

Lecture 3

Memory

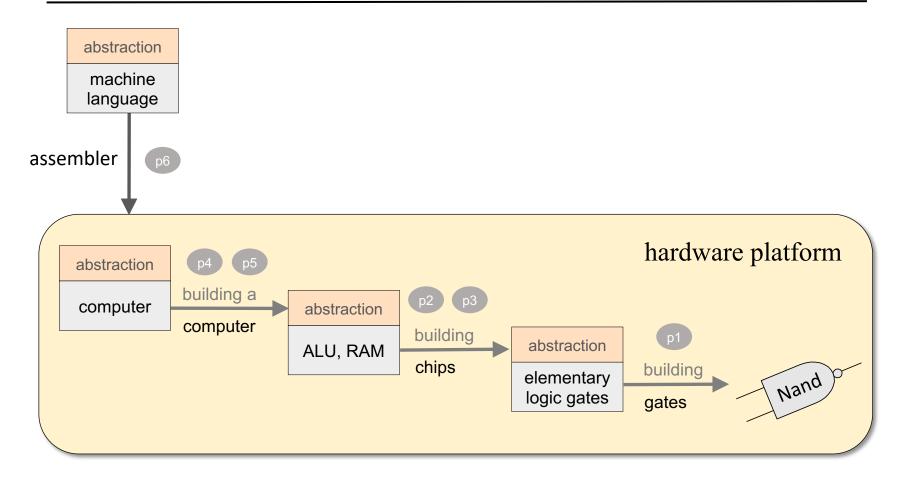
These slides support chapter 3 of the book

The Elements of Computing Systems

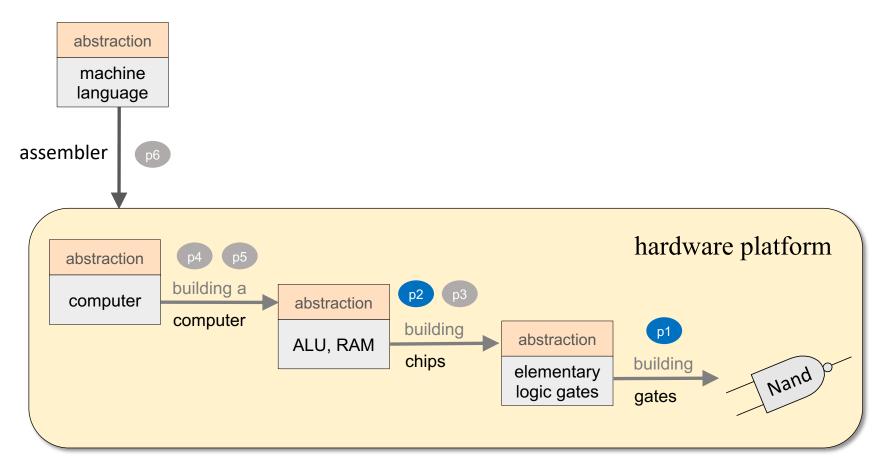
By Noam Nisan and Shimon Schocken

MIT Press, 2021

Nand to Tetris Roadmap: Hardware



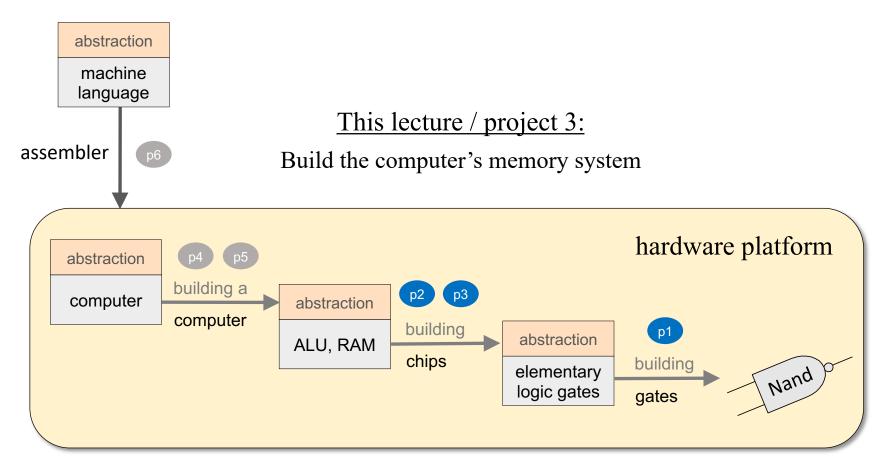
Nand to Tetris Roadmap: Hardware



<u>Project 1</u>: Build basic logic gates

Project 2: Build the ALU

Nand to Tetris Roadmap: Hardware



Project 1: Build basic logic gates

Project 2: Build the ALU

Combinational logic

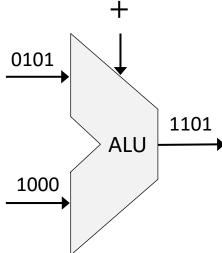
The type of digital logic used for building all the gates and chips that we saw so far:

- The chip's current inputs are just "sitting there" fixed and unchanging
- The chip's output is a function ("combination") of the current inputs, and the current inputs only

This type of digital logic is called:

- □ Combinational logic
- Time-independent logic

ALU: The "topmost" combinational chip



Hello, time

Software needs

- The hardware must be able to remember things, *over time*:
- The hardware must be able to do things, *one at a time* (sequentially):

Hardware needs

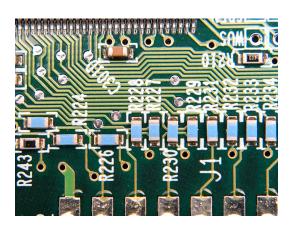
• The hardware must handle the *physical time delays* associated with *moving* and *computing* data

Example (variables)

$$x = 17$$

Example (iteration)

for i in range(0, 10):
 print(i)



Hello, time

Software needs

- The hardware must be able to remember things, *over time*:
- The hardware must be able to do things, *one at a time* (sequentially):

Hardware needs

• The hardware must handle the *physical time delays* associated with *moving* and *computing* data

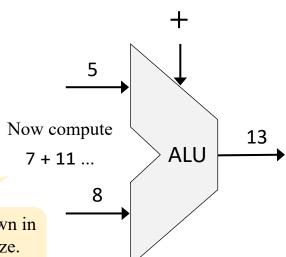
It will take some time before 7 and 11 will settle down in the input pins, and before the sum 7 + 11 will stabilize. *Till then, the ALU will output nonsense.*

Example (variables):

$$x = 17$$

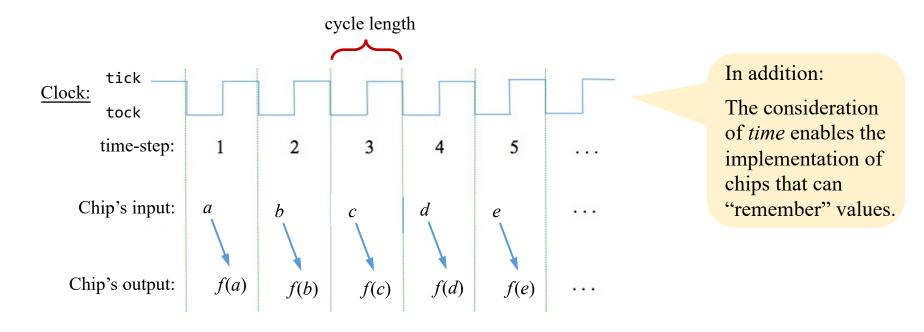
Example (iteration):

for i in range(0, 10):
 print(i)



Hello, time

Solution: Neutralize the time delays by using *discrete time*



- Design decision: Set the *cycle length* to be slightly > than the maximum time delay
- Observe / use the chips' outputs only at the end of cycles (time-steps), ignoring what happens within cycles
- Details later.

