

Chapter 3. Algor. Design Techniques

We discuss 3 techniques :

- Divide-and-Conquer
- Dynamic Programming
- Greedy Method

3.1. The Divide-and-Conquer Technique.

We illustrate this technique through a few examples :

- Multiplying long integers
- Finding minimum/maximum
- Faster integer multiplication

Basic Idea:

- Divide probl. into smaller subprobl.
- Recursively solve subproblems
- Combine solutions of subprobl. into a solution of larger probl.

Multiplying Long Integers

The problem is def. as follows.

Input. 2 n-bit integers X, Y .

Output. The product $X \cdot Y$.

Remark. School method takes $\Theta(n^2)$ steps.

Goal: An $O(n^{\lg 3})$ algor. based on divide-and-conquer.

Idea:

$$X = \boxed{A \quad B} = A \cdot 2^{\frac{n}{2}} + B$$

$$Y = \boxed{C \quad D} = C \cdot 2^{\frac{n}{2}} + D$$

Then:

$$X \cdot Y = A \cdot C \cdot 2^n + (A \cdot D + B \cdot C) 2^{\frac{n}{2}} + B \cdot D$$

Based on this, we have the recurrence:

$$T(1) = 1 \quad \text{and} \quad T(n) = 4T\left(\frac{n}{2}\right) + cn$$

which has solution: $T(n) = O(n^2)$

Q: Can we reduce 4 multiplications of $\frac{n}{2}$ -bit integers to 3?

Consider this: (Making use of $A \cdot C, B \cdot D$)

$$X \cdot Y = A \cdot C \cdot 2^n + \{(A-B) \cdot (D-C) + A \cdot C + B \cdot D\} \cdot 2^{\frac{n}{2}} + B \cdot D$$

→ We reduce 1 $n/2$ -bit integer multip. at the expense of 4 $n/2$ -bit integer additions.

The recurrence becomes :

$$T(1) = 1, \quad T(n) = 3T(n/2) + c.n$$

whose solution is :

$$T(n) = O(n^{\lg 3}) = O(n^{1.59})$$

Finding Maximum & Minimum of a Set.

A straightforward approach :

- Find max using $n-1$ comparisons
- Find min of remaining $n-1$ elements using $n-2$ comparisons

⇒ Total of $2n-3$ comparisons

The divide. and. conquer approach :

- Find max & min of $A[1..n/2], A[n/2+1, n]$
- Now find max of 2 max's
min of 2 min's

using 2 comparisons.

Thus : $T(2) = 1, T(n) = 2T(n/2) + 2$

Solution is : $T(n) = \frac{3}{2}n - 2$

Pf.

$$\begin{aligned}
 T(n) &= 2 + 2T(n/2) \\
 &= 2 + 2 \{ 2 + 2T(n/4) \} \\
 (n=2^k) \quad &= 2 + 4 + 8 + \dots + 2^{k-1} + 2^{k-1}T(2) \\
 &= \sum_{i=1}^{k-1} 2^i + 2^{k-1} \\
 &= 2 \left(\sum_{i=0}^{k-2} 2^i \right) + 2^{k-1} \\
 &= 2 \left(2^{k-1} - 1 \right) + 2^{k-1} \\
 &= 2^k + 2^{k-1} - 2 \\
 &= n + \frac{n}{2} - 2 \\
 &= \frac{3n}{2} - 2 \quad \square
 \end{aligned}$$

Fast Divide-and-Conquer Integer Multiplication

Observation. In previous divide-and-conquer integer multiplication we reduce 4 $\frac{n}{2}$ -bit int. mult. to 3 $\frac{n}{2}$ -bit int. mult. and achieve $O(n^{\log_2 3})$

Note: $a=3, b=2 \Rightarrow O(n^{\log_2 3})$.

Question. Can we get a faster alg. by splitting x, y into even smaller pieces?

Let's revisit previous algor.

$$X = \boxed{x_1 \quad x_2} = x_1 \cdot 2^{\frac{n}{2}} + x_2$$

$$Y = \boxed{y_1 \quad y_2} = y_1 \cdot 2^{\frac{n}{2}} + y_2$$

Setting $t = 2^{\frac{n}{2}}$ we rewrite

$$X(t) = x_1 \cdot t + x_2, \quad Y(t) = y_1 \cdot t + y_2$$

$\Rightarrow X(t), Y(t)$ are polynomials in t .

$$\Rightarrow Z(t) := X(t) \cdot Y(t)$$

$$\begin{aligned} &= \underbrace{x_1 y_1 \cdot t^2}_{a \cdot t^2} + \underbrace{(x_1 y_2 + x_2 y_1)t}_{b \cdot t} + \underbrace{x_2 y_2}_{c} \end{aligned}$$

$Z(t)$ is a polynomial in t of degree 2.

Note: a, b, c are coefficients of $Z(t)$

Question. Can we compute a, b, c fast?

Fact. For a polynomial of degree l , if we know its values at $l+1$ points, then its coefficients can be det. through interpolation using La Grange's formula.

Ex. Consider $Z(t) = X(t) \cdot Y(t)$ and the points $t = -1, 0, 1$. We have:

$$Z(t) = \sum_{i=-1}^1 \prod_{\substack{j=-1 \\ j \neq i}}^1 \frac{t-j}{i-j} \cdot Z(i)$$

$$= \boxed{\begin{aligned} & \frac{t}{-1} \cdot \frac{t-1}{-1-1} \cdot Z(-1) \\ & + \frac{t+1}{1} \cdot \frac{t-1}{-1} \cdot Z(0) \\ & + \frac{t+1}{2} \cdot \frac{t}{1} \cdot Z(1) \end{aligned}} = \boxed{\begin{aligned} & \frac{t^2-t}{2} Z(-1) \\ & + \frac{-t^2+1}{1} \cdot Z(0) \\ & + \frac{t^2+t}{2} Z(1) \end{aligned}}$$

$$\begin{aligned} & = \underbrace{\left(\frac{1}{2} Z(-1) - Z(0) + \frac{1}{2} Z(1) \right)}_a \cdot t^2 \\ & + \underbrace{\left(-\frac{1}{2} Z(-1) + \frac{1}{2} Z(1) \right)}_b \cdot t \\ & + \underbrace{Z(0)}_c \end{aligned}$$

Observation. Given $Z(0), Z(-1), Z(1)$ the coefficients a, b, c of $Z(t)$ can be computed via additions & subtractions.

Observation. If we split x, y into k pieces, then $X(t), Y(t)$ are of degree $k-1$ and $Z(t) = X(t) \cdot Y(t)$ is of degree $2k-2$.

Given fixed k , choose suitable small values for the $2k-1$ points t_1, \dots, t_{2k-1} :

(1) Evaluation: Compute $X(t), Y(t)$

on the $2k-1$ points t_1, \dots, t_{2k-1} .

