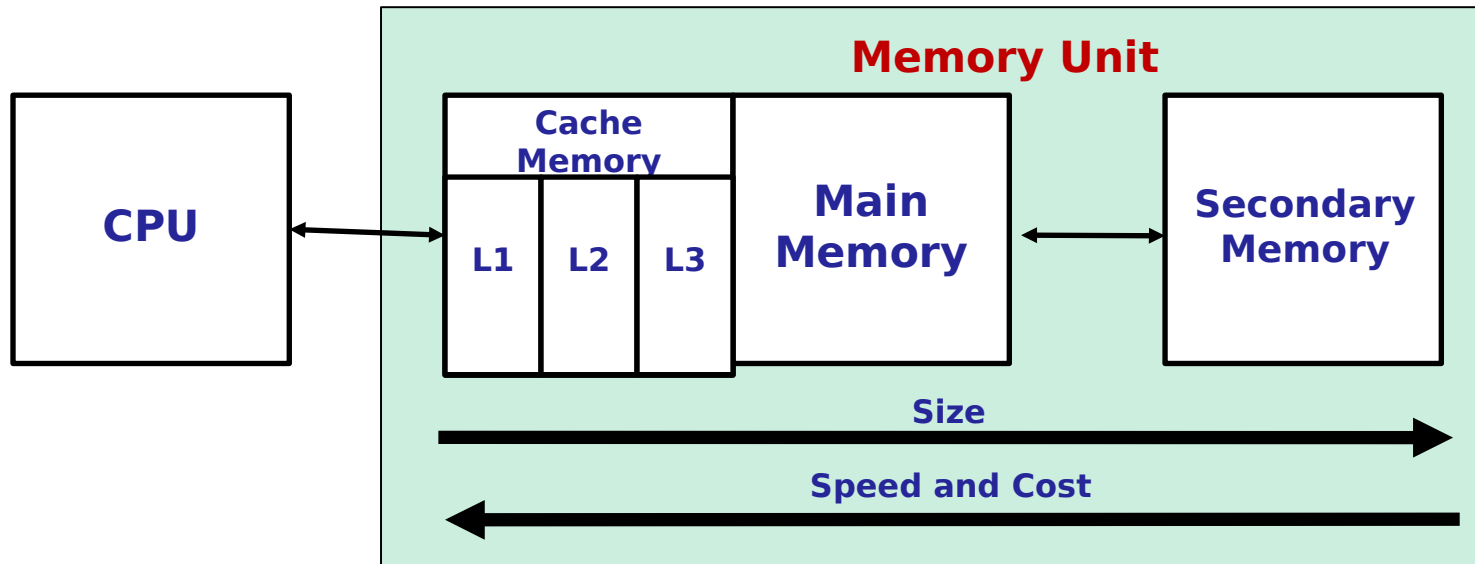


# Memory Unit

# Memory Hierarchy



- Processor processes instructions and **data faster** than it can be fetched from memory unit
- **Memory access time** is the bottleneck
- One way to reduce **memory access time** is to use **faster memory**
  - A small and faster **memory bridge** the gap between processor and main memory