Memory

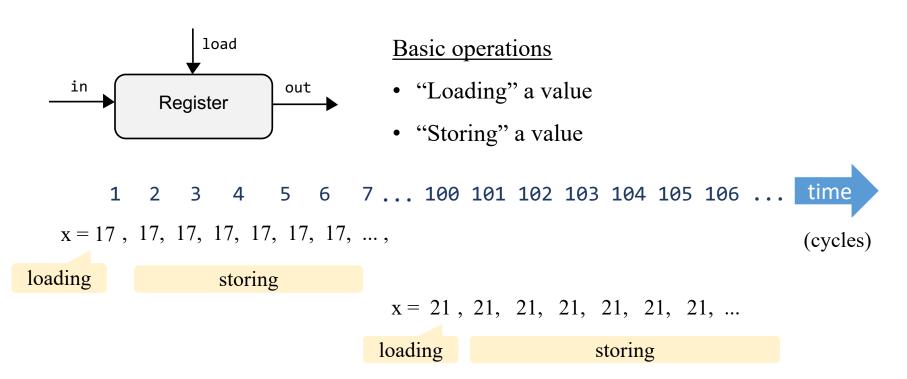
Memory: The faculty of the brain by which data or information is encoded, stored, and retrieved when needed. It is the *retention of information over time* for the purpose of influencing future action (Wikipedia)

Memory is time-based:

We remember *now* what was committed to memory *earlier*.



Memory



The challenge: Building chips that realize this functionality,

i.e. chips designed to maintain state and change state.

