\vec{X} continuous rv $P(\vec{X} \in A) = \int \int \int_{\vec{X}} (\vec{x}) dx_1 ... dx_k$

let T= X,+X2~ f,(+) =?

note filt) = F'(t) CDF method

usually it is difficult to find the CDF of continuous ru's, so this is not the usual method. The usual A:=[[x',]; x_ < \cdot \ formula (which we will now derive)

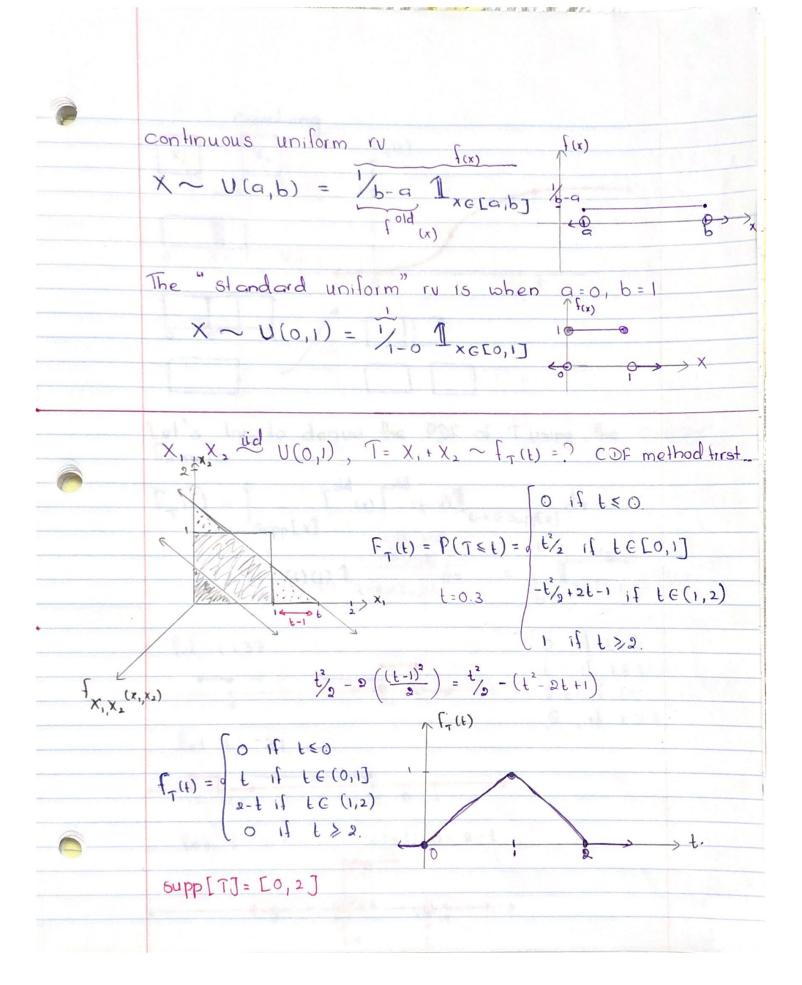
 $F_{T}(t) = P(T \leq t) = P(\overline{X} \in A_t) = \iint f_{X_1,X_2}(x_1,x_2) dx_1 dx_2$ $\int_{X_{1},X_{2}} f_{X_{1},X_{2}}(x, x_{2}) dx_{2} dx, = \int_{D} \int_{-\infty}^{L} f_{X_{1},X_{2}}(x, v-x) dv dx$

