

Monday November 23 2020

Lecture 20

$$\frac{\bar{X} - \mu}{\frac{S}{\sqrt{n}}} = \frac{\bar{X} - \mu}{\frac{1}{\sqrt{n}} \sqrt{S^2 \cdot \frac{n-1}{\sigma^2}}} = \frac{\bar{X} - \mu}{\frac{S}{\sqrt{n}} \sqrt{\frac{n-1}{\sigma^2}}} = \frac{\frac{\bar{X} - \mu}{\frac{S}{\sqrt{n}}}}{\sqrt{\frac{n-1}{\sigma^2}}} \sim T_{n-1}$$

Due to Cochran's thm we know \bar{X} and S^2 are independent.

"New Unit"

Multivariate Normal Distribution (MVN)

Standard MVN

$$Z_1, \dots, Z_n \text{ iid } N(0, 1) \quad \vec{Z} = \begin{bmatrix} Z_1 \\ \vdots \\ Z_n \end{bmatrix}, \quad E[\vec{Z}] = \vec{0}_n, \quad \text{Var}[\vec{Z}] = I_n$$

$$\vec{Z} \sim f_{\vec{Z}}(\vec{z}) = \prod_{i=1}^n f_{Z_i}(z_i) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi}} e^{-z_i^2/2} = \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} \sum z_i^2} = \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} \vec{z}^T \vec{z}} = N_n(\vec{0}, I)$$

$$\vec{X} = \vec{Z} + \vec{\mu}, \quad \vec{\mu} \in \mathbb{R}^n, \quad E[\vec{X}] = \vec{\mu}, \quad \text{Var}[\vec{X}] = I_n$$

$$\Rightarrow \vec{X} \sim N_n(\vec{\mu}, I)$$

$$\vec{X} = A \vec{Z} = \begin{bmatrix} Z_1 \\ Z_1 + Z_2 \\ Z_1 + Z_2 + Z_3 \\ \vdots \\ Z_1 + \dots + Z_n \end{bmatrix} \sim \begin{matrix} N(0, 1) \\ N(0, 2) \\ N(0, 3) \\ \vdots \\ N(0, n) \end{matrix}$$

but the components are dependent

$$A = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 1 & 1 & 0 & \dots & 0 \\ 1 & 1 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & 1 & 1 & \dots & 1 \end{bmatrix}$$

$$\text{Cov}[X_1, X_2] = \text{Cov}[Z_1, Z_1 + Z_2]$$

$$= \text{Cov}[Z_1, Z_1] + \text{Cov}[Z_1, Z_2]$$

$$= 1 \Rightarrow X_1, X_2 \text{ dependent}$$

Let's derive a general formula for the Variance-Covariance matrix of A (an $n \times n$ matrix of scalars) times a random vector X of dim n :

$$\text{Var}[A\vec{X}] := E[(A\vec{X})(A\vec{X})^T] = E[A\vec{X}\vec{X}^T A^T] = A E[\vec{X}\vec{X}^T] A^T$$

$$= A E[\mathbf{x} \mathbf{x}^T] A^T - A E[\mathbf{x}] (A E[\mathbf{x}])^T$$

$$E[\mathbf{x}]^T A^T$$

$$= A (E[\mathbf{x} \mathbf{x}^T] - E[\mathbf{x}] E[\mathbf{x}]^T) A^T = A \Sigma A^T$$

$$\Sigma = \text{Var}[\mathbf{x}]$$

(Homework)

$$\mathbf{\tilde{x}} = A \mathbf{\tilde{z}}, \text{Var}[\mathbf{\tilde{x}}] = A I_n A^T = A A^T \text{ Conjecture: } \mathbf{\tilde{x}} \sim N(\mathbf{0}, A A^T)$$

$$\mathbf{\tilde{x}} = A \mathbf{\tilde{z}} + \mathbf{\tilde{u}}, A \in \mathbb{R}^{n \times n}, \mathbf{\tilde{u}} \in \mathbb{R}^n, \mathbf{\tilde{x}} \sim f_{\mathbf{\tilde{x}}}[\mathbf{\tilde{x}}] = ?$$

