

Embedded Driver Development

Day 1 & 2

Topics to be discussed

- Introduction to Embedded Programming
- Getting to know the Embedded Target
- Datatypes and Variables
- Address
- Storage Classes
- Function

Program???

What is there in a program??

Popular Programming Languages used for Embedded System

- C & C++ (Widely Used)
- Rust
- Assembly
- Java
- Python

Survey by Embedded.com

It's Mostly C, Some C++, and Not Much Else



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Dan Saks
Writing better
embedded Software



Meeting Embedded 2018

Embedded Target Introduction

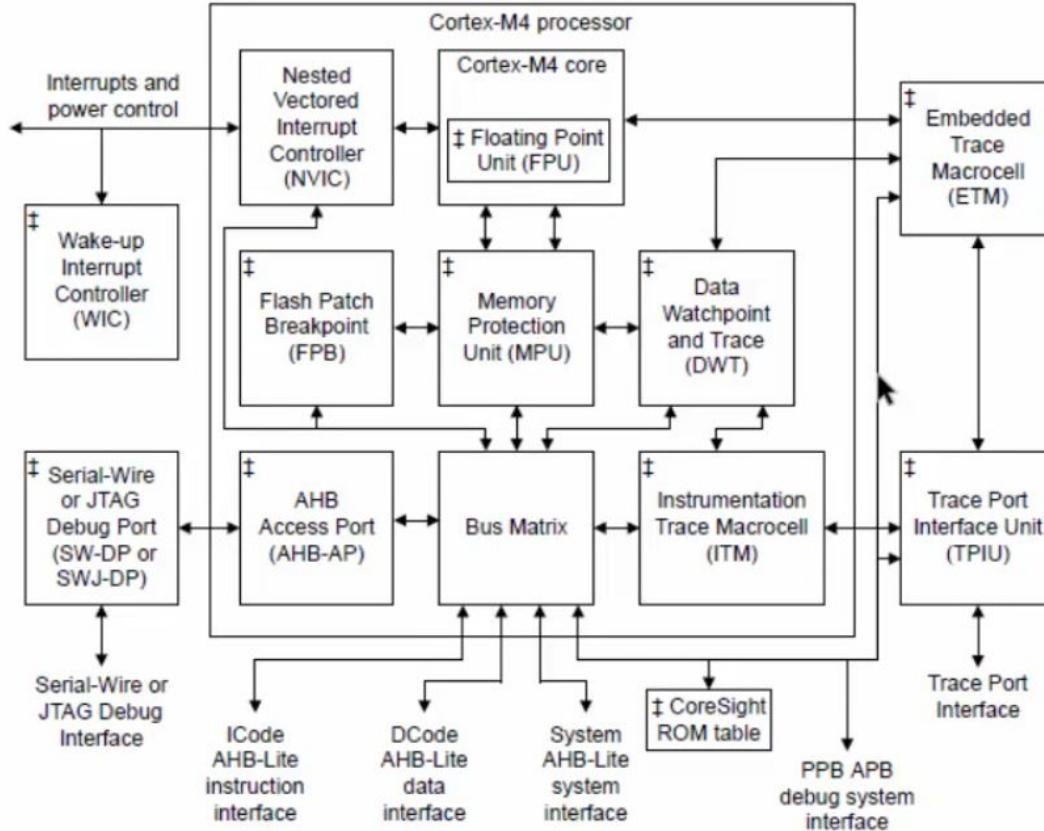
<https://www.st.com/en/evaluation-tools/stm32f4discovery.html>

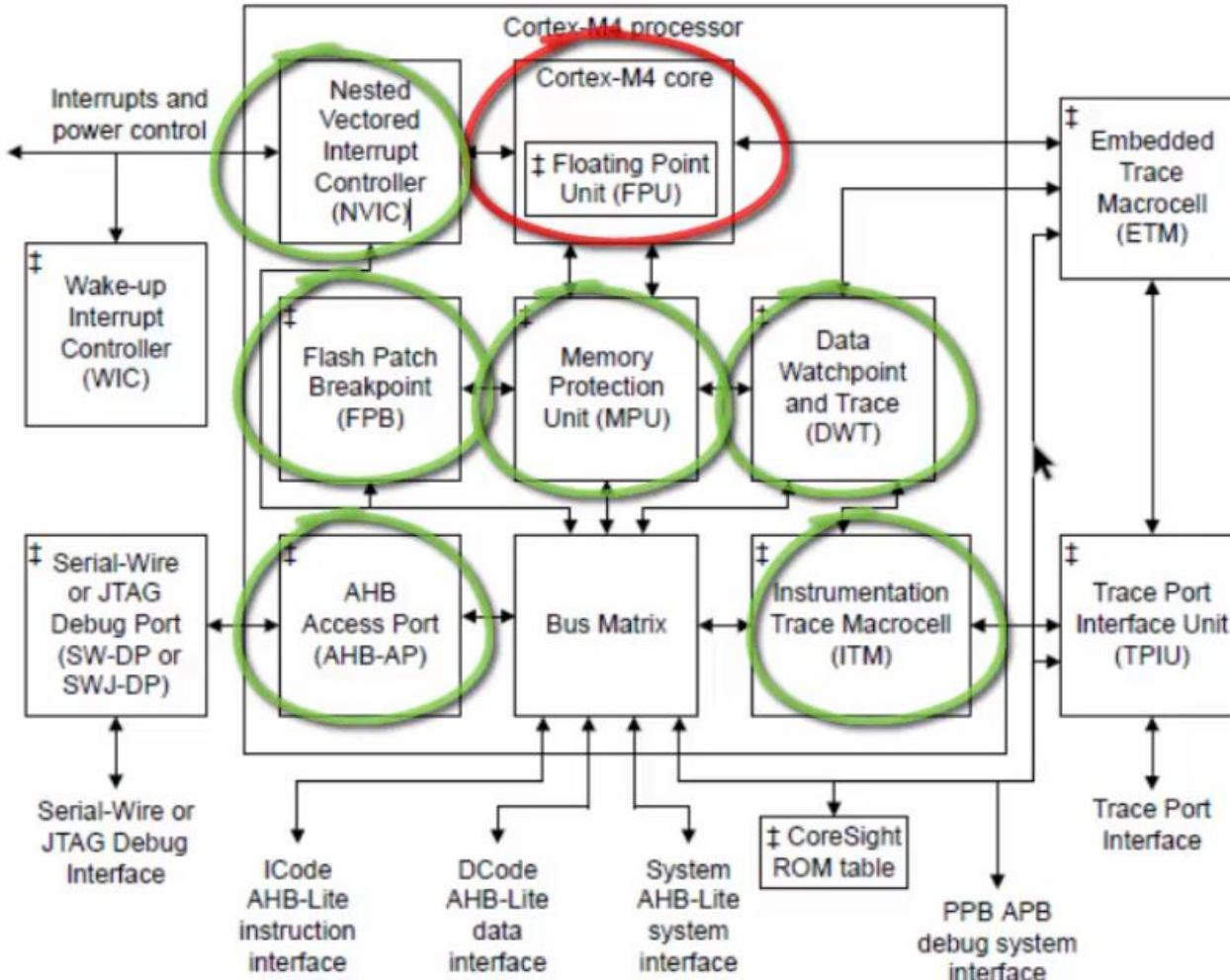
Processor and Processor Core

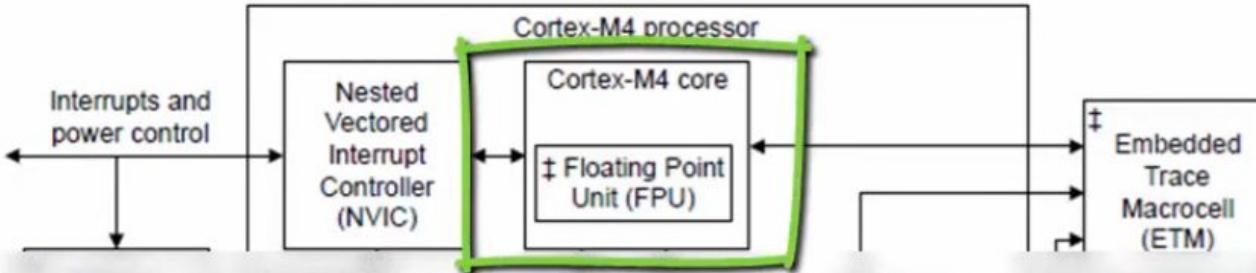
Arm Cortex M4 technical reference manual :

<https://developer.arm.com/documentation/100166/0001>

Block Diagram







Core consists of ALU where data computation takes place and result will be generated

It has the logic to decode and execute an Instruction

It has many registers to store and manipulate data

It has pipe line engine to boost the instruction execution

It consists of hardware multiplication and division engine

Address generation unit

Online GDB

<https://www.onlinegdb.com/>

First ‘C’ Program “Hello World”

Let’s write a ‘C’ code which simply displays the text **Hello world** on the “console” and exits.

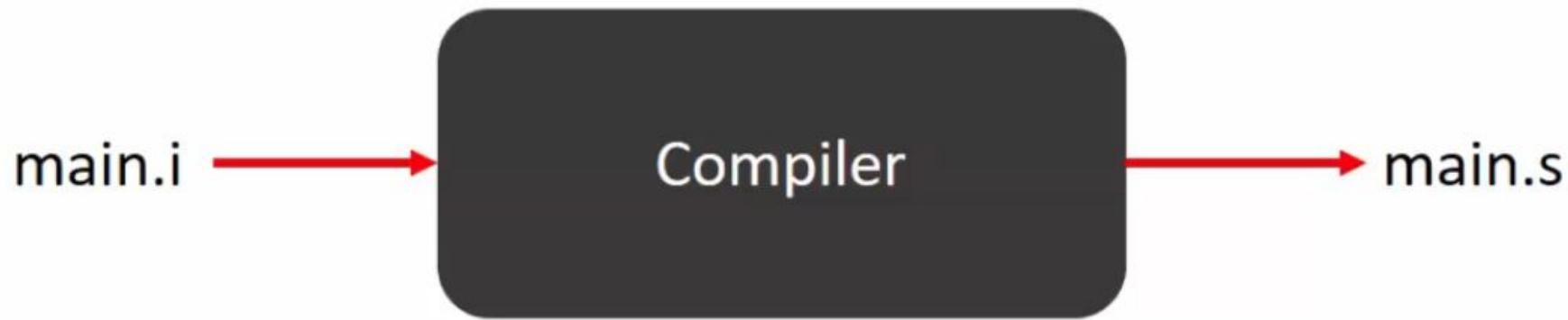
Modify the settings of the Compiler

Type the compiler Argument : -save-temp

Rerun the code

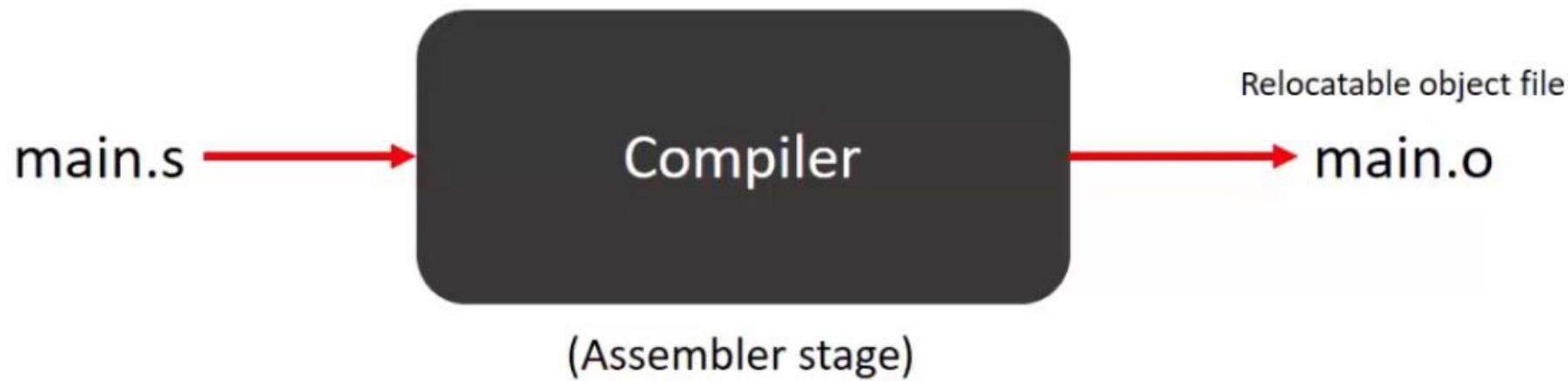


All pre-processing directives will be resolved



(Code generation stage)

Higher level language code statements will be converted
into processor architectural level mnemonics



Assembly level mnemonics are converted into
opcodes(machine codes for instructions)

Assignment 1: (In Class)

WAP to print the following in a certain way mentioned below

Hello World!!

I am enjoying the day!!

'C' data types and variables

Data types :

- ✓ Data type is used for declaring the type of a variable
- ✓ In C programming, data types determine the type and size of data associated with variables
- ✓ Before storing any value in a variable, first programmer should decide its type

Representing real world data

- Data as numbers (Integer or real numbers)
- Data as characters
- Data as strings (Collection of characters)

Examples

- Roy's age is **44** years, **6** months and **200** days
- The temperature of the city **X** is **+27.2** degrees Celsius.
- Today date is **21**st June
- I got an '**A**' grade in school assignment

'C' data types

Integer data types

Float data types

Integer data are represented by different integer data types

Integer data types(for signed data)

char

Short int¹

int

long int²

long long int³



1: also referred by just “short”; “int” is assumed

‘short int’ is synonymous with ‘short’

2 : also referred by just “long”; “int” is assumed

3: also referred by just “long long”; “int” is assumed

Integer data types(for unsigned data)

unsigned char



unsigned short int

unsigned int

unsigned long int

unsigned long long int

'C' integer data types , their storage sizes and value ranges

DATA TYPE	MEMORY SIZE (BYTES)	RANGE
signed char	1	-128 to 127
unsigned char	1	0 to 255
short int	2	-32,768 to 32,767
unsigned short int	2	0 to 65,535
int	4	-2,147,483,648 to 2,147,483,647
unsigned int	4	0 to 4,294,967,295
long	8	-9223372036854775808 to 9223372036854775807
unsigned long	8	0 to 18446744073709551615
long long int	8	-9223372036854775808 to 9223372036854775807
unsigned long long int	8	0 to 18446744073709551615

Meaning of memory size :

The compiler(e.g., GCC) will generate the code to allocate 64 bits (8 bytes of memory) for each long long variable.