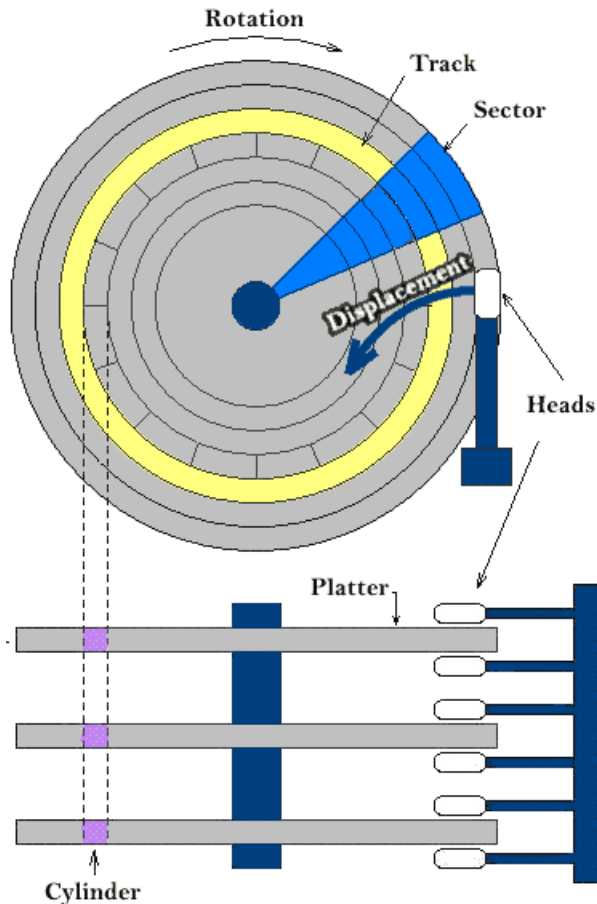
# Secondary Storage

# Secondary Storage

- Secondary storage include:
  - Magnetic disks:
    - Example: Hard disks
    - Used in personal computers
  - Redundant Array of Independent Disks (RAID):
    - Uses disk arrays to achieve greater performance and higher availability
    - Multiples disks are used as a parallel array of data storage devises built with redundancy to compensate for dis failures
    - Used in servers and large systems
  - Optical disks:
    - Uses optical storage technology
    - Examples: CDRom and DVD

# Magnetic Disks

- A **disk** is a **circular platter** constructed of nanomagnetic material, called **substrate**
- Usually **both the sides** are coated with a **magnetisable material**



- Data are **recorded** on and **retrieved** from the disk via a conducting coil called **head**
- **Read/write head**
- Each head consists of a **magnetic yoke** and **magnetisable coil**
- Floppy disk
- Winchester disk (Hard disk)

# Read and Write Mechanism

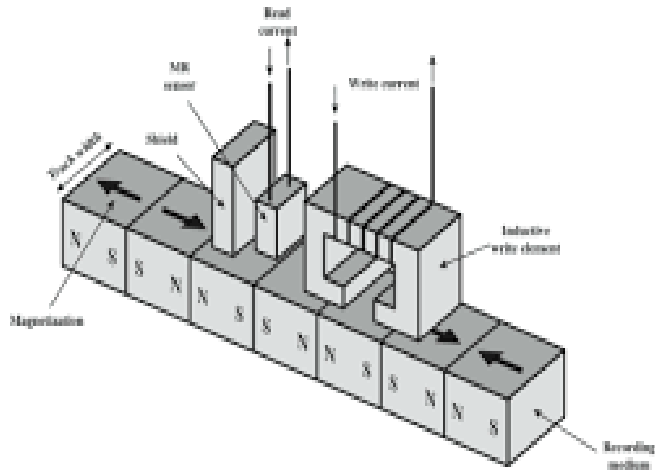


Figure 6.1 Inductive Write/Magnetoresistive Read Head

## Write mechanism

- Electricity flowing through the coil (head) produces magnetic field
- This induced magnetic field magnetises the small area of the recording medium
- Different patterns of positive and negative current indicates 1 and 0

- Read mechanism

- It exploits the fact that magnetic field moving relative to a coil produces an electric current in the coil (head)
- When the surface of the disk passes under the head, it generates a current of the same polarity as the one already recorded

# Data Organization on the Disk

- Track:

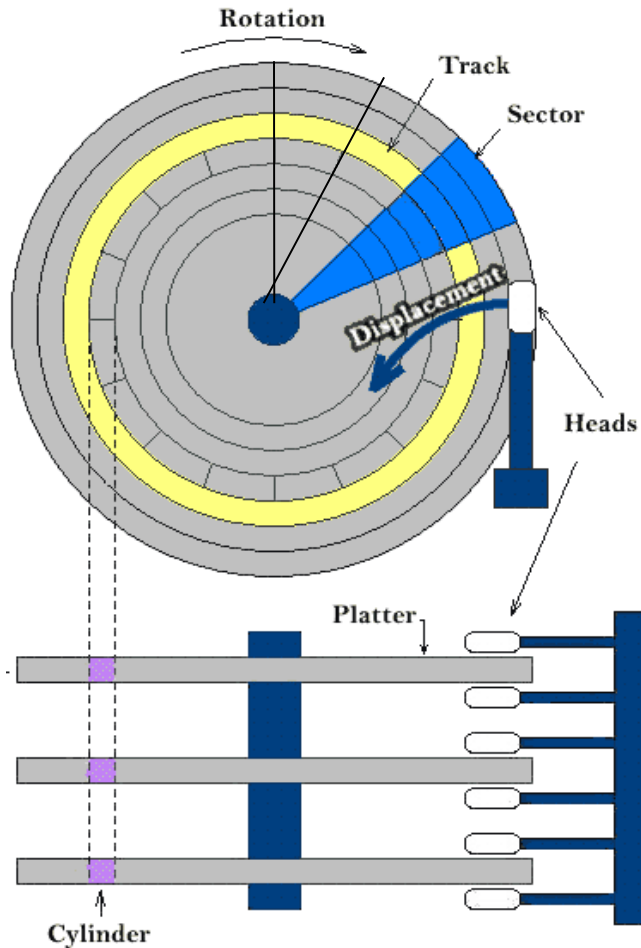
- Concentric set of rings on the platter
- Each track is of the same width as head

