end{bmatrix} \\
= e^{i(\underbrace{k} \cdot \cdot \cdot \cdot \cdot \cdot \cdot \cdot \cdot A)} \begin{bmatrix} c \\ c \\ c \\ c \\ c \\ c \\ c \end{bmatrix}$$

arginal distributions.
$$\overrightarrow{X} \sim \mathcal{N}(\overrightarrow{R}, \underline{S}) \Rightarrow \Phi_{\overrightarrow{X}}\begin{pmatrix} \underline{t} \\ \underline{t} \\ \underline{t} \end{pmatrix} = e^{i \underline{t} \cdot \underline{t} \cdot \underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} & \underline{t} \\ \underline{t} \cdot \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t} \cdot \underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} & \underline{t} & \underline{t} \end{pmatrix}}_{\underline{t}} \underbrace{\begin{pmatrix} \underline{t} \cdot \underline{t} & \underline{t} & \underline{t} & \underline{t} & \underline{t} \\ \underline{t} & \underline{t} & \underline{t} & \underline{t} & \underline{t}$$

the bottom line is we can use multivariate chf's to immediately geometric arginal distributions.

$$\overrightarrow{X} \sim \mathcal{N}(\overrightarrow{R}, \Sigma) \Rightarrow \phi_{\overrightarrow{X}}(\begin{bmatrix} \varepsilon \\ 0 \end{bmatrix}) = e^{i \underbrace{(\varepsilon \cdot \cdot \cdot \cdot \cdot)}_{\overrightarrow{R}} \cdot \frac{1}{2} \underbrace{(\varepsilon \cdot \cdot \cdot \cdot \cdot)}_{x}} \underbrace{\left\{ \underbrace{(\varepsilon \cdot \cdot \cdot \cdot \cdot)}_{x} \right\}_{x}^{x}}_{x}$$