

Consider the optimization problem

$$\begin{aligned} & \min f(x) \\ & \text{subject to } x \in \Omega \end{aligned} \quad \text{--- (1)}$$

① The function  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  that we wish to minimize is called objective function or cost function.

②  $x = (x_1, x_2, \dots, x_n)$  are called the decision variable

③ The set  $\Omega \subseteq \mathbb{R}^n$  is called the feasible set or constrained set.

The above problem is a decision problem that involves finding a vector  $x^*$  that results the smallest value of the objective function.

Note Maximization problem can be represented equivalently in the form of a minimization problem because maximization  $f(x)$  is equivalent to minimizing  $-f(-x)$ .

Note 2 The above problem (1) is known as constrained optimization problem. If  $\Omega = \mathbb{R}^n$ , then

the above problem (1) is called unconstrained optimization problem.

Def<sup>n</sup> Suppose that  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  is a real valued function. A point  $x^* \in \mathbb{R}^n$  is said to be a local minima of  $f$  if there exists an  $\epsilon > 0$  such that  $f(x) \geq f(x^*)$  for all  $x$  satisfying  $\|x - x^*\| < \epsilon$

□ A point  $x^* \in \mathbb{R}^n$  is a global minima of  $f$  if  $f(x) \geq f(x^*)$   $\forall x \in \mathbb{R}^n$ .

Remark An optimization problem is solved only when a global minimizer is found. However, it is difficult to find a global minima. Thus we have to find local minima in practice.

Notation Let  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  be a differentiable function. Then the first order derivative of  $f$  is denoted by  $Df$  is  $Df = \left( \frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \dots, \frac{\partial f}{\partial x_n} \right)$

The gradient of  $f$  is defined by

$$\nabla f = (Df)^T = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{pmatrix}$$

Let  $f$  be twice differentiable, that is,  $\nabla f$  is differentiable and we write derivative of  $\nabla f$  as

$$\underline{D^2 f} = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_2 \partial x_1} & \dots & \frac{\partial^2 f}{\partial x_n \partial x_1} \\ \frac{\partial^2 f}{\partial x_1 \partial x_2} & \frac{\partial^2 f}{\partial x_2^2} & \dots & \frac{\partial^2 f}{\partial x_n \partial x_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_1 \partial x_n} & \dots & \dots & \frac{\partial^2 f}{\partial x_n^2} \end{bmatrix}$$

The matrix  $D^2 f$  is called the Hessian matrix of  $f$  at  $x$  and denoted by  $H(x)$ .

First order necessary condition for local minima (FONC)

Let  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  be differentiable at  $x^*$  and  $x^*$  is a local minima of  $f$ , then  $\nabla f(x^*) = 0$

Note  $\nabla f(x^*) = 0$  is not a sufficient condition for  $x^*$  to become a local minima.

Example Let  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$  by  $f(x_1, x_2) = x_1^2 - x_2^2$

$$\nabla f(x_1, x_2) = 0 \Rightarrow (2x_1, -2x_2) = (0, 0)$$

$$x_1 = x_2 = 0$$

Suppose  $x^* = (0, 0)$  is a local minima. But

$$f\left(\frac{\epsilon}{2}, 0\right) = \frac{\epsilon^2}{4} > f(0, 0)$$

$$\text{and } f(0, \frac{\epsilon}{2}) = -\frac{\epsilon^2}{4} < f(0,0)$$

Now, Both the points  $(\frac{\epsilon}{2}, 0)$  and  $(0, \frac{\epsilon}{2})$  having distance from  $x^* = (0,0)$  is less than  $\epsilon$  for any  $\epsilon > 0$ .

$\therefore x^* = (0,0)$  is not a local minima

Second order necessary condition (SONC)

Let  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  be twice differentiable at  $x^*$  and  $x^*$  is a local minima of  $f$ .

Then  $\nabla f(x^*) = 0$  and  $F(x^*)$  is positive semidefinite where  $F$  is the Hessian matrix.

[Note: A  $n \times n$  matrix  $F$  is said to PSD if  $x^T F x \geq 0 \quad \forall x \in \mathbb{R}^n$ ]

Prob 1

Consider the function  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$  by

$$f(x) = x^T \begin{pmatrix} 1 & 2 \\ 4 & 7 \end{pmatrix} x + x^T \begin{pmatrix} 3 \\ 5 \end{pmatrix} + 6$$

$$\text{where } x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

(a) Find the gradient and Hessian matrix of  $f$  at the point  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ .

- ⑥ Find a point that satisfy FONC for  $f$ .  
 check that the <sup>some</sup> point satisfy the SONC  
 or not.

Ans ⑥  $\nabla f\left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}\right) = (11, 25)$  ,  $H\left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 2 & 6 \\ 6 & 14 \end{pmatrix}$

⑦  $f(x_1, x_2) = x_1^2 + 6x_1x_2 + 7x_2^2 + 3x_1 + 5x_2 + 6$

$\Rightarrow f(x_1, x_2) = (2x_1 + 6x_2 + 3, 6x_1 + 14x_2 + 5)$

$\nabla f(x_1, x_2) = (0, 0)$

$\Rightarrow x_1 = 1.5, x_2 = -1$

$\therefore (1.5, -1)$  satisfies the FONC.

$H(x_1, x_2) = \begin{pmatrix} 2 & 6 \\ 6 & 14 \end{pmatrix}$

Let  $d = \begin{bmatrix} d_1 \\ d_2 \end{bmatrix}$  , Now  $d^T H d = [d_1 \ d_2] \begin{bmatrix} 2d_1 + 6d_2 \\ 6d_1 + 14d_2 \end{bmatrix}$

$= 2d_1^2 + 6d_1d_2 + 6d_1d_2 + 14d_2^2$

$= d_1^2 + d_2^2 + 2 \cdot d_1 \cdot 3d_2 + 9d_2^2$   
 $+ 6d_1d_2 + 5d_2^2$

take  $(d_1, d_2) = [2, -1]$ , then

$$d^T H d = 8 - 24 + 14 = -2 < 0$$

$\therefore$  the Hessian matrix is not PSD.

This implies that SONC is not satisfying.

Hence  $x^* = (1.5, -1)$  is not a local minima.

$\therefore$  The function has no optimal soln.

Prob 2 Let  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$

$$f(x_1, x_2) = (x_1 - x_2)^4 + x_1^2 - x_2^2 - 2x_1 + 2x_2 + 1$$

Find all points satisfying FONC.

$$(1, 1) \quad x_1 = x_2$$