- Sector:

- The tracks are divided into hundreds of sectors per track
- Each sector stores 512 bytes of information

- Cylinder:

- The set of all the tracks in the same relative position on the platters

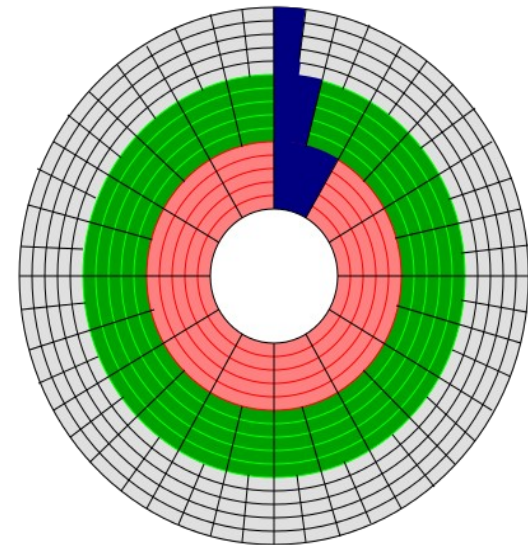


# Multiple zone recording

It is proposed to increase the density of data in outer track

It has advantage over CAV  
(Constant angular velocity )

Data transfer from outer tracks will be higher.  
Hence OS fill its own files in outer tracks