(Since t_1, \dots, t_{2k-1} are fixed, theirs

powers t_i^j 's are fixed. Hence,

$X(t), Y(t)$ can be computed using simple add/sub. of $\frac{n}{k}$ -bit integers.)

(2) Point-wise Product. Compute $Z(t) =$

$X(t) \cdot Y(t)$ for $t = t_1, \dots, t_{2k-1}$.

(This req. $2k-1$ mult. of $\frac{n}{k}$ -bit int.)

(3) Interpolation. Using La Grange's

formula, compute the coefficients

$$\text{of } Z(t) \quad (= \sum_{j=0}^{2k-2} [\underbrace{\sum * Z(t_i)}_{\hookrightarrow \text{from Lagrange}}] t^j)$$

\hookrightarrow from Lagrange

Complexity of Step (1):

$$x(t) = x_{k-1} t^{k-1} + \dots + x_1 t + x_0$$

$$y(t) = y_{k-1} t^{k-1} + \dots + y_1 t + y_0$$

x_j, y_j are $\frac{n}{k}$ -bit integers, $0 \leq j \leq k-1$

t_i^j 's are fixed

$\Rightarrow x(t_i), y(t_i)$ can be evaluated in

$$O(k \cdot k \cdot \frac{n}{k} \underbrace{k \log k}_{\text{length of } t_i^j}) = O(n)$$

since k is fixed.

Step (2): Note that mult. of $\frac{n}{k} + O(k \log k)$ -bit integers is $T(\frac{n}{k}) + O(n)$, k is const.

Complexity of Step (3):

Recover z_{2k-2}, \dots, z_0 from

$z(t_1), \dots, z(t_{2k-1})$

based on La Grange's formula

For $j = 0, \dots, 2k-2$:

$$z_j = \sum_{i=1, \dots, 2k-1} z(t_i)$$

takes $O(k \cdot \frac{n}{k}) = O(n)$

(Note: addition of $\frac{n}{k} + O(k \log k)$ -bit integers can be done in $O(n)$ where k is const.)

Step (1):

$$1 \leq i \leq 2k-1, 0 \leq j \leq k-1$$

$x_j * t_i^j$ takes $O(\frac{n}{k} \cdot k \cdot \log k)$
 \downarrow $\frac{n}{k}$ bits \downarrow $k \log k$ bits
bit operations each

$$\Rightarrow O(k \cdot k \cdot \frac{n}{k} k \cdot \log k) = O(n)$$

to compute these terms

$$x(t_i) = \sum_{j=0}^{k-1} x_j t_i^j \text{ takes } O(k \cdot \frac{n}{k} \cdot k \cdot \log k) \\ = O(n)$$

$y(t_i)$ is similar

\Rightarrow Step (1) takes $O(n)$

Step (2):

$$x(t_i) * y(t_i) \text{ take } T\left(\frac{n}{k}\right) + O(n)$$

$(\frac{n}{k} + c)$ bits $(\frac{n}{k} + c)$ bit steps

Thus, the recurrence is:

$$T(n) = (2k-1) \cdot T\left(\frac{n}{k}\right) + O(n)$$

$$\Rightarrow T(n) = O(n^{\log_k(2k-1)}).$$

Note: $T(n) = O(n^{1+\epsilon})$ when k is sufficiently large, where $\epsilon > 0$

(Remark: The integers in (2) may be slightly longer than $\frac{n}{k}$ bits. However, operations can be done on $\frac{n}{k}$ -bit int. and the extra cost can be absorbed into the term $O(n)$.)

Note: For a k^{th} degree polynomial $Z(t)$

La Grange's formula for $t = -\frac{k}{2}, \dots, 0, \dots, \frac{k}{2}$:

$$Z(t) = \sum_{i=-\frac{k}{2}}^{\frac{k}{2}} \cdot \prod_{\substack{j=-\frac{k}{2} \\ j \neq i}}^{\frac{k}{2}} \left(\frac{(t-j)}{(i-j)} \cdot Z(i) \right)$$

3.2. Dynamic Programming

We've seen a few examples : NFAs \rightarrow REs,
CYK algor. in Automata Theory

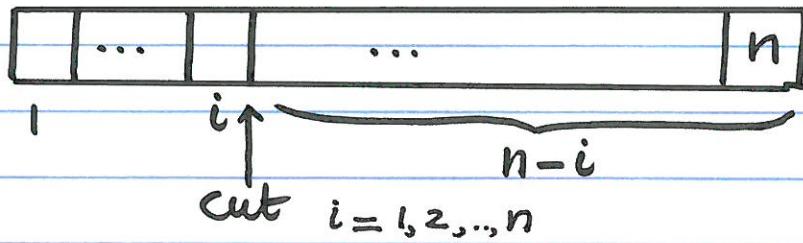
Rod Cutting

Input. A rod of length n and sale prices p_i for rod of length i , $i=1, \dots, n$.

Output. Max. revenue r_n by cutting rod and selling the pieces.

Fact. There are 2^{n-1} ways of cutting rod of length n into pieces.

Pf.



Cut at position $i \rightarrow$ rod of length i and recursively cut rod of length $n-i$
Now prove Fact by induction on n . \square

Observation. From above proof we have:

$$r_n = \max_{1 \leq i \leq n} (p_i + r_{n-i})$$

↑
 sale price of
 rod of length i of
 ↑
 max rev.
 from rod
 of length $n-i$

Given array $p[1..n]$ of sale prices and n :

CUT-Rod (p, n)

if $n = 0$ return 0

$q := -\infty$

for $i = 1$ to n

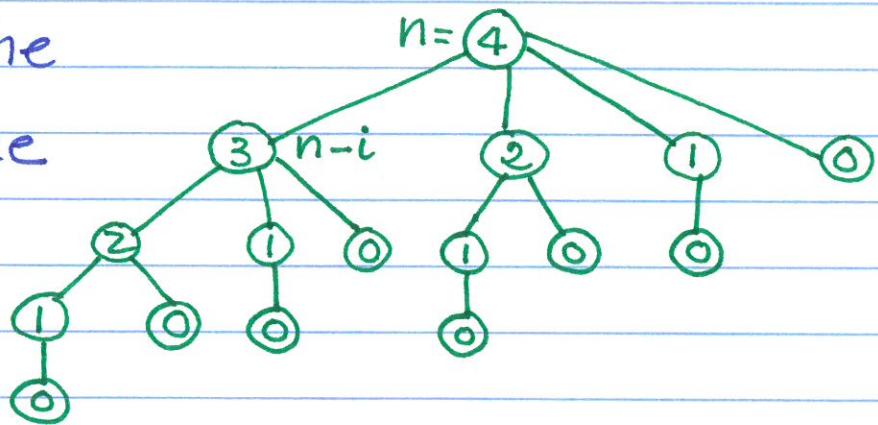
$q = \max(q, p[i] + \text{CUT-Rod}(p, n-i))$

return q

This gives the

recursion tree

(for $n = 4$)



Running time of Cut-Rod is :

$$T(n) = O(n) + \sum_{j=0}^{n-1} T(j) = O(2^n)$$

Observ. There are repetitions in rec. tree of CUT-Rod. For ex., if we have computed r_2 before, we don't have to re-comp. it.