Chapter 3: Memory

Abstraction

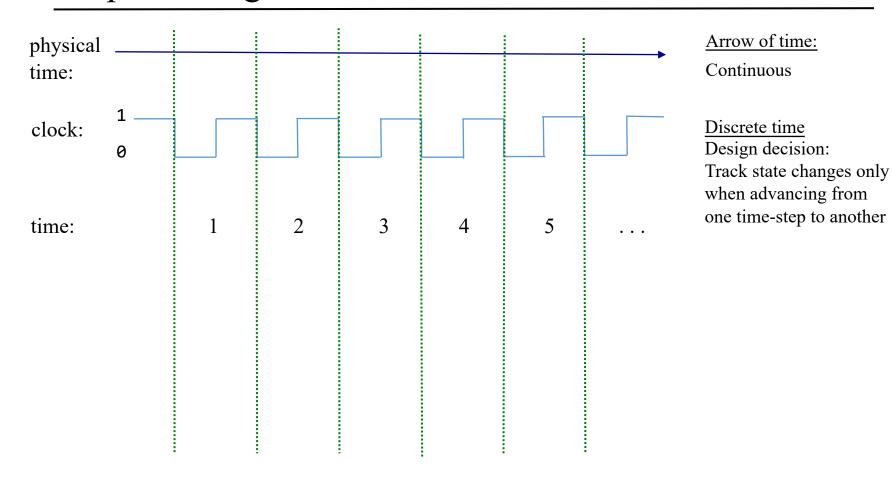


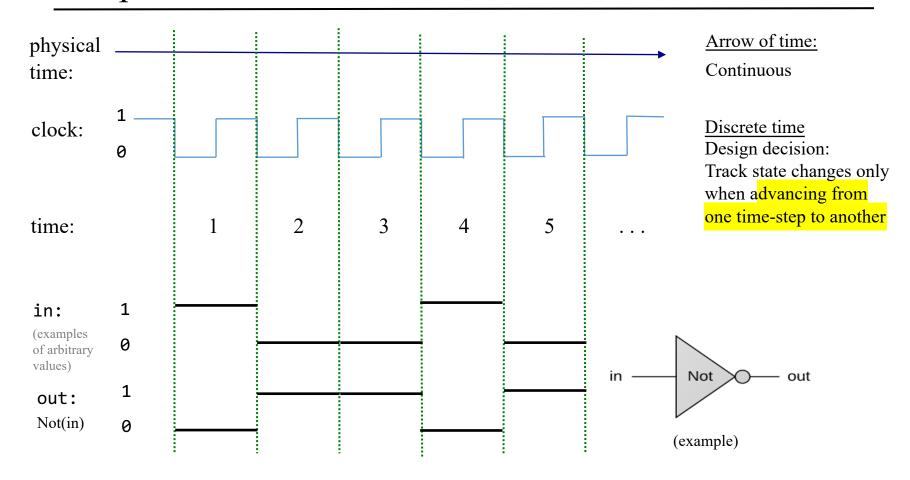
- Clock
- Registers
- RAM
- Counter

Implementation

- Data Flip Flop
- Registers
- RAM
- Project 3: Chips
- Project 3: Guidelines

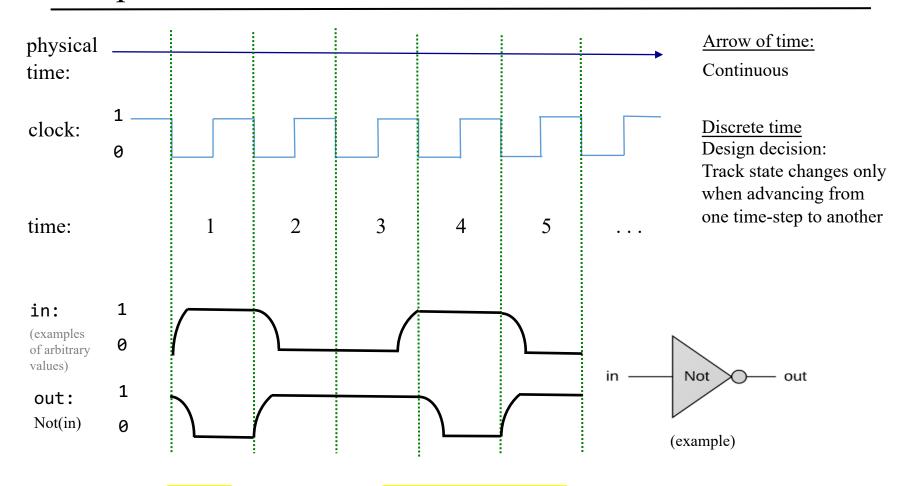
Representing time





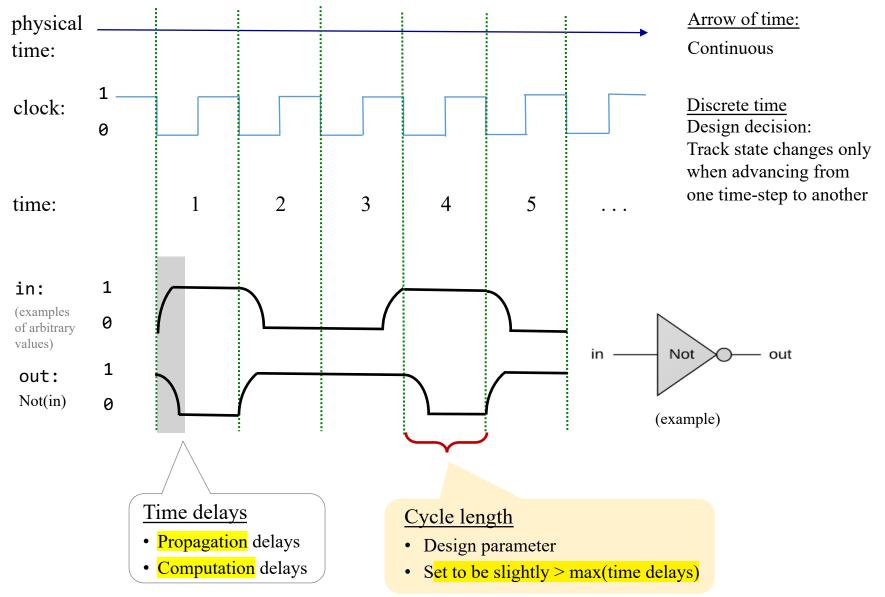
Desired / idealized behavior of the in and out signals:

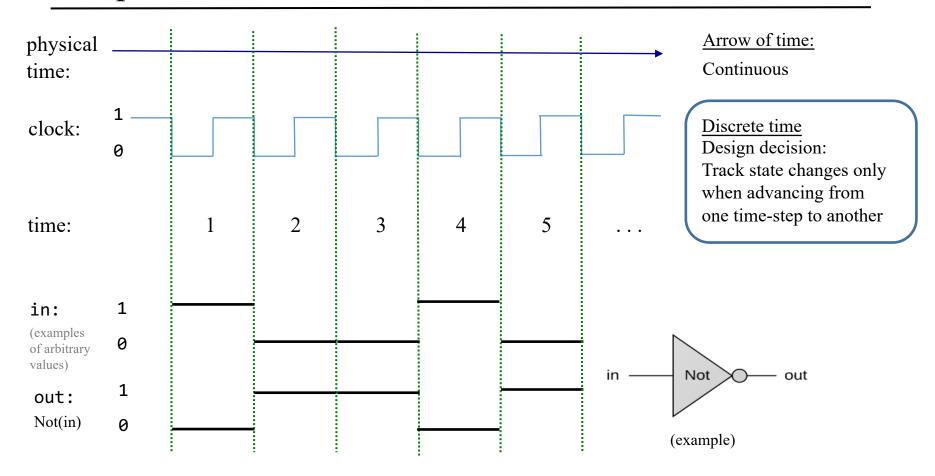
That's how we want the hardware to behave



Actual behavior of the in and out signals:

Influenced by physical time delays





Resulting effect

Since we track state changes only at cycle ends,

Combinational chips (like Not) react "immediately" to their inputs.

Chapter 3: Memory

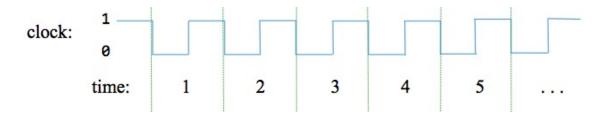
Abstraction

- ✓ Representing time
- Clock
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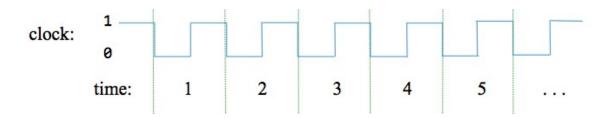
Implementation

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Clock



Clock: Simulated implementation

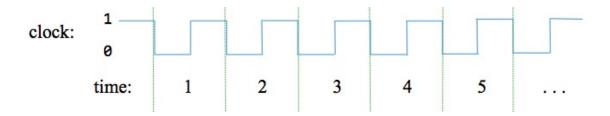


<u>Interactive simulation</u>

A clock icon, used to generate a sequence of tick-tock signals:



Clock: Simulated implementation



<u>Interactive simulation</u>

A clock icon, used to generate a sequence of tick-tock signals:





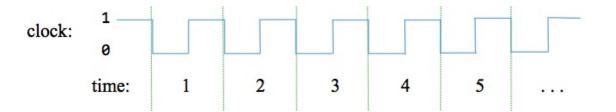
Script-based simulation

"tick" and "tock" commands, used to advance the clock:

```
// Sets inputs, advances the clock, and
// writes output values as it goes along.
set in 19,
set load 1,
tick,
output,
tock,
output,
tick, tock,
output,
...
```

Clock: Physical implementation

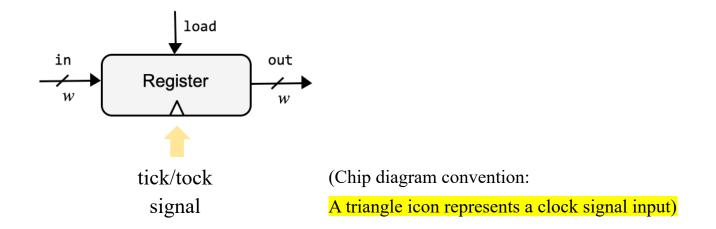




Physical clock

An *oscillator* is used to deliver an ongoing train of "tick/tock" signals

"1 MHz electronic oscillator circuit uses the resonant properties of an internal quartz crystal to control the frequency. Provides the clock signal for digital devices such as computers." (Wikipedia)



Chapter 3: Memory

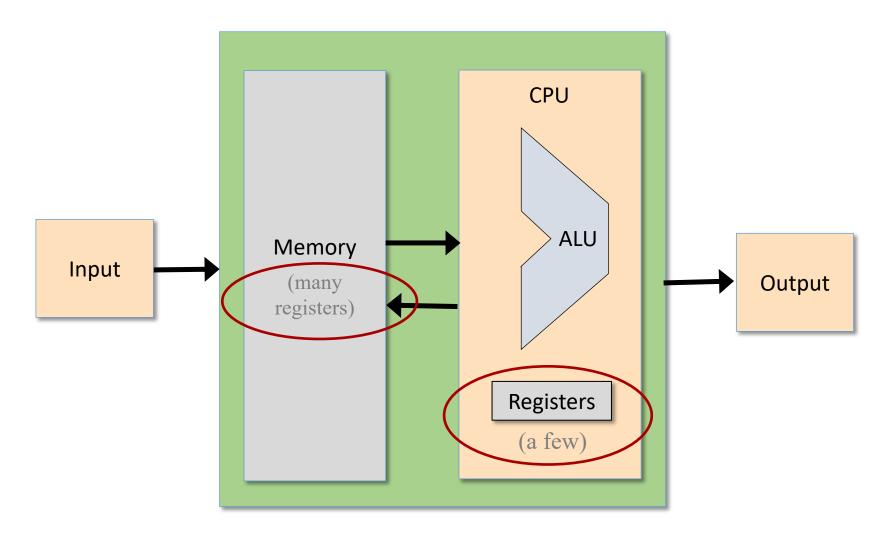
Abstraction

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Implementation

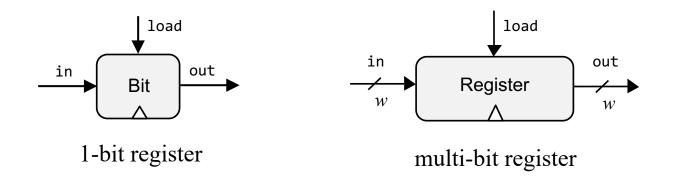
- Data Flip Flop
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Registers