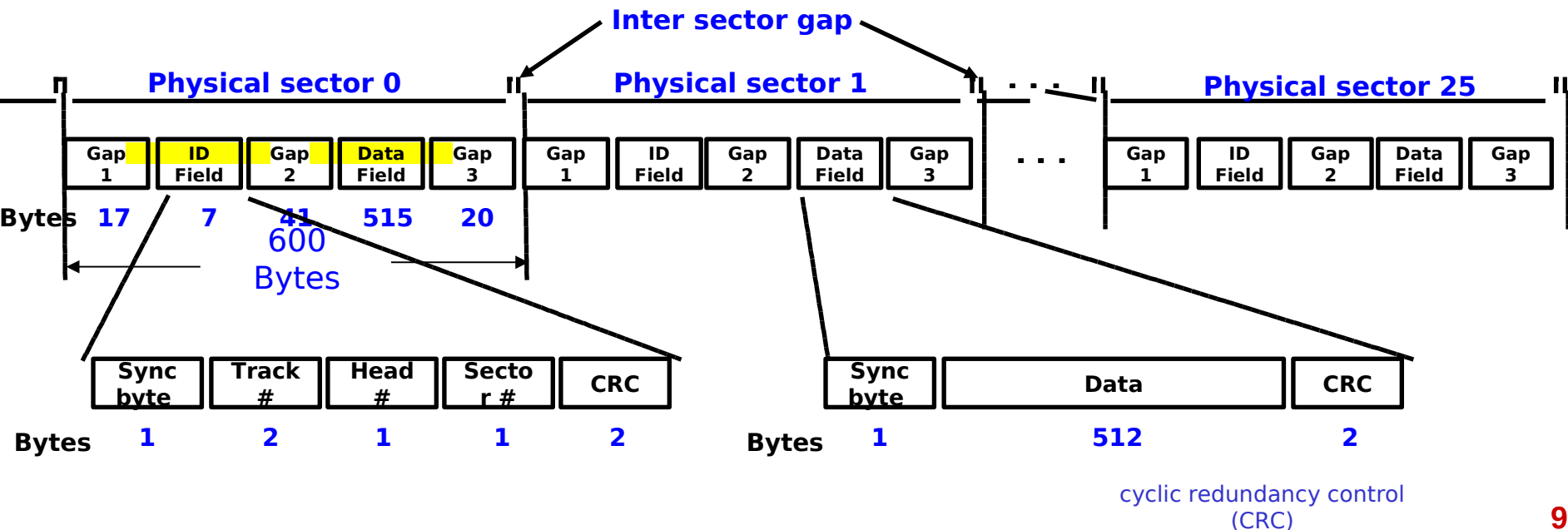


■ Sector 0

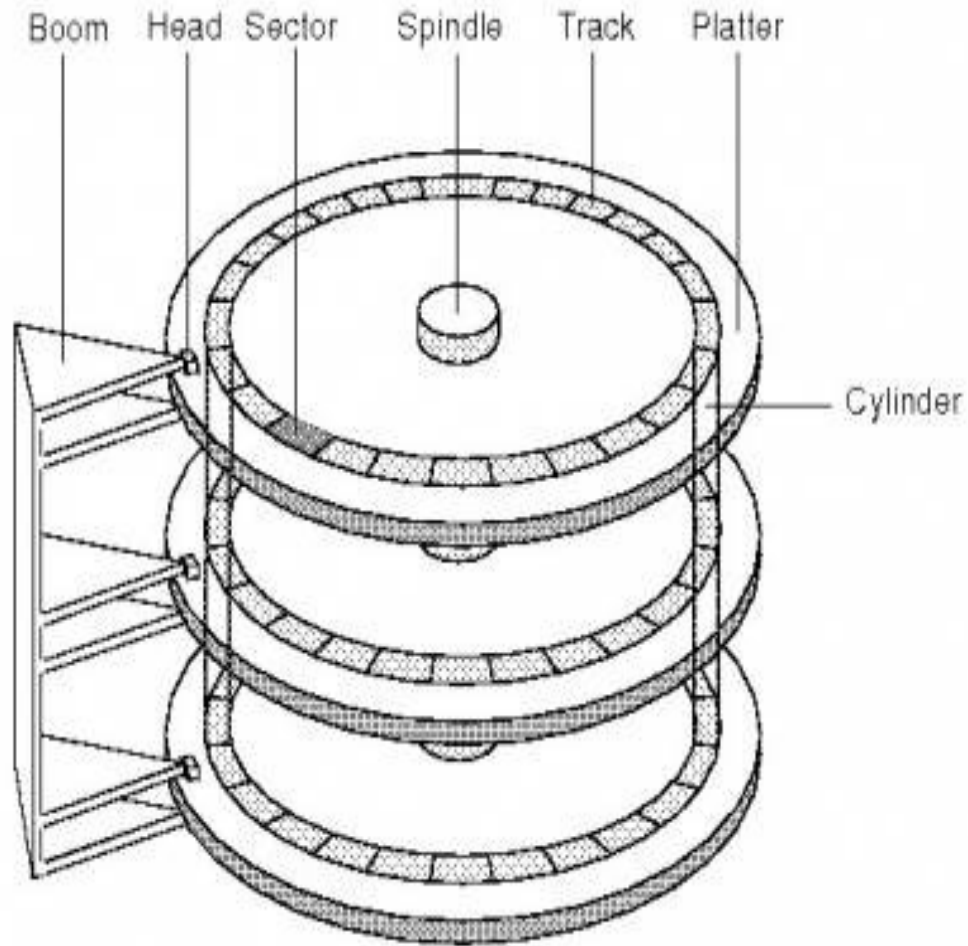


# Winchester Disk Format

- Some means needed to **locate sector positions with in a track** – identifying start and end of each sector
- This is handled using **control data** recorded on the disk
- **Formatted disk**
  - Some **extra data (control data)** used only by the disk controller
  - Operating system does the formatting of disk
- **Each sector holds 512 bytes of data and control information**



# Component of Disk Drive



# Disk Performance Parameters

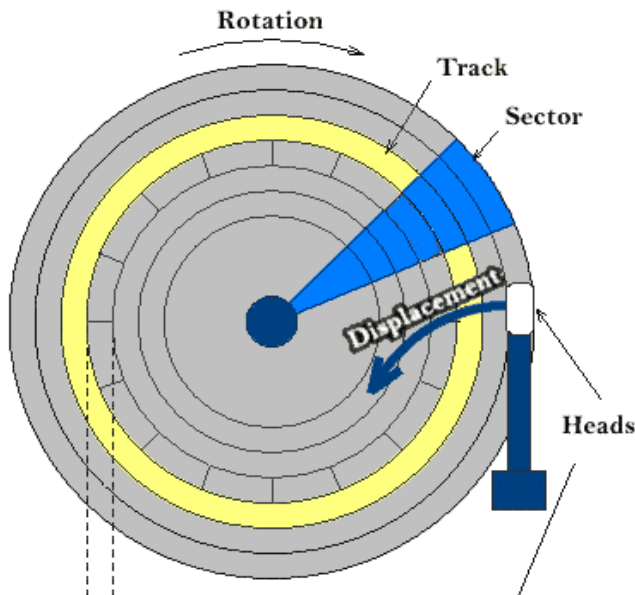
- When the disk drive is operating, the disk is rotating at a constant speed
- During read or write operation, the head must be positioned at the desired track and at the beginning of the desired sector on that track