⇒ Store interm. results in $r[0..n]$
 & proceed recursively from smaller subproblems.

Revised-Cut-Rod (P, n)

Let $r[0..n]$ be new

$$r[0] = 0 \quad * r[j] = \max_{1 \leq i \leq j} \{ p[i] + r[j-i] \}$$

for $j=1$ to n

$$q = -\infty$$

for $i=1$ to j

$$(*) \quad q = \max(q, p[i] + r[j-i])$$

$$r[j] = q$$

return $r[n]$

Example.

i	1	2	3	4	5	6	7	8	9	10
$p[i]$	1	5	8	9	10	17	17	20	24	30
$r[i]$	0	1	5	8	10	13	17	18	22	25

Question. How to obtain the opt. cut?

Solution. In line (*) record value i for which the max is found using array $s[0..n]$.

$$(**) \quad \left\{ \begin{array}{l} \text{if } q < p[i] + r[j-i] \text{ then} \\ \quad q = p[i] + r[j-i] \\ \quad s[j] = i \end{array} \right.$$

Example.

i	0	1	2	3	4	5	6	7	8	9	10
$r[i]$	0	1	5	8	10	13	17	18	22	25	30
$s[i]$	0	1	2	3	2	2	6	1	2	3	10

Principles of Dynamic Prog.

- Compute solutions to all subproblems: starting from smaller subproblems and proceeding to larger.
- Store solutions to subproblems in a table (programming \leftrightarrow tabular nature)
- Once a subproblem is solved, its solution is stored in table. (no need to recalculate)
- At most poly. many subprobl. of size $< n$ each solvable in polynomial time.

World Series Odds

- Two teams A, B play $\leq 2n-1$ games
- First team achieving n victories is WINNER

Assumptions: (1) No ties

(2) Game outcomes are independent

$$(3) P(A \text{ wins}) = p$$

$$P(B \text{ wins}) = q = 1-p$$

$P(i,j) =$ Probability A eventually wins the series given that

- A needs i more victories to win
- B " j " "

Thus, $P(n,n) = \text{Prob. A wins before the entire match.}$

$$P(0,i) = 1, \quad 1 \leq i \leq n$$

$$P(i,0) = 0, \quad 1 \leq i \leq n$$

We have: For $i,j \geq 1$:

$$P(i,j) = p \cdot P(i-1,j) + q \cdot P(i,j-1)$$

Goal: Compute $P(i,j)$, $i,j \geq 0$

W-SERIES(i,j)

if $i = 0$ then return 1

else if $j = 0$ then return 0

return $p \cdot \text{W-SERIES}(i-1,j) + q \cdot \text{W-SERIES}(i,j-1)$

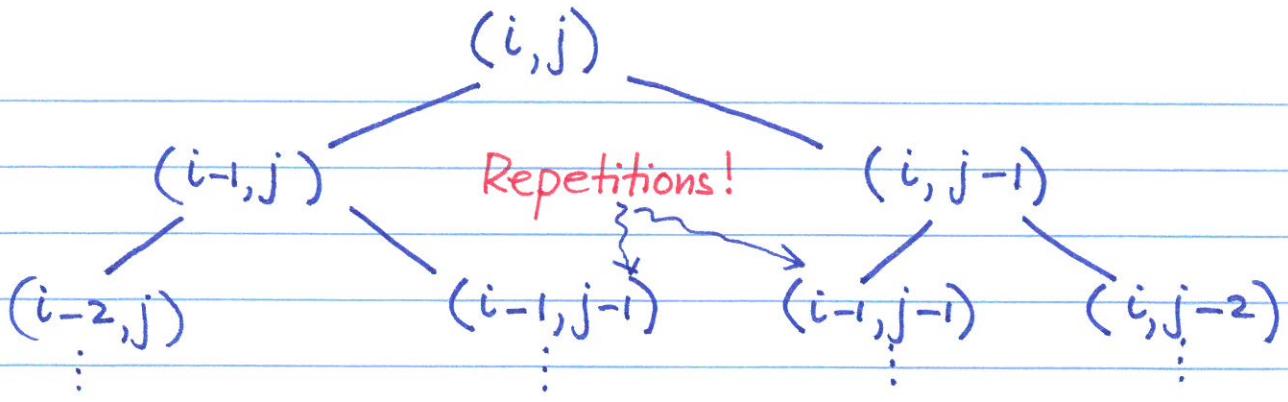
Let $T(k)$, $k=i+j$, denote running time of W-SERIES(i,j). Then

$$T(1) = \Theta(1) \text{ and } T(k) \leq 2T(k-1) + \Theta(1)$$

$$\text{Thus, } T(k) = O(2^k) = O(4^n) \quad |_{\substack{k= \\ 2n}}$$

$$\text{Claim. } T(k) = \Omega(4^n) \quad |_{\substack{i=j=n}}$$

Pf. What does W-SERIES' recursion tree look like?



Total number of nodes is $2 \binom{i+j}{j} - 1$

For $i=j=n$, noting $\binom{2n}{n} \geq \frac{4^n}{2n+1}$ we have:

$$\begin{aligned} T(2n) &= \Omega\left(\binom{2n}{n}\right) = \Omega\left(\frac{4^n}{2n+1}\right) \\ &= \Omega\left(\frac{4^n}{n}\right) \quad \blacksquare \end{aligned}$$

Observ. There are only n^2 values to be computed, and they can be stored in a table!

Ex. Table of odds ($p=q=\frac{1}{2}$, $n=4$)

4	-1-	15/16	13/16	21/32	1/2	← upper half!
3	1	7/8	11/16	1/2	11/32	
2	1	3/4	1/2	5/16	3/16	
j↑ 1	1	1/2	1/4	1/8	1/16	
0	0	0	0	0	0	
i →	0	1	2	3	4	↓

lower half!

⇒ Calculate lower half to table
and then upper half!

REV. W. SERIES (n, p)

Let $P[0..n, 0..n]$ be array

$$q = 1 - p$$

for $s = 1 \text{ to } n \text{ do}$ /* lower half */

$$P[0, s] = 1; P[s, 0] = 0;$$

for $k = 1 \text{ to } s-1 \text{ do}$

$$P[k, s-k] = p \cdot P[k-1, s-k] + q \cdot P[k, s-k-1]$$

/* We Now calculate upper half */

for $s = 1 \text{ to } n \text{ do}$

for $k = 0 \text{ to } n-s \text{ do}$

$$P[s+k, n-k] = p \cdot P[s+k-1, n-k] + q \cdot P[s+k, n-k-1]$$

Time complexity : $O(n^2)$

Chained Matrix Multiplication

We wish to compute matrix product

$$M = M_1 \times M_2 \times \dots \times M_n$$

Different orders of calculation require different number of arith. operations.

