

# KARA LIU

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## EDUCATION

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**University of California, Berkeley** 2016 - Present  
B.S. in Computer Science and Cognitive Science GPA: 3.97

*Honors:* UC Berkeley EECS Honors Degree Program (2018), UC Berkeley Leadership Award (2016, 2018)

## TECHNICAL SKILLS

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*Computer Languages:* Python, C++, Java, SQL, HTML  
*Software & Tools:* PyTorch, TensorFlow, Git, LaTeX, Vim

## EXPERIENCE

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**Berkeley Artificial Intelligence Research (BAIR) Lab** 2018 – Present  
*Undergraduate Researcher*

- Focused on integrating machine learning methods with robotics, specifically on long-horizon visual planning and representation learning, under the advising of Pieter Abbeel.

**Hong Kong Advanced Science Technology and Research Institute** 2018  
*Research Intern*

- Worked on the Security and Data Sciences team in investigating generative models and their potential impact in the security sector.

## PUBLICATIONS

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**Learning Robotic Manipulation through Visual Planning and Acting** RSS 2019  
*A. Wang, T. Kurutach, K. Liu, A. Tamar, P. Abbeel*

- Proposed a self-supervised, data-driven approach to planning robotic manipulation on deformable objects.
- Used Causal InfoGAN to generate visual plan, and use learned inverse control model to execute actions on PR2.

### **Hallucinative Topological Memory for Zero-Shot Visual Planning**

*K. Liu, T. Kurutach, A. Tamar, P. Abbeel* NeurIPs Deep RL Workshop 2019

- Presented a model-based algorithm for long-horizon visual planning.
- Employed a conditional VAE to visualize potential states, a classifier based on contrastive loss to search for feasibly trajectories, and a low-level controller to execute the plan.

## TEACHING & LEADERSHIP

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**University of California, Berkeley** 2019 - Present  
*Undergraduate Student Instructor, CS 189 - Machine Learning*

**Medical Technologies at Berkeley** 2019 - Present  
*Machine Learning Co-Instructor*

**Girl Up** 2016 - 2018  
*Vice President*

**Alpha Chi Omega** 2018 - 2019  
*Vice President of Facility Operations*