XC8 is a cross compiler for PIC 8 bit microcontrollers

Data Type	Size in Bits	Data Range/Usage
unsigned char	8-bit	0 to 255
char	8-bit	-128 to +127
unsigned int	16-bit	0 to 65,535
int	16-bit	-32,768 to +32,767
unsigned short	16-bit	0 to 65,535
short	16-bit	-32,768 to +32,767
unsigned short long	24-bit	0 to 16,777,215
short long	24-bit	-8,388,608 to +8,388,607
unsigned long	32-bit	0 to 4,294,967,295
long	32-bit	-2,147,483,648 to +2,147,483,648

armcc cross compiler for 32 bit ARM based microcontrollers

Type	Size in bits	Natural alignment in bytes	Range of values
char	8	1 (byte-aligned)	0 to 255 (unsigned) by default. -128 to 127 (signed) when compiled with <code>--signed_chars</code> .
signed char	8	1 (byte-aligned)	-128 to 127
unsigned char	8	1 (byte-aligned)	0 to 255
(signed) short	16	2 (halfword-aligned)	-32,768 to 32,767
unsigned short	16	2 (halfword-aligned)	0 to 65,535
(signed) int	32	4 (word-aligned)	-2,147,483,648 to 2,147,483,647
unsigned int	32	4 (word-aligned)	0 to 4,294,967,295
(signed) long	32	4 (word-aligned)	-2,147,483,648 to 2,147,483,647
unsigned long	32	4 (word-aligned)	0 to 4,294,967,295
(signed) long long	64	8 (doubleword-aligned)	-9,223,372,036,854,775,808 to 9,223,372,036,854,775,807
unsigned long long	64	8 (doubleword-aligned)	0 to 18,446,744,073,709,551,615

Integer data type : char

- ✓ This is an integer data type to store a single character(ASCII code) value or 1 byte of signed integer value (+ve or -ve value)
- ✓ A **char** data type variable consumes 1 byte of memory.
- ✓ **char** happens to be the smallest integer data type of 1 byte.
- ✓ There is no other special meaning for the **char** data type, and it is just another integer data type.

Range of **char** data type

??

Brain Teaser!!!!

I want to store the current temperature data of city 'X' in my program.

City X's today's temperature is 25 degree Celsius.

I am sure that X's temperature never goes below 0 degrees and never goes above 40 degrees Celsius.

That means City X's temperature will always be a positive value, and the max value is less than 255.

Variable definition

Data type	Variable name
unsigned char	cityXTemperature;
	/* This is a variable definition */
cityXTemperature = 25;	/* This is variable initialization */

Assignment 2: (In Class)

Write a C program to calculate and print distance from A to C



STEPS

1. Create the variables to hold these data
2. Compute the sum of the data
3. Store the result
4. Print the result as shown in the format

sizeof operator

- **sizeof** operator of C programming language is used to find out the size of a variable.
- The output of the **sizeof** operator may be different on different machines because it is compiler dependent.

Variable scopes

- Variables have scopes
- A **Variable scope** refers to the accessibility of a variable in a given program or function
- For example, a variable may only be available within a specific function, or it may be available to the entire C program

Variable scopes

- Local scope variables (local variables)
- Global scope variables (global variables)

Always remember that when the execution control goes out of the scope of a local variable, the local variable dies that means a variable loses its existence

Address of a variable

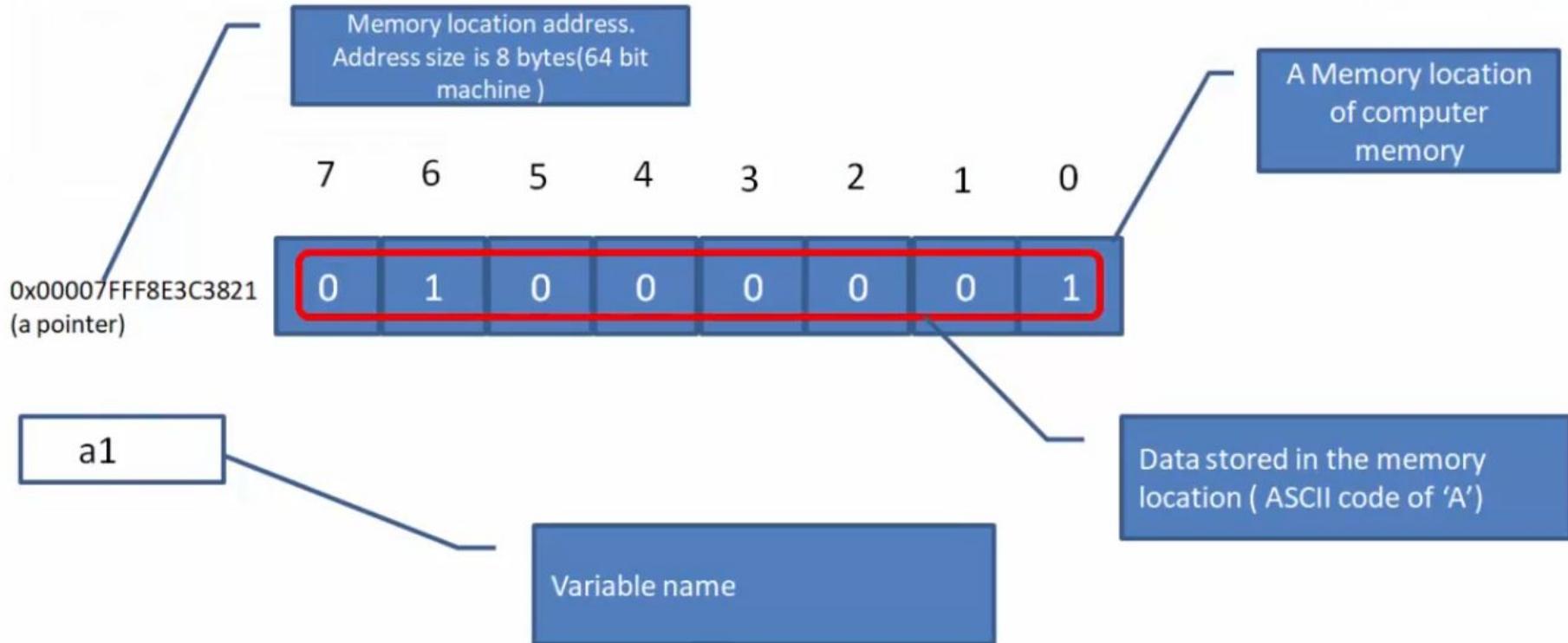
Write a program to print the address of variables.

```
int myData;
```



ampersand

`&myData` → gives you memory location
address of `myData` variable .



This represent a variable.
Variables are represented by
variable data type

TYPE : unsigned long int

unsigned long int addressOfa1 =

This is a pointer data.
Pointer data are
represented by pointer data
type in 'C'

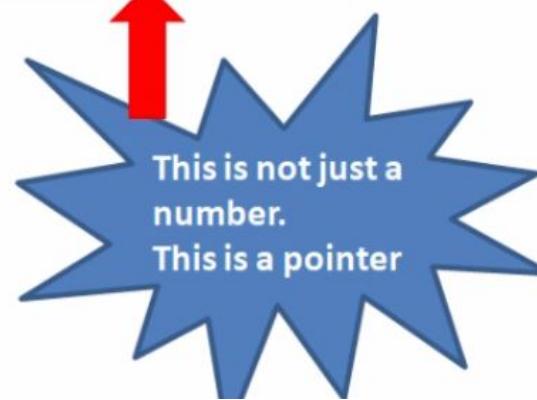
TYPE : char *

&a1;

We are trying to assign a pointer type data into a variable.
Hence there is a data type mismatch warning.

To solve this issue, convert pointer data type into variable
data type using typecasting.

(more on this later)



This is not just a
number.
This is a pointer

Type casting

```
unsigned long int addressOfa1 = (unsigned long int) &a1;
```

Now, this is a number of type unsigned long int.
Not a pointer

Storage classes in ‘C’

The Storage Classes in ‘C’ Language decides:

- ✓ Scope of a variable
- ✓ Visibility of a variable or function
- ✓ Life time of a variable.

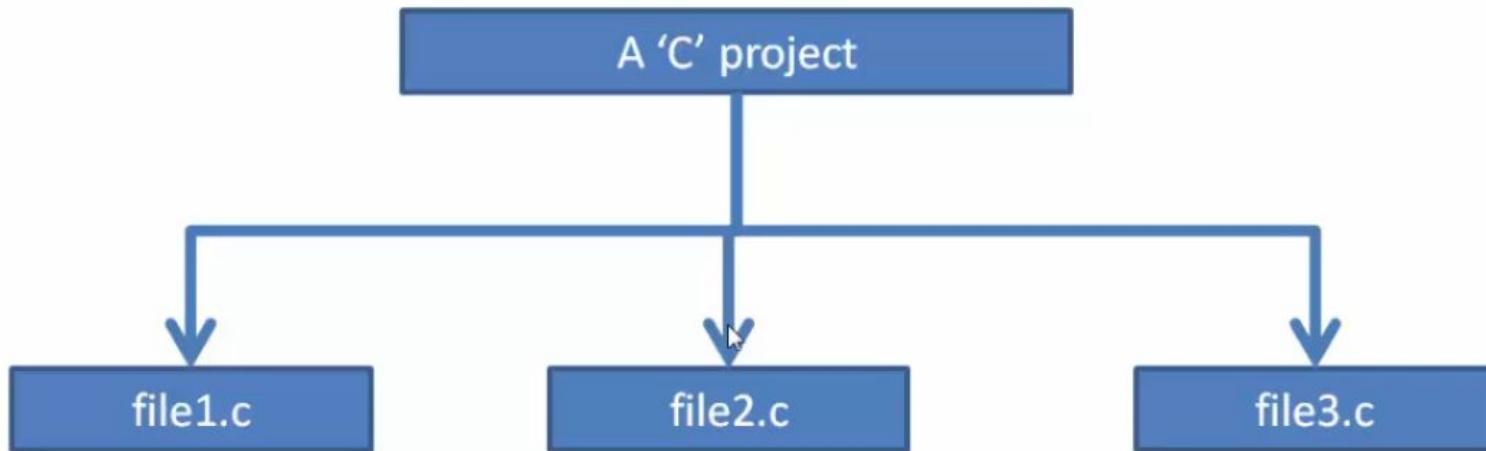
Scope, visibility, and lifetime are features of a variable . These features can be modified by using storage class specifiers.

Storage class specifiers in ‘C’

There are two widely used storage class specifiers in ‘C’

- ✓ static
- ✓ extern

Now, our requirement for this program is, we want a global variable that is private to a function. We want a private variable that does not lose its existence even if the execution control goes out of the scope of that variable.



A 'C' project can be a collection of multiple source files, and a '**static**' storage class specifier can be used to manage the visibility of the variables across various files effectively.

Extern

'extern' storage class specifier is used to access the global variable , which is defined outside the scope of a file.

'extern' storage class specifier can also be used during the function call, when the function is defined outside the scope of the file.

Extern

The keyword 'extern' is relevant only when your project consists of multiple files, and you need to access a variable defined in one file from another file.

'extern' keyword is used to extend the visibility of a function or variable.

Functions in ‘C’

- In ‘C’, you write executable statements inside a function .
- A ‘C’ function is nothing but a collection of statements to perform a specific task.
- Every C program, at least, has one function called “main.”
- Using functions bring modularity to your code, easy to debug, modify and increases the maintainability of the code
- Using C function also minimizes code size and reducing code redundancy
- Functions provide abstraction. For example, printf is a function given by a standard library code. You need not worry about how it is implemented, and it serves the purpose.

- In your program, if you want to perform the same set of tasks again and again, then create a function to do that task and call it every time you need to perform that task.
- This reduces code redundancy and brings modularity to your program and also decreases the final executable size of your program.

The general form of a function definition in C

```
return_data_type  function_name( parameter list )  
{  
    // body of the function  
}
```

main function definition with no input arguments.

```
int main()
{
    /* ... */
}
```

main function definition with 2 input arguments (Command line arguments).

```
int main(int argc, char* argv[])
{
    /* ... */
}
```

We don't use this definition of main for embedded systems because most of the time, there are no command-line arguments in embedded systems.

Function prototype (declaration)

- In ‘C’ functions first have to be declared before they are used.
- Prototype lets compiler to know about the return data type, argument list and their data type and order of arguments being passed to the function .

Type casting

Typecasting is a way of converting a variable or data from one data type to another data type.