- Seek time ( $T_s$ ):

- Time required to move or position the head to the required track
- It depends on where is the initial position
- We consider average seek time

- Track-to-track seek time:

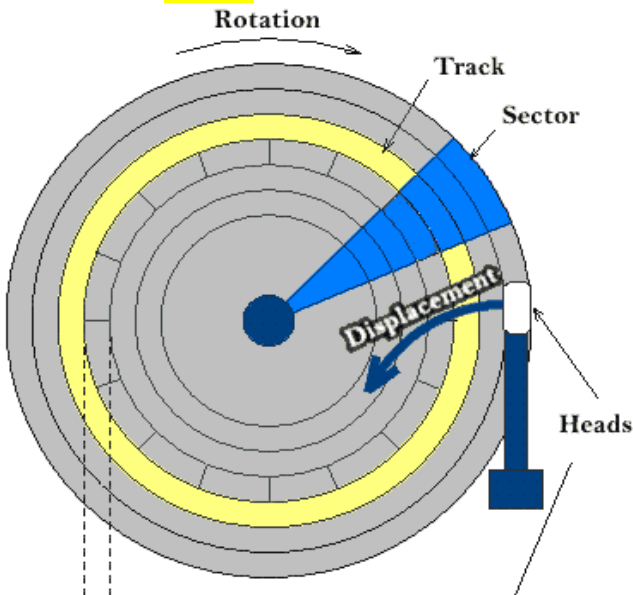
- Time to move the head from one track to an adjacent track



# Disk Performance Parameters

- Rotational delay or Rotational latency ( $T_r$ ):
  - Time taken for the beginning of the sector to read by the head
  - Average time needed for the required sector to pass under the head once the head has positioned at the correct track
  - Let  $r$  is the rotation speed measured in revolutions per sec

$$T_r = \frac{1}{2r}$$



# Disk Performance Parameters

- Transfer time ( $T$ ):
  - Time taken to transfer  $b$  bytes of data to or from a track of the disk
  - $b$  : Number of bytes to be transferred
  - $r$  : Rotational speed
  - $N$  : Number of bytes on the track

$$T = \frac{b}{rN}$$

- Total time to access the data
  - Sum of the average seek time, rotational delay and transfer time

$$T_a = T_s + T_r + T$$

# Hard Disk Parameter

- **Example: Segate Barracuda ES.2**
  - Capacity : 1TB
  - Track-to-track seek time : 0.8 ms
  - Average seek time : 8.5 ms
  - Spindle speed : 7200 rpm
  - Average rotational delay : 4.16 ms
  - Maximum transfer rate : 3GB/sec
  - Bytes per sector : 512
  - Tracks per cylinder : 8 (4 platters)

# Secondary Storage

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# **RAID Systems**



# Mass Storage

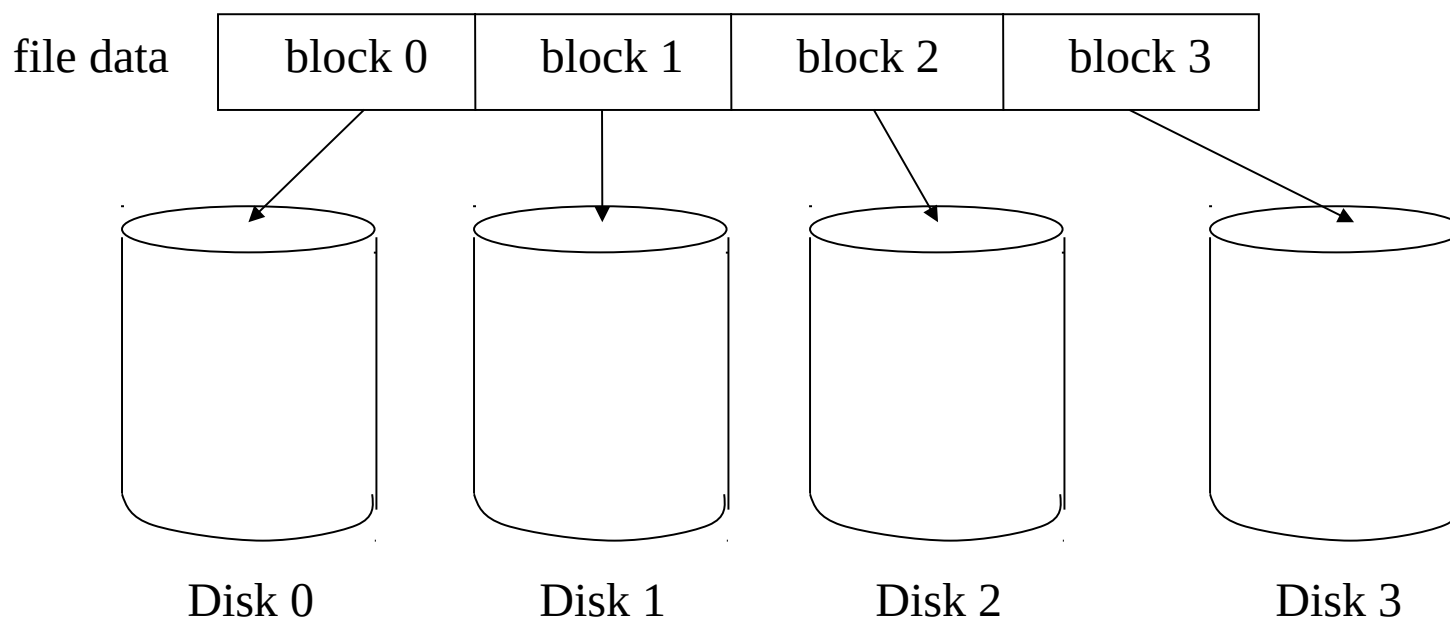
- Many systems today need to store many terabytes of data
- Don't want to use single, large disk
  - too expensive
  - failures could be catastrophic
- Would prefer to use many smaller disks