Ex. $M = A \times B \times C \times D$

A is 13×5 , B is 5×89 , C is 89×3 , D is 3×34

(1) $((AB)C)D$ requires 10,582 scalar mult.

(Note: $A \times B$ req. 5,785 " "

$(A \times B) \times C$ — 3,471 " "

$((A \times B) \times C) \times D$ — 1,326 " "

(2) $(AB)(CD)$ requires 54,201 " "

(3) $(A(B(C)))D$ — 2,856 " "

(4) $A((BC)D)$ — 4,055 " "

(5) $A(B(CD))$ — 26,418 " " □

Goal: To compute the opt. order that gives the least number of scalar mult. in computing the product $M_1 \times \dots \times M_n$

Question. How many ways can we parenthesize $M_1 \times M_2 \times \dots \times M_n$?

Let $S(n)$ be # of ways to parenthesize $M_1 \times \dots \times M_n$. Then $S(1) = 1$ and

$$S(n) = \sum_{i=1}^{n-1} S(i) \cdot S(n-i)$$

Claim. $S(n) = \frac{1}{n} \binom{2n-2}{n-1} = \Omega\left(\frac{4^n}{n^2}\right) \square$

Let M_i be of dimension $d_{i-1} \times d_i$, $i=1, \dots, n$

Let m_{ij} denote the opt. number of scalar mult. for $M_i \times \dots \times M_j$.

Then: $m_{ii} = 0 \quad i=1, \dots, n$

$$m_{i,i+1} = d_{i-1} \times d_i \times d_{i+1} \quad i=1, \dots, n-1$$

and for $1 < s < n$ and $i = 1, \dots, n-s$

$$m_{i,i+s} = \min_{i \leq k < i+s} (m_{ik} + m_{k+1,i+s} + d_{i-1} d_k d_{i+s})$$

$$(M_i \times \dots \times M_k) (M_{k+1} \times \dots \times M_{i+s})$$

$$\begin{matrix} d_{i-1} \times d_k \\ \rightarrow m_{ik} \end{matrix}$$

$$\begin{matrix} d_k \times d_{i+s} \\ \rightarrow m_{k+1,i+s} \end{matrix}$$

Observ. We only need to compute $O(n^2)$

values m_{ij} 's which can be stored in a table!

		4	$m_{14} = 2856$
	3		$m_{13} = 1,530 \quad m_{24} = 1,845$
2			$m_{12} = 5,785 \quad m_{23} = 1,335 \quad m_{34} = 9,878$
1			$m_{11} = 0 \quad m_{22} = 0 \quad m_{33} = 0 \quad m_{44} = 0$

MAT-MULT ($d[0..n]$, n)

Let $m[1..n, 1..n]$ be an array

for $i = 1$ to n do $m[i, i] = 0$

for $s = 1$ to $n-1$ do

for $i = 1$ to $n-s$ do

$$j = i+s$$

$$m[i, j] = \min_{i \leq k < j} (m[i, k] + m[k+1, j] + d_{i-1} \cdot d_k \cdot d_j)$$

Time complexity : $O(n^3)$

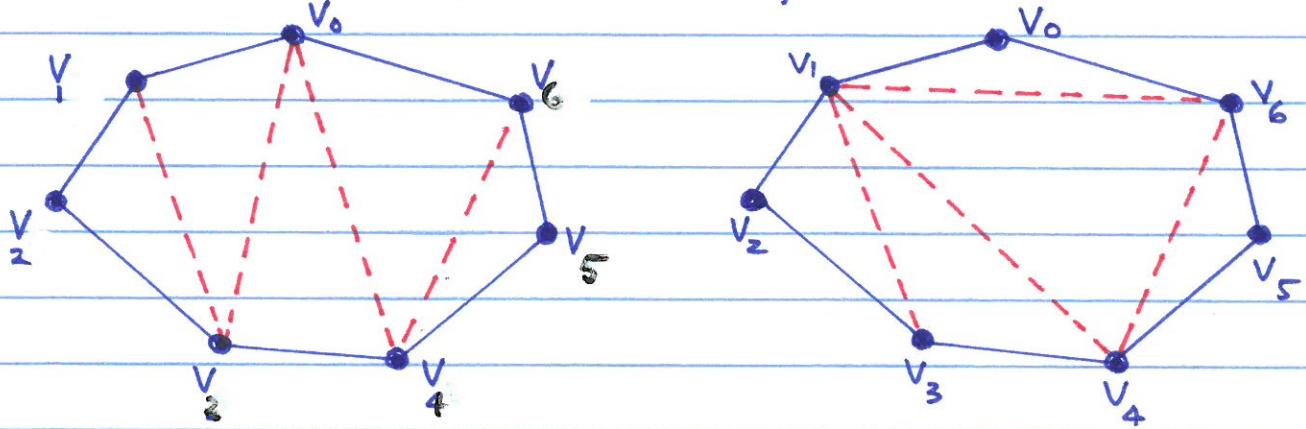
(Note the similarity between this and the CYK algorithm.)

Question. How to output the optimal order?

The Triangulation Problem.

- A polygon is represented by listing its vertices in counter clockwise order
- If $P = \langle v_0, v_1, \dots, v_{n-1} \rangle$ is a polygon, then its sides are: $\overline{v_0 v_1}, \overline{v_1 v_2}, \dots, \overline{v_{n-1} v_n}$ (where $v_n = v_0$)
- If v_i, v_j are non adjacent, $\overline{v_i v_j}$ is chord
- A chord divides a polygon into 2 polygons.
- A triangulation T is a set of chords that divides P into disjoint triangles.

Ex. Two triangulations of a polygon



Note: In a triangulation : no chords intersect one another and any other chord intersects a chord in the triangulation.

Fact. Every triangulation of an n -vertex polygon has $n-3$ chords and yields $n-2$ triangles. \square

Polygon triangulation is def. as follows:

Input. A polygon $P = \langle v_0, v_1, \dots, v_{n-1} \rangle$ and a weight function ω def. on all triangles $\omega(\Delta v_i v_j v_k)$.

Output. A triangulation T that mini. mizes the sum of weights of its triangles.

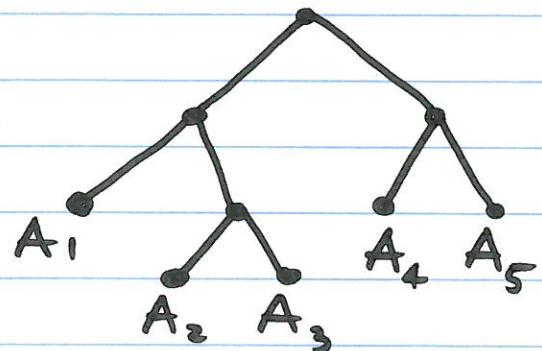
Polygon triangulation & Chained Matrix Prod.

