

Lecture 20

Math 621

11-23-2020

(1)

$$\begin{aligned} \frac{\bar{X} - \mu}{\frac{s}{\sqrt{n}}} &= \frac{\bar{X} - \mu}{\frac{1}{\sqrt{n}} \sqrt{s^2 \cdot \frac{n-1}{\sigma^2}}} = \frac{\bar{X} - \mu}{\frac{\sigma}{\sqrt{n}} \sqrt{\frac{n-1}{\sigma^2} s^2}} \\ &= \frac{\bar{X} - \mu}{\frac{\sigma}{\sqrt{n}} \sqrt{\frac{n-1}{\sigma^2} s^2}} = \frac{\bar{X} - \mu}{\frac{\sigma}{\sqrt{n}}} \left\{ \frac{s^2}{\sigma^2} \right\}^{\frac{1}{2}} \chi_{n-1}^2 \end{aligned}$$

Due to Cochran's thm, $\rightarrow \sim T_{n-1}$
 we know \bar{X} and s^2 are independent

Multivariate Normal Distribution (MVN)

$z_1, \dots, z_n \sim N(0, 1)$, $\vec{z} = \begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix}$, $E[\vec{z}] = \vec{0}_n$

$$\vec{z} \sim f_{\vec{z}}(\vec{z}) = \prod_{i=1}^n f_{z_i}(z_i) \quad \text{Var}[\vec{z}] = I_n \quad \text{identity matrix}$$

$$= \prod_{i=1}^n \frac{1}{\sqrt{2\pi}} e^{-z_i^2/2} = \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} \sum z_i^2}$$

$$= \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} \vec{z}^T \vec{z}} = N_n(\vec{0}, I)$$

= Standard MVN.

$$\vec{X} = \vec{z} + \vec{\mu}, \quad \vec{\mu} \in \mathbb{R}^n, \quad E[\vec{X}] = \vec{\mu},$$

$$\text{Var}[\vec{X}] = I_n$$

$$\Rightarrow \vec{X} \sim N_n(\vec{\mu}, I)$$

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$$\vec{x} = A\vec{z} \quad A = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 1 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & 1 & 1 & \dots & 1 \end{bmatrix} \quad \begin{bmatrix} z_1 \\ z_1 + z_2 \\ \vdots \\ z_1 + \dots + z_n \end{bmatrix} \sim N(0, n)$$

but the components are dependent.

$$\begin{aligned} \text{e.g. } \text{Cov}[x_1, x_2] &= \text{Cov}[z_1, z_1 + z_2] \\ &= \underbrace{\text{Cov}[z_1, z_1]}_1 + \underbrace{\text{Cov}[z_1, z_2]}_0 \end{aligned}$$

let's derive a general formula for the Variance-Covariance matrix of A

(an $n \times n$ matrix of scalars) times a random vector X of dim n :

$$\begin{aligned} \text{Var}[A\vec{x}] &= E[(A\vec{x})(A\vec{x})^T] - E[A\vec{x}]E[A\vec{x}]^T \\ &= A E[\vec{x}\vec{x}^T] A^T - A E[\vec{x}] (A E[\vec{x}])^T \\ &= A (E[\vec{x}\vec{x}^T] - E[\vec{x}]E[\vec{x}]^T) A^T \\ &= A \underbrace{\Sigma}_{\text{sigma}} A^T \end{aligned}$$

$$\vec{x} = A\vec{z}, \quad \text{Var}[\vec{x}] = A I_n A^T = A A^T$$

Conjecture: $\vec{x} \sim N(\vec{0}, A A^T)$

$$\vec{x} = A\vec{z} + \vec{\mu}, \quad A \in \mathbb{R}^{n \times n}, \quad \vec{\mu} \in \mathbb{R}^n;$$

$$\vec{x} \sim f_{\vec{x}}(\vec{x}) = ?$$

$g(\vec{z}), h(\vec{x}) = \vec{z}$, where g, h are inverses

$h(\vec{x}) = A^{-1}(\vec{x} - \vec{\mu}) \Rightarrow$ in order for the inverse to exist... A has to be invertible

