

PX2IO – Input / Output and Servo Module

QUICK START – HARDWARE VERSION 1.1

Description

PX2IO is an input/output board providing servo and receiver inputs/outputs. It also provides four solid-state relays and a wide range of additional I/O connectors. The 30-pin expansion bus allows to combine it with other modules to provide additional I/O.

<http://github.com/qgc/hardware>

Features

- 24 Mhz Cortex-M3 I/O multiplexer
- 6-18V wide supply in, 5V / 2.25 A and 3.3 V / 1 A supply out
- 8x high-speed servo outputs (up to 400 Hz), max. 1 A combined
- PPM sum signal input
- Spektrum receiver input
- S-BUS compatible receiver input
- 2x 0-40 V, 1 A solid-state relay (MOSFET)
- 2x 5 V, 0.5 A solid-state switched 5 V supply (current-limiting)
- PX2 Expansion bus (PX2FMU: Flight Management Unit)
- 50x35x14 mm (1.38x1.97x0.55"), 20g, 30x30 mm mounting

Connectors, Jumpers and Dimensions

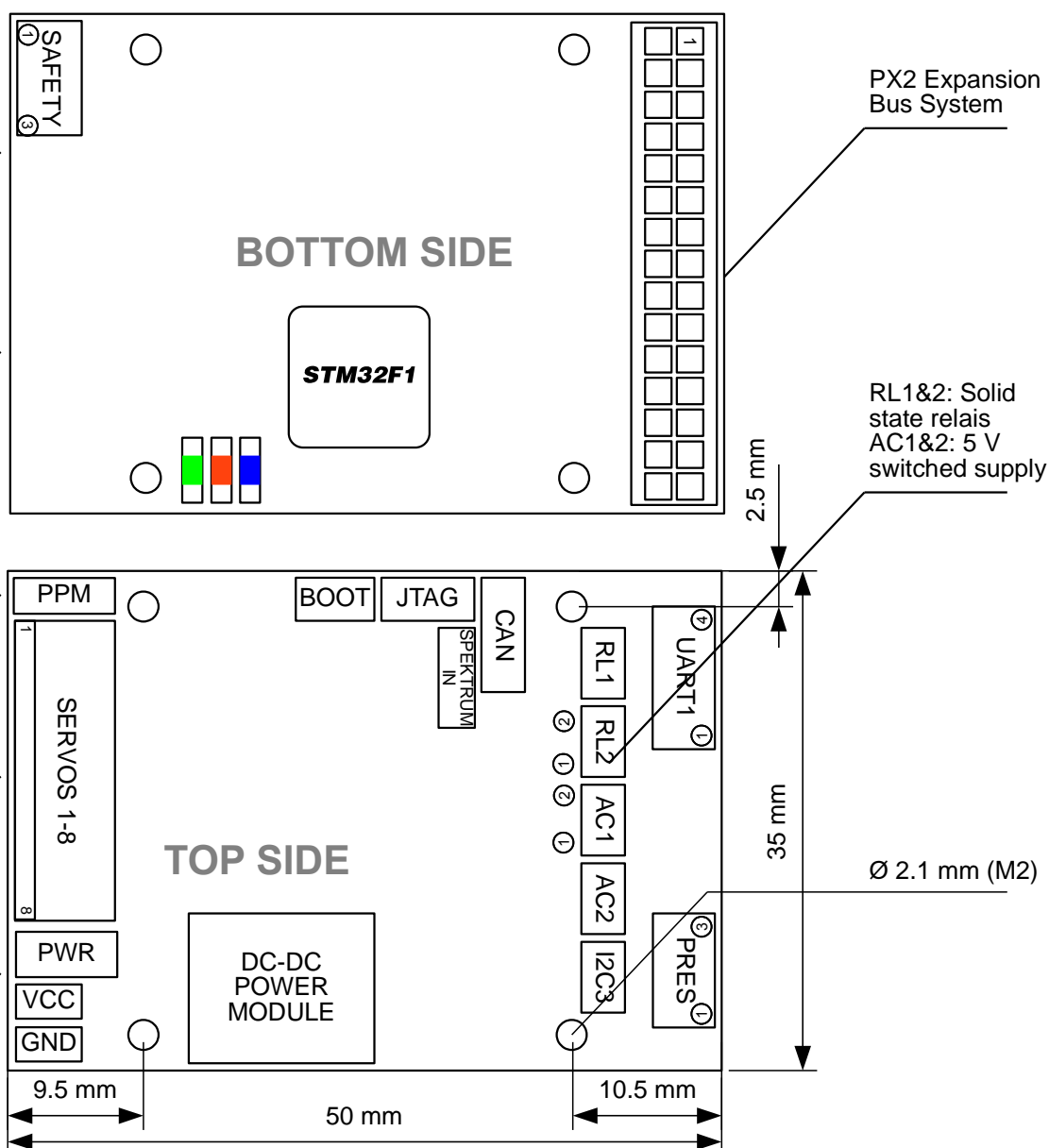
Safety switch connector

Status Leds
Green: Power on
Blue: Activity
Amber: Error

RC Receiver
PPM sum input or
S-Bus input

High-speed
Servo
Outputs

6-18 V, 2.25 A
Power in

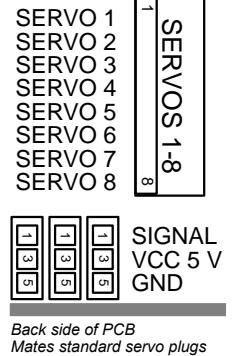


Pinout and absolute maximum Ratings

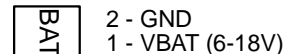
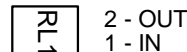
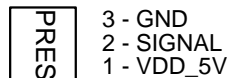
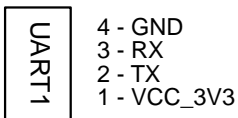
- Input: 6-18 V, max current: 2.5 A
- Accessory outputs: 5 V, 0.5 A current limited each
- Peripherals output: 3.3 V, 0.5 A current limited
- Servo Output: 5V, 1.0 A current limited
- Do NOT connect a 6 V servo system without REMOVING diode D1 before

VDD_5V	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30
GND	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
CAN2_RX	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
USART1_RX_EXT	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
I2C3_SDA	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
SPI3_MOSI	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
SPI3_NSS	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
UART5_RX	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
I2C2_SDA	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
USART2_RTS	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
USART2_RX	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