Recall: Evaluation order of matrix chain
 \leftrightarrow Parenthesis structure

$$((A_1, (A_2 A_3)) (A_4 A_5)) \leftrightarrow$$

$(((())) ())$

well-formed
parenthesis string

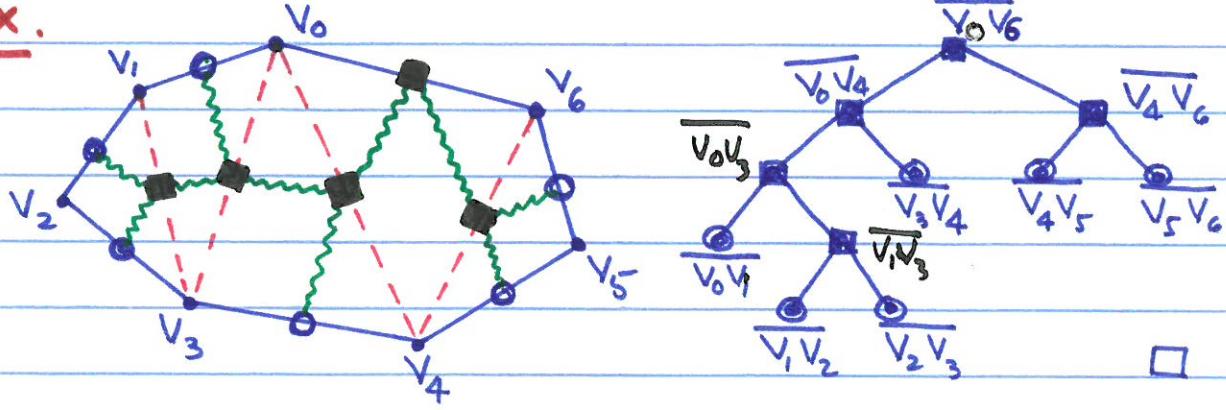


parse tree

Correspondence between triangulations and parse trees : A triangulation T of a polygon $P = \langle v_0, v_1, \dots, v_{n-1} \rangle$ def. a parse tree as follows.

- every side corresp. to a leaf
- every chord " " an internal node
- node assoc. with $\overline{v_{n-1} v_0}$ is root

Ex.

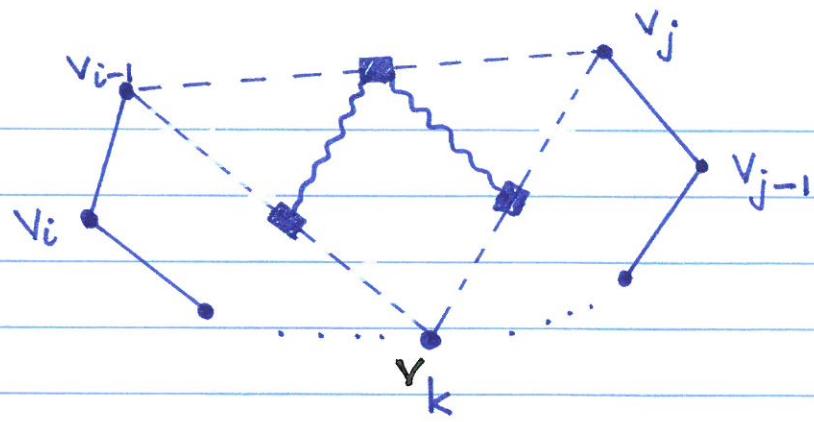


- Every subtree corresponds to a triangulation of a subpolygon.

Ex. Subtree rooted at $\overline{v_0 v_4}$ corresp. to triangulation of $\langle v_0, v_1, \dots, v_4 \rangle$.

For $0 \leq i \leq j \leq n-1$:

m_{ij} := weight of opt. triangulation of $\langle v_{i-1}, \dots, v_j \rangle$



Thus we have the recursion: $1 \leq i \leq j \leq n-1$:

$$m_{ij} = \min_{i \leq k \leq j-1} (m_{ik} + m_{k+1,j} + \omega(\Delta v_{i-1} v_k v_j))$$

where $m_{ii} = 0$

POLYGON-TRIANGULATION ($\omega, n, v_0, \dots, v_{n-1}$)

for $i = 1 \underline{\text{to}} n$ do $m[i,i] = 0$

for $l = 2 \underline{\text{to}} n$ do

for $i = 1 \underline{\text{to}} n-l+1$ do

$$j = i + l - 1$$

$$m[i,j] = \infty$$

for $k = i \underline{\text{to}} j-1$ do

$$q = m[i,k] + m[k+1,j] + \omega(\Delta v_{i-1} v_k v_j)$$

if $q < m[i,j]$ then

$$m[i,j] = q; s[i,j] = k$$

return m, s

record k when opt value found

3.3. Greedy Algorithms.

Example. Activity Selection Problem.

Given a set of n activities $S = \{a_1, a_2, \dots, a_n\}$

Each activity has start time s_i

finish time $f_i > s_i$

If selected, a_i takes place during $[s_i, f_i)$

a_i and a_j are compatible if intervals

$[s_i, f_i)$ and $[s_j, f_j)$ do not overlap, i.e.,

$s_i \geq f_j$ or $s_j \geq f_i$.

Goal. Find largest set of mutually compat. activities!

w.l.o.g: $f_1 \leq f_2 \leq \dots \leq f_{n-1} \leq f_n$.

Optimal Substructure of Activity-Selection.

$S_{ij} = \text{set of activities } a_\ell \text{ s.t.}$

$f_i \leq s_\ell$ and $f_\ell \leq s_j$

(i.e., a_ℓ can take place after a_i and before a_j)

$c[i, j] := \text{size of opt. solution for } S_{ij}$

Then:

$$c[i,j] = \begin{cases} 0 & \text{if } S_{ij} = \emptyset \\ \max_{a_k \in S_{ij}} \{c[i,k] + c[k,j] + 1\} & \text{otherwise} \end{cases}$$

Making Greedy Choice

Let $S_k := \{a_i \in S \mid s_i \geq f_k\}, 0 \leq k \leq n,$

= set of activities starting after a_k finishes

(Note: $S_0 = S$)

Claim. Let $S_k \neq \emptyset$. If $a_m \in S_k$ has the earliest finish time, then a_m is included in some opt. solution of S_k

Pf. Let A_k be an opt. sol. of S_k .

Let a_j be activity in A_k with earliest finish time.