# RAID

- Redundant Array of Inexpensive Disks
- Basic idea is to connect multiple disks together to provide
  - large storage capacity
  - faster access to reading data
  - redundant data
- Many different levels of RAID systems
  - differing levels of redundancy, error checking, capacity, and cost

# Striping

- Take file data and map it to different disks
- Allows for reading data in parallel



# Parity

- Way to do error checking and correction
- In the event of drive failure, Parity drive is accessed and data is reconstructed from the remaining devices
- Considered an array of five drives
- X0 through X4 contain data and X4 is the parity disk
- Using exclusive-OR function, the parity bit is computed as
- $$X_4(i) = X_3(i) \otimes X_2(i) \otimes X_1(i) \otimes X_0(i)$$
- Suppose X1 has failed then it can be recovered as

$$X_1(i) = X_4(i) \otimes X_2(i) \otimes X_1(i) \otimes X_0(i)$$

# Mirroring

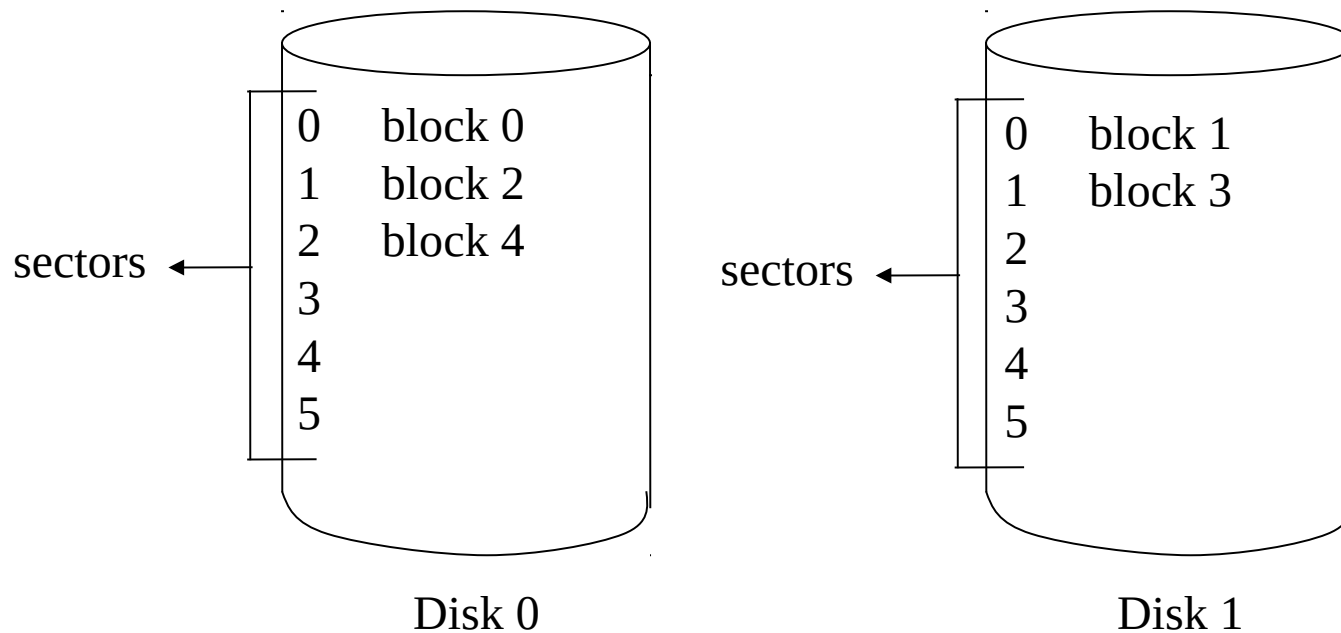
- Keep to **copies of data** on two separate disks
- Gives **good error recovery**
  - if some data is lost, get it from the other source
- **Expensive**
  - requires twice as many disks
- **Write performance** can be **slow**
  - have to write data to two different spots
- **Read performance is enhanced**
  - can read data from file in parallel