GPIO_EXT1	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
PC8	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
ADC123_IN11	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
ADC123_IN13	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	

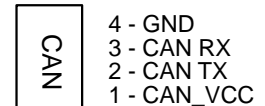
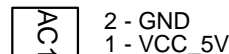
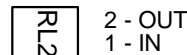
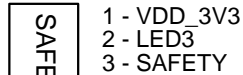
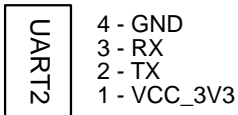
Mates 2 mm header: 3M "9532230-2000-AR-PR"



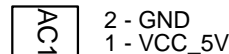
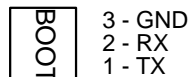
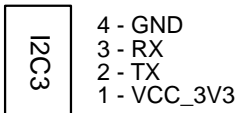
All connectors are oriented the same way as shown in the overview picture. Check the pin 1 markings in the overview if unsure.



Mates 2 pos JST PA housings
Part # PAP-02V-S(P)
Crimp terminals
Part# SPHD-001T-P0.5 (for AWG 22-26 wire)



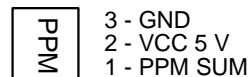
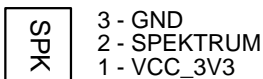
Mates 4 pos JST ZH housings
Part # ZHR-4
Crimp terminals
Part # SZH-002T-P0.5 (for AWG 28-26 wire)



Mates 2 pos Molex PicoBlade housings
Part # 51021-0200
Crimp terminals
Part # 50058-8000 (for AWG 28 wire)
Crimp tool
Part # 0638190400

Mates 4 pos Molex PicoBlade housings
Part # 51021-0400
Crimp terminals
Part # 50058-8000 (for AWG 28 wire)
Crimp tool
Part # 0638190400

Mates 3 pos Molex PicoBlade housings
Part # 51021-0300
Crimp terminals
Part # 50058-8000 (for AWG 28 wire)
Crimp tool
Part # 0638190400



Mates Spektrum RC receiver cables:
JST
Part #
Crimp terminals
Part # (for AWG xx wire)

Mates 3-pos servo cable. Solder cables into the holes and connect RC receiver with it.
Fits 0.1" header (both straight and right-angle)

Upgrading Firmware / Developing Custom Code

PX2IO is designed as failsafe board with a stable codebase. It's code is automatically updated by a connected PX2FMU board if necessary. Building custom firmware is only recommended for very advanced users. To develop custom code, follow the PX2FMU toolchain guide at: http://www.example.com/developers_guide

Contact, Copyleft and further Information

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Further information is available here:

- PX2FMU website
- Appropriate mailing list 1
- Appropriate community 1