

# Workshop 1

COMP90051 Machine Learning Semester 2, 2018

#### Plan

1. Icebreaker

- 2. COMP90049 Knowledge & Technologies revision
- 3. Getting acquainted with Jupyter Notebook

## COMP90049 Revision

Assumed knowledge for this course

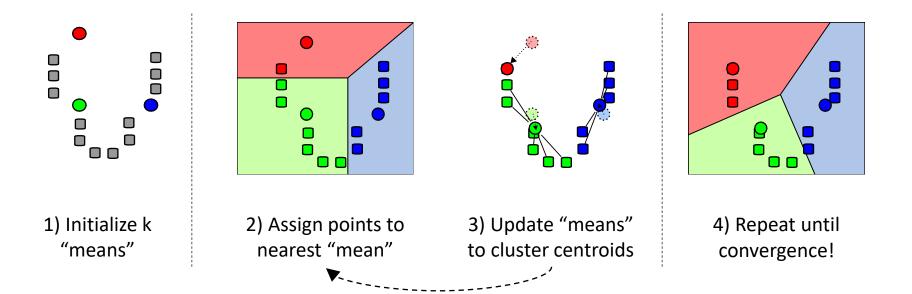
#### Key concepts

- un/supervised learning
- probability theory, entropy
- association rule mining
- k-means clustering
- naive Bayes
- instance-based learning

- feature selection (mutual information)
- decision stump/tree induction (OR, 1R, ID5)
- basic sampling (hold-out, cross-validation)
- evaluation (precision/recall/F, ROC)
- seen: SVMs, bit of Bayes nets

## k-means clustering

- Set-up: a set of n data points  $X = \{x_1, ..., x_n\}$
- Want to partition X into k clusters (minimal within-cluster variance)
- Often use k-means algorithm (has no guarantees)



## Naive Bayes (NB) classifiers

- Want to classify a data point  $\mathbf{x}=(x_1,\dots,x_p)$  into one of k classes  $\{c_1,\dots,c_k\}$
- NB models conditional probability:

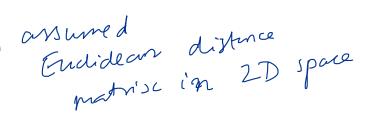
$$P(c_j|\mathbf{x}) \propto P(c_j) \prod_{i=1}^p P(x_i|c_j)$$

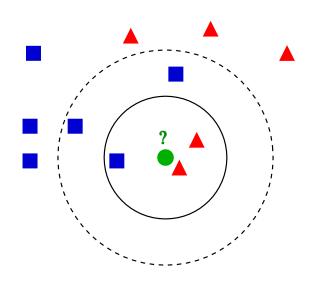
- Relies on Bayes' rule; "naive" conditional independence assumption; assumptions for distributions
- Turn into a classifier: select class  $c_i$  with max probability

$$\hat{y} \in \operatorname{argmax} P(c_j) \prod_{i=1}^p P(x_i|c_j)$$

## Nearest Neighbour (NN) classifiers

- Set-up: have a training set (points + class labels)
- k-NN: classify an unseen point according to the majority class of its k nearest neighbours in the training set
- Need a distance metric
- E.g. of instance-based learning





Predicted class for unseen (green) point depends on k.

for K=3, -> red triangle for K=5, -> blue square.

## Similarity/distance metrics

Euclidean distance

$$||x - y|| = \sqrt{(x - y) \cdot (x - y)} = \sqrt{\sum_{i} (x_i - y_i)^2}$$

Cosine similarity

$$\operatorname{sim}(\boldsymbol{x}, \boldsymbol{y}) = \frac{\boldsymbol{x} \cdot \boldsymbol{y}}{\|\boldsymbol{x}\| \|\boldsymbol{y}\|} = \frac{\sum_{i} x_{i} y_{i}}{\sqrt{\sum_{i} x_{i}^{2}} \sqrt{\sum_{i} y_{i}^{2}}}$$

#### **Decision Trees**

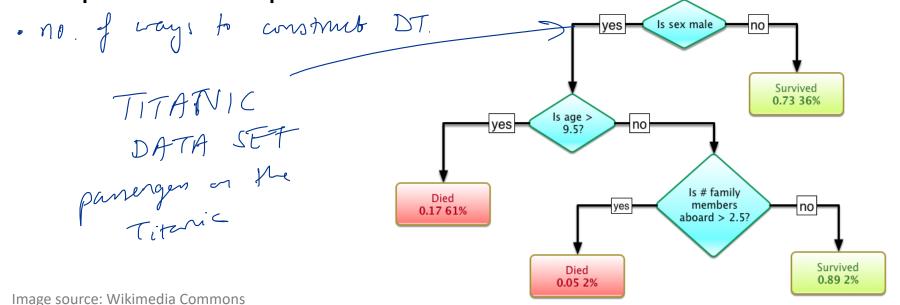
discrete and nonovdered i.e. gender

· Also works quite Lell, when your features are categorical

• Classifies an instance by applying a sequence of decision rules . Easy to interpret —> so good for industry.

