MIT 18.06 Exam 3, Spring 2023 Gilbert Strang & Andrew Horning

Your name:(printed)	Solutions!	
Student ID:		
Recitation		

Problem 1 (12 + 10 + 12 = 34 points):

Record your final answer in the allotted spaces. You may use the remaining space for your calculations.

1(a) Find the eigenvalues λ_1, λ_2 and eigenvectors $\boldsymbol{x}_1, \boldsymbol{x}_2$ of A:

$$A = \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix}$$

Eigenvalues
$$det(A-\lambda I)=\begin{vmatrix} 2-\lambda & 3\\ 1 & 4-\lambda \end{vmatrix}$$

$$= 8-6\lambda+\lambda^2-3$$

$$= \lambda^2-6\lambda+5$$

$$= (\lambda-1)(\lambda-5)$$

$$\lambda=1, \lambda_2=5$$

Eigenverdors

$$A_{1}=1$$

$$A-T=\begin{bmatrix}1&3\\1&3\end{bmatrix}$$

$$\rightarrow x_{1}=\begin{pmatrix}3\\1\end{pmatrix} \text{ Solves}$$

$$A_{2}=5$$

$$A_{3}=\begin{bmatrix}-3\\1&-1\end{bmatrix}$$

$$A_{4}=5$$

$$A_{5}=\begin{bmatrix}-3&3\\1&-1\end{bmatrix}$$

$$A_{5}=5$$

$$A_{6}=5$$

$$A_{7}=5$$

$$A_{7}=6$$

$$\lambda_1 = oldsymbol{I}$$
 $\lambda_2 = oldsymbol{5}$ $oldsymbol{x}_1 = oldsymbol{\begin{bmatrix} 3 \\ -1 \end{bmatrix}}$ $oldsymbol{x}_2 = oldsymbol{\begin{bmatrix} 1 \\ 1 \end{bmatrix}}$

1(b) Diagonalize $A = X\Lambda X^{-1}$ by finding those three matrices X and Λ and X^{-1}

$$X = \begin{bmatrix} x_1 & x_2 \end{bmatrix} = \begin{bmatrix} 3 & 1 \\ -1 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 5 \end{bmatrix}$$

$$X = \begin{bmatrix} 1 & -1 \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 5 \end{bmatrix}$$

$$X = \begin{bmatrix} 3 & 1 \\ -1 & 1 \end{bmatrix} \qquad \Lambda = \begin{bmatrix} 1 & 0 \\ 0 & 5 \end{bmatrix} \qquad X^{-1} = \begin{bmatrix} 1 & -1 \\ 4 & 1 \end{bmatrix}$$

1(c) Express the vector $\mathbf{u} = \begin{bmatrix} 4 \\ 0 \end{bmatrix}$ as a combination of the eigenvectors x_1 and x_2 of A.

Then express the vector A^4u as a combination of those eigenvectors of A

of A

$$u = c_1 x_1 + c_2 x_2 = \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$
 $\begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = X^{-1}u = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 4 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$
 $A^{4}u = A^{4}(c_1 x_1 + c_2 x_2) = c_1 A_1^{4} x_1 + c_2 A_2^{4} x_2$
 $= 1^{4}x_1 + 5^{4}x_2$

$$u = \chi_1 + \chi_2 = \begin{pmatrix} 3 \\ -1 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$A^4 u = \chi_1 + 5^4 \chi_2 = \begin{pmatrix} 3 \\ -1 \end{pmatrix} + 5^4 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

(blank page for your work if you need it)

Problem 2 (10 + 10 = 20 points):

Record your final answer in the allotted spaces. You may use the remaining space for your calculations.

2(a) Find the determinant of this permutation matrix P and explain your reasoning!

$$P = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

determinant of P = -1b/c P is three now permutations

away from the identity mutrice. Each

permutation snitches the sign of

det I = 1.

Alternate: Coluctor formula or big formula "

2(b) Find the cofactor of A_{11} and the determinant of A

$$A = \begin{bmatrix} 2 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix}$$

$$det(A) = 2C_{11} - 1C_{12}$$
via coluetor
$$= 2(1)$$
coluetor
$$= 2$$

Cofactor of $A_{11} = 1$

Determinant of A = 2

(blank page for your work if you need it)

Problem 3 (12 + 12 = 24 points):

Record your final answer in the allotted spaces. You may use the remaining space for your calculations.

An n by n real matrix Q is an orthogonal matrix if $Q^{T}Q = I$.

3(a) Show that the length of x =the length of Qx for every real vector x

bengths
$$||x|| = \sqrt{x^2 + \dots + x^2} = \sqrt{x^7} x$$

$$||Q_N|| = \sqrt{(Q_N)^7 Q_N}$$

$$||Qx|| = \sqrt{(Qx)^{2}(Qx)} = \sqrt{x^{2}Q^{2}Qx}$$

$$= \sqrt{x^{2}x} = 1|x||$$

3(b) Show that the determinant of Q is 1 or -1

Recall

Q 7 Q = I

Product! Transpose identity for determinant.

det AB = det A det B

Symme

A, B

det A? = det A

or symme

T

$$Q^{T}Q = I \implies \det Q^{T}Q = \det I = 1$$
 $1 = \det Q^{T}Q = \det Q^{T} \det Q$
 $= \det Q \det Q$
 $= \det Q \det Q$
 $= (\det Q)^{2}$
 $= \det Q = \pm 1$

Problem 4 (12 + 10 = 22 points):

Record your final answer in the allotted spaces. You may use the remaining space for your calculations.

- 4(a) What are the possible eigenvalues of a symmetric projection matrix P and why? $\rho^{\tau} = \rho$
 - · Note that $C(P) = C(P^T) = 1$ N(P), so every X can be written $X = V + J^{in} N(P)$ Line(P)
 - "If v is in C(P) then v can be written as a combo of P's cohumns, v=Pn for some u. In particular $Pv = P(Pn) = P^2 u = Pn = v$.

If
$$Px = \lambda x$$
, then
$$P(v + w) = Pv + Pw \qquad ^{720} \text{ since } w$$

$$= (1)v + (0)w$$

$$= (1)v + (0)w$$

$$\Rightarrow \text{ the only way } x \text{ can be an eigner}$$

$$\Rightarrow \forall v = 0 \text{ (then, } \lambda = 0) \text{ or if } w = 0$$

$$\text{(then, } \lambda = 1).$$

4(b) If the vectors $\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_n$ are orthonormal and $\mathbf{v} = c_1 \mathbf{q}_1 + c_2 \mathbf{q}_2 + \dots + c_n \mathbf{q}_n$, find a formula for the last coefficient c_n .

$$V = C_1 q_1 + C_2 q_2 + --+ C_n q$$

$$Z \left[\begin{array}{c} 1 & q_2 \\ q_1 & q_2 \\ \end{array} \right] \left[\begin{array}{c} C_1 \\ C_2 \\ \end{array} \right]$$

$$Q \left[\begin{array}{c} C_1 \\ C_2 \\ \end{array} \right] = Q \left[\begin{array}{c} Q \\ \end{array} \right] V = Q \left[\begin{array}{c} Q \\ \end{array} \right]$$

$$= \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right] V = \left[\begin{array}{c} Q \\ Q \\ \end{array} \right$$