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$$\text{Let } A^{-1} = B$$

$$\text{So, } h(\vec{x}) = B(\vec{x} - \vec{\mu}) = B\vec{x} - B\vec{\mu}$$

$$= \begin{bmatrix} \vec{b}_1 \vec{x} - \vec{b}_1 \vec{\mu} \\ \vec{b}_2 \vec{x} - \vec{b}_2 \vec{\mu} \\ \vdots \\ \vec{b}_n \vec{x} - \vec{b}_n \vec{\mu} \end{bmatrix} = \begin{matrix} h_1 \\ h_2 \\ \vdots \\ h_n \end{matrix}$$

(Jacobian)

$$J_n = \det \begin{bmatrix} \partial h_1 / \partial x_1 & \dots & \partial h_1 / \partial x_n \\ \vdots & & \vdots \\ \partial h_n / \partial x_1 & \dots & \partial h_n / \partial x_n \end{bmatrix}$$

$$= \det \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \dots & b_{nn} \end{bmatrix} = \det[A^{-1}] = \frac{1}{\det[A]}$$

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$$DD^{-1} = I$$

$$\Rightarrow \det[DD^{-1}] = \det[I] = 1$$

$$\Rightarrow \det[D] \det[D^{-1}] = 1$$

$$f_{\vec{x}}(\vec{x}) = f_{\vec{z}}(h(\vec{x})) |J_n|$$

$$= \frac{1}{\det[A]} \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} (A^{-1}(\vec{x} - \vec{\mu}))^T A^{-1}(\vec{x} - \vec{\mu})}$$

Math 231

$$DD^{-1} = I \Rightarrow (DD^{-1})^T = I^T = I$$

$$\Rightarrow (D^{-1})^T D^T = I \Rightarrow (D^{-1})^T = (D^T)^{-1}$$

$$(CD)^{-1} = D^{-1}C^{-1}$$

$$(\vec{x} - \vec{\mu})^T (A^{-1})^T A^{-1}(\vec{x} - \vec{\mu})$$

$$= \frac{1}{\sqrt{(2\pi)^n \det[A]^2}} e^{-\frac{1}{2} (\vec{x} - \vec{\mu})^T (A^T)^{-1} A^{-1}(\vec{x} - \vec{\mu})}$$

$$(AA^T)^{-1}$$

$$\text{Let } \Sigma = AA^T = \text{Var}[\vec{x}]$$

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$$\det[\Sigma] = \det[A A^T] = \det[A] \det[A^T] \\ = \det[A] \det[A] = \det[A]^2$$

$$\text{So, } \frac{1}{\sqrt{(2\pi)^n \det[\Sigma]}} e^{-\frac{1}{2}(\vec{x}-\vec{\mu})^T \Sigma^{-1}(\vec{x}-\vec{\mu})}$$

$= N_n(\vec{\mu}, \Sigma)$, you need Σ sigma to be invertible

A little bit of multivariate characteristic functions:

$$\phi_{\vec{X}}(\vec{t}) = E[e^{i\vec{t}^T \vec{X}}] = E[e^{i(t_1 x_1 + \dots + t_n x_n)}]$$

$$= E[e^{it_1 x_1} \cdot \dots \cdot e^{it_n x_n}]$$

if x_1, \dots, x_n independent

$$= E[e^{it_1 x_1}] \cdot \dots \cdot E[e^{it_n x_n}]$$

$$= \phi_{x_1}(t_1) \phi_{x_2}(t_2) \cdot \dots \cdot \phi_{x_n}(t_n)$$

$$(P_0) \phi_{\vec{X}}(\vec{0}) = E[e^{i\vec{0}^T \vec{X}}] = 1$$

(P1) If two chf's are equal then the two rv's are equal in distribution

$$(P2) \vec{Y} = A\vec{X} + \vec{b}, \quad A \in \mathbb{R}^{m \times n}, \quad \vec{b} \in \mathbb{R}^m,$$

$\Rightarrow \vec{Y}$ in \vec{X} in dimension n
 $\Rightarrow \vec{Y}$ in dim m .

