2. THE MOORE-PENROSE PSEUDO-INVERSE EXERCISE

Creating Data.

A) Creating a random Matrix D of size mx4.

```
m=4
m = 4
D = randi([1,5],[m,4])
D = 4 \times 4
    4
         4
              4
                    5
    3
         3
              1
                    2
         1
              4
D(:,4) = 4*D(:,1) -3*D(:,2) +2*D(:,3) -1
D = 4 \times 4
    4
         4 4 11
    3
        3
             1
                   4
    1
              4
                   8
        1
    1
         2
              2
                    1
```

B) Introducing Small additive errors in data.

```
eps = 1.e-4
eps = 1.0000e-04
D=D*eps
D = 4 \times 4
                           0.0011
   0.0004
          0.0004 0.0004
                           0.0004
   0.0003
         0.0003 0.0001
   0.0001 0.0001 0.0004 0.0008
   0.0001
         0.0002 0.0002
                           0.0001
```

2. Find the coefficients of x solving Dx = b.

A) Compute the Singular Value Decomposition.

```
[U,S,V]=svd(D)
U = 4 \times 4
  -0.7757 -0.1305 -0.2303
                         -0.5729
                         0.6643
  -0.3258 -0.6454 -0.1897
                         0.4675
  -0.5211 0.6842 0.2042
  -0.1437 -0.3134 0.9323 -0.1087
S = 4 \times 4
          0
                     0
   0.0017
                              0
                  0
         0.0004
                              0
      Ω
          0 0.0002
       0
                               0
       0
              0
                   0 0.0000
```

```
V = 4 \times 4
-0.2834 -0.5948 -0.1903 0.7278
-0.2920 -0.6841 0.3114 -0.5914
-0.3465 0.2686 0.8453 0.3055
-0.8452 0.3257 -0.3903 -0.1650
```

B) Compute Moore-Penrose pseudo-inverse using A) and find x

```
for i =1:1:3
    if(S(i,i)>0)
        S(i,i)=1/S(i,i);
    end
end
S=S.'
S = 4 \times 4
10^{3} \times
            0
   0.5974
                       0
                   0
       0
         2.8493
                                0
            0 5.3807
       0
                                0
       0
               0
                    0
                          0.0000
```

A_dagger=V*S*U.'

```
A_dagger = 4x4

10<sup>3</sup> X

0.5882 1.3432 -1.2805 -0.3989

0.0039 0.9970 -0.9006 2.1983

-0.9866 -1.2893 1.5604 4.0303

0.7541 -0.0361 0.4692 -2.1765
```

b=[1;1;1;1]

b = 4x1 1 1 1

x1=A_dagger*b

x1 = 4x1 10³ X 0.2520 2.2986 3.3148 -0.9893

C) Compute using Matlab built-in function

A_Dagger_Matlab=pinv(D)

```
A_Dagger_Matlab = 4×4

10<sup>4</sup> X

-5.0000 6.0000 4.0000 -1.0000

4.1111 -4.6667 -3.4444 1.0000

-2.2222 2.3333 1.8889 -0.0000

1.2222 -1.3333 -0.8889 0.0000
```

```
x2=A_Dagger_Matlab*b
x2 = 4x1
10^4 \times
   4.0000
  -3.0000
  2.0000
  -1.0000
m1=3
m1 = 3
D2 =randi([1,5],[m1,4])
D2 = 3 \times 4
    2
        4 4
                   4
    1
        3 4 5
    3
        3 4 2
D2(:,4) = 4*D2(:,1) -3*D2(:,2) +2*D2(:,3) -1
D2 = 3 \times 4
    2
        4 4 3
    1
        3 4
                  2
    3
         3
             4 10
eps = 1.e-4
eps = 1.0000e-04
D2=D2*eps
D2 = 3x4
10^{-3} \times
  0.2000
          0.4000 0.4000 0.3000
   0.1000
          0.3000 0.4000 0.2000
   0.3000
          0.3000
                    0.4000
                             1.0000
[U2,S2,V2]=svd(D2)
U2 = 3 \times 3
  -0.4508 0.5737 0.6838
  -0.3490 0.5919 -0.7266
  -0.8216 -0.5662 -0.0666
S2 = 3 \times 4
          0
                    0
   0.0014
       0
           0.0004
                                 0
           0
                   0.0001
V2 = 4 \times 4
  -0.2699 0.0093 0.6136 -0.7420
  -0.3861
          0.5445 0.4948 0.5565
  -0.4711
          0.5503 -0.6081 -0.3246
  -0.7458 \quad -0.6329 \quad -0.0941 \quad 0.1855
for i =1:1:3
    if(S2(i,i)>0)
        S2(i,i)=1/S2(i,i);
    end
end
```

```
S2=S2.'
S2 = 4 \times 3
10^{4} \times
                0
   0.0726
                              0
             0.2296
        0
                               0
              0
         0
                        1.3905
         0
                   0
                               0
A_D=V2*S2*U2.'
A_D = 4 \times 3
10^{3} \times
   5.9355 -6.1183 -0.4194
  5.5484 -4.1613 -0.9355
-4.9032 7.0108 0.1290
-1.4839 0.2796 1.3548
b2=[1;1;1]
b2 = 3x1
     1
     1
     1
X2=A_D*b2 % VALUE OF X solved manually
x2 = 4 \times 1
10<sup>3</sup> ×
   -0.6022
   0.4516
    2.2366
    0.1505
A_D_M=pinv(D2)
A_D_M = 4 \times 3
10^{3} \times
   5.9355 -6.1183 -0.4194
   5.5484 -4.1613 -0.9355
   -4.9032 7.0108 0.1290
   -1.4839 0.2796 1.3548
X2_M=A_D_M*b2 % VALUE OF X on applying pinv()
X2_M = 4 \times 1
10<sup>3</sup> ×
   -0.6022
   0.4516
    2.2366
    0.1505
```

null(D2)

ans = 4x1 -0.7420 0.5565 -0.3246 0.1855

Final Outcome := Since m=3 we have infinitely many solutions thus we get a nonempty null vector as above. The set of all possible solutions are X2_M + lamda*null(D2).