Lecture 20
$$\frac{\overline{X} - M}{\frac{S}{\sqrt{n}}} = \frac{\overline{X} - M}{\frac{1}{\sqrt{n}} \sqrt{S^{2} \frac{\partial^{2}}{n-1} \cdot \frac{n-1}{\partial^{2}}}} = \frac{\overline{X} - M}{\frac{\partial}{\sqrt{n}} \sqrt{\frac{n-1}{\partial^{2}} S^{2}}} = \frac{\overline{X} - M}{\frac{\partial}{\sqrt{n}}} = \frac{\overline{X} - M}{\frac{\partial}{\sqrt{n}} \sqrt{\frac{n-1}{\partial^{2}} S^{2}}} = \frac{\overline{$$

Tn −1 Due to cochran's thin, we know xbar
 and s² are independent:

Multivariate Normal Distribution (MVN) $Z_{1}, \dots, Z_{n} \stackrel{\text{iid}}{\rightleftharpoons} NCO_{1}, \overline{Z} = \begin{bmatrix} z_{1} \\ z_{n} \end{bmatrix}, \overline{E}[\overline{Z}] = \overline{O}_{n}, \overline{Y} \text{ ar}[\overline{Z}] = \overline{Z}_{n}, \overline{Z}_{n} = \overline{Z}_{n}$ $\overline{Z} \sim \overline{J}_{\overline{z}}(\overline{z}) = \pi_{i=1}^{n} \underline{J}_{z}(z_{i}) = \pi_{i=1}^{n} \frac{1}{|\overline{Z}|} e^{-\overline{Z}_{n}^{*}/Z} = \frac{1}{(2\pi)^{n}} e^{-\frac{1}{2}\overline{Z}^{*}Z} = N_{n}(\overline{O}_{1}, \overline{z})$

 $\overrightarrow{X} = \overrightarrow{Z} + \overrightarrow{\omega}_1 \ \overrightarrow{\omega} \in \mathbb{R}^N, \ \overrightarrow{E}[\overrightarrow{X}] = \overrightarrow{\mathcal{M}}_1 \ \text{Var} \ \overrightarrow{[X]} = \overrightarrow{I}_n \implies \overrightarrow{X} \land N_N \ \overrightarrow{(\mathcal{M}_1 I)}$ $\overrightarrow{X} = \overrightarrow{AZ} = \begin{bmatrix} Z_1 \\ Z_1 + Z_1 \\ Z_1 + \cdots + Z_n \end{bmatrix} \xrightarrow{\sim} \underset{N \downarrow \mathcal{O}(1)}{\overset{N(\mathcal{O}(1))}{\sim}} \quad \text{but the component are dependent}$ $\stackrel{\text{e.g. } CNV \ [X_1, X_2] = CDV \ [Z_1, Z_1 + Z_2]}{= CDV \ [Z_1, Z_1] + CDV \ [Z_1, Z_2] = |Z_2|} = \underset{N_1 \downarrow X_2}{\overset{N_2 \downarrow 0}{\sim}} \quad \underset{N_2 \downarrow 0}{\overset{N_2 \downarrow 0}{\sim}}$

Letts derive a general formula for the variance - covariance matrix of A

(on nxn matytx of scalors) and non nc noise to the noise of the noise

 $\vec{X} = A\vec{z}$, $Var[\vec{Y}] = AI_nA^T = AA^T$ Conserture: $\vec{X} \sim N$ (\vec{o} , AA^T) $\vec{X} = A\vec{z} + \vec{x}$, $A \in \mathbb{R}^{n \times n}$. $\vec{X} \in \mathbb{R}^n$, $\vec{X} \sim \vec{S}_{\vec{x}}$ (\vec{x}) =? $\vec{y}_{(\vec{z})}$, $h(\vec{x}) = \vec{z}$ where hopefully g_1h are inverses