Data will be truncated when the higher data type is converted in to lower

There are 2 types of casting

- Implicit casting (Compiler does this)
- Explicit casting (Programmer does this)

Explicit casting

$$\frac{\text{(float)}80}{3}$$

(Explicit)
Promoted to float

(implicit)
Promoted to float

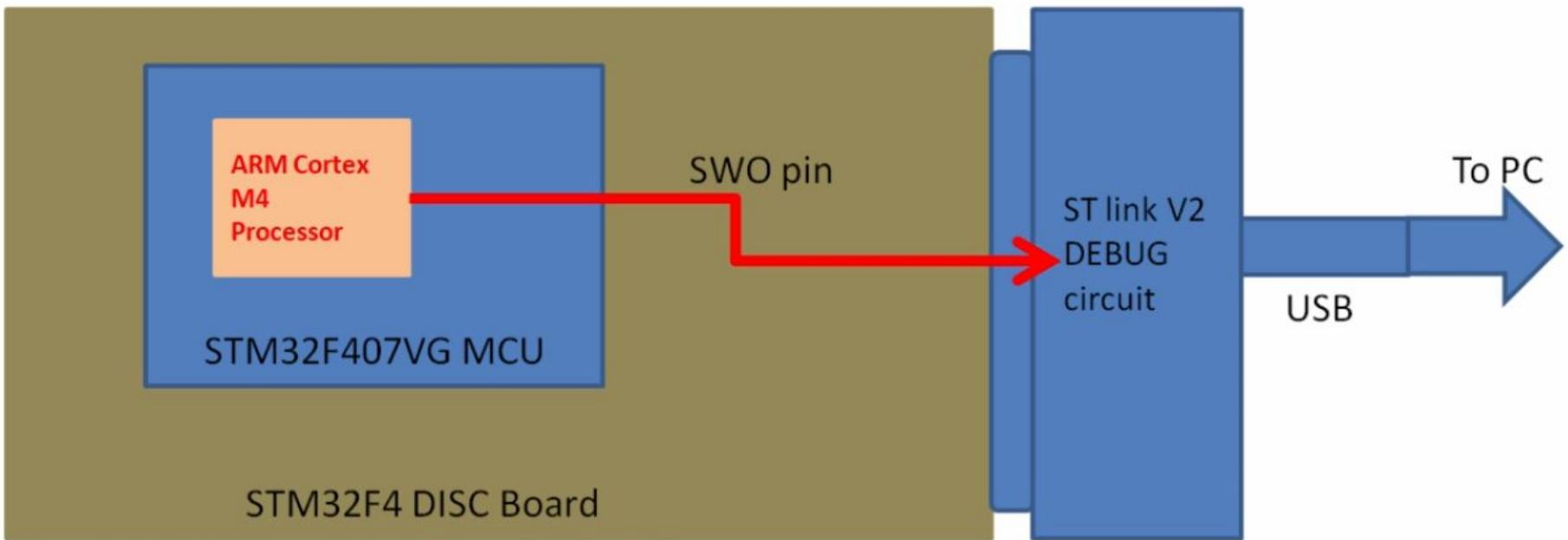
(So, the division is now float divided float which yields float)

Embedded – ‘Hello World’

How are we going to see the message output without a display device connected to our board?

Using printf outputs on ARM Cortex M3/M4/M7 based MCUs

- This discussion is only applicable to MCUs based on ARM Cortex M3/M4/M7 or higher processors.
- printf works over SWO pin(Serial Wire Output) of SWD interface



ARM Cortex M4 Processor

ITM unit

Debug connector(SWD)

SWD(Serial Wire Debug)

2 pin (debug) + 1 pin (Trace)

Instrumentation Trace Macrocell Unit

The ITM is an optional application-driven trace source that supports printf style debugging to trace operating system and application events, and generates diagnostic system information

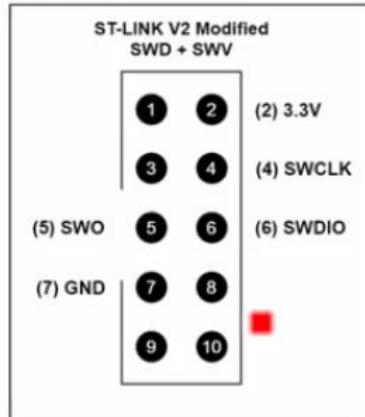
Serial Wire Debug (SWD) is a two-wire protocol for accessing the ARM debug interface

SWD

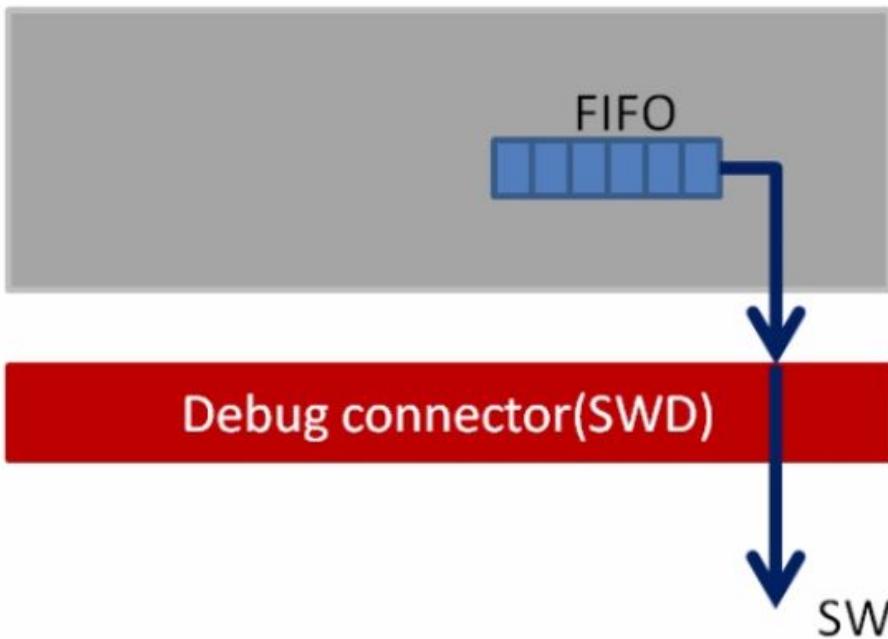
- ✓ Serial Wire Debug (SWD) is a two-wire protocol for accessing the ARM debug interface
- ✓ It is part of the ARM Debug Interface Specification v5 and is an alternative to JTAG
- ✓ The physical layer of SWD consists of two lines
 - SWDIO: a bidirectional data line
 - SWCLK: a clock driven by the host
- ✓ By using SWD interface should be able to program MCUs internal flash , you can access memory regions , add breakpoints, stop/run CPU.
- ✓ The other good thing about SWD is you can use the serial wire viewer for your printf statements for debugging.

SWD and JTAG

JTAG was the traditional mechanism for debug connections for ARM7/9 family, but with the Cortex-M family, ARM introduced the Serial Wire Debug (SWD) Interface. SWD is designed to reduce the pin count required for debug from the 4 used by JTAG (excluding GND) down to 2. In addition, SWD interface provides one more pin called SWO(Serial Wire Output) which is used for Single Wire Viewing (SWV), which is a low cost tracing technology



ITM unit



This SWO pin is connected to ST link circuitry of the board and can be captured using our debug software (IDE)

Printf implementation in std. library

```
printf( )
```

```
{  
    __write();  
}
```

Your project

```
printf();
```

Your project

```
__write()
```

```
{  
    ITM_sendChar();  
    LCD_sendChar();  
}
```

Cross compilation

X86/x86_64 architecture

ARM Architecture

Host Machine



Cross compiler
arm-none-eabi-gcc

Produces executable for different
architecture

Target machine

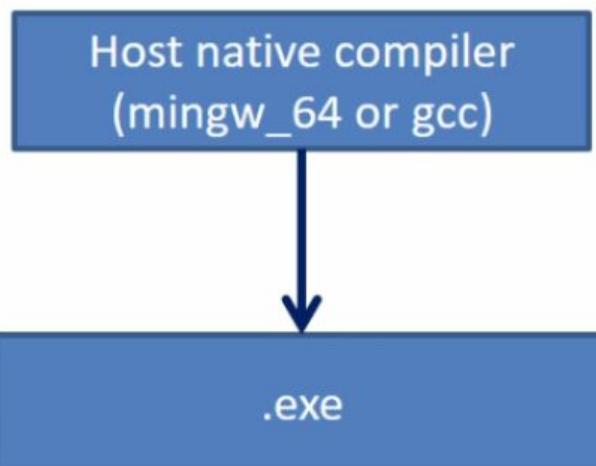


.elf / .bin / .hex

This compiler runs on host machine

Native compilation

Host Machine

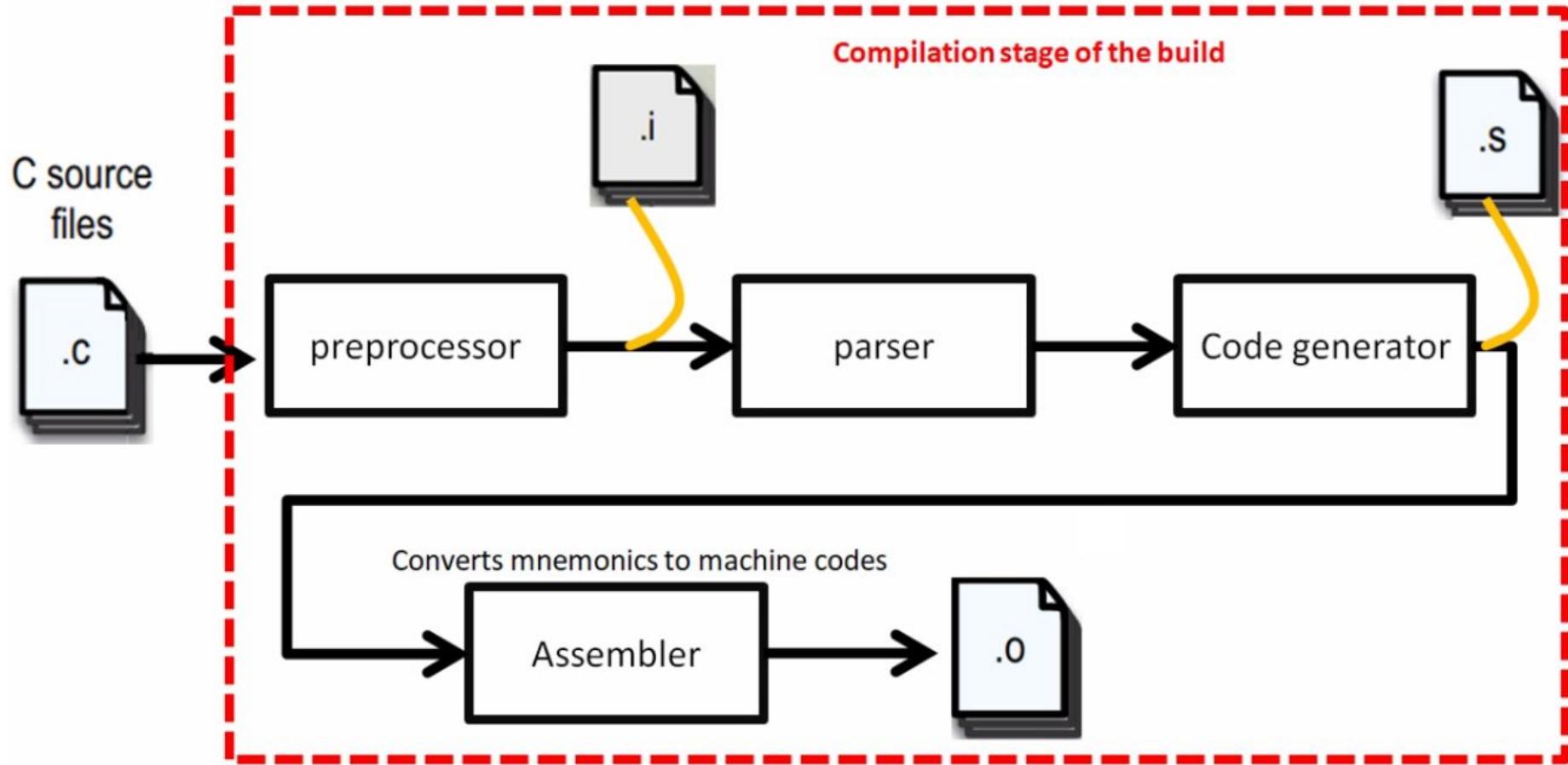


This compiler runs on host machine

Produces executable which also runs on the same machine

Build process

- Preprocessing
- Parsing
- Producing object file(s)
- Linking object files(s)
- Producing final executable
- Post processing of final executable



Navigate Search Project Run Window Help



```
22 struct DataSet
23 {
24     char data1 ;
25     int data2 ;
26     char data3 ;
27     short data4 ;
28 }__attribute__((packed));
29
30
31
32 struct DataSet data ; //this consumes 12 bytes in memory(RAM)
33
34 int main(void)
35 {
36     data.data1 = 0xAA;
37     data.data2 = 0xFFFFFFFF,
38     data.data3 = 0x55;
39     data.data4 = 0xA5A5;
40
41     printf("data.data1 = %d\n",data.data1);
42     printf("data.data2 = %d\n",data.data2);
43     printf("data.data3 = %d\n",data.data3);
44     printf("data.data4 = %d\n",data.data4);
45 }
```