" $g(\mathbf{\tilde{z}}), h(\mathbf{\tilde{x}}) = \mathbf{\tilde{z}}$ where g, h are inverses

$h(\mathbf{\tilde{x}}) = A^{-1}(\mathbf{\tilde{x}} - \mathbf{\tilde{u}}) \Rightarrow$ In order for the ^{inverse} function to exist... A has to be invertible.

$$= B \mathbf{\tilde{x}} - B \mathbf{\tilde{u}} = \begin{bmatrix} b_{11} \mathbf{\tilde{x}} - b_{11} \mathbf{\tilde{u}} \\ b_{21} \mathbf{\tilde{x}} - b_{21} \mathbf{\tilde{u}} \\ \vdots \\ b_{n1} \mathbf{\tilde{x}} - b_{n1} \mathbf{\tilde{u}} \end{bmatrix} = \begin{bmatrix} h_1 \\ h_2 \\ \vdots \\ h_n \end{bmatrix}$$

$$J_h = \det \begin{bmatrix} \partial h_1 / \partial x_1 & \dots & \partial h_1 / \partial x_n \\ \vdots & & \vdots \\ \partial h_n / \partial x_1 & \dots & \partial h_n / \partial x_n \end{bmatrix} = \det \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \dots & b_{nn} \end{bmatrix} = \det[A^{-1}] = \frac{1}{\det[A]}$$

$$f_{\mathbf{\tilde{x}}}(\mathbf{\tilde{x}}) = f_{\mathbf{\tilde{z}}}(h(\mathbf{\tilde{x}})) |J_h| = \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} (\mathbf{\tilde{x}} - \mathbf{\tilde{u}})^T (A^{-1})^T A^{-1} (\mathbf{\tilde{x}} - \mathbf{\tilde{u}})} \frac{1}{|\det[A]|}$$

$$D D^{-1} = I$$

$$\Rightarrow \det[D D^{-1}] = \det[I] = 1$$

$$\Rightarrow \det[D] \det[D^{-1}] = 1$$

$$D D^{-1} = I \Rightarrow (D D^{-1})^T = I^T = I \Rightarrow (D^{-1})^T D^T = I \Rightarrow (D^{-1})^T = (D^T)^{-1}$$

$$= \frac{1}{\sqrt{(2\pi)^n \det[A]^2}} e^{-\frac{1}{2} (\mathbf{\tilde{x}} - \mathbf{\tilde{u}})^T (A^T)^{-1} A^{-1} (\mathbf{\tilde{x}} - \mathbf{\tilde{u}})} \quad (A A^T)^{-1} = D^{-1} C^{-1}$$

$$\text{let } \Sigma = A A^T = \text{Var}[\mathbf{\tilde{x}}]$$

$$\det[\Sigma] = \det[A A^T]$$

$$= \det[A] \det[A^T]$$

you need Σ to be invertible.

$$= \frac{1}{\sqrt{(2\pi)^n \det[\Sigma]}} e^{-\frac{1}{2} (\mathbf{\tilde{x}} - \mathbf{\tilde{u}})^T \Sigma^{-1} (\mathbf{\tilde{x}} - \mathbf{\tilde{u}})} = N_n(\mathbf{\tilde{u}}, \Sigma)$$

A little bit of multivariate characteristic functions:

$$\phi_{\vec{x}}(\vec{t}) := E[e^{i\vec{t}^T \vec{x}}] = E[e^{i(t_1 x_1 + \dots + t_n x_n)}] = E[e^{it_1 x_1} \dots e^{it_n x_n}]$$

if x_1, \dots, x_n indep

$$\downarrow \\ = E[e^{it_1 x_1}] \dots E[e^{it_n x_n}] = \phi_{x_1}(t_1) \phi_{x_2}(t_2) \dots \phi_{x_n}(t_n)$$