$$\overrightarrow{Z} = h(\overrightarrow{X}) = A^{-1}(\overrightarrow{X} - \overrightarrow{M}) \Rightarrow \text{ in order for the inverse to exist.}$$

$$= B\overrightarrow{X} - B\overrightarrow{M} = \begin{bmatrix} \overrightarrow{b} \cdot \overrightarrow{X} - \overrightarrow{b} \cdot \overrightarrow{M} \end{bmatrix} = h_1$$

$$= B\overrightarrow{X} - B\overrightarrow{M} = \begin{bmatrix} \overrightarrow{b} \cdot \overrightarrow{X} - \overrightarrow{b} \cdot \overrightarrow{M} \end{bmatrix} = h_1$$

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 $= \frac{1}{\sqrt{(2\pi)^n \operatorname{le+CAJ}^2}} e^{-\frac{1}{2}(\frac{1}{2}-\frac{1}{2})^{-1}(A^{-1})^{-1}A^{-1}(\bar{X}-\bar{X})^{-1}} \frac{1}{|\operatorname{det}(A)|}$

 $= \frac{1}{\sqrt{(2\pi)^{n} \det [A]^{2}}} e^{-\frac{1}{2}(\overline{X}-\overline{M})^{T}(A^{T})^{-1}A^{-1}}(\overline{X}-\overline{M})$ $= \frac{1}{\sqrt{(2\pi)^{n} \det [E]}} e^{-\frac{1}{2}(\overline{X}-\overline{M})^{T}} z^{-1}(\overline{X}-\overline{M})$ $= \frac{1}{\sqrt{(2\pi)^{n} \det [E]}} e^{-\frac{1}{2}(\overline{X}-\overline{M})^{T}} z^{-1}(\overline{X}-\overline{M})$ You need E to we invertible

A little bit of multivartate characteristic functions: $\phi_{\overline{x}}(\overline{t}) := \mathbb{E}\left[e^{\lambda \overline{t}^T \overline{x}}\right] : \mathbb{E}\left[e^{\lambda (t_1 X_1 + \cdots + t_n X_n)}\right] = \mathbb{E}\left[e^{\lambda t_1 X_1} \cdot \dots \cdot e^{\lambda t_n X_n}\right]$ $\stackrel{\text{ind}}{=} \mathbb{E}\left[e^{\lambda t_1 X_n}\right] \cdot \dots \cdot \mathbb{E}\left[e^{\lambda t_n X_n}\right] = \phi_{X_1}(t_1) \phi_{X_2}(t_2) \cdots \phi_{X_n}(t_n)$

- (B) \$\frac{1}{x} (0) = E[e^{i\overline{\pi} \chi_x}] = 1
- (P.) If two chf's are equal => the two rv's are equal in dist.
- (B) Y= AX+b, AERMY BERM, X indim n. =) Y is din n

φ_η (t)= E [eit LAX+1)]= E [eit AX eit]= eit E[ei(AT) ττ]
= eit β_η (AT)

 $\overrightarrow{Y} = \overrightarrow{B}\overrightarrow{X} + \overrightarrow{C} \quad \mathcal{N}? \quad \overrightarrow{B} \in \mathbb{R}^{M \times M}, \quad \overrightarrow{C} \in \mathbb{R}$ $\phi_{\overrightarrow{V}}(\overrightarrow{E}) = e^{\lambda \overrightarrow{E} + \overrightarrow{C}} \phi_{\overrightarrow{X}}(B^{T} \overrightarrow{E}) = e^{\lambda \overrightarrow{E} + \overrightarrow{C}} e^{\lambda (B^{T} \overrightarrow{E})^{T} \overrightarrow{M}} - \frac{1}{2} (B^{T} \overrightarrow{E})^{T} \overrightarrow{M} - \frac{1}{2} (B^{$

* In one dimension $(x-u)(B^2)^{-1}(x-u) = \frac{(x-u)^2}{B^2}$ $= \left(\frac{x-u}{B}\right)^2$