Assembly mnemonics

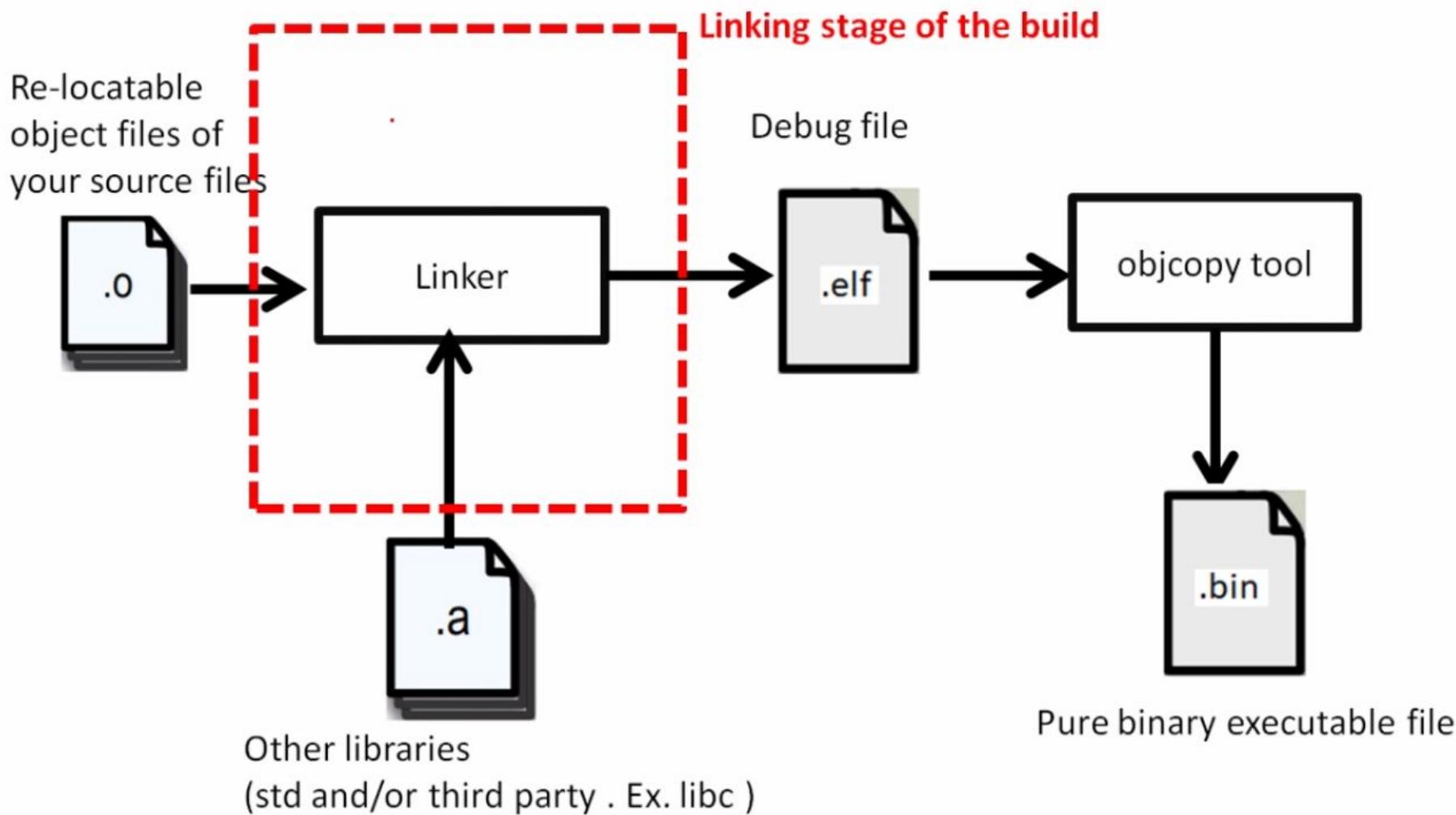
'C' statement

Variables Breakpoints Modules Disassembly SFRs

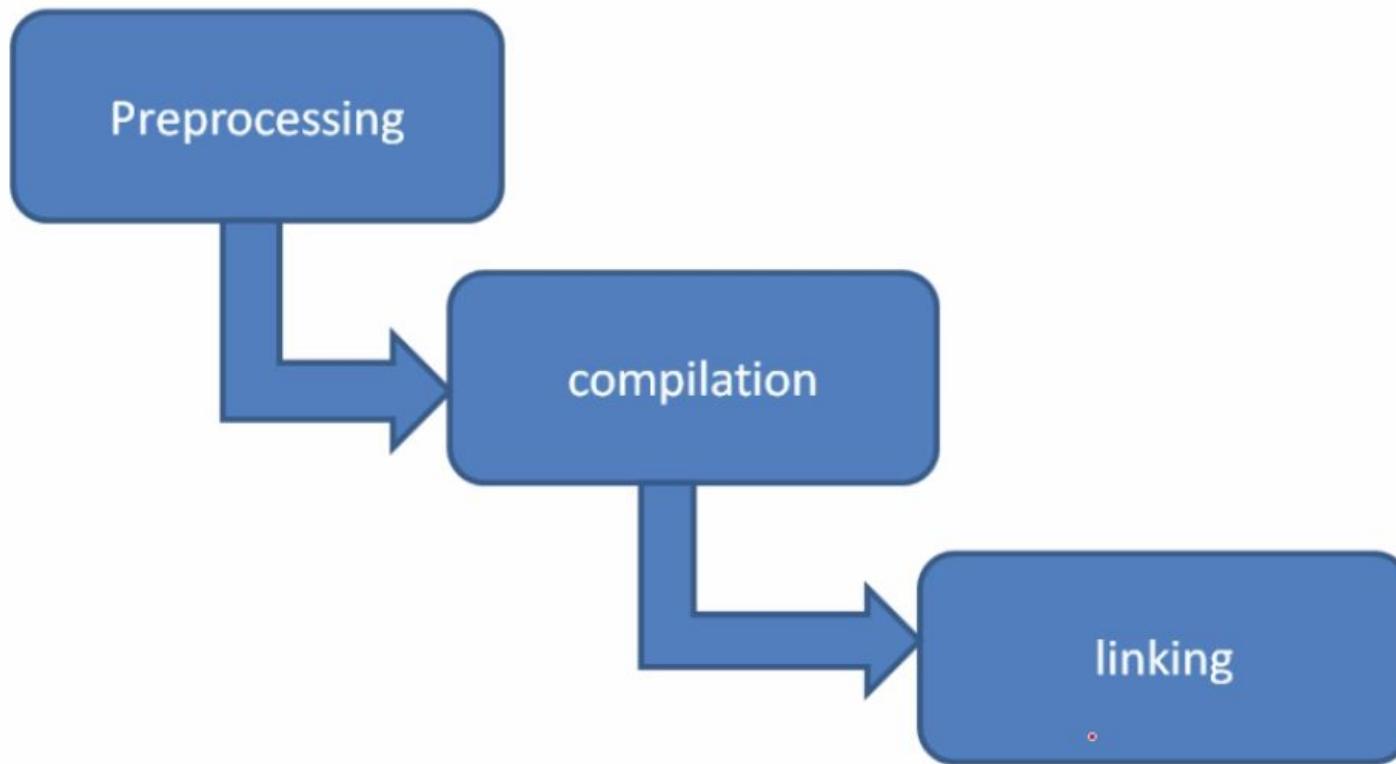
Enter location here

main:

08000290:	push	{r7, lr}
08000292:	add	r7, sp, #0
37		data.data1 = 0xAA;
08000294:	ldr	r3, [pc, #112] ; (0x8000308
08000296:	movs	r2, #170 ; 0xaa
08000298:	strb	r2, [r3, #0]
38		data.data2 = 0xFFFFFFFF,
0800029a:	ldr	r3, [pc, #108] ; (0x8000308
0800029c:	movs	r2, #0
0800029e:	orn	r2, r2, #17
080002a2:	strb	r2, [r3, #1]
080002a4:	movs	r2, #0
080002a6:	orn	r2, r2, #17
080002aa:	strb	r2, [r3, #2]
080002ac:	mov.w	r2, #4294967295
080002b0:	strb	r2, [r3, #3]
080002b2:	mov.w	r2, #4294967295
080002b6:	strb	r2, [r3, #4]
39		data.data3 = 0x55;
080002b8:	ldr	r3, [pc, #76] ; (0x8000308
080002ba:	movs	r2, #85 ; 0x55
080002bc:	strb	r2, [r3, #5]



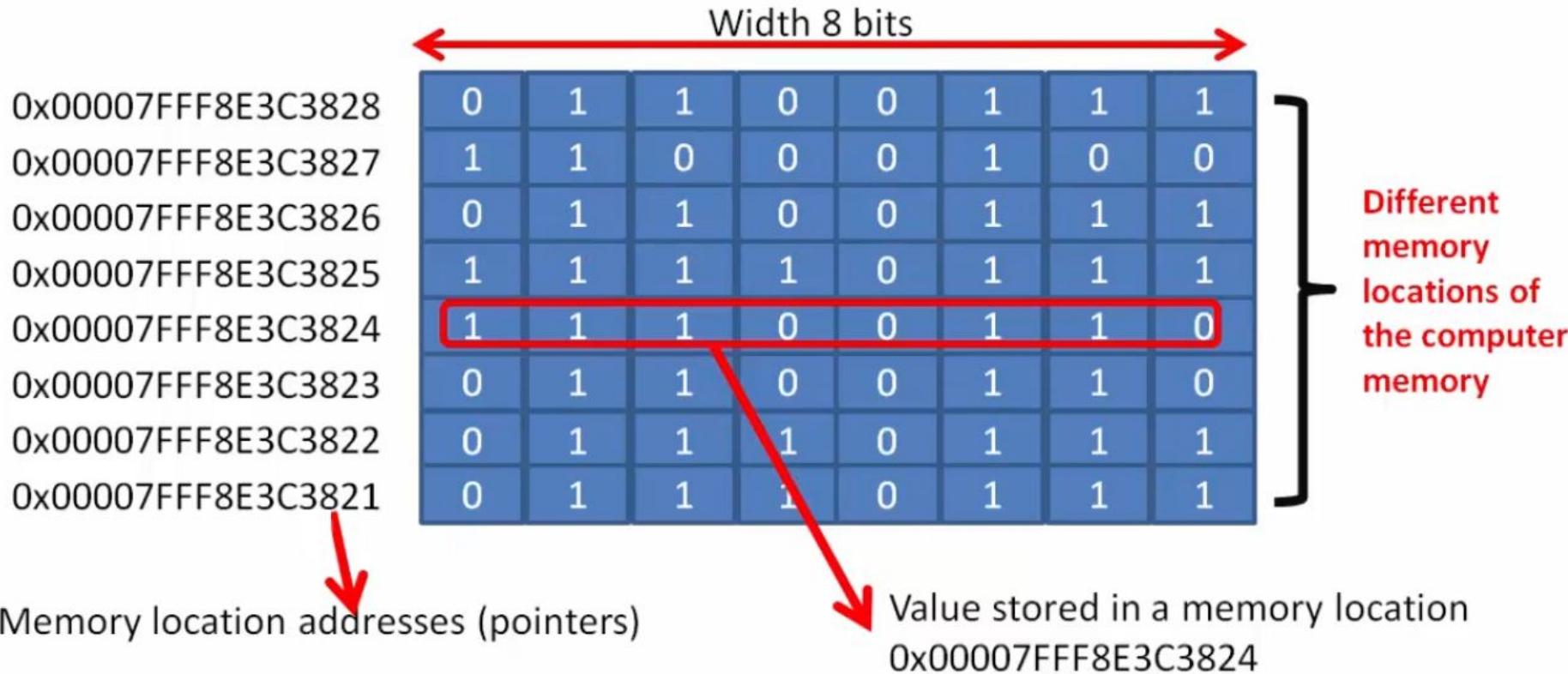
Summary of build process



Pointers in ‘C’

Pointers in 'C'

- Pointers are one of the essential programming features which are available in 'C'.
- Pointers make 'C' programming more powerful
- Pointers are heavily used in embedded 'C' programming to
 - Configure the peripheral register addresses
 - Read/Write into peripheral data registers
 - Read/Write into SRAM/FLASH locations and for many other things.



On 64 bit machine , the pointer size (memory location address size) is 8 bytes (64bit)

Now, let's see how to store a pointer inside the program.

Pointer variable definition

<pointer data type > <Variable Name > ;

Pointer data types

During variable declaration asterisk(*) is used to differentiate between a pointer variable declaration and a non pointer variable declaration.

char*

int*

long long int*

float*

double*

unsigned char*

unsigned int*

unsigned long long int*

unsigned float*

unsigned double*

Pointer variable definition and initialization

This is a pointer variable
of type **char***

```
char* address1 = (char*) 0x00007FFF8E3C3824;
```



Compiler allocates 8 bytes for this variable to store this pointer.



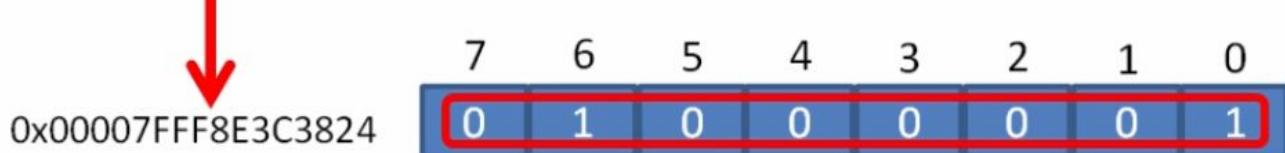
0x1F007FFF8E3C4828
0x1F007FFF8E3C4827
0x1F007FFF8E3C4826
0x1F007FFF8E3C4825
0x1F007FFF8E3C4824
0x1F007FFF8E3C4823
0x1F007FFF8E3C4822
Address of the pointer variable 0x1F007FFF8E3C4821

address1

0x00
0x00
0x7F
0xFF
0x8E
0x3C
0x38
0x24

Pointer stored in a pointer variable

Pointer variable creation and initialization



0x00007FFF8E3C3824

0x1F007FFF8E3C4821

address1

An initialized pointer variable

0x85

0x00007FFF8E3C3824

A memory location address and value

```
char* address1  
int* address1  
long long int* address1  
double* address1
```



The compiler will always reserve **8 bytes** for the pointer variable irrespective of their pointer data type.

In other words, the pointer data type doesn't control the memory size of the pointer variable.

Pointer variable definition and initialization

Then, what is the purpose of mentioning “Pointer data type”?