The leaves of the tree represent predictions

 Often construct top-down: choose an attribute at each step that best splits the instances



#### Iterative Dichotomiser 3 (ID3)

- Greedy algorithm for constructing a decision tree
- Recursive divide-and-conquer approach
- Relies on metric to determine splitting rule

```
FUNCTION ID3 (Root)

IF all instances at root have same class

THEN stop

ELSE Select a new attribute to use in partitioning root node instances

Create a branch for each attribute value and partition up root node instances according to each value

Call ID3(LEAF<sub>i</sub>) for each leaf node LEAF<sub>i</sub>
```

## ID3 splitting metrics

• **Entropy** for node *R* is

$$H(R) = -\sum_{c \in C} p(c) \log_2 p(c)$$

where C is the set of classes and p(c) is the rel. freq. of class c in R.

• Information gain after splitting node R on attribute A

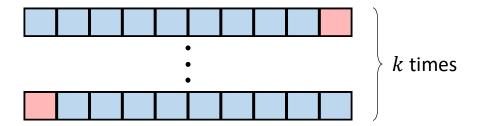
$$IG(R,A) = H(R) - \sum_{r \in R'} p(r)H(r)$$

where R' are the subsets created by splitting R on A and p(r) is the relative size of r (vs R).

## Sampling for evaluation

- Holdout: randomly partition data into a training set and test set.
   training set ↔ model fitting. test set ↔ evaluation.
- Random subsampling: repeat holdout multiple times (fixing the train:test ratio) and take the average evaluation result.
   Random split, may not be representative of inderlying data distribution.
   Stratified random sub-sampling: same as above, but preserves
- Stratified random sub-sampling: same as above, but preserves
  the class distribution in the training/test sets

   weful for intraced dames
- k-fold cross-validation: partition data into k folds, use k-1 for training and 1 as test, repeat for all k permutations



#### Classifier evaluation

- Compare model predictions with ground truth on a held-out test set
- Confusion matrix: counts correct/incorrect predictions
- Evaluation measure: summarises error as a scalar (often between 0 and 1)

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Prediction

	Binary class	Positive	Negative
	Positive	True positive	False positive
	Negative	False negative	True negative

#### Classifier evaluation

 Many evaluation measures to consider—depending on types of errors that are important

$$Precision = \frac{TP}{TP + FP}$$

$$Recall = \frac{TP}{TP + FN}$$

$$F_{\beta} = (1 + \beta^2) \frac{\text{Pr} \cdot \text{Re}}{\text{Re} + \beta^2 \cdot \text{Pr}}$$

nportant

not good for introduced application

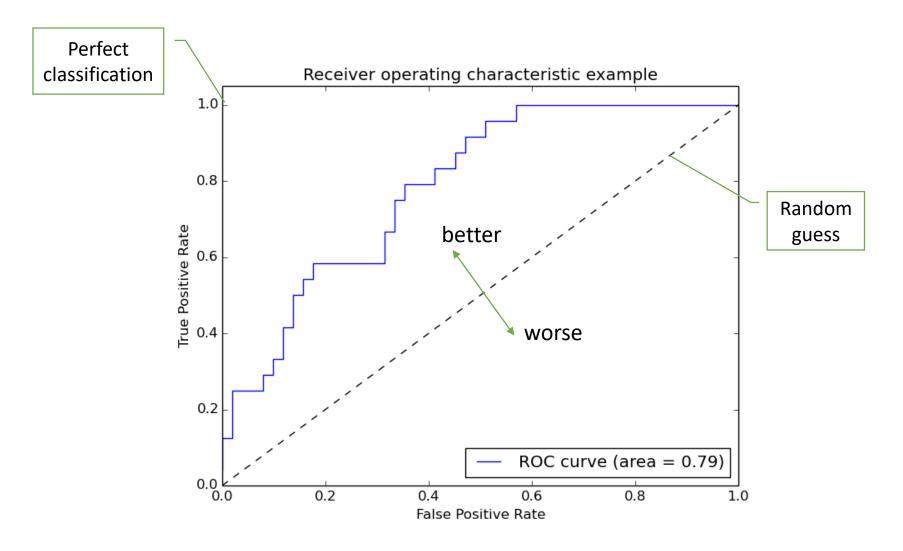
$$TP + TN$$
Accuracy = 
$$\frac{TP + TN}{TP + TN + FP + FN}$$

Error rate = 
$$\frac{FP + FN}{TP + TN + FP + FN}$$

#### Receiver operating characteristic (ROC) curves

- Plots true positive rate (TPR) vs false positive rate (FPR) as the classifier threshold varies
- E.g. for a NB classifier, could compute for thresholds [0.0, 0.1, 0.2, ..., 1.0]
- $FPR = \frac{FP}{FP+TN} = 1 \text{Specificity}; TPR = \frac{TP}{TP+FN} = \text{Recall}$
- Another commonly used measure, Area Under Curve (AUC) is derived from the area under the ROC curve.

#### Receiver operating characteristic (ROC) curves



# Jupyter Notebook

## Running Jupyter Notebook

- 1. Download worksheet01.ipynb from the LMS
- Move the downloaded file to a working directory %WORKDIR%
- 3. Start  $\rightarrow$  Anaconda3 (64-bit)  $\rightarrow$  Anaconda Prompt
- 4. Type the following command at the prompt: jupyter notebook --notebook-dir=%WORKDIR%
- 5. The Jupyter UI should open in a web browser.
- 6. Click on worksheet1.ipynb to get started.