Computer Architecture

Registers



Designed to:

- "Store" a value, until...
- "Loaded" with a new value

time:

$$x = 17, 17, 17, 17, 17, 17, 17, 17, ..., 17$$

loading

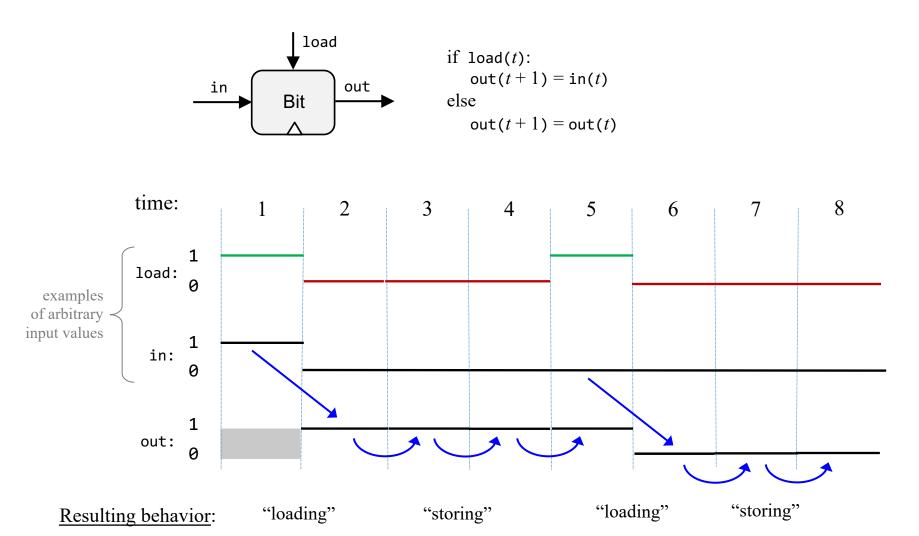
storing

$$x = 21, 21, 21, 21, 21, 21, ..., 21$$

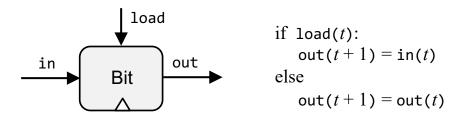
loading

storing

1-Bit register



1-Bit register



<u>Usage:</u> To read:

probe out

(out always emits the register's state)

To write:

set in = v

set load = 1

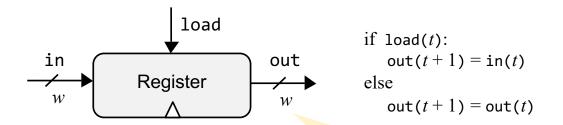
Result: The register's state becomes v;

From the next time-step onward, out will emit *y*,

until the next load.

Best practice: After writing, set load to 0

Multi-bit register



We'll focus on bit width w = 16, without loss of generality

<u>Load / store behavior:</u> Exactly the same as a 1-bit register

Read / write usage: Exactly the same as a 1-bit register



Chapter 3: Memory

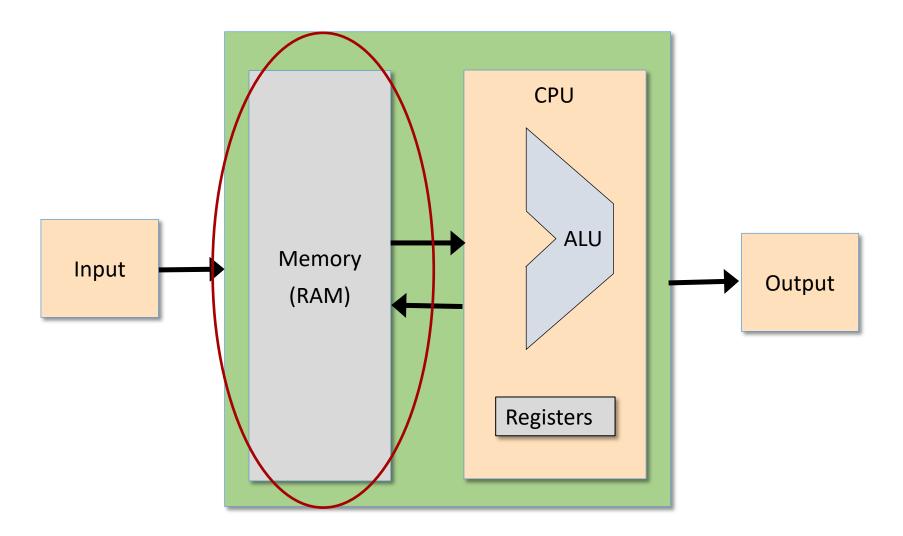
Abstraction

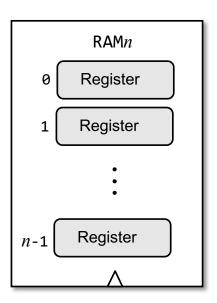
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Implementation

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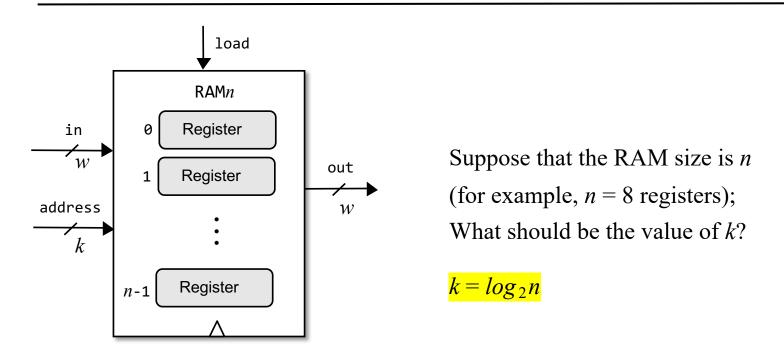
Computer architecture





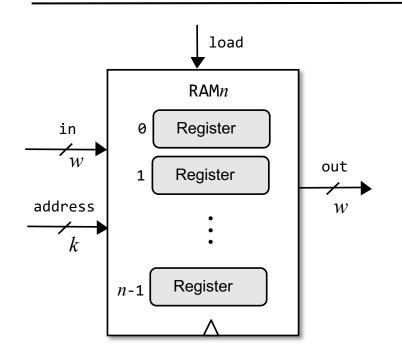
<u>Abstraction</u>: A sequence of *n* addressable, *w*-bit registers

Word width: Typically w=16, 32, 64, 128 bits (Hack computer: w=16)



Abstraction: A sequence of *n* addressable, *w*-bit registers

Word width: Typically w=16, 32, 64, 128 bits (Hack computer: w=16)



Behavior

If load == 0, the RAM maintains its state

If load == 1, RAM[address] is set to the value of in

The loaded value will be emitted by out from the next time-step (cycle) onward

(Only one RAM register is selected; All the other registers are not affected)

<u>Usage</u>

To read register i:

set address = i, probe out

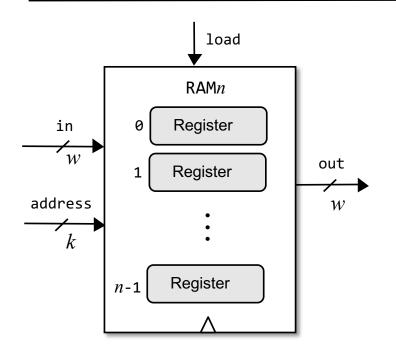
(out always emits the value of RAM[i])

To write v in register i:

set address = i, set in = v, set load = 1

Result: $RAM[i] \leftarrow v$

From the next time-step onward out will emit v



Why "Random Access Memory"?