# RAID Level-0

- Often called striping
- Break a file into blocks of data
- Stripe the blocks across disks in the system
- Simple to implement
- provides no redundancy or error detection

# RAID Level-0

file data	block 0	block 1	block 2	block 3	block 4
-----------	---------	---------	---------	---------	---------



# RAID Level-1

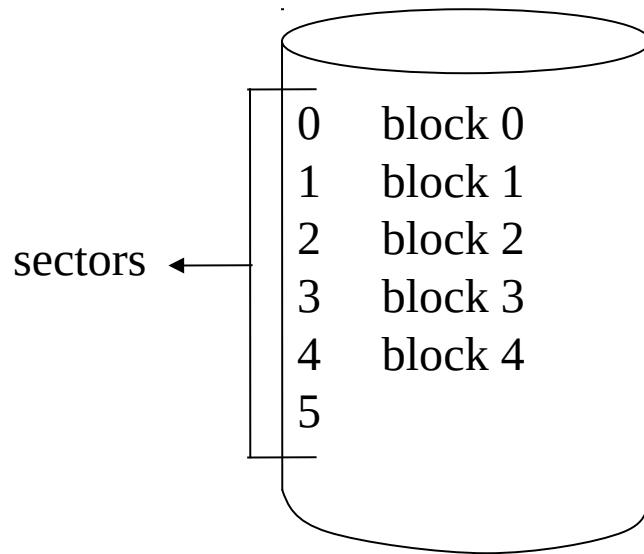
- A complete file is stored on a single disk
- A second disk contains an exact copy of the file
- Provides complete redundancy of data
- Read performance can be improved
  - file data can be read in parallel
- Write performance suffers
  - must write the data out twice
- Most expensive RAID implementation
  - requires twice as much storage space



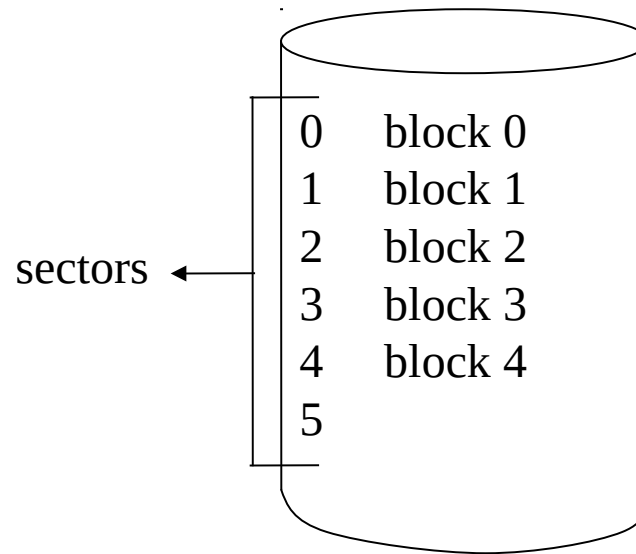
# RAID Level-1

file data

block 0	block 1	block 2	block 3	block 4
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Disk 0