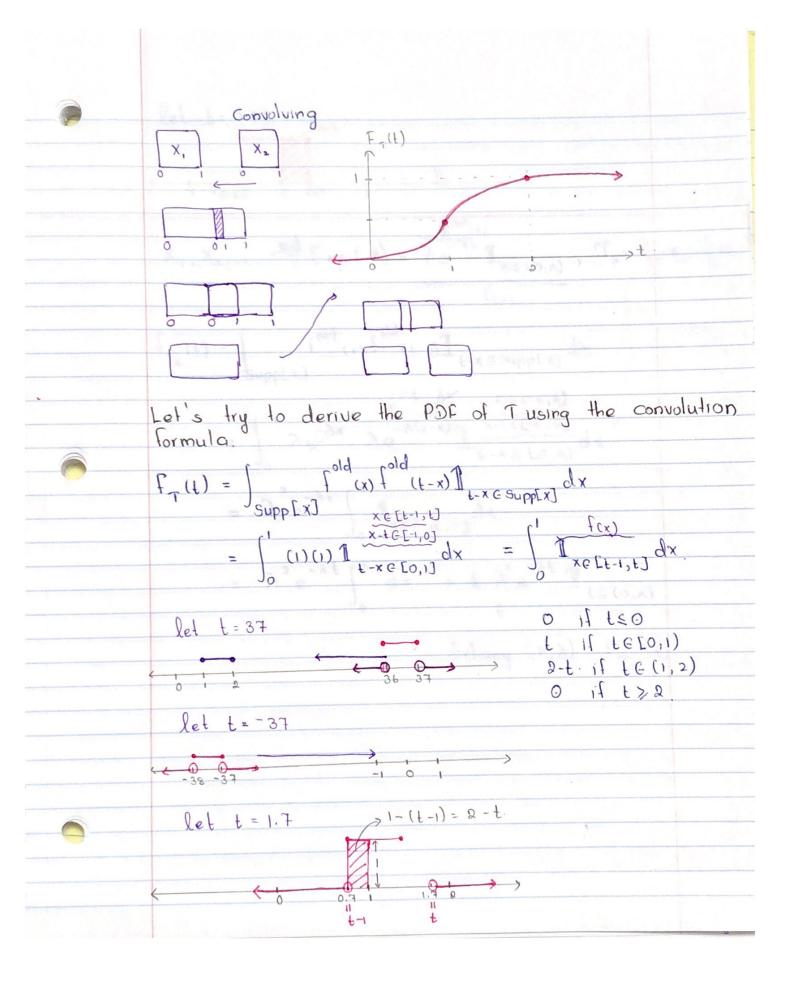
 $\left(\int_{\mathbb{R}}^{\mathcal{B}} t^{x',x'}(x'\wedge -x)qx\right)q\wedge$ let $X_1 = X$ $X_2 = V - X \Rightarrow V = X_2 + X \Rightarrow dx_2 = dv$ X2 = - 0 => V= - K $X_2 = t - x => V = t$.

 $= \int_{\mathbb{R}} f_{x_2, x_2}(x, t-x) dx = f_{T}(t)$

= fx(x) * fx(x) formula.

Leibnitz's Rule for derivatives of integral functions. $\frac{d}{dx} \left[\int_{-\infty}^{b(x)} g(x,y) dy \right] = g(x,b(x))b'(x) + g(x,a(x))a'(x) + \frac{1}{2}$ (b(x) %x[g(x,y)]dy. If the derivative is with respect to a third variable, t, then: $\frac{d}{dt} \left[\int_{a(t)}^{b(t)} g(x,y) dy \right] = g(x,b(t)) b'(t) + g(x,o(t)) a'(t) + \frac{b(t)}{a(t)} \left[\int_{a(t)}^{b(t)} g(x,y) dy \right]$ If one of the bounds in constant then $\frac{d}{dt} \left[\int_{c}^{b(t)} g(x,y)dy \right] = g(x,b(t))b'(t) + g(x,c) \frac{d}{dt} [c]$ $f_{\tau}(t) = ddt \left[\int_{-\infty}^{t} \left(\int_{\mathbb{R}} f_{x_1, x_2}(x, v-x) dx \right) dv \right]$ General $= \int_{\mathbb{R}} f_{x_1,x_2}(x, t-x) dv \text{ formula}$ $= \int_{\mathbb{R}} f_{x_1,x_2}(x, t-x) dv \text{ formula}$ $=\int_{\Omega} f(x) f(t-x) dx = \int_{Supp[X]} fold(x) f(t-x) \frac{1}{t-x} esupp[X,J] dx$





let t= 0.37 X_1, X_2, \dots and $E \times p(\lambda) = \lambda e^{-\lambda x} \mathbf{1}_{x \in [0, n]}$ f(x) tG (0, x) = Erlang (2, 1) = f (t)