$$\phi_{\vec{Y}}(\vec{t}) = E[e^{i\vec{t}^T (A\vec{X} + \vec{b})}]$$

$$= E[e^{i\vec{t}^T A\vec{X}} e^{i\vec{t}^T \vec{b}}] \\ = E[e^{i(\vec{A}^T \vec{t})^T \vec{X}}] e^{i\vec{t}^T \vec{b}}$$

$$= e^{i\vec{f}^T \vec{b}} \int [e^{i(A^T \vec{f})^T \vec{x}}] \\ = e^{i\vec{f}^T \vec{b}} \phi_{\vec{x}}(A^T \vec{f})$$

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let's derive the chf of the standard MVN:

$$\phi_{\vec{z}}(\vec{f}) = \prod_{i=1}^n \phi_{z_i}(f_i) = \prod_{i=1}^n e^{-f_i^2/2} \\ = e^{-\frac{1}{2} \sum f_i^2} = e^{-\frac{1}{2} \vec{f}^T \vec{f}}$$

let's derive the chf of the general MVN:

$$\vec{X} = A\vec{z} + \vec{\mu} \sim N(\vec{\mu}, AA^T)$$

$$\phi_{\vec{X}}(\vec{f}) \stackrel{(P_2)}{=} e^{i\vec{f}^T \vec{\mu}} \phi_{\vec{z}}(A^T \vec{f}) \\ = e^{i\vec{f}^T \vec{\mu}} e^{-\frac{1}{2} (A^T \vec{f})^T A^T \vec{f}} \\ = e^{i\vec{f}^T \vec{\mu} - \frac{1}{2} \underbrace{\vec{f}^T A A^T \vec{f}}_{\Sigma}} \\ = e^{i\vec{f}^T \vec{\mu} - \frac{1}{2} \vec{f}^T \Sigma \vec{f}}$$

$$\vec{Y} = B\vec{X} + \vec{c} \sim ? \quad B \in \mathbb{R}^{m \times n}, \vec{c} \in \mathbb{R}^m$$

$$\phi_{\vec{Y}}(\vec{f}) \stackrel{(P_2)}{=} e^{i\vec{f}^T \vec{c}} \phi_{\vec{X}}(B^T \vec{f}) \\ = e^{i\vec{f}^T \vec{c}} e^{i \underbrace{(B^T \vec{f})^T \vec{\mu}}_{\vec{f}^T B \vec{\mu}} - \frac{1}{2} \underbrace{(B^T \vec{f})^T \Sigma (B^T \vec{f})}_{\vec{f}^T B \Sigma B^T \vec{f}}}$$

$$= e^{i\vec{f}^T (\vec{c} + B\vec{\mu}) - \frac{1}{2} \vec{f}^T B \Sigma B^T \vec{f}}$$

$$\stackrel{(P_1)}{\Rightarrow} \vec{Y} \sim N_m(B\vec{\mu} + \vec{c}, B\Sigma B^T)$$

(if $B\Sigma B^T$ is invertible)

let $\vec{X} \sim N_n(\vec{\mu}, \Sigma)$.

Consider $(\vec{X} - \vec{\mu})^T \Sigma^{-1} (\vec{X} - \vec{\mu}) \sim ?$
called Mahalanobis Distance

⑥

Recall: $\vec{z} = A^{-1}(\vec{x} - \vec{\mu})$

$$\Sigma^{-1} = (A A^T)^{-1} = (A^T)^{-1} A^{-1} = (A^{-1})^T A^{-1}$$

$$\begin{aligned} \text{So, } &= (\vec{x} - \vec{\mu})^T (A^{-1})^T A^{-1} (\vec{x} - \vec{\mu}) \\ &= (A^{-1} (\vec{x} - \vec{\mu}))^T A^{-1} (\vec{x} - \vec{\mu}) \\ &= \vec{z}^T \vec{z} \sim \chi_n^2 \end{aligned}$$

PC Mahalanobis discovered this in 1936. He was India's founding father of statistics and founded the Indian Institute of Statistics.

This is kind of like distance in \mathbb{R}^n adjusted for all the dependencies among the dimensions like a multivariate "z-Score".

In One direction,

$$\begin{aligned} (\vec{x} - \vec{\mu}) (\sigma^2)^{-1} (\vec{x} - \vec{\mu}) &= \frac{(\vec{x} - \vec{\mu})^2}{\sigma^2} = \left(\frac{\vec{x} - \vec{\mu}}{\sigma} \right)^2 \\ &= z^2 \end{aligned}$$