P₀ $\phi_{\vec{x}}(\vec{0}) = E[e^{i\vec{0}^T \vec{x}}] = 1$

P₁ If two chf's are equal \Rightarrow the two RV's are equal in distribution

P₂ $\vec{y} = A\vec{x} + \vec{b}$, $A \in \mathbb{R}^{m \times n}$, $\vec{b} \in \mathbb{R}^m$, \vec{x} is dim n . $\Rightarrow \vec{y}$ is dim m

$$\begin{aligned} \phi_{\vec{y}}(\vec{t}) &:= E[e^{i\vec{t}^T (A\vec{x} + \vec{b})}] = E[e^{i\vec{t}^T A \vec{x}} e^{i\vec{t}^T \vec{b}}] = e^{i\vec{t}^T \vec{b}} E[e^{i(\vec{t}^T A) \vec{x}}] \\ &= e^{i\vec{t}^T \vec{b}} \phi_{\vec{x}}(A^T \vec{t}) \end{aligned}$$

Let's derive the chf of the standard MVN

$$\phi_{\vec{z}}(\vec{t}) = \prod_{i=1}^n \phi_{z_i}(t_i) = \prod_{i=1}^n e^{-t_i^2/2} = e^{-\frac{1}{2} \sum t_i^2} = e^{-\frac{1}{2} \vec{t}^T \vec{t}}$$

Let's derive the chf of the general MVN $\vec{x} = A\vec{z} + \vec{\mu} \sim N(\vec{\mu}, AA^T)$

$$\begin{aligned} \phi_{\vec{x}}(\vec{t}) &\stackrel{P_2}{=} e^{i\vec{t}^T \vec{\mu}} \phi_{\vec{z}}(A^T \vec{t}) = e^{i\vec{t}^T \vec{\mu}} e^{-\frac{1}{2} (A^T \vec{t})^T A^T \vec{t}} \\ &= e^{i\vec{t}^T \vec{\mu} - \frac{1}{2} \vec{t}^T A A^T \vec{t}} \end{aligned}$$

$\vec{y} = B\vec{x} + \vec{c} \sim ?$ $B \in \mathbb{R}^{m \times n}$, $\vec{c} \in \mathbb{R}^m$

$$\begin{aligned} \phi_{\vec{y}}(\vec{t}) &\stackrel{P_2}{=} e^{i\vec{t}^T \vec{c}} \phi_{\vec{x}}(B^T \vec{t}) = e^{i\vec{t}^T \vec{c}} e^{i(\vec{t}^T B)^T \vec{\mu} - \frac{1}{2} (\vec{t}^T B)^T A A^T (B^T \vec{t})} \\ &= e^{i\vec{t}^T (\vec{c} + B\vec{\mu}) - \frac{1}{2} \vec{t}^T B A A^T B^T \vec{t}} \stackrel{P_1}{\Rightarrow} \vec{y} \sim N(B\vec{\mu} + \vec{c}, B A A^T B^T) \end{aligned}$$

if $B A A^T B^T$ is invertible

Let $\vec{X} \sim N_n(\vec{\mu}, \Sigma)$. Consider $(\vec{X} - \vec{\mu})^T \Sigma^{-1} (\vec{X} - \vec{\mu}) \sim ?$

Recall: $\vec{Z} = A^{-1}(\vec{X} - \vec{\mu})$

$$\begin{aligned} &= (\vec{X} - \vec{\mu})^T (A^{-1})^T A^{-1} (\vec{X} - \vec{\mu}) \\ &= (A^{-1}(\vec{X} - \vec{\mu}))^T A^{-1} (\vec{X} - \vec{\mu}) \\ &= \vec{Z}^T \vec{Z} \sim \chi_n^2 \end{aligned}$$

$$\Sigma^{-1} = (A A^T)^{-1} = (A^T)^{-1} A^{-1} = (A^{-1})^T A^{-1}$$

P.C. Mahalanobis discovered this in 1926. He was India's founding father of statistics and founded the Indian Institute of Statistics.

This is kind of like distance in \mathbb{R}^n adjusted for all the dependencies among the dimensions like a multivariate "z-score".

In one dimension $(x - \mu) (\sigma^2)^{-1} (x - \mu) = \frac{(x - \mu)^2}{\sigma^2} = \left(\frac{x - \mu}{\sigma}\right)^2 = z^2$