



University of  
Pittsburgh

# Algorithms and Data Structures 2

## CS 1501



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(Slides are adapted from Dr. Ramirez's and Dr. Farnan's CS1501 slides.)

# Announcements

- Upcoming Deadlines
  - Homework 7: this Friday @ 11:59 pm
  - Lab 6: next Monday 10/31 @ 11:59 pm
  - **Assignment 2: Friday 11/4 @ 11:59 pm**
  - Lab 7: Monday 11/7 @ 11:59 pm
- Live Support Session for Assignment 2
  - This Friday 7-8 pm (<https://pitt.zoom.us/my/khattab>)
- Weekly Live QA Session on Piazza
  - Friday 4:30-5:30 pm

# Previous lecture

- ADT Graph
  - definitions
  - representations
    - two-arrays
    - adjacency matrix
    - adjacency lists
  - traversals
    - BFS
      - shortest paths based on number of edges
      - connected components

# This Lecture

- ADT Graph
  - traversals
    - DFS
      - finding articulation points of a graph
  - representation
    - Graph compression

# Problem of previous lecture

- **Input:** A file containing LinkedIn (LI) accounts and their connections
  - Account1: Connection1, Connection2, ...
  - Account2: Connection1, Connection2, ...
  - ...
- **Output:** Answer the following questions:
  - Given two LI accounts, how “far” are they from each other?
    - e.g., 1<sup>st</sup> connection?, 2<sup>nd</sup> connection?, etc.
  - Are the accounts in the file all ***connected***?
    - If not, how many ***connected components*** are there?
  - For each connected component, are there certain accounts that if removed, the remaining accounts become ***partitioned***?