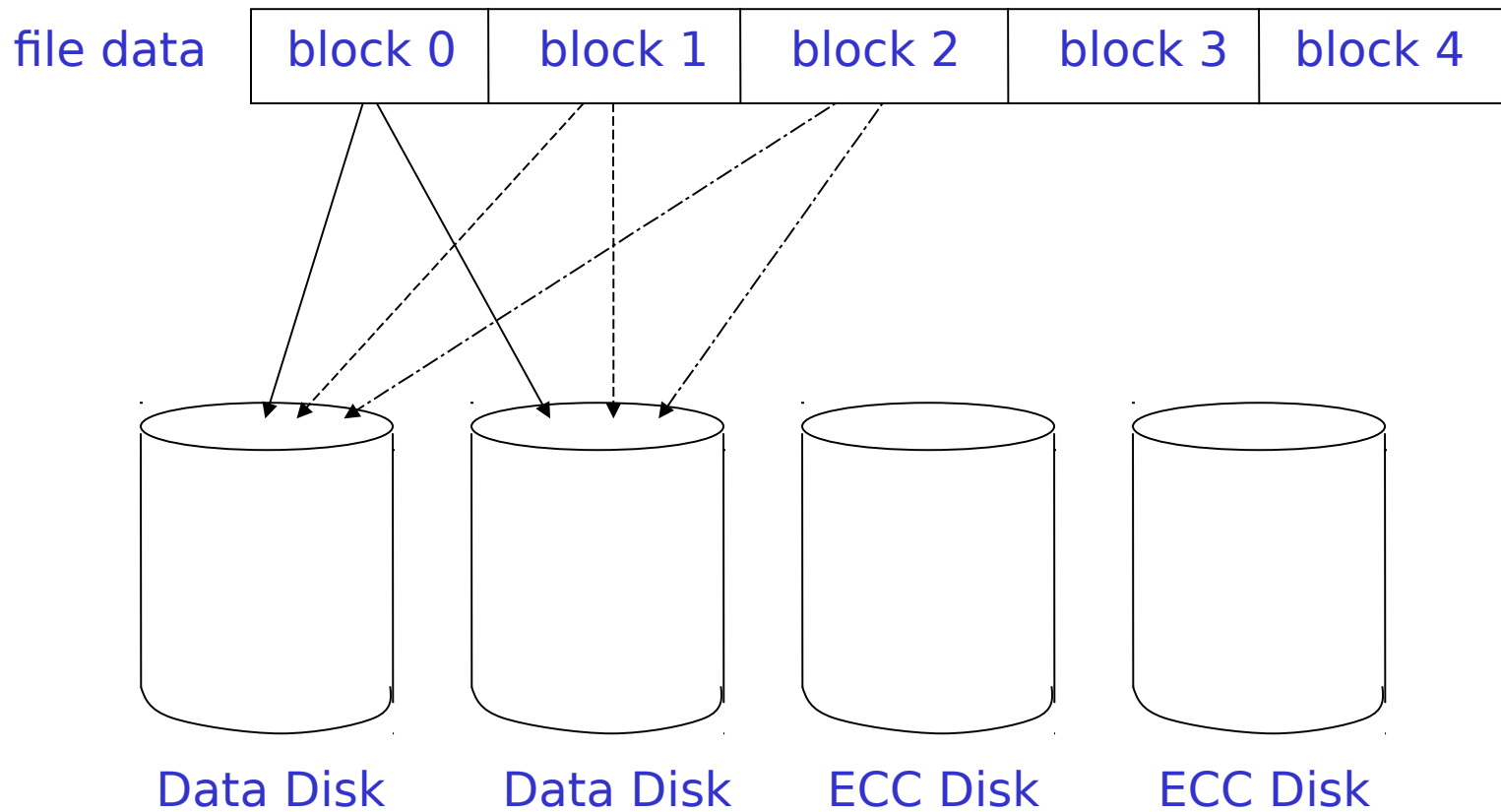


Disk 1

# RAID Level-2

- **Stripes** data across disks similar to Level-0
  - difference is data is bit interleaved instead of block interleaved
- Uses **ECC** to monitor correctness of information on disk
- **Multiple disks record the ECC information to determine which disk is in fault**

# RAID Level-2



# RAID Level-2

- Requires fewer disks than Level-1 to provide redundancy
- Still needs quite a few more disks
  - for 10 data disks need 4 check disks
- Big problem is performance
  - must read data plus ECC code from other disks
  - for a write, have to modify data, ECC,
- Another big problem is only one read at a time
  - while a read of a single block can be done in parallel
  - multiple blocks from multiple files can't be read because of the bit-interleaved placement of data

# RAID Level-3

- One big problem with Level-2 are the disks needed to detect which disk had an error
- Modern disks can already determine if there is an error
  - using ECC codes with each sector
- So just need to include a parity disk
  - if a sector is bad, the disk itself tells us, and use the parity disk to correct it

# RAID Level-4

- Big problem with Level-2 and Level-3 is the bit interleaving
  - to access a single file block of data, must access all the disks
  - allows good parallelism for a single access but doesn't allow multiple I/O's
- Level-4 interleaves file blocks
  - allows multiple small I/O's to be done at once

- RAID Level-05:
- RAID Level-09:
- RAID Level-10: The most expensive system