?

char* address1 = **(char*) 0x00007FFF8E3C3824;**

?

char* address1 = (**char***) 0x00007FFF8E3C3824;



*The **pointer** data type decides the behavior of the operations carried out on the pointer variable.*

Operations : read, write, increment, decrement

```
/* Read operation on address1 variable yields 1 byte of data */
char* address1 = (char*) 0x00007FFF8E3C3824;

/* Read operation on address1 variable yields 4 bytes of data */
int* address1 = (int*) 0x00007FFF8E3C3824;

/* Read operation on address1 variable yields 8 bytes of data */
long long int* address1 = (long long int*) 0x00007FFF8E3C3824;
```

Pointer variable to char type data

```
/* Read operation on address1 variable yields 1 byte of data */  
char* address1 = (char*) 0x00007FFF8E3C3824;
```

Pointer variable to int type data

```
/* Read operation on address1 variable yields 4 bytes of data */  
int* address1 = (int*) 0x00007FFF8E3C3824;
```

```
/* Read operation on address1 variable yields 8 bytes of data */  
long long int* address1 = (long long int*) 0x00007FFF8E3C3824;
```

Pointer variable to long long int type data

Read operation on the pointer

```
char* address1 = (char*) 0x00007FFF8E3C3824;
```

Read data from the pointer

```
char data = *address1; //dereferencing a pointer to read data
```

1 byte of data is read from the pointer and stored in to “data” variable

* : “Value at Address” Operator

& : “Address of” operator

0x00007FFF8E3C3824

0x1F007FFF8E3C4821

address1

An initialized pointer variable

```
char data = *address1;  
(data = 0x85)
```

0x85

0x00007FFF8E3C3824

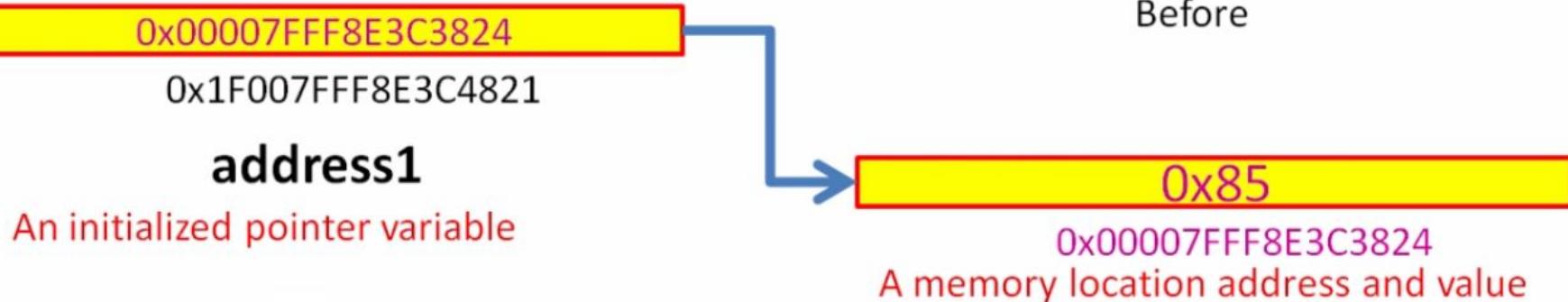
A memory location address and value

Write operation on the pointer

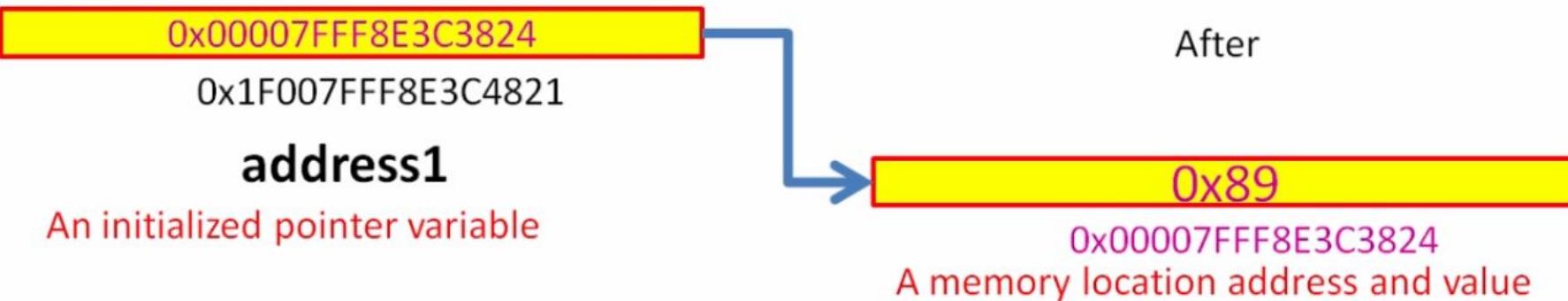
```
char* address1 = (char*) 0x00007FFF8E3C3824;
```

Write data to a pointer

```
*address1 = 0x89; //dereferencing a pointer to write data
```



`*address1 = 0x89;`



Exercise

- 1) Create a char type variable and initialize it to value 100
- 2) Print the address of the above variable.
- 3) Create a pointer variable and store the address of the above variable
- 4) Perform read operation on the pointer variable to fetch 1 byte of data from the pointer
- 5) Print the data obtained from the read operation on the pointer.
- 6) Perform write operation on the pointer to store the value 65
- 7) Print the value of the variable defined in step 1

Bitwise Operators in ‘C’

Bitwise Operators in 'C'



(bitwise AND)



(bitwise Right Shift)



(bitwise OR)



(bitwise NOT) (Negation)



(bitwise Left Shift)



(bitwise XOR)

Difference between Logical operator and bitwise operator

- `&&` is a ‘logical AND’ operator
- `&` is a ‘bitwise AND’ operator

char A = 40;

C = A && B; ?

C = A & B; ?

char B = 30;

char A = 40; char B = 30; char C;

C = A && B;
(Logical)

C = A & B;
(Bitwise)

C=1;

A b 00101000
&
B b 00011110

C= b 00001000

Bitwise
operation

```
char A = 40; char B = 30; char C;
```

```
C = A || B;
```

```
C=1;
```

```
C = A | B;
```

A b 00101000
|
B b 00011110
—————
C= b 00111110

Bitwise
operation

```
char A = 40;  char B = 30;  char C;
```

C = ! A;

C=0;

C = ~A;

A b 00101000

C= ~A b 11010111

C= -41

Bitwise
operation

char A = 40; **char** B = 30; **char** C;

C = A ^ B;

Truth table for XOR Gate

INPUTS		OUTPUTS
A	B	$Y = A \wedge B$
0	0	0
0	1	1
1	0	1
1	1	0

$$\begin{array}{r} A \\ \wedge \\ B \end{array} \begin{array}{l} b \\ \hline \end{array} \begin{array}{r} 00101000 \\ + 00011110 \\ \hline \end{array}$$

Bitwise
operation

$$C = \begin{array}{r} b \\ \hline 00110110 \end{array}$$

$$C = 54$$

Applicability of bitwise operations

In an Embedded C program, most of the time you will be doing,

- ✓ Testing of bits (&)
- ✓ Setting of bits (|)
- ✓ Clearing of bits (~ and &)
- ✓ Toggling of bits (^)

Exercise

- Write a program which takes 2 integers from the user , computes bitwise &,|,^ and ~ and prints the result.

Applicability of bitwise operations

In an Embedded C program, most of the time you will be doing,

- ✓ Testing of bits (&)
- ✓ Setting of bits (|)
- ✓ Clearing of bits (~ and &)
- ✓ Toggling of bits (^)

Exercise: Testing of bits

- Write a program to find out whether a user entered integer is even or odd.
- Print an appropriate message on the console.
- Use testing of bits logic

46 (0x2E)
lsb
b00101110

Number is EVEN

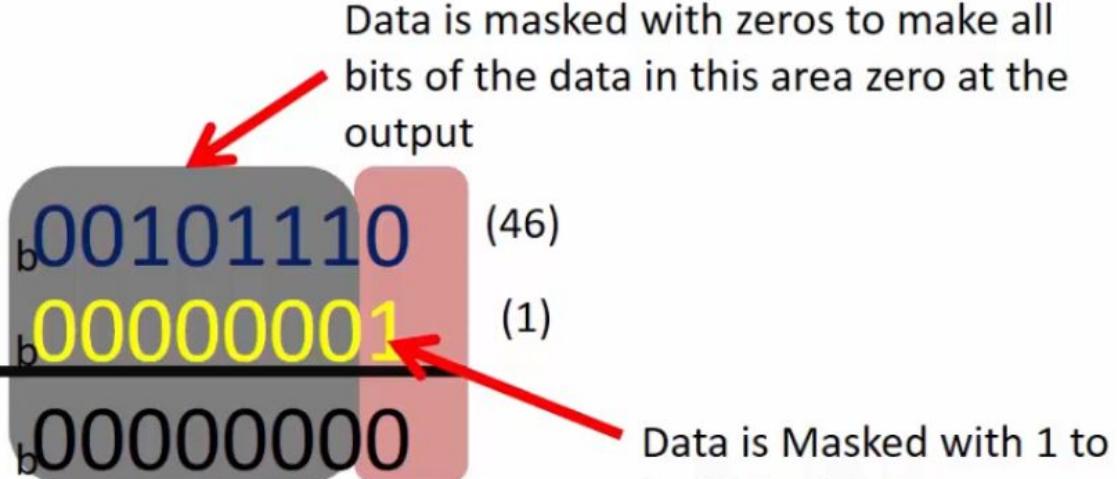
47 (0x2F)
lsb
b00101111

Number is ODD

Test the least significant bit of the number using bitwise operation
If the lsb is zero, then number is EVEN
If the lsb is one, then number is ODD

Bit-Masking

[input] number
&
[mask] Mask_value



Bit Masking is a technique in programming used to test or modify the states of the bits of a given data.

Modify : if the state of the bit is zero, make it one or if the state of the bit is 1 then make it 0

Test : check whether the required bit position of a data is 0 or 1

	7 6 5 4 3 2 1 0
[data]	00101110
&	
[Mask]	00000010
	<hr/>
[output]	00000010

[data]	10101110
&	
[Mask]	10000000
<hr/>	
[output]	10000000

[data]	00101110
&	
[Mask]	00000011

[output]	00000010
----------	----------

[data]	00101110
&	
[Mask]	00010000
<hr/>	
[output]	00000000

EVEN or ODD using Bitwise operation

```
If ( number & 1)
{
    print(number odd)
}else
{
    print(Number even)
}
```

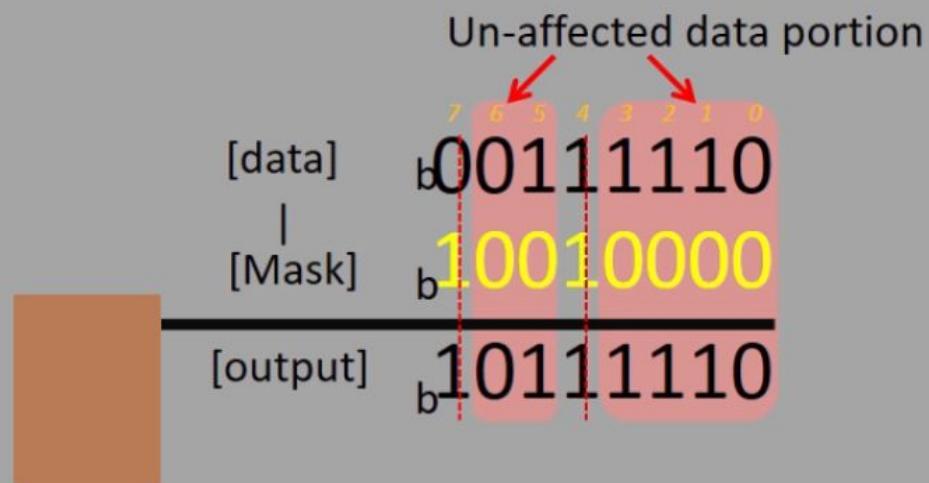
↗ Mask value

Exercise: Setting of bits

- Write a program to set(make bit state to 1) 4th and 7th-bit position of a given number and print the result.

