Homework 12

Karan Sarkar sarkak2@rpi.edu

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[array([[-0.83224736, -0.83224736]], dtype=float32), array([-0.83224736], dtype=float32), array([[-0.13732731]], dtype=float32), array([[-0.21621275], dtype=float32)]]

1. (a) [[array([[-0.8322436, -0.83222436]], dtype=float32), array([-0.21621275], dtype=float32)]]

[array([[-0.83222436, -0.83222436]], dtype=float32), array([-0.83222436], dtype=float32)]]

(b) [[-0.13726544]], dtype=float32), array([-0.2169545], dtype=float32)]

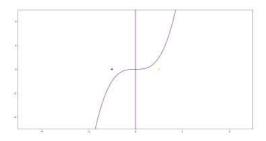
2. (a) [[-0.13726544]], dtype=float32), array([-0.2169545], dtype=float32)]

(b) [[-0.13726544]], dtype=float32), array([-0.2169545], dtype=float32)]

2. (a) [[-0.13726544]], dtype=float32), array([-0.2169545], dtype=float32)]

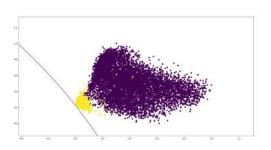
(b) [[-0.13726544]], dtype=float32), array([-0.2169545], dtype=float32)]

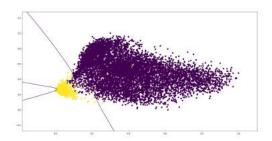
(b) i. The data points are (1,0) and (-1,0) ii. The optimal hyperplane is $z_1 = 0$.



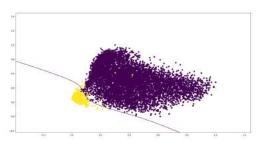
(c)

- (d) $K(x,y) = (x_1^3 x_2)(y_1^3 y_2) + x_1x_2y_1y_2$.
- (e) The decision boundary is $x_1^3 x_2 = 0$.
- 4. (a) Here is the decision boundaries for a small C of 0.01 and 1000000 respectively.





(b) The parameter C says how much margin the decision boundary should give data points. When C is small it gives a large boundary yielding a more simple less complex boundary. When C is large, it gives a small margin yielding a more curvy and complex function.



(c)

This uses C = 100.

5. The linear model performs the worst with a test error of 0.0299. The KNN performs exceptionally well at a test error of 0.00644. The RBF network performs similarly at 0.00722. The neural network also performs poorly at test error of 0.012. Finally, the SVM performs best at a test error of 0.005.

The SVM is very successful. Unfortunately it is a cubic algorithm and thus may not scale well to larger datasets. The Neural Network's linear complexity may allow it to outperform the SVM for very large datasets.