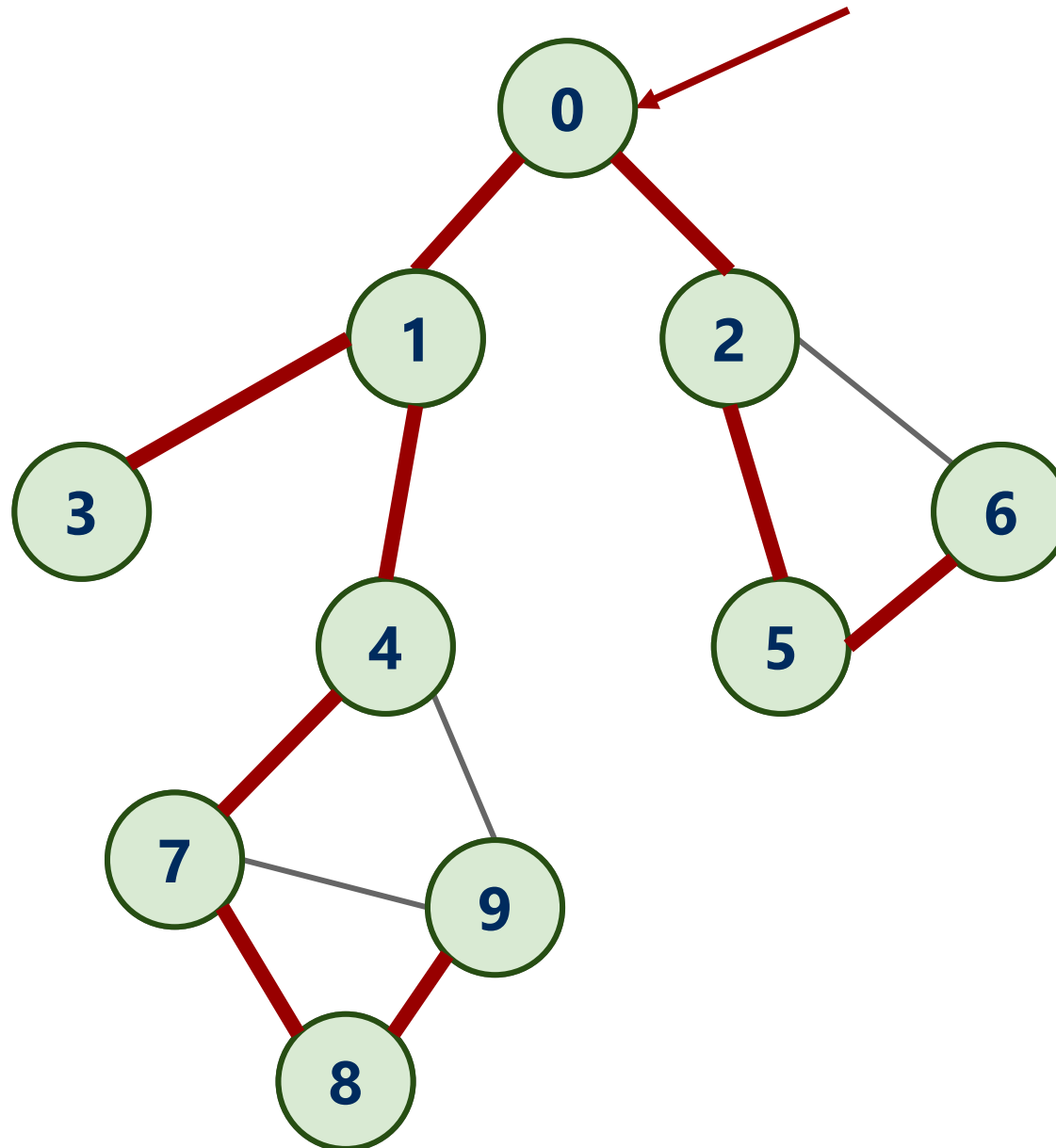
# DFS – Depth First Search

- Already seen and used this throughout the term
  - For Huffman encoding...
    - as we build the codebook out of the Huffman Trie
- Can be easily implemented recursively
  - For each vertex, visit *first* unseen neighbor
  - Backtrack at deadends (i.e., vertices with no unseen neighbors)
    - Try *next* unseen neighbor after backtracking
  - An arbitrary order of neighbors is assumed

# DFS Pseudo-code

```
DFS(vertex v) {  
    seen[v] = true //mark v as seen  
  
    for each unseen neighbor w  
        parent[w] = v  
  
        DFS(w)  
  
}
```

# DFS example



9
8
6
5
2
0

Runtime Stack



# When to visit a vertex

```
DFS(vertex v) {  
  
    seen[v] = true //mark v as seen  
  
    visit v //pre-order DFS  
  
    for each unseen neighbor w  
  
        parent[w] = v  
  
        DFS(w)  
  
}
```

# When to visit a vertex

```
DFS(vertex v) {  
    seen[v] = true //mark v as seen  
  
    for each unseen neighbor w  
        parent[w] = v  
  
        DFS(w)  
  
    visit v //post-order DFS  
}
```

# When to visit a vertex

```
DFS(vertex v) {  
    seen[v] = true //mark v as seen  
  
    for each unseen neighbor w  
        parent[w] = v  
  
        DFS(w)  
  
    (re)visit v //in-order DFS  
}
```

# Runtime Analysis of BFS

- Each vertex is added to the queue exactly once and removed exactly once
  - $v$  add/remove operations
    - $O(v)$  time for vertex processing
- Edges are checked when adding the list of neighbors to the queue
- Each edge is checked at most twice, one per edge endpoint
  - $O(e)$  time for edge processing
- Total time: vertex processing time + edge processing time
  - $O(v + e)$

# Runtime Analysis for DFS

- For Adjacency Matrix representation, BFS checks each *possible* edge!
  - $O(v^2)$  time for edge processing with Adjacency Matrix
- Total time:  $O(v^2 + v) = O(v^2)$

# Runtime Analysis of DFS

- Each vertex is seen then visited exactly once
  - $O(v)$  time for vertex processing
  - except when (re)visiting a vertex after each child
    - vertex processing happens inside edge processing in that case
- Edges are checked when finding the list of neighbors
- Each edge is checked at most twice, one per edge endpoint
  - $O(e)$  time for edge processing
- Total time: vertex processing time + edge processing time
  - $O(v + e)$