Exercise: Setting of bits

[data]	b00111110
& [Mask]	b10010000
[output]	b00010000



'&' is used to 'TEST' not to 'SET'

'|' is used to 'SET' not to 'TEST'

Toggling of bits

[Led_state]	00000001
^	
[mask]	00000001
<hr/>	
[Led_state]	00000000
^	↑
[mask]	00000001
<hr/>	
[Led_state]	00000001
^	↑
[mask]	00000001
<hr/>	
[Led_state]	00000000
^	↑
[mask]	00000001
<hr/>	
[Led_state]	00000001

`Led_state = Led_state ^ 0x01`

Output toggles

Applicability of bitwise operations in Embedded Systems

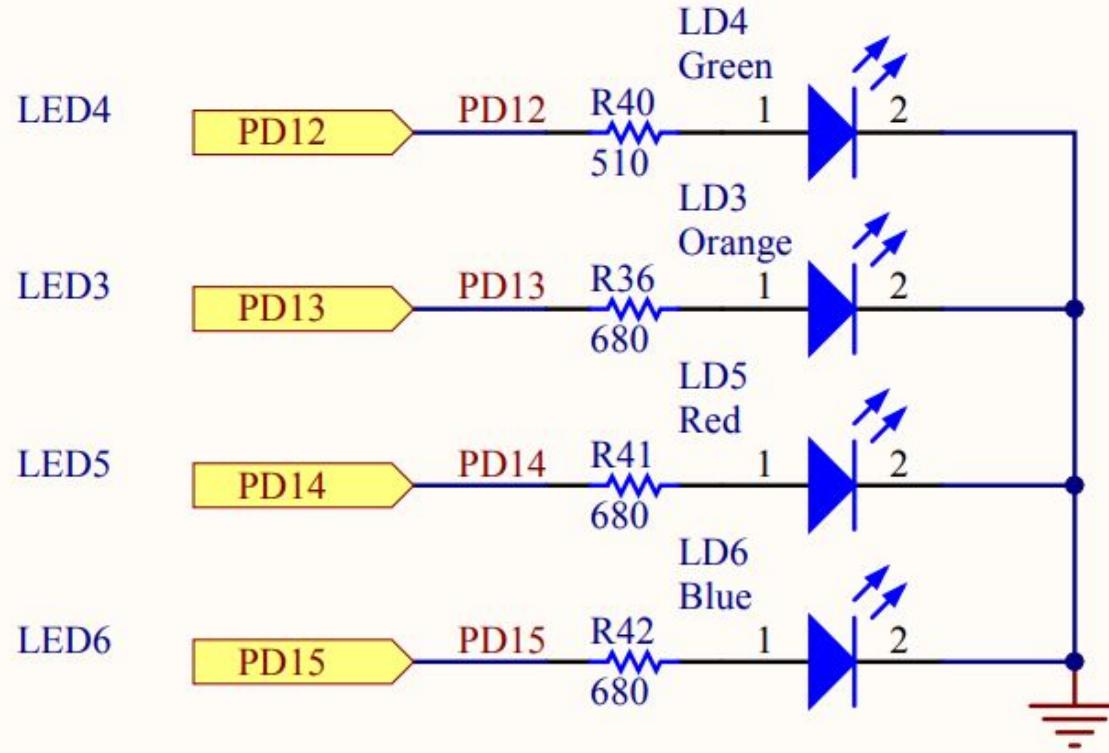
Exercise

- Write a program to turn on the LED of your target board
- For this exercise we need the knowledge of
 - Pointers
 - Bitwise operations
 - Hardware connections

Hardware connections

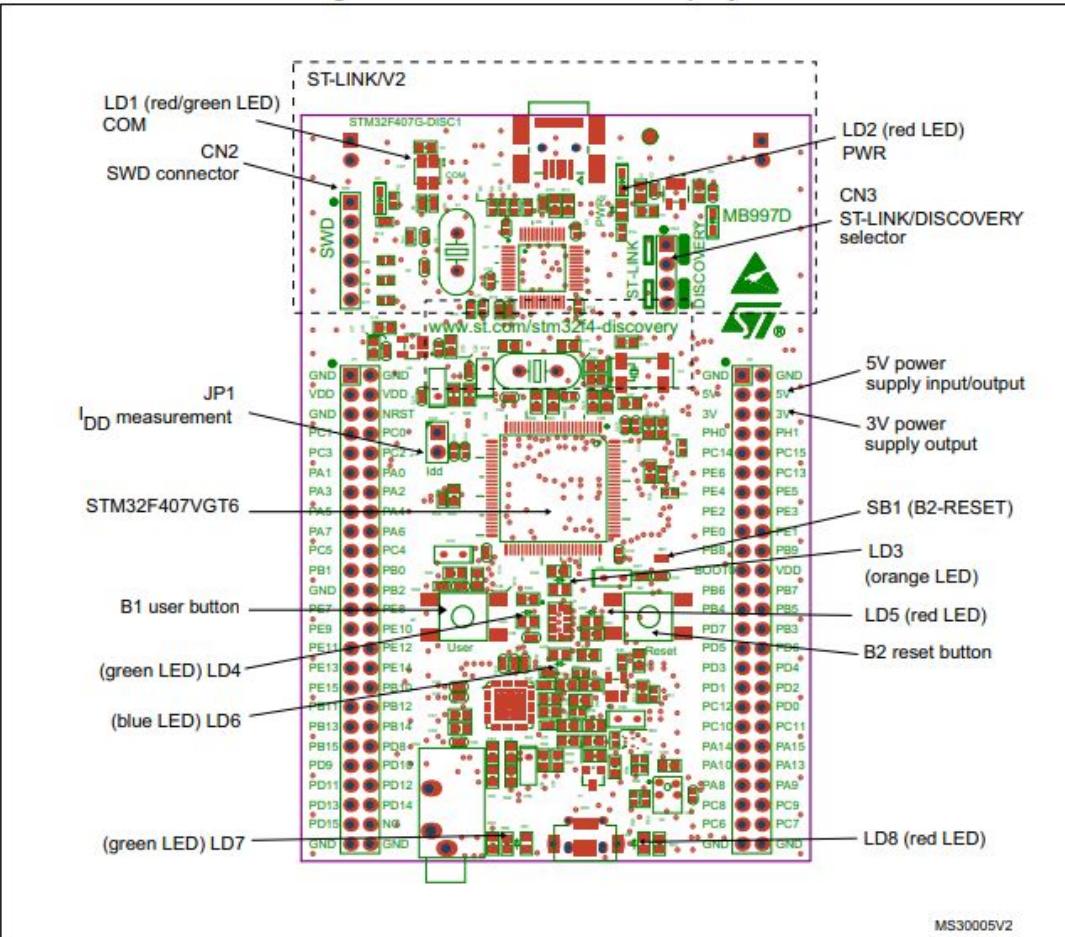
- Lets understand how external hardware (LED) is connected to MCU
 - Refer schematic of the board you are using

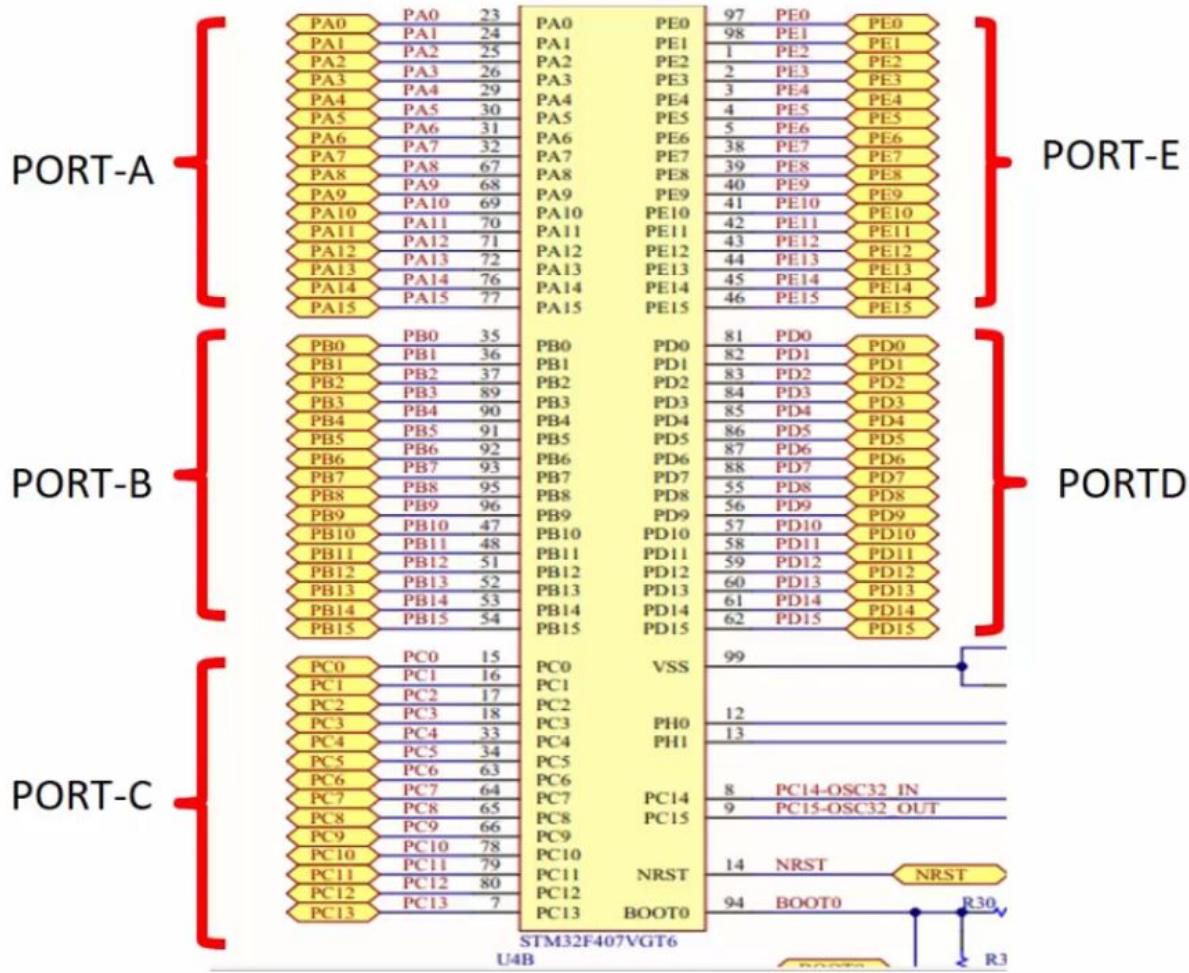
<https://www.st.com/en/evaluation-tools/stm32f4discovery.html#cad-resources>



LEDs

Figure 3. STM32F4DISCOVERY top layout



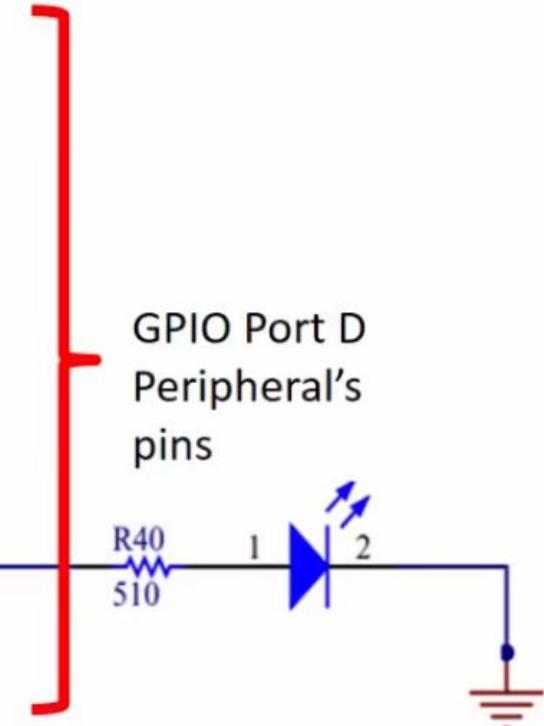


In STM32Fx based MCUs , each port has 16 pins where you can connect external peripherals .
 (LED, Display , button, Bluetooth transceiver , external memory (e.g. EEPROM), Joy stick , keypad ,etc)

How do you access 12th pin of GPIO PORT-D peripheral from software ?

PB0	PB0	35	PB0	PD0	81
PB1	PB1	36	PB1	PD1	82
PB2	PB2	37	PB2	PD2	83
PB3	PB3	89	PB3	PD3	84
PB4	PB4	90	PB4	PD4	85
PB5	PB5	91	PB5	PD5	86
PB6	PB6	92	PB6	PD6	87
PB7	PB7	93	PB7	PD7	88
PB8	PB8	95	PB8	PD8	55
PB9	PB9	96	PB9	PD9	56
PB10	PB10	47	PB10	PD10	57
PB11	PB11	48	PB11	PD11	58
PB12	PB12	51	PB12	PD12	59
PB13	PB13	52	PB13	PD13	60
PB14	PB14	53	PB14	PD14	61
PB15	PB15	54	PB15	PD15	62

GPIO Port D
Peripheral's
pins



Now your goal is to control the I/O pin PD12's state either HIGH or LOW through software to make LED turn ON or OFF.

PD12 : 12th pin of the GPIO PORT D peripheral

*GPIO: General Purpose Input Output

It also has set of registers which are used to control pin's mode, state and other functionalities

GPIO D
peripheral

MICROCONTROLLER

81	PD0	PD0
82	PD1	PD1
83	PD2	PD2
84	PD3	PD3
85	PD4	PD4
86	PD5	PD5
87	PD6	PD6
88	PD7	PD7
55	PD8	PD8
56	PD9	PD9
57	PD10	PD10
58	PD11	PD11
59	PD12	PD12
60	PD13	PD13
61	PD14	PD14
62	PD15	PD15

Bitwise Operators in 'C'



(bitwise AND)



(bitwise OR)



(bitwise Left Shift)



(bitwise Right Shift)



Unary
(bitwise NOT) (Negation)



(bitwise XOR)

Bitwise right shift operator(>>)

- This operator takes 2 operands
- Bits of the 1st operand will be right shifted by the amount decided by the 2nd operand
- Syntax : **operand1 >> operand2**
- Lets see an example

