CVO103: Programming Languages

Lecture 13 — Automatic Type Inference (3)

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Putting It All Together

- So far we have informally discussed automatic type inference.
- In this lecture, we define the algorithm precisely.

Goal

$\mathsf{typeof}: E \to T$

Deriving Type Equations

• Type equations:

$$TyEqn \rightarrow \emptyset \mid T \stackrel{.}{=} T \land TyEqn$$

Algorithm for generating equations:

$$\mathcal{V}: (\mathit{Var} \to \mathit{T}) \times \mathit{E} \times \mathit{T} \to \mathit{TyEqn}$$

 $m{\mathcal{V}}(\Gamma,e,t)$ generates the condition for e to have type t in Γ :

$$\Gamma \vdash e:t$$
 iff $\mathcal{V}(\Gamma,e,t)$ is satisfied.

- $ightharpoonup \mathcal{V}([x\mapsto \mathsf{int}],\mathsf{x+1},\alpha)=\pmb{\alpha}\doteq \mathsf{int}$
- ▶ $\mathcal{V}(\emptyset, \text{proc } (x) \text{ (if } x \text{ then } 1 \text{ else } 2), \alpha \to \beta) = \alpha \stackrel{.}{=} \text{bool } \land \beta \stackrel{.}{=} \text{int}$

Deriving Type Equations

$$\mathcal{V}(\Gamma,n,t) = t \doteq \mathrm{int}$$
 $\mathcal{V}(\Gamma,x,t) = t \doteq \Gamma(x)$
 $\mathcal{V}(\Gamma,e_1+e_2,t) = t \doteq \mathrm{int} \wedge \mathcal{V}(\Gamma,e_1,\mathrm{int}) \wedge \mathcal{V}(\Gamma,e_2,\mathrm{int})$
 $\mathcal{V}(\Gamma,\mathrm{iszero}\ e,t) = t \doteq \mathrm{bool} \wedge \mathcal{V}(\Gamma,e,\mathrm{int})$
 $\mathcal{V}(\Gamma,\mathrm{if}\ e_1\ e_2\ e_3,t) = \mathcal{V}(\Gamma,e_1,\mathrm{bool}) \wedge \mathcal{V}(\Gamma,e_2,t) \wedge \mathcal{V}(\Gamma,e_3,t)$
 $\mathcal{V}(\Gamma,\mathrm{let}\ x = e_1\ \mathrm{in}\ e_2,t) = \mathcal{V}(\Gamma,e_1,\alpha) \wedge \mathcal{V}([x \mapsto \alpha]\Gamma,e_2,t) \ (\mathrm{new}\ \alpha)$
 $\mathcal{V}(\Gamma,\mathrm{proc}\ (x)\ e,t) = t \doteq \alpha_1 \to \alpha_2 \wedge \mathcal{V}([x \mapsto \alpha_1]\Gamma,e,\alpha_2) \ (\mathrm{new}\ \alpha_1,\alpha_2)$
 $\mathcal{V}(\Gamma,e_1\ e_2,t) = \mathcal{V}(\Gamma,e_1,\alpha \to t) \wedge \mathcal{V}(\Gamma,e_2,\alpha) \ (\mathrm{new}\ \alpha)$

Example

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 \begin{array}{l} \mathcal{V}(\emptyset, (\operatorname{proc}\;(x)\;(x))\; 1, \alpha) \\ = \mathcal{V}(\emptyset, \operatorname{proc}\;(x)\;(x), \alpha_1 \to \alpha) \wedge \mathcal{V}(\emptyset, 1, \alpha_1) & \operatorname{new}\; \alpha_1 \\ = \alpha_1 \to \alpha \doteq \alpha_2 \to \alpha_3 \wedge \mathcal{V}([x \mapsto \alpha_2], x, \alpha_3) \wedge \alpha_1 \doteq \operatorname{int} & \operatorname{new}\; \alpha_2, \alpha_3 \\ = \alpha_1 \to \alpha \doteq \alpha_2 \to \alpha_3 \wedge \alpha_2 \doteq \alpha_3 \wedge \alpha_1 \doteq \operatorname{int} \end{array}
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Exercise 1

$$\mathcal{V}(\emptyset, exttt{proc}\ (f)\ (f\ 11), lpha)$$

Exercise 2

$$\mathcal{V}([x\mapsto \mathsf{bool}], \mathsf{if}\ x\ \mathsf{then}\ (x-1)\ \mathsf{else}\ 0, lpha)$$