Irrespective of the RAM size (n),
any randomly selected register can
be accessed "instantaneously",
in one time cycle.



Chapter 3: Memory

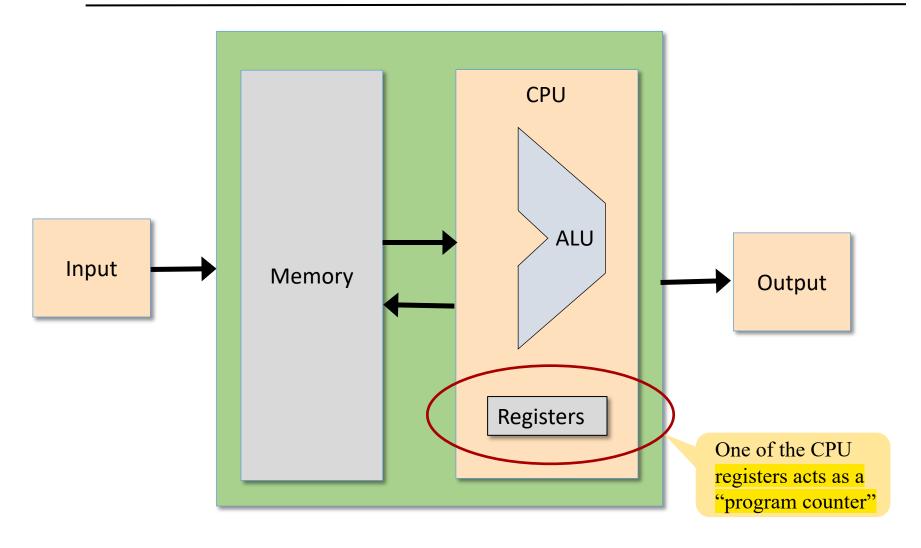
Abstraction

- ✓ Representing time
- ✓ Clock
- ✓ Registers
- **✓** RAM
- Counter

Implementation

- Data Flip Flop
- Registers
- RAM
- Project 3: Chips
- Project 3: Guidelines

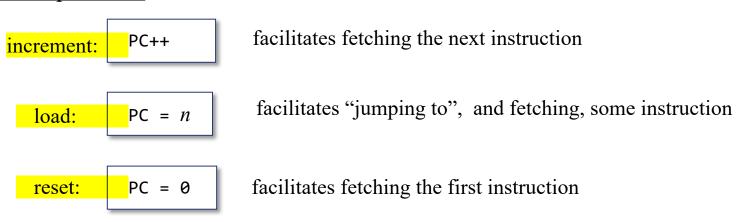
Computer architecture



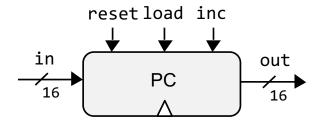
Counter

- The computer (that we will build later in the course) needs to keep track of which instruction should be fetched and executed next
- This is done using a register typically called Program Counter
- The PC is used to store the address of the instruction that should be fetched and executed next

Basic PC operations



Counter



if reset(t):
$$out(t+1) = 0$$

else if $load(t)$: $out(t+1) = in(t)$
else if $inc(t)$: $out(t+1) = out(t) + 1$
else $out(t+1) = out(t)$

<u>Usage:</u> To read: probe out

To increment: assert inc,

set the other control bits to 0

HW Simulator

PC chip demo

To load:

set in to v, assert load, set the other control bits to 0

To reset:

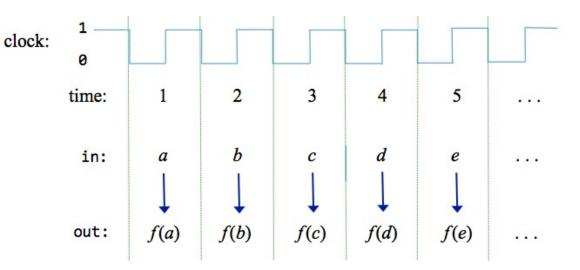
assert reset, set the other control bits to 0

Recap: Combinational logic / Sequential logic

Combinational logic

The output depends on current inputs only

The clock is used to stabilize outputs

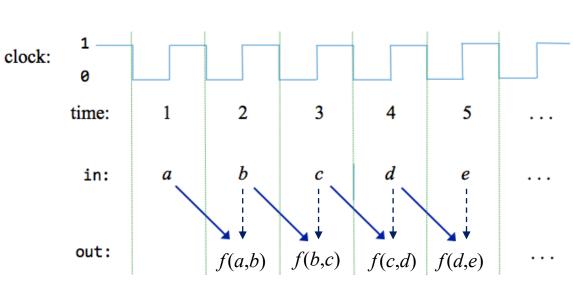


Sequential logic

The output depends on:

- Previous inputs
- And, optionally, also on current inputs

Used for building memory chips (registers, RAM)



Chapter 3: Memory

Abstraction

• Representing time



• Clock

• Registers

• RAM

• Counter

Implementation

• Data Flip Flop

• Registers

• RAM

• Project 3: Chips

• Project 3: Guidelines

Chapter 3: Memory

Abstraction

- Representing time
- Clock
- Registers
- RAM
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Implementation



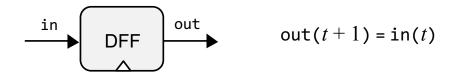
Data Flip Flop

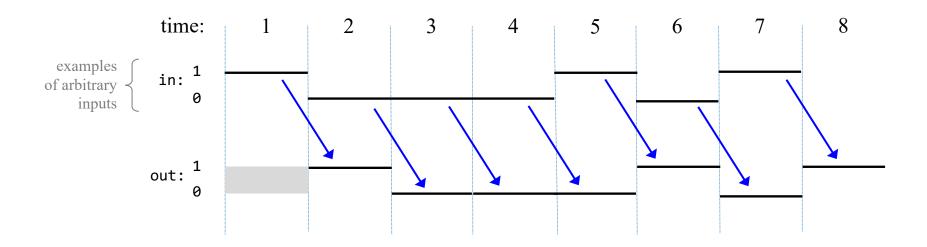
- Registers
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DFF

Data Flip Flop (aka latch)

The most elementary sequential gate: Outputs the input in the previous time-step





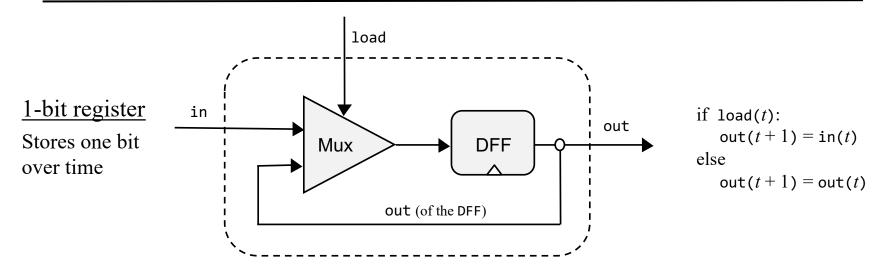
How can we "load" and then "maintain" a value (0 or 1) over time, without having to feed the value in every cycle?