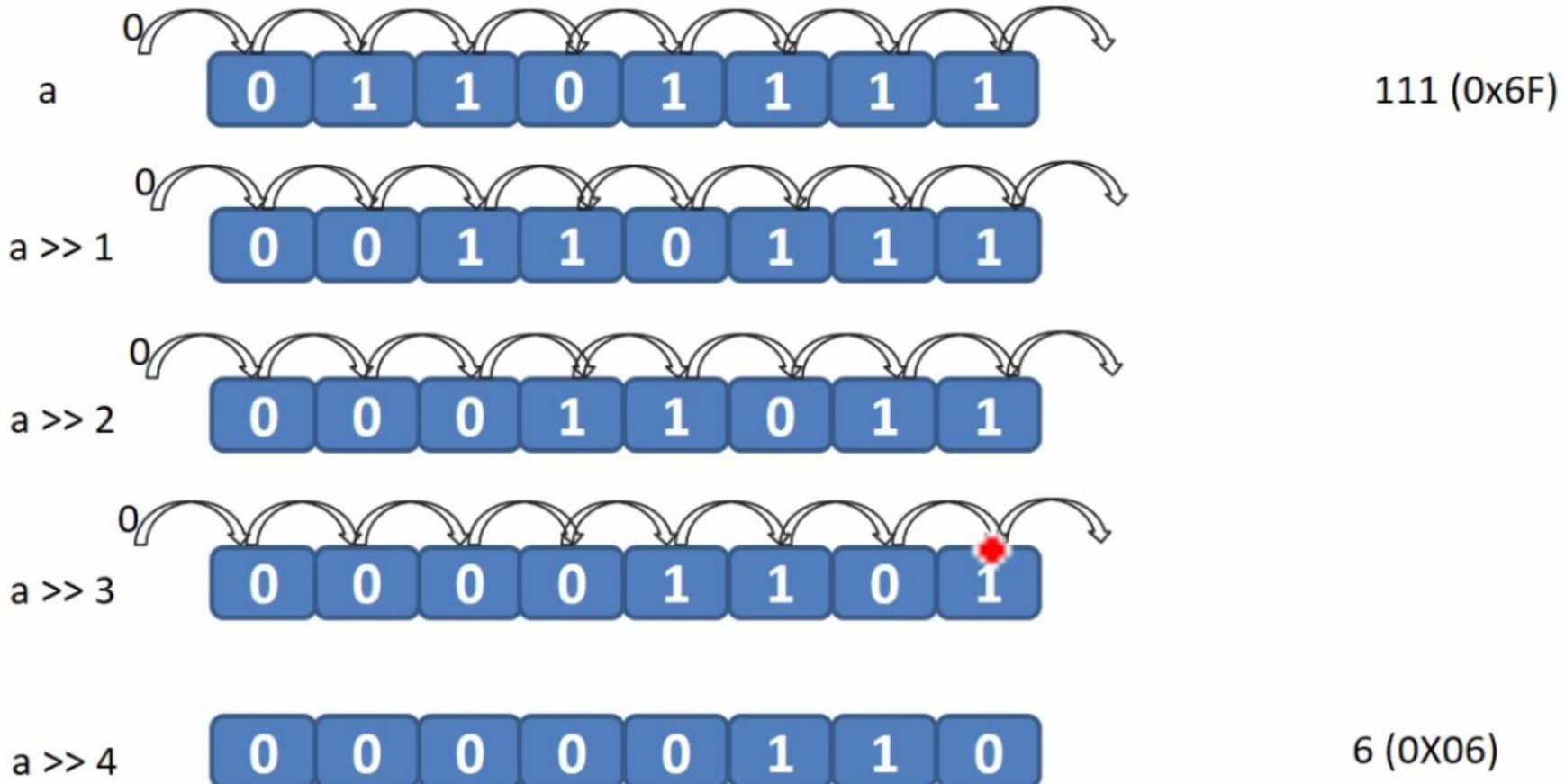
```
char a = 111
```

```
char b = a >> 4
```

```
b = ?
```

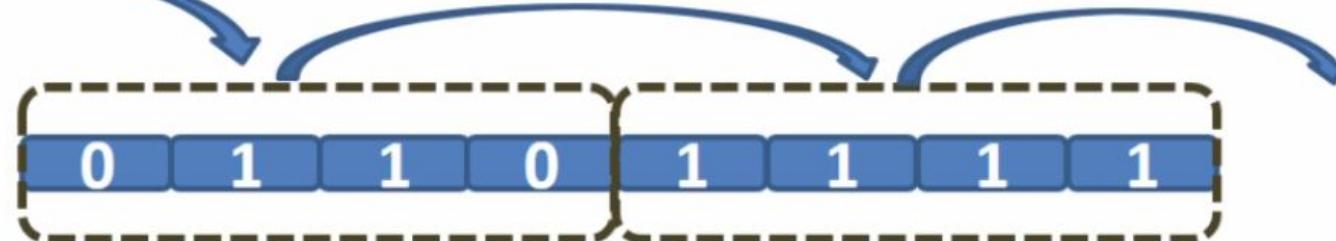


Now, 'a' must be shifted by 4 times to the right

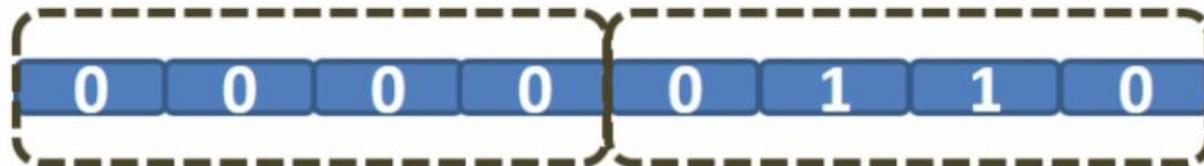




a

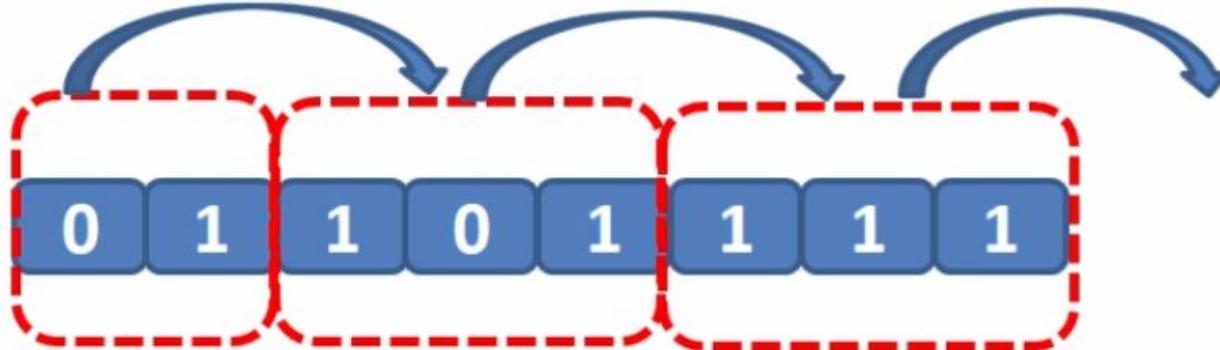


$a \gg 4$



0 0 0

a



$A \gg 3$



Bitwise Operators in 'C'



(bitwise AND)



(bitwise Right Shift)



(bitwise OR)



(bitwise NOT) (Negation)



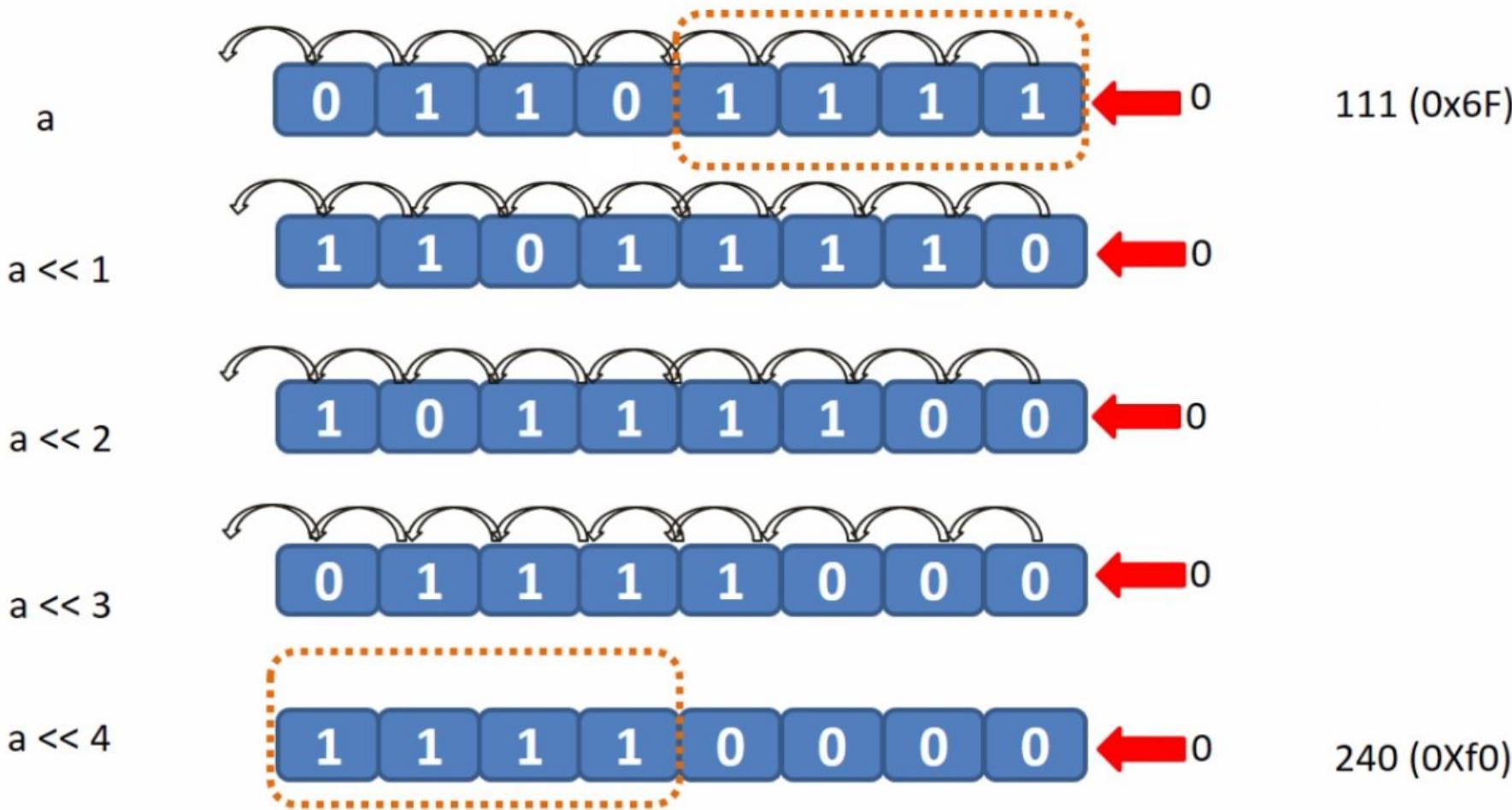
(bitwise Left Shift)



(bitwise XOR)

Bitwise left shift operator(<<)

- This operator takes 2 operands
- Bits of the 1st operand will be left shifted by the amount decided by the 2nd operand
- Syntax : **operand1 << operand2**
- Lets see an example



<< VS >>

<< (left shift)	>> (right shift)
$4 << 0 => 4$	$128 >> 0 => 128$
$4 << 1 => 8$	$128 >> 1 => 64$
$4 << 2 => 16$	$128 >> 2 => 32$
$4 << 3 => 32$	$128 >> 3 => 16$
$4 << 4 => 64$	$128 >> 4 => 8$
$4 << 5 => 128$	$128 >> 5 => 4$

A value will be multiplied by 2 for each left shift

A value will be divided by 2 for each right shift

Applicability of bitwise shift operations
in embedded programming code

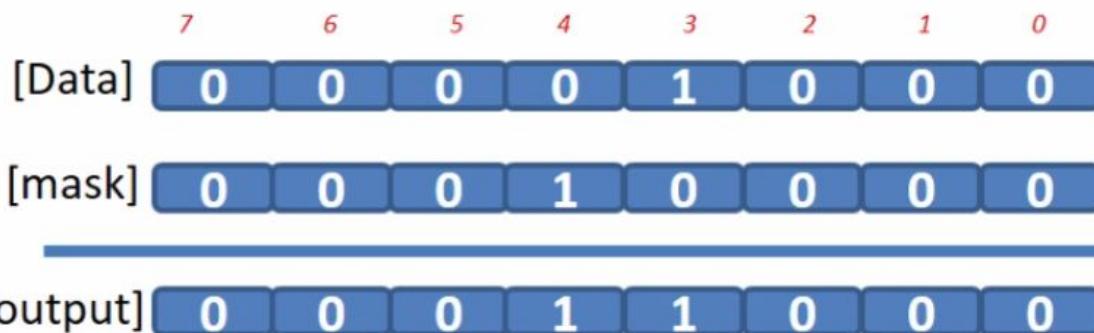
Applicability

- Bitwise shift operators are very much helpful in bit masking of data along with other bitwise operators
- Predominantly used while setting or clearing of bits
- Lets consider this problem statement :Set 4th bit of the given data