Case (1): $a_j = a_m \checkmark$

Case (2): $a_j \neq a_m$. Let $A'_k = A_k - \{a_j\} \cup \{a_m\}$

Clearly, A'_k is an opt. sol. of S_k and A'_k includes a_m . \square

Strategy: Choose a_k (w/earliest finish time) for S_0 and proceed recursively!

ACTIVITY-SELECTOR (s, f, k, n) (for S_k)

$$m = k+1$$

while $m \leq n$ and $s[m] < f[k]$

$$m = m + 1$$

* This finds first activity in S_k that starts after a_k *

if $m \leq n$ then

return $\{a_m\} \cup \text{ACTIVITY-SELECTOR}(s, f, m, n)$

else return \emptyset

Note: ACTIVITY-SELECTOR ($s, f, 0, n$) solves the original problem.

Complexity: $\Theta(n)$

Iterative version of ACTIVITY-SELECTOR:

GREEDY-ACTIVITY-SELECTOR (s, f, n)

$$A = \{a_1\}; k = 1$$

for $m = 2$ to n do

if $s[m] \geq f[k]$

$$A = A \cup \{a_m\}$$

$$k = m$$

return A

Principle of greedy strategy:

- Cast problem s.t: greedy choice
+ 1 subproblem to solve
- Show there is an opt. sol. that includes greedy choice
- Show opt. substructure : opt. sol to subprobl. + greedy choice \Rightarrow opt. sol. to orig. prob.

Huffman Code

$C = \{c_1, \dots, c_n\}$ be an alphabet s.t.
 each c_i is assigned prob. $f(c_i)$, $\sum_{i=1}^n f(c_i) = 1$
 Encode each $c \in C$ by binary codeword
 $w_c \in \{0, 1\}^+$ s.t.

- Decoding can be done unambiguously
- $\sum_{c \in C} f(c) \cdot |w_c|$ is minimized.

Prefix Codes. A set of binary codewords
 is a prefix code if no codeword is prefix
 of another.

Prefix Codes & Binary trees.

A prefix code can be associated with a bin. tree :

- Left (right) edge is labeled 0 (1)
- A codeword \leftrightarrow string obtained by following a path from root to leaf

Note: The binary tree of an opt. prefix code is **fully binary** : every internal node has exactly 2 children.

By associating with leaves the prob. $f(c)$,

$$\sum_{c \in C} f(c) \cdot |w_c| = \text{average depth of the tree.}$$

Let W be a prefix code for C . Def.

$$H(W) := \sum_{c \in C} f(c) \cdot |w_c|$$

$H(W)$ is also the average number of bits to encode a character $c \in C$.

Input. A set C of characters and

$$f: C \rightarrow \mathbb{R}^+ \text{ s.t. } \sum_{c \in C} f(c) = 1$$

Output. A (opt.) prefix code W for C

s.t. $H(W) = \sum_{c \in C} f(c) \cdot |w_c|$ is minimal.

Idea of Huffman's algor.

- A character c with low prob. occurs less often and is associated with longer codeword.

- Let c_{n-1}, c_n have lowest prob.

- Construct prefix code W' for

$$C' = \{c_1, \dots, c_{n-2}, d_{n-1}\}$$

$$\text{where } f(d_{n-1}) = f(c_{n-1}) + f(c_n)$$

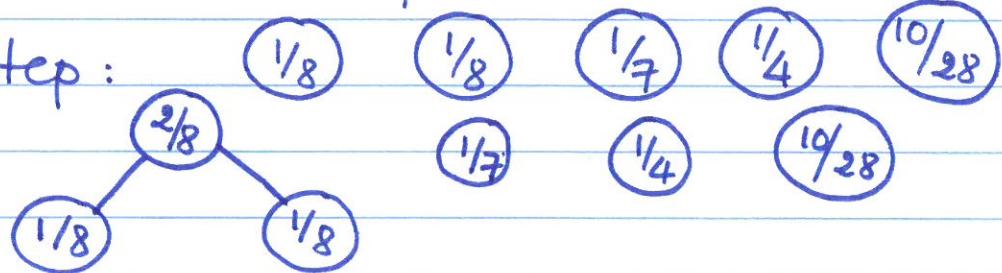
- If $W' = \{w_1, \dots, w_{n-1}\}$

$$\text{then } W = \{w_1, \dots, w_{n-2}, w_{n-1}0, w_{n-1}1\}$$

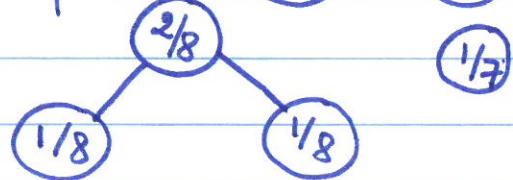
Ex. $C = \{c_1, \dots, c_5\}$ with prob. $\frac{1}{8}, \frac{1}{8}, \frac{1}{7}, \frac{1}{4}, \frac{10}{28}$

Constr. bin. tree as follows:

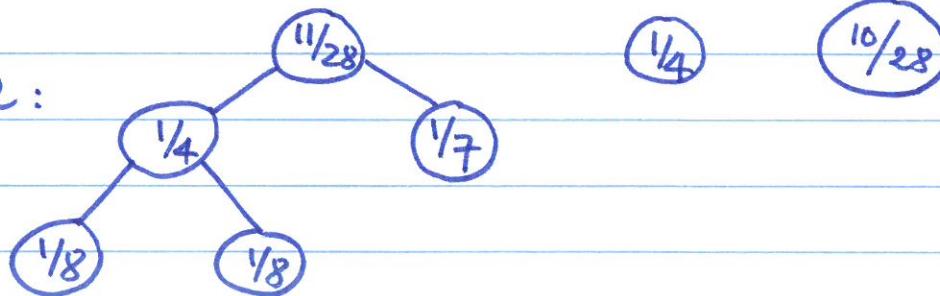
Initial step:



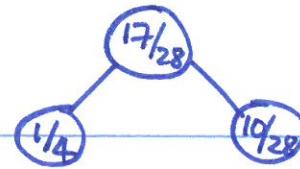
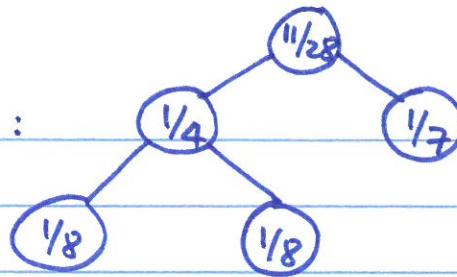
Step 1:



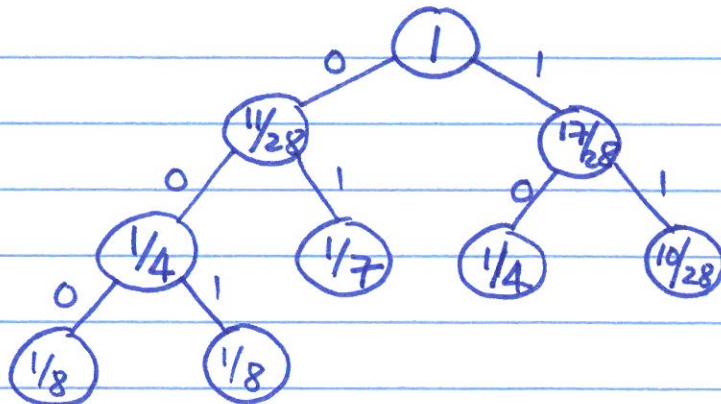
Step 2:



Step 3 :



Step 4 :



The opt. prefix code is $\{000, 001, 01, 10, 11\}$ □

HUFFMAN(C, f)

$$Q = C$$

for $i = 1$ to $n-1$ do

Let z be a new node

Let x, y be roots of 2 trees in Q
with least probabilities

Let z be parent of x, y

$$f(z) = f(x) + f(y)$$

Prop. If $x, y \in C$ have least prob., then
there is an opt. prefix code s.t. $w_x = w_0$
and $w_y = w_1$ for some w .

Pf. Let T be a tree obtained from an opt. prefix code for C . Let a, b be sibling leaves at max. depth in T . Then a, b can be replaced by x, y to yield a tree T' whose aver. depth \leq aver. depth of T \square

Prop. Let $x, y \in C$ have least prob. Let $C' = C - \{x, y\} \cup \{z\}$, where $f(z) = f(x) + f(y)$. Let T' be a tree repres. an opt. prefix code for C' . Then T obtained from T' by making x, y children of z is an opt. prefix code for C . \square

Complexity of HUFFMAN.

- Maintain a min heap for f
 - Need to do insertion / deletion of minimal elements
- \Rightarrow Complexity is $O(n \lg n)$

3.4. MATROIDS & GREEDY METHODS

Def. Let S be a finite set and \mathcal{I} be a nonempty family of subsets of S .

- (S, \mathcal{I}) is an independent system if

$$A \subseteq B \wedge B \in \mathcal{I} \Rightarrow A \in \mathcal{I}$$

i.e., it is hereditary

- Each element $A \in \mathcal{I}$ is called an independent set
- An independent system (S, \mathcal{I}) is called a matroid if it satisfies the following

$$A, B \in \mathcal{I} \wedge |A| > |B|$$

$$\Rightarrow \exists x \in A - B : B \cup \{x\} \in \mathcal{I}$$

called the exchange property

Ex. Matric Matroid.

Let M be a matrix, S be set of rows of M . Let \mathcal{I} be collection of all lin. independent subsets of S . Then (S, \mathcal{I}) is a matroid. \square

Ex. Graphic Matroid

Let $G = (V, E)$ be undir. graph. Let $S = E$ and \mathcal{I} = collection of sets of edges that induce a forest in G .

Claim. (S, \mathcal{I}) is a matroid.

Pf. (1) (S, \mathcal{I}) is obviously an indep. syst.

(2) (S, \mathcal{I}) sat. exchange property:

Let $A, B \in \mathcal{I}$ s.t. $|A| > |B|$ and

consider forests F_A, F_B def. by A, B .

Fact. A forest F in G has $|V| - |F|$ trees.

Thus, F_A has fewer trees than F_B

\Rightarrow Some tree in F_A have vertices in two different trees in F_B

$\Rightarrow \exists$ edge $e \in A$ connecting these 2 trees in F_B

\Rightarrow Adding e to B doesn't create cycle \square

Def. Let (S, \mathcal{I}) be a matroid and $A \in \mathcal{I}$.

$x \notin A$ is called an extension of A

if $A \cup \{x\} \in \mathcal{I}$

Ex. Consider graphic matroid. edge e is an extension of $A \in \mathcal{I}$ iff $A \cup \{e\}$ does not create a cycle.

Def. $A \in \mathcal{I}$ is maximal if it has no extension

Prop. All maximal indep. subsets in a matroid have the same size

Pf. Suppose otherwise that $A, B \in \mathcal{I}$ are maximal and $|A| > |B|$. Exchange prop. $\Rightarrow \exists x \in A - B : B \cup \{x\} \in \mathcal{I}$, contradicting the maximality of B \square

Ex. In a graphic matroid, $A \in \mathcal{I}$ is maximal iff F_A is a spanning tree \square

Def. A matroid $M = (S, \mathcal{I})$ is weighted if it is associated with a weight fct

$$w: S \rightarrow \mathbb{R}^+$$

s.t. $w(x)$ is strictly pos. $\forall x \in S$.

w is extended to subsets $A \subseteq S$ by:

$$w(A) = \sum_{x \in A} w(x)$$

Question. How to compute max.-weight indep. subset A in a matroid?

Greedy algor. on weighted matroids

Ex. (Computing minimum-spanning trees)

Let $G = (V, E)$ be a connected graph with edge weight $c: E \rightarrow \mathbb{R}^+$. Then

Computing min.-spanning tree is equiv.

to finding max.-weight indep. subset in graphic matroid M_G with weight

$$c^*(e) = c_{\max} - c_e$$

where $c_{\max} = \sum_{e \in E} c(e)$ \square

(Note: max.-weight indep. subset is maximal)

Computing max.-weight ind. subset in a matroid

GREEDY $((S, I), w)$

sort S in monoton. decreasing order

$$w(x_1) \geq w(x_2) \geq \dots \geq w(x_n)$$

$$A = \emptyset$$

for $i = 1 \text{ to } n$ do

if $A \cup \{x_i\} \in I$

then $A = A \cup \{x_i\}$

return A

we first show greedy-choice property:

Lem. Let x be first on list s.t. $\{x\} \in \mathcal{I}$.

Then there is an opt. sol. A containing x .

Pf. Suppose otherwise there is an opt. sol.

B s.t. $x \notin B$. Using exchange prop.

Constr. from x a set A by adding element of B to A . Since $w(x) \geq w(y)$

$\forall y \in B$, it follows that $w(A) \geq w(B)$.

Thus, A is an opt. sol. containing x . \square

Fact. (1) If x is extension of A , then x is extension of \emptyset

(2) If x is not an extension of \emptyset , then x is not an extension of any $A \in \mathcal{I}$.

Lem. (Optimal substructure property)

Let x be first element chosen by GREEDY.

Def. matroid $M' = (S', \mathcal{I}')$ by:

$$S' = \{y \in S \mid \{y, x\} \in \mathcal{I}\}$$

$$\mathcal{I}' = \{B \subseteq S' \mid B \cup \{x\} \in \mathcal{I}\}$$

Then finding a max.. weight ind. subset containing x reduces to finding max.. weight ind. subset in M'

Theorem. GREEDY $((S, I), w)$ returns opt. sol. \square

Ex. (Task-scheduling probl. as matroid.)

