

$$\textcircled{2} \quad \alpha_k = - \frac{g^k d^k}{(d^k)^T Q d^k}$$

$$\textcircled{3} \quad x^{k+1} = x^k + \alpha_k d^k$$

Theorem For any starting point $x^{(0)}$, the conjugate direction algorithm converges to unique x^* (that solves $Qx=b$) in n steps, that is $x^{(n)} = x^*$.

Proof since $\{d^{(0)}, \dots, d^{(n-1)}\}$ are l.g., they must span the whole space \mathbb{R}^n .

So for the vector $x^* - x^0 \in \mathbb{R}^n$, \exists $\beta_0, \dots, \beta_{n-1}$ s.t.

$$x^* - x^0 = \beta_0 d^0 + \beta_1 d^1 + \dots + \beta_{n-1} d^{n-1}$$

so now premultiplying this equation by $(d^k)^T Q$ for $k=0, \dots, n-1$, we get

$$(d^k)^T Q (x^* - x^0) = \beta_k (d^k)^T Q d^k$$

$$\Rightarrow \beta_k = \frac{(d^k)^T Q (x^* - x^0)}{(d^k)^T Q d^k} \quad \textcircled{A}$$

Again $x^{(k)} = x^0 + \alpha_0 d^0 + \dots + \alpha_{k-1} d^{k-1}$
 $0 \leq k \leq n-1$

$$\Rightarrow x^{(k)} - x^0 = \alpha_0 d^{(0)} + \dots + \alpha_{k-1} d^{k-1}$$

Now $x^* - x^{(0)} = (x^* - x^{(k)}) + (x^{(k)} - x^{(0)})$

premultiplying $(d^k)^T Q$ we get

$$(d^k)^T Q (x^* - x^0) = (d^k)^T Q (x^* - x^{(k)}) + (d^k)^T Q (x^{(k)} - x^0)$$

$$= (d^k)^T Q (x^* - x^{(k)})$$

$$= (d^k)^T [b - Qx^{(k)}] = -(d^k)^T g^k$$

By (A) & (B),

$$\begin{aligned} &[\because Qx^* = b \text{ and} \\ &g^{(k)} = \nabla f(x^{(k)}) \\ &= Qx^{(k)} - b] \end{aligned}$$

$$\beta_k = \frac{-(d^k)^T g^k}{(d^k)^T Q d^k}$$

$$\therefore \alpha_k = \beta_k \quad \forall k$$

$$\begin{aligned} x^* &= x_0 + \alpha_0 d^0 + \dots + \alpha_{n-1} d^{n-1} \\ &= x_n \end{aligned}$$