# COSE215: Theory of Computation

Lecture 3 — Nondeterministic Finite Automata

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## **Definition**

# Definition (NFA)

A nondeterministic finite automaton (or NFA) is defined as,

$$M = (Q, \Sigma, \delta, q_0, F)$$

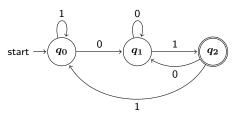
#### where

- Q: a finite set of states
- ullet  $\Sigma$ : a finite set of *input symbols* (or input alphabet)
- $ullet q_0 \in Q$ : the initial state
- ullet  $F\subseteq Q$ : a set of *final states*
- $oldsymbol{\delta}:Q imes\Sigma o 2^Q$ : transition function

# Example

$$(\{q_0,q_1,q_2\},\{0,1\},\delta,q_0,\{q_2\})$$
 
$$\delta(q_0,0)=\{q_0,q_1\} \qquad \delta(q_0,1)=\{q_0\}$$
 
$$\delta(q_1,0)=\emptyset \qquad \qquad \delta(q_1,1)=\{q_2\}$$
 
$$\delta(q_2,0)=\emptyset \qquad \qquad \delta(q_2,1)=\emptyset$$
 start 
$$0$$

cf) Compare with the equivalent DFA:

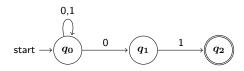


### **Extended Transition Function**

$$\delta^*:Q imes \Sigma^* o 2^Q$$

- (Basis)  $s = \epsilon$ :
- (Induction) s = wa:

# Example



$$\begin{split} \delta^*(q_0,00101) &= \bigcup_{s_i \in \delta^*(q_0,0010)} \delta(s_i,1) = \delta(q_0,1) \cup \delta(q_1,1) = \{q_0\} \cup \{q_2\} = \{q_0,q_2\} \\ \delta^*(q_0,0010) &= \bigcup_{s_i \in \delta^*(q_0,001)} \delta(s_i,0) = \delta(q_0,0) \cup \delta(q_2,0) = \{q_0,q_1\} \cup \emptyset = \{q_0,q_1\} \\ \delta^*(q_0,001) &= \bigcup_{s_i \in \delta^*(q_0,001)} \delta(s_i,1) = \delta(q_0,1) \cup \delta(q_1,1) = \{q_0\} \cup \{q_2\} = \{q_0,q_2\} \\ \delta^*(q_0,00) &= \bigcup_{s_i \in \delta^*(q_0,00)} \delta(s_i,0) = \delta(q_0,0) \cup \delta(q_1,0) = \{q_0,q_1\} \cup \emptyset = \{q_0,q_1\} \\ \delta^*(q_0,0) &= \bigcup_{s_i \in \delta^*(q_0,\epsilon)} \delta(s_i,0) = \delta(q_0,0) = \{q_0,q_1\} \\ \delta^*(q_0,\epsilon) &= \{q_0\} \end{split}$$

# Exercise: Language of an NFA

The language of NFA  $M=(Q,\Sigma,\delta,q_0,F)$  is defined as follows:

$$L(M) = \{$$

### Exercises

Design NFAs for the following languages:

- $L = \{x01y \mid x, y \in \{0, 1\}^*\}$

- $\bullet \ L = \{w \in \{0,1\}^* \mid w \text{ contains exactly two } 0\text{'s}\}$
- $\textbf{0} \ L = \{w \in \{0,1\}^* \mid w \text{ has three consecutive 0's} \}$

# Equivalence of DFA and NFA

# Theorem (Equivalence)

A Language L is accepted by some NFA if and only if L is accepted by some DFA.

#### Proof.

By the two Lemmas below.

## Lemma (DFA to NFA)

Given a DFA D, there always exists an NFA N such that L(D) = L(N).

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### DFA to NFA

### Lemma (DFA to NFA)

Given a DFA D, there always exists an NFA N such that L(D) = L(N).

Proof) Assume a DFA  $D=(Q,\Sigma,\delta_D,q_0,F)$  is given. Define an NFA as follows:

$$N=(Q,\Sigma,\delta_N,q_0,F)$$
 where  $\delta_N(q,a)=\{\delta_D(q,a)\}$ 

To prove:

$$L(D) = \{ w \in \Sigma^* \mid \delta_D^*(q_0, w) \in F \} = \{ w \in \Sigma^* \mid \delta_N^*(q_0, w) \cap F \neq \emptyset \} = L(N)$$

It is enough to show that

$$\delta_N^*(q_0, w) = \{\delta_D^*(q_0, w)\}$$

The proof is by induction on |w|.