Input. . A set $S = \{1, 2, \dots, n\}$ of n unit-time tasks

- A set d_1, \dots, d_n , $1 \leq d_i \leq n$, of integer deadlines s.t. task i has to finish by time d_i , $i = 1, \dots, n$.
- A set w_1, \dots, w_n of (nonnegative) penalties s.t. w_i is incurred if task i is not finished by time d_i , $i = 1, \dots, n$.

Output. A schedule for S that minimizes the total penalty incurred for missed deadlines.

Let \mathcal{S} be a schedule.

Task i is late in \mathcal{S} if it finishes after d_i ; otherwise it's early.

\mathcal{S} is in early-first form if early tasks precede late tasks.

\mathcal{S} is in canonical form if it's early-first and early tasks are scheduled in order of non-decreasing deadlines.

Fact. Every schedule \mathcal{S} can be put into canonical form.

Def. A set A of tasks is independent if there exists a schedule s.t. no task in A is late.

$$\text{For } t=0, \dots, n, N_t(A) := |\{i \in A \mid d_i \leq t\}|$$

Lem. A is independent $\Leftrightarrow N_t(A) \leq t$ for all $t = 0, \dots, n$.

Pf. " \Rightarrow ": Obvious

" \Leftarrow ": If tasks in A are scheduled in order of non-decreasing deadlines, then no task is late. \square

Theorem. Let S be a set of unit-time tasks and I be the collection of all indep. sets of tasks. Then (S, I) is a matroid.

Pf. (1) Hereditary: trivial.

(2) Exchange property: Consider 2 indep. sets of tasks A, B with $|A| < |B|$.

Let k be largest t s.t. $N_t(A) \geq N_t(B)$

Then $k < n$ and for $t = k+1, \dots, n$:

$$N_t(A) < N_t(B).$$

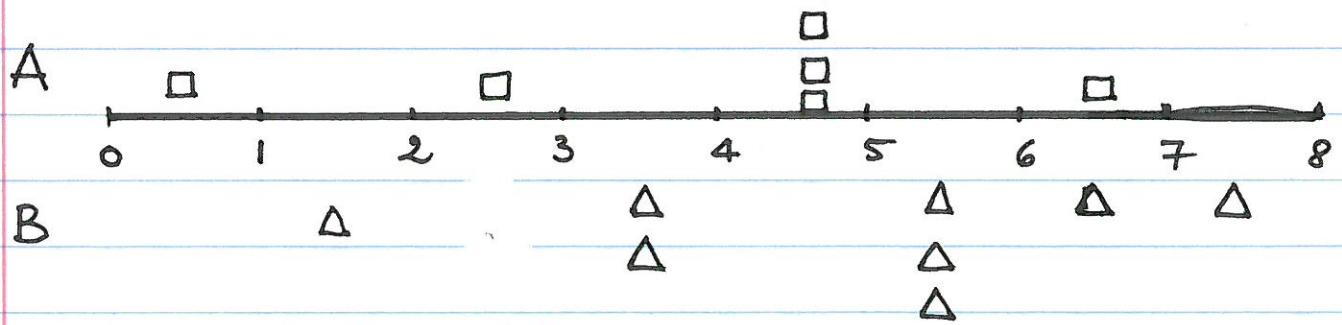
Choose $x \in \{i \in B - A \mid d_i = k+1\}$
 $\Rightarrow d_x = k+1$

$n=8$

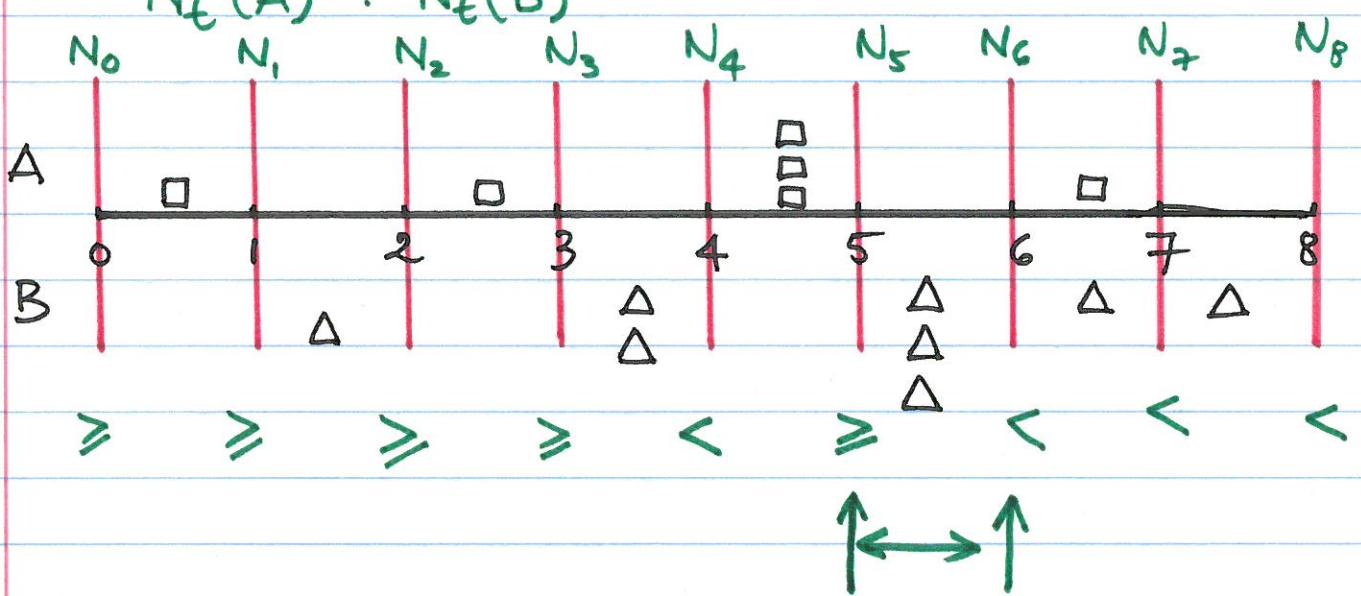
$|A|=6$

$|B|=8$

A and B are independent



$N_t(A) ? N_t(B)$



Then $N_t(A \cup \{x\}) = N_t(A)$ for $t=0, \dots, k$
 and $N_t(A \cup \{x\}) \leq N_t(A) + 1 \leq N_t(B) \leq t$
 for $t = k+1, \dots, n$.

Thus, by Lemma above, $A \cup \{x\}$ is indep.
 We solve the task. scheduling probl.:

- Use greedy algor. to find max.-weight independent set A of tasks.
- Create an opt. schedule by first scheduling tasks in A in order of non-decreasing deadlines.

Complexity:

- Sort S in monot. decreasing order of penalties : $O(n \log n)$
- for loop : $O(n)$ steps
- checking for independence : $O(n)$ } $O(n^2)$
 (using Lemma)

\Rightarrow Total running time : $O(n^2)$