# Runtime Analysis of BFS and DFS

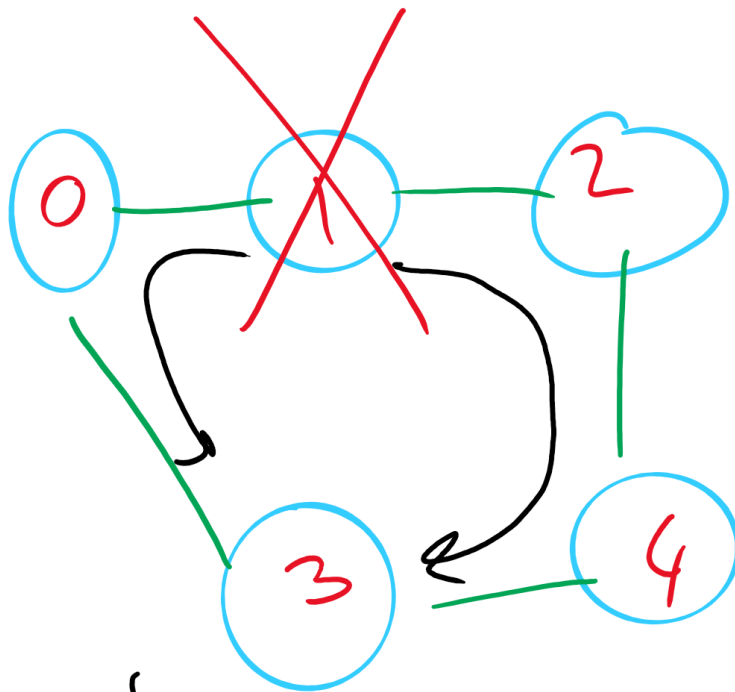
- At a high level, DFS and BFS have the same runtime
  - Each vertex must be seen and then visited, but the order will differ between these two approaches
- The representation of the graph affect the runtimes of of these traversal algorithms?
  - $O(v + e)$  with Adjacency Lists
  - $O(v^2)$  with Adjacency Matrix
  - Note that for a dense graph,  $v + e = O(v^2)$

# Biconnected graphs

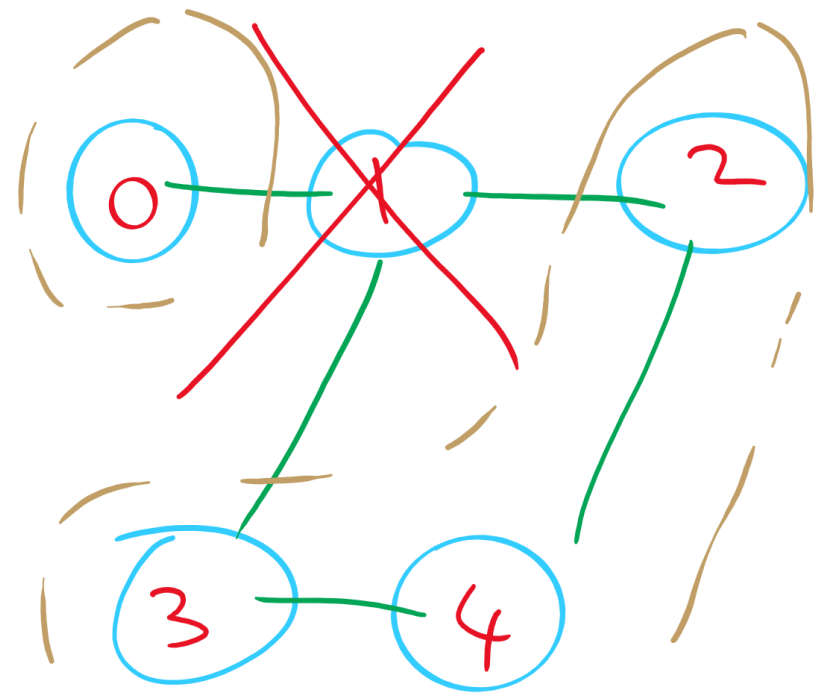
- A *biconnected graph* has at least 2 distinct paths between all vertex pairs
  - a distinct path shares no common edges or vertices with another path except for the start and end vertices
- A graph is biconnected graph iff it has zero *articulation points*
  - Vertices, that, if removed, will separate the graph



# Biconnected Graph