- $w=\epsilon$ : By the definitions of  $\delta_D^*$  and  $\delta_N^*$ ,  $\delta_D^*(q_0,\epsilon)=q_0$  and  $\delta_N^*(q_0,\epsilon)=\{q_0\}$ .
- $\bullet$  w = sa:

$$\begin{split} \delta_N^*(q_0,sa) &= \bigcup_{s_i \in \delta_N^*(q_0,s)} \delta_N(s_i,a) & \text{by definition of } \delta_N^* \\ &= \delta_N(\delta_D^*(q_0,s),a) & \text{by I.H.} \\ &= \{\delta_D(\delta_D^*(q_0,s),a)\} & \text{by definition of } \delta_N \\ &= \{\delta_D^*(q_0,sa)\} & \text{by definition of } \delta_D^* \end{split}$$

# NFA to DFA (Subset Construction)

## Lemma (NFA to DFA)

Given an NFA N, there always exists a DFA D such that L(N) = L(D).

Proof) Assume an NFA  $N=(Q_N,\Sigma,\delta_N,q_0,F_N)$ . Define a DFA as follows

$$D = (Q_D, \Sigma, \delta_D, \{q_0\}, F_D)$$

where

- $Q_D = 2^{Q_N}$
- $\bullet \ F_D = \{ S \in Q_D \mid S \cap F_N \neq \emptyset \}.$
- For each  $S \in Q_D$  and input symbol  $a \in \Sigma$ :

$$\delta_D(S,a) = \bigcup_{p \in S} \delta_N(p,a)$$

### NFA to DFA

Then, we can prove L(N) = L(D) by showing that

$$\delta_D^*(\{q_0\},w) = \delta_N^*(q_0,w).$$

The proof is by induction on the length of w.

- $ullet w = \epsilon$ : By definition,  $\delta_D^*(\{q_0\},\epsilon) = \{q_0\} = \delta_N^*(q_0,\epsilon)$ .
- w = sa: Induction hypothesis (I.H.):

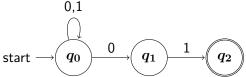
$$\delta_D^*(\{q_0\}, s) = \delta_N^*(q_0, s).$$

$$\begin{split} \delta_D^*(\{q_0\},sa) &= \delta_D(\delta_D^*(\{q_0\},s),a) & \text{by definition of } \delta_D^* \\ &= \delta_D(\delta_N^*(q_0,s),a) & \text{by I.H.} \\ &= \bigcup_{p \in \delta_N^*(q_0,s)} \delta_N(p,a) & \text{by definition of } \delta_D \\ &= \delta_N^*(q_0,sa) & \text{by definition of } \delta_N^* \end{split}$$

# **Example: Subset Construction**

Find a DFA that is equivalent to:

$$N = (\{q_0, q_1, q_2\}, \{0, 1\}, \delta, q_0, \{q_2\})$$
 $\delta(q_0, 0) = \{q_0, q_1\}$ 
 $\delta(q_0, 1) = \{q_0\}$ 
 $\delta(q_1, 0) = \emptyset$ 
 $\delta(q_1, 1) = \{q_2\}$ 
 $\delta(q_2, 0) = \emptyset$ 
 $\delta(q_2, 1) = \emptyset$ 



## **Example: Subset Construction**

$$D = (Q_D, \{0,1\}, \delta_d, \{q_0\}, F_D)$$

- $Q_D = 2^{\{q_0,q_1,q_2\}} = \{\emptyset,\{q_0\},\{q_1\},\dots,\{q_0,q_1,q_2\}\}$
- $F_D = \{\{q_2\}, \{q_0, q_2\}, \{q_1, q_2\}, \{q_0, q_1, q_2\}\}$
- ullet  $\delta_D$ :

	0	1
Ø	Ø	Ø
$egin{array}{l}  ightarrow \{q_0\} \ \{q_1\} \ *\{q_2\} \end{array}$	$\{q_0,q_1\}$	$\{q_0\}$
$\{q_1\}$	Ø	$\{q_2\}$
$*\{q_2\}$	Ø	Ø
$\{q_0,q_1\} \ *\{q_0,q_2\}$	$\{q_0,q_1\}$	$\{q_0,q_2\}$
$*\{q_0,q_2\}$	$\{q_0,q_1\}$	$\{q_0\}$
$*\{q_1,q_2\}$	Ø	$\{q_2\}$
	$\{q_0,q_1\}$	$\{q_0,q_2\}$

# **Example: Subset Construction**