Exercise 3

 $\mathcal{V}(\emptyset, \mathtt{proc}\; (f)\; (\mathtt{iszero}\; (f\; f)), lpha)$

Substitution

Solutions of type equations are represented by substitution:

$$S \in Subst = TyVar \rightarrow T$$

Applying a substitution to a type:

$$S(\mathsf{int}) = \mathsf{int}$$
 $S(\mathsf{bool}) = \mathsf{bool}$
 $S(lpha) = egin{cases} t & \mathsf{if} \ lpha \mapsto t \in S \ lpha & \mathsf{otherwise} \end{cases}$
 $S(T_1 o T_2) = S(T_1) o S(T_2)$

Example

Applying the substitution

$$S = \{t_1 \mapsto \mathsf{int}, t_2 \mapsto \mathsf{int} \to \mathsf{int}\}$$
 to to the type $(t_1 \to t_2) \to (t_3 \to \mathsf{int})$: $S((t_1 \to t_2) \to (t_3 \to \mathsf{int}))$ $= S(t_1 \to t_2) \to S(t_3 \to \mathsf{int})$ $= (S(t_1) \to S(t_2)) \to (S(t_3) \to S(\mathsf{int}))$ $= (\mathsf{int} \to (\mathsf{int} \to \mathsf{int})) \to (t_3 \to \mathsf{int})$

Unification

Update the current substitution with equality $t_1 \doteq t_2$.

$$\mathsf{unify}: T \times T \times Subst \to Subst$$

$$\begin{array}{rcl} & \mathsf{unify}(\mathsf{int},\mathsf{int},S) & = & S \\ & \mathsf{unify}(\mathsf{bool},\mathsf{bool},S) & = & S \\ & \mathsf{unify}(\alpha,\alpha,S) & = & S \\ & \mathsf{unify}(\alpha,t,S) & = & \left\{ \begin{array}{l} \mathsf{fail} & \alpha \; \mathsf{occurs} \; \mathsf{in} \; t \\ \mathsf{extend} \; S \; \mathsf{with} \; \alpha \doteq t \; \mathsf{otherwise} \end{array} \right. \\ & \mathsf{unify}(t,\alpha,S) & = \; \mathsf{unify}(\alpha,t,S) \\ & \mathsf{unify}(t_1 \to t_2,t_1' \to t_2',S) & = \; \mathsf{let} \; S' = \mathsf{unify}(t_1,t_1',S) \; \mathsf{in} \\ & \mathsf{let} \; S'' = \mathsf{unify}(S'(t_2),S'(t_2'),S') \; \mathsf{in} \\ & S'' \\ & \mathsf{unify}(\cdot,\cdot,\cdot) & = \; \mathsf{fail} \end{array}$$

Exercises

- $\operatorname{unify}(\alpha, \operatorname{int} \to \operatorname{int}, \emptyset) =$
- unify(α , int $\rightarrow \alpha$, \emptyset) =
- $\operatorname{unify}(\alpha \to \beta, \operatorname{int} \to \operatorname{int}, \emptyset) =$
- $\operatorname{unify}(\alpha \to \beta, \operatorname{int} \to \alpha, \emptyset) =$

Solving Equations

$$\begin{array}{rcl} \text{unifyall}: TyEqn \rightarrow Subst \rightarrow Subst \\ & \text{unifyall}(\emptyset,S) &=& S \\ \text{unifyall}((t_1 \doteq t_2) \ \land \ u,S) &=& \text{let } S' = \text{unify}(S(t_1),S(t_2),S) \\ & \text{in unifyall}(u,S') \end{array}$$

Let \mathcal{U} be the final unification algorithm:

$$\mathcal{U}(u) = \mathsf{unifyall}(u,\emptyset)$$

$\mathsf{typeof}: E \to T$

$$\begin{array}{l} \mathsf{typeof}(E) = \\ \mathsf{let} \ S = \mathcal{U}(\mathcal{V}(\emptyset, E, \alpha)) \quad (\mathsf{new} \ \alpha) \\ \mathsf{in} \ S(\alpha) \end{array}$$

Examples

- typeof((proc(x) x) 1)
- typeof(let x = 1 in proc(y) (x + y))

Summary: Automatic Type Inference

Design and implementation of static type system:

- logical rules for inferring types
- algorithmic procedure for inferring types