Set 4th bit of the given data

Data = 0x08

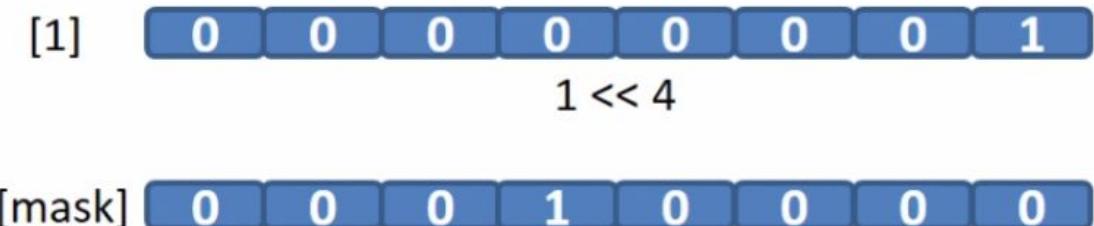
Data = Data | 0x10
= 0x18



Set 4th bit of the given data

Data = 0x108

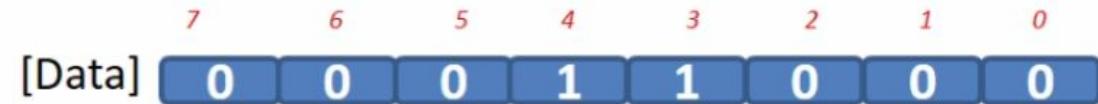
Data = Data | (1 << 4)
= 0x18



Clear 4th bit of the given data

Data = 0x18

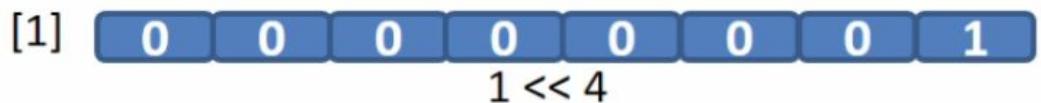
Data = Data & 0xEF
= 0x08



Clear 4th bit of the given data

Data = 0x18

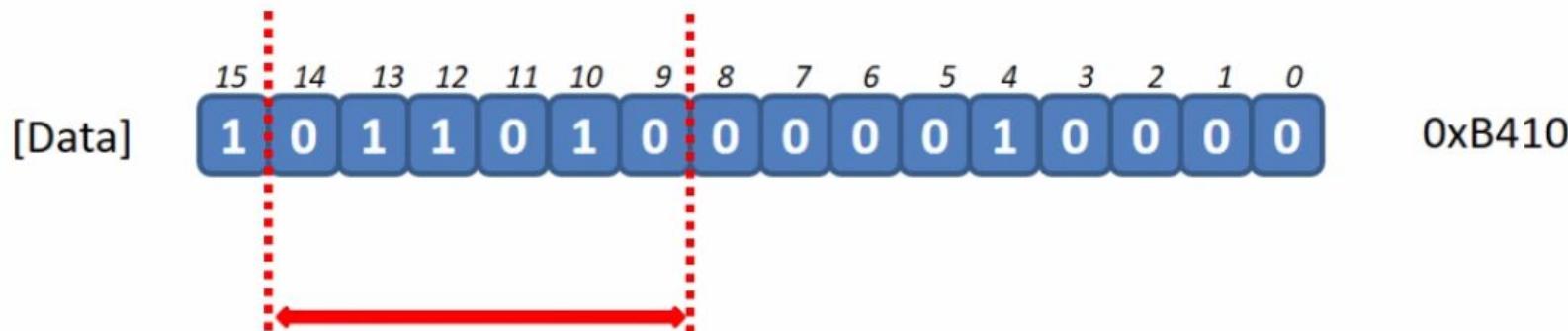
Data = Data & ~(1 << 4)
= 0x08



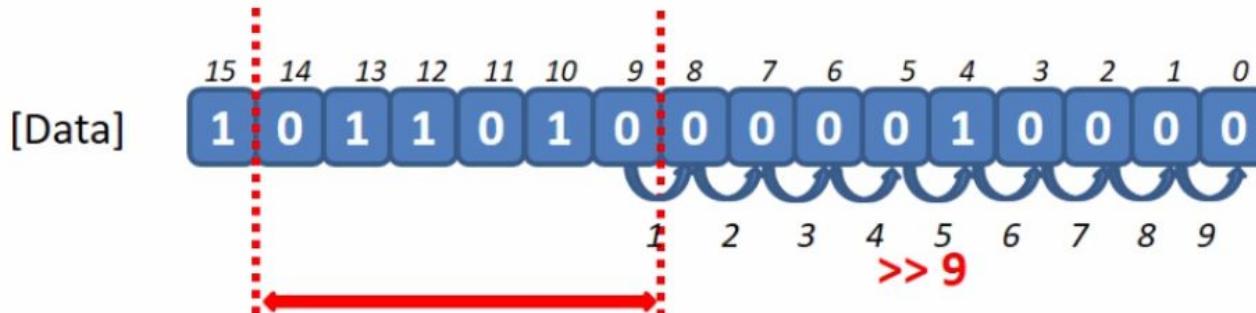
Bit extraction

- Lets consider this problem statement

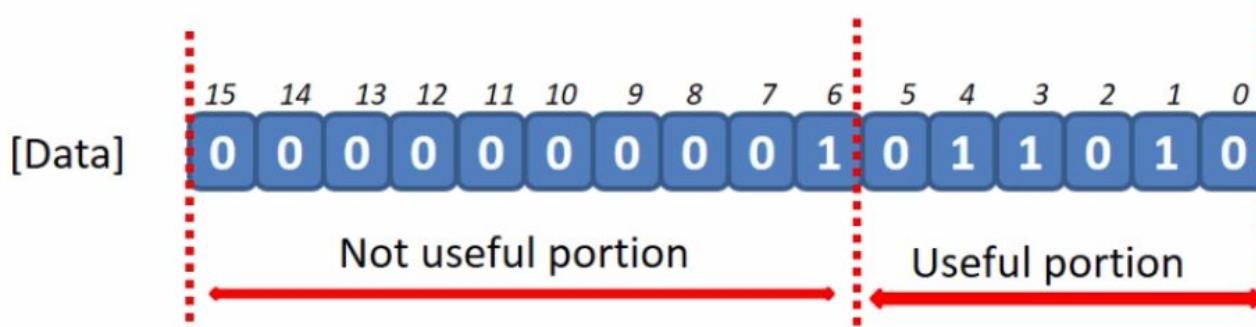
Extract bit positions from 9th to 14th [14:9] in a given data and save it in to another variable .



- 1) Shift the identified portion to right hand side until it touches the least significant bit (0th bit)
- 2) Mask the value to extract only 6 bits [5:0] and then save it in to another variable

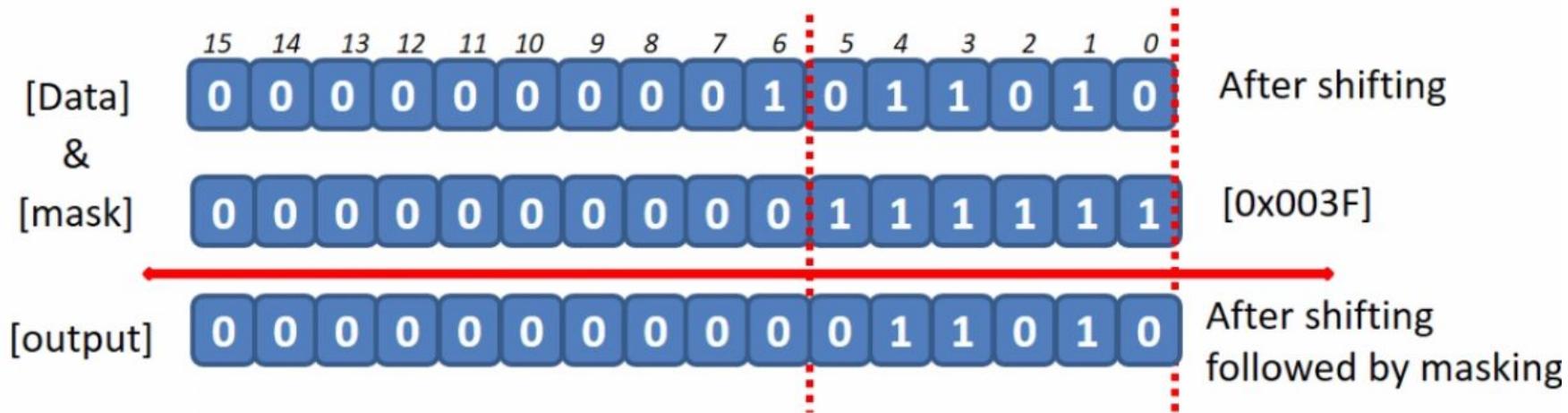


- 1) Shift the identified portion to right hand side until it touches the least significant bit (0th bit)



Mask Data to retain useful portion and zero out not useful portion

2) Mask the new value to extract only first 6 bits[5:0] and then save it in to another variable



```
uint16_t Data = 0xB410;  
uint8_t output ;  
  
output = (uint8_t) ((Data >> 9) & 0x003F)
```

Pre-processor Directives

Pre-processor Directives

- In C programming pre-processor directives are used to affect compile-time settings
- Pre-processor directives are also used to create macros used as a textual replacement for numbers and other things.
- Pre-processor directives begin with the “#” symbol.
- Pre-processor directives are resolved or taken cared during the pre-processing stage of compilation

Pre-processor Directives supported in ‘C’

Objective	Syntax of pre-processor directive
Macros	<code>#define <identifier> <value></code> Used for textual replacement
File inclusion	<code>#include <std lib file name></code> <code>#include “user defined file name”</code> Used for file inclusion
Conditional compilation	<code>#ifdef , #endif, #if , #else, #ifndef, #undef</code> Used to direct the compiler about code compilation
Others	<code>#error #pragma</code>

Macros in 'C' (#define)

- Macros are written in 'C' using **#define** pre-processor directive
- Macros are used for textual replacement in the code, commonly used to define constants.
- Syntax : **#define <Identifier> <value>**
- Example : **#define MAX_RECORD 10**

Use case

```
#include <stdio.h>
#include <stdint.h>

int main(void)
{
    uint8_t age = get_voter_age();

    if(age < 18)
    {
        printf("you cannot vote !\n");
    }
    else
    {
        printf("Congratulations ! you can vote\n");
    }
}
```

```
#include <stdio.h>
#include <stdint.h>

//This is a macro which defines minimum age for evaluation
#define MIN_AGE 18

int main(void)
{
    uint8_t age = get_voter_age();

    if(age < MIN_AGE)
    {
        printf("you cannot vote !\n");
    }
    else
    {
        printf("Congratulations ! you can vote\n");
    }
}
```

During pre-processing stage of the compilation process, macro names(identifiers) are replaced by the associated values inside the program.

```
#include <stdio.h>
#include <stdint.h>

//This is a macro which defines minimum age for evaluation
#define MIN_AGE 18

int main(void)
{
    uint8_t age = get_voter_age();

    if(age < MIN_AGE)
    {
        printf("you cannot vote !\n");
    }
    else
    {
        printf("Congratulations ! you can vote\n");
    }
}
```

This is NOT a variable . This is an identifier (macro name)

Just a textual replacement for a number

In Embedded system programming , we use lots of 'C' macros to define pin numbers, pin values, crystal speed, peripheral register addresses, memory addresses and for other configuration values.



```
#define PIN_8          8
#define GREE_LED        PIN_8
#define LED_STATE_ON    1
#define Led_state_off   0
#define XTAL_SPEED      8000000UL
#define FLASH_BASE_ADDR 0x08000000UL
#define SRAM_BASE_ADDR  0x20000000ul

#define PI      3.1415; 
```

function-like macros

To define a function-like macro, use the same ‘**#define**’ directive, but put a pair of parentheses immediately after the macro name.

```
#define PI_VALUE 3.1415
```

```
#define AREA_OF_CIRCLE(r) PI_VALUE * r * r
```

areaCircle = AREA_OF_CIRCLE(radius); Original 'C' statement

areaCircle = PI_VALUE * radius * radius;

areaCircle = 3.1415 * radius * radius;

Processed by pre-processor

This macro is poorly written and dangerous

```
#define AREA_OF_CIRCLE(r) PI_VALUE * r * r
```



You have to be careful with
macro ‘values’ when you are
doing some “operations”
using multiple “operands.”

```
#define PI_VALUE 3.1415
```

```
#define AREA_OF_CIRCLE(r) PI_VALUE * r * r
```

```
areaCircle = AREA_OF_CIRCLE(radius+1);      Original 'C' statement
```

```
areaCircle = 3.1415 * radius+1 * radius+1    Processed by pre-processor
```

This macro is poorly written and dangerous



```
#define AREA_OF_CIRCLE(r) PI_VALUE * r * r
```



```
#define AREA_OF_CIRCLE(r) ( (PI_VALUE) * (r) * (r) )
```

Best practises while writing Macros in ‘C’

1. Use meaningful macro names
2. It's recommended that you use UPPER case letters for macro names to distinguish them from variables.
3. Remember, macro's names are not variables. They are labels or identifiers, and they don't consume any code space or ram space during compile time or run time of the program.
4. make sure that parentheses surround the macro value
5. While using function-like macros or when you are using macros along with any operators, always surround the operands with parentheses.

Conditional compilation using
pre-processor directives

Conditional compilation in ‘C’

```
#if  
#ifdef  
#endif  
#else  
#undef  
#ifndef
```

Example of condition compilation directives.

These directives help you to include or exclude individual code blocks based on various conditions set in the program

#if and #endif directive

Syntax :

```
#if <constant expression>
```

```
#endif
```

Example :

```
#if 0
```

```
//code block
```

```
#endif
```

This directive checks whether the constant expression is zero or non zero value. If constant is 0, then the code block will note be included for the code compilation. If constant is non zero, the code block will be included for the code compilation.

#endif directive marks the end of scope of #if, #ifdef, #ifndef, #else, #elif directives

#if ...#else#endif

Syntax :

#if <constant expression>

#else

#endif

Example :

#if 1

//Code block-1

#else

//Code block-2

#endif

#ifdef

Syntax :

```
#ifdef <identifier>
```

```
#endif
```

#ifdef directive checks whether the identifier is defined in the program or not. If the identifier is defined, the code block will be included for compilation.

Example:

```
#ifdef NEW_FEATURE  
//Code block  
#endif
```

2. Execute circle area calculation code block only if **AREA_CIR** macro is defined and execute triangle area calculation code block only if **AREA_TRI** macro is defined in the program

3. Execute circle area code block only if **AREA_TRI** is not defined

#ifndef

Syntax :

```
#ifndef <identifier>
```

```
#endif
```

Example :

```
#ifndef NEW_FEATURE  
//Code block for old feature  
#endif
```

#ifndef directive checks whether the identifier is defined in the program or not. If the identifier is not defined then the code block will be included for compilation.

#ifdef and #else

```
#ifdef NEW_FEATURE
//Code block of new feature
#else
//code block for old feature
#endif
```

#if and 'defined' operator

- The defined operator is used when you want to check definitions of multiple macros using single #if, #ifdef or #ifndef directives
- You can also use 'C' logical operators such as AND, NOT, OR with 'defined' operator

Thank You