From DFF to a 1-Bit register



We have to realize a "loading" behavior and a "storing" behavior, and be able to select between these two states

From DFF to a 1-Bit register

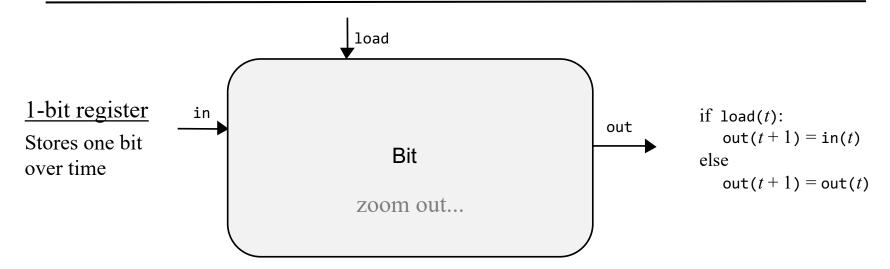


We have to realize a "loading" behavior and a "storing" behavior, and be able to select between these two states

Behavior

if load == 1 the register's value becomes in else the register maintains its current value

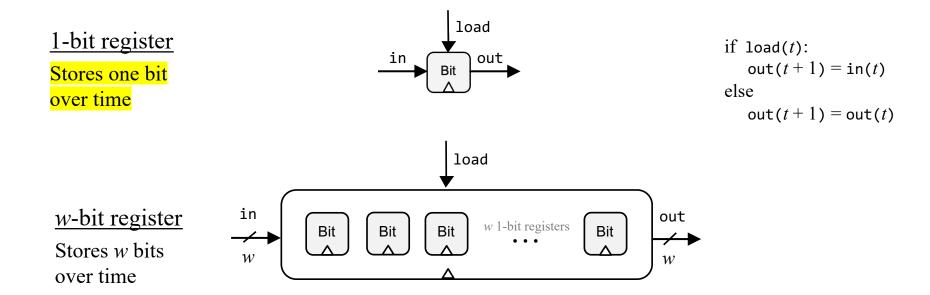
Register



Behavior

if load == 1 the register's value becomes in else the register maintains its current value

Register



Behavior

if load == 1 the register's value becomes in else the register maintains its current value

Chapter 3: Memory

Abstraction

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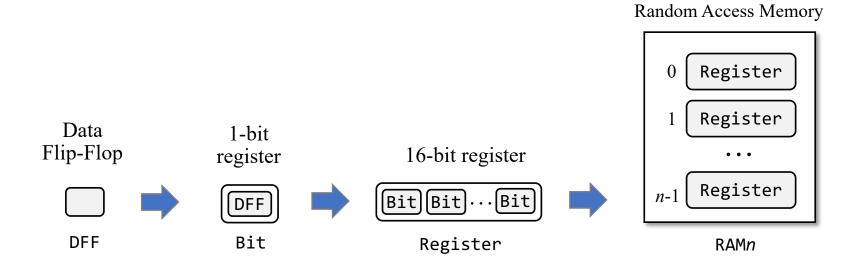




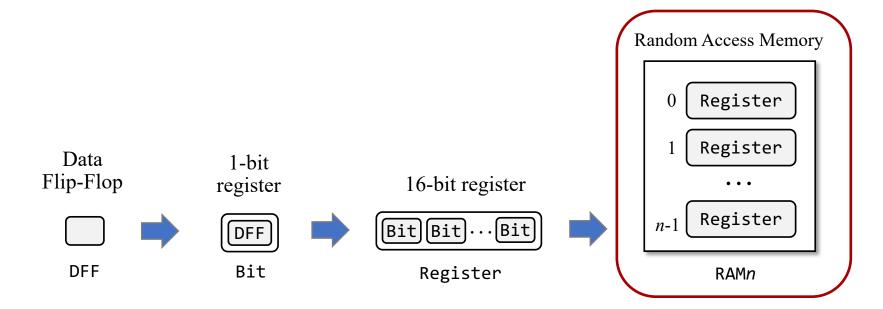


- Project 3: Chips
- Project 3: Guidelines

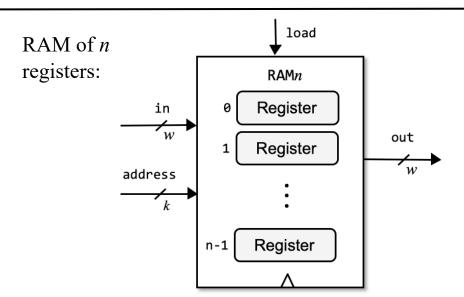
From DFF to RAM



From DFF to RAM



RAM: Abstraction



<u>Usage:</u> To read register i:

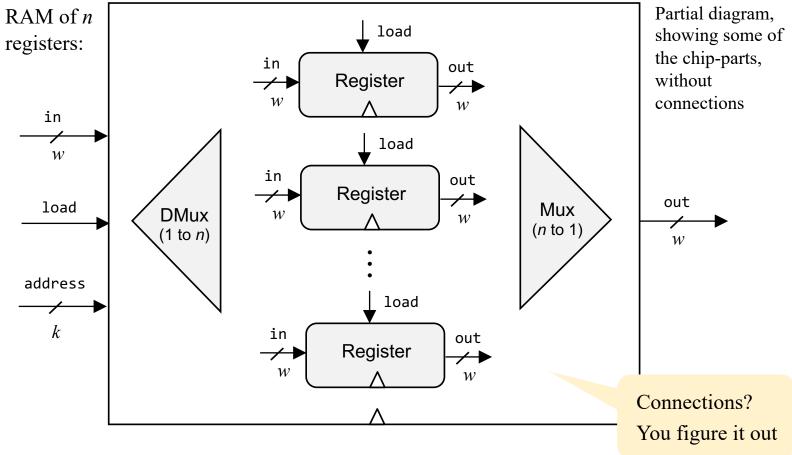
```
set address = i, probe out (out always emits the state of RAM[i])
```

To write v in register i:

```
set address = i,

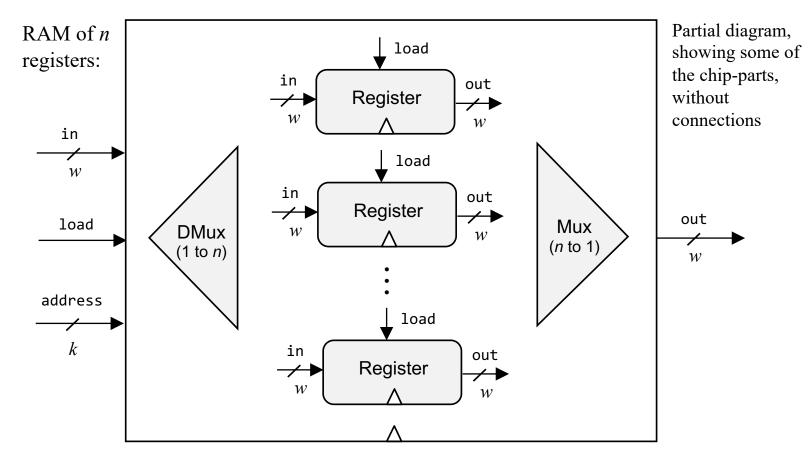
set in = v, Result: RAM[i] \leftarrow v

set load = 1 From the next time-step onward, out emits v
```



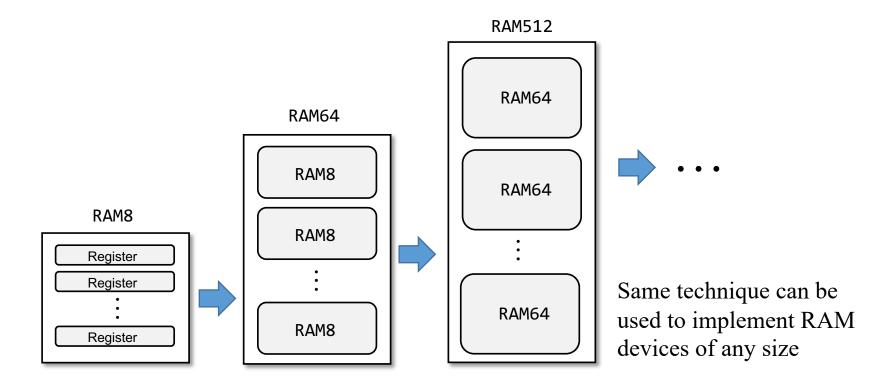
Reading: Can be realized using a Mux

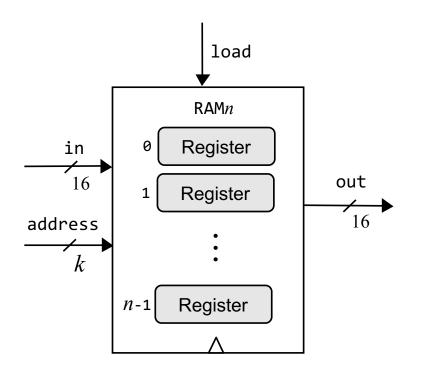
Writing: Can be realized using a DMux



How the magic of direct access works

- Like every memory chip, the storage behavior is based on sequential logic
- But, the *addressing* is realized by the Mux / DMux chips, which are *combinational*.





A family of 16-bit RAM chips:

chip name	n	k
RAM8	8	3
RAM64	64	6
RAM512	512	9
RAM4K	4096	12
RAM16K	16384	14

Why stop at RAM16K?

Because that's what we need for building the Hack computer.

Chapter 3: Memory

Abstraction

- Representing time
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Implementation









• Project 3: Guidelines

Project 3

Given:

- All the chips built in projects 1 and 2
- Data Flip-Flop (built-in DFF gate)

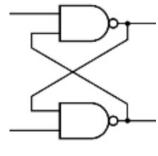
Why is the DFF built-in?

Build:

- Bit
- Register
- PC
- RAM8
- RAM64
- RAM512
- RAM4K
- RAM16K

DFF implementation

- A DFF gate can be built by connecting Nand gates with feedback loops
- The resulting implementation is elegant, yet impossible to realize on the supplied hardware simulator:
 - Our hardware simulator does not allow loops of combinational chips (like Nand)
- Instead, we use a built-in DFF implementation:



Part of a possible DFF implementation

```
/** Data Flip-flop: out(t) = in(t-1)
  * where t is the current time unit. */
CHIP DFF {
    IN in;
    OUT out;
    BUILTIN DFF;
    CLOCKED in;
}
```

Implementation note

HDL-wise, we need the DFF as a chip-part in one chip only: Bit

All the other memory chips are built on top of Bit.

Project 3

Given:

- All the chips built in projects 1 and 2
- Data Flip-Flop (built-in DFF gate)

Build:

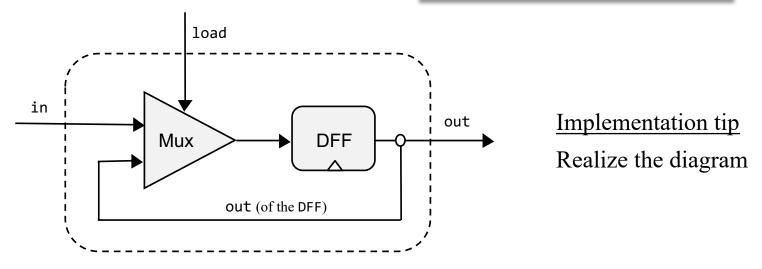


- Register
- PC
- RAM8
- RAM64
- RAM512
- RAM4K
- RAM16K

1-Bit register

in Bit

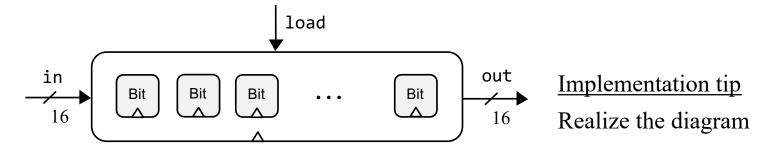
Bit.hdl



16-bit Register

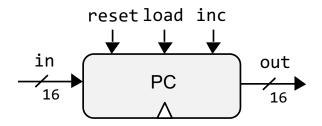
in Out Register 16

Register.hdl



Partial diagram, showing chip-parts without connections

16-bit Counter



PC.hdl

<u>Implementation notes</u>

- Can be built using the following chip-parts: Register, Inc16, Mux16
- Tip: The value of an internal pin can simultaneously feed the input pins of several chips
- Recommendation: Start by building a basic PC chip that has one mode and one control bit only: inc; Next, extend your design and HDL code to handle the load bit, and the reset bit.

Project 3

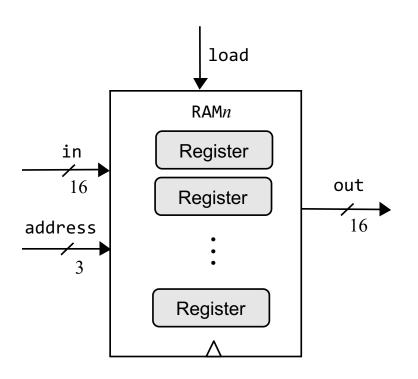
<u>Given</u>

- All the chips built in projects 1 and 2
- Data Flip-Flop (built-in DFF gate)

Build the following chips

- **√** Bit
- ✓ Register
- **√** PC
- RAM8
 - RAM64
 - RAM512
 - RAM4K
 - RAM16K

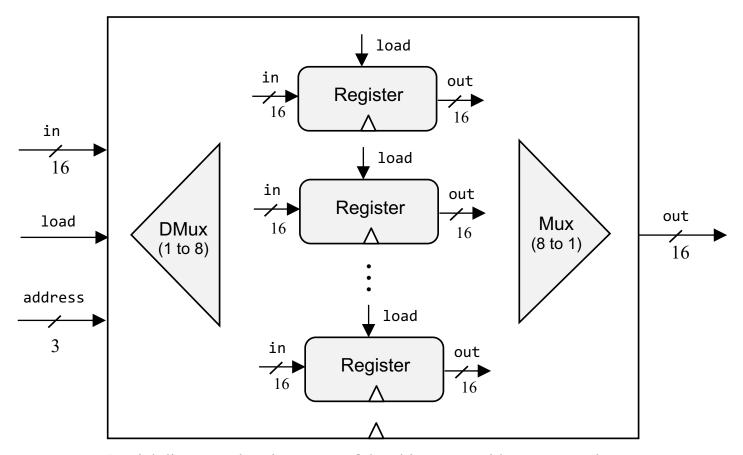
8-Register RAM



RAM8.hdl

```
/* Memory of 8 registers, each 16 bit-wide.
out holds the value stored at the memory location
specified by address. If load==1, then the in value
is loaded into the memory location specified by
address (the loaded value will appear in out from
the next time step onward).
*/
CHIP RAM8 {
    IN in[16], load, address[3];
    OUT out[16];
    PARTS:
    //// Replace with your code
}
```

8-Register RAM



Partial diagram, showing some of the chip-parts, without connections

Implementation tip

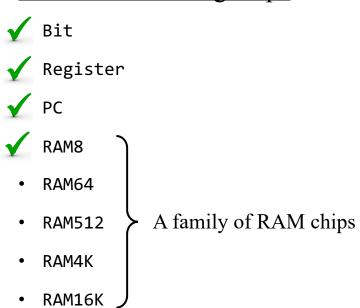
Figure out the missing connections, and realize the diagram.

Project 3

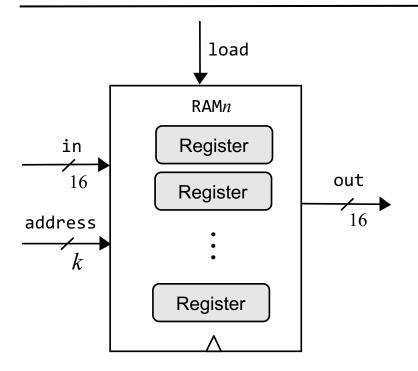
Given

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Build the following chips

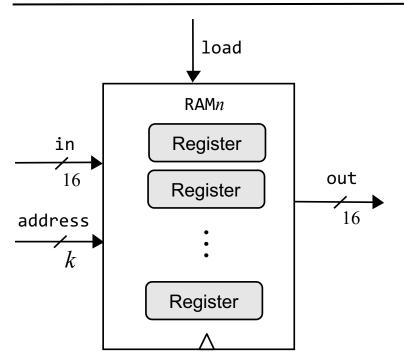


n-Register RAM



$RAM_n.hdl$

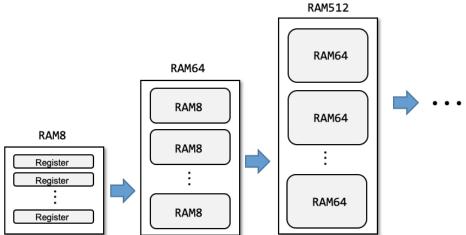
n-Register RAM



chip name	n	k
RAM8	8	3
RAM64	64	6
RAM512	512	9
RAM4K	4096	12
RAM16K	16384	14

<u>Implementation tips</u>

- Think about the RAM's address input as consisting of two fields:
 - One field selects a RAM-part;
 - The other field selects a register within that RAM-part
- Use logic gates to effect this addressing scheme



Chapter 3: Memory

Abstraction

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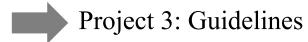
Implementation











Guidelines

- Implement the chips in the order in which they appear in the project guidelines
- If you don't implement some chips, you can still use their built-in implementations
- No need for "helper chips": Implement / use only the chips we specified
- In each chip definition, strive to use as few chip-parts as possible
- You will have to use chips implemented in previous projects; For efficiency and consistency's sake, use their built-in versions, rather than your own HDL implementations.

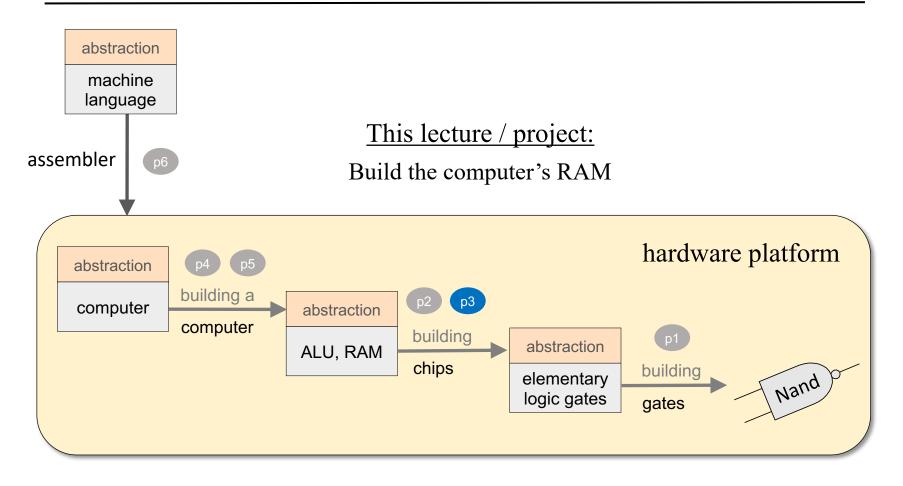
For technical reasons, the chips of project 3 are organized in two sub-folders named projects/03/a and projects/03/b

When writing and simulating the .hdl files, keep this folder structure as is.

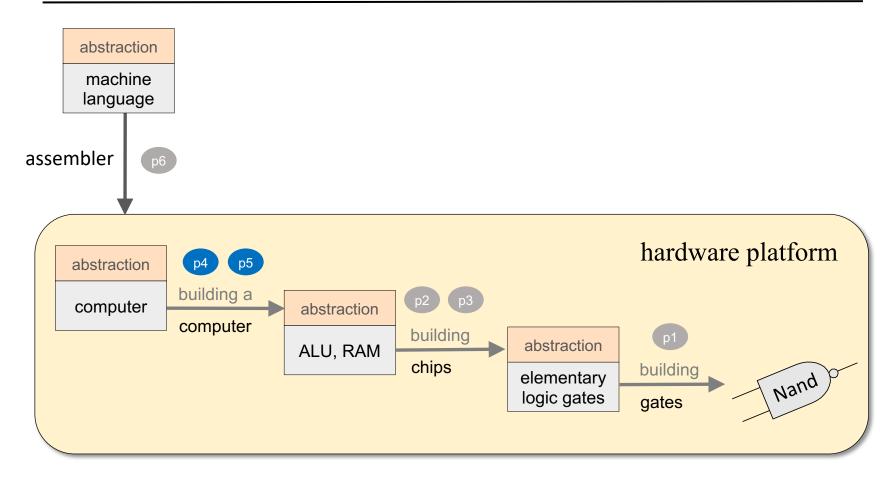
That's It!

Go Do Project 3!

Nand to Tetris Roadmap: Hardware



Nand to Tetris Roadmap: Hardware



Next two lectures / projects:

We'll build the computer (p5)

But first, we'll get acquainted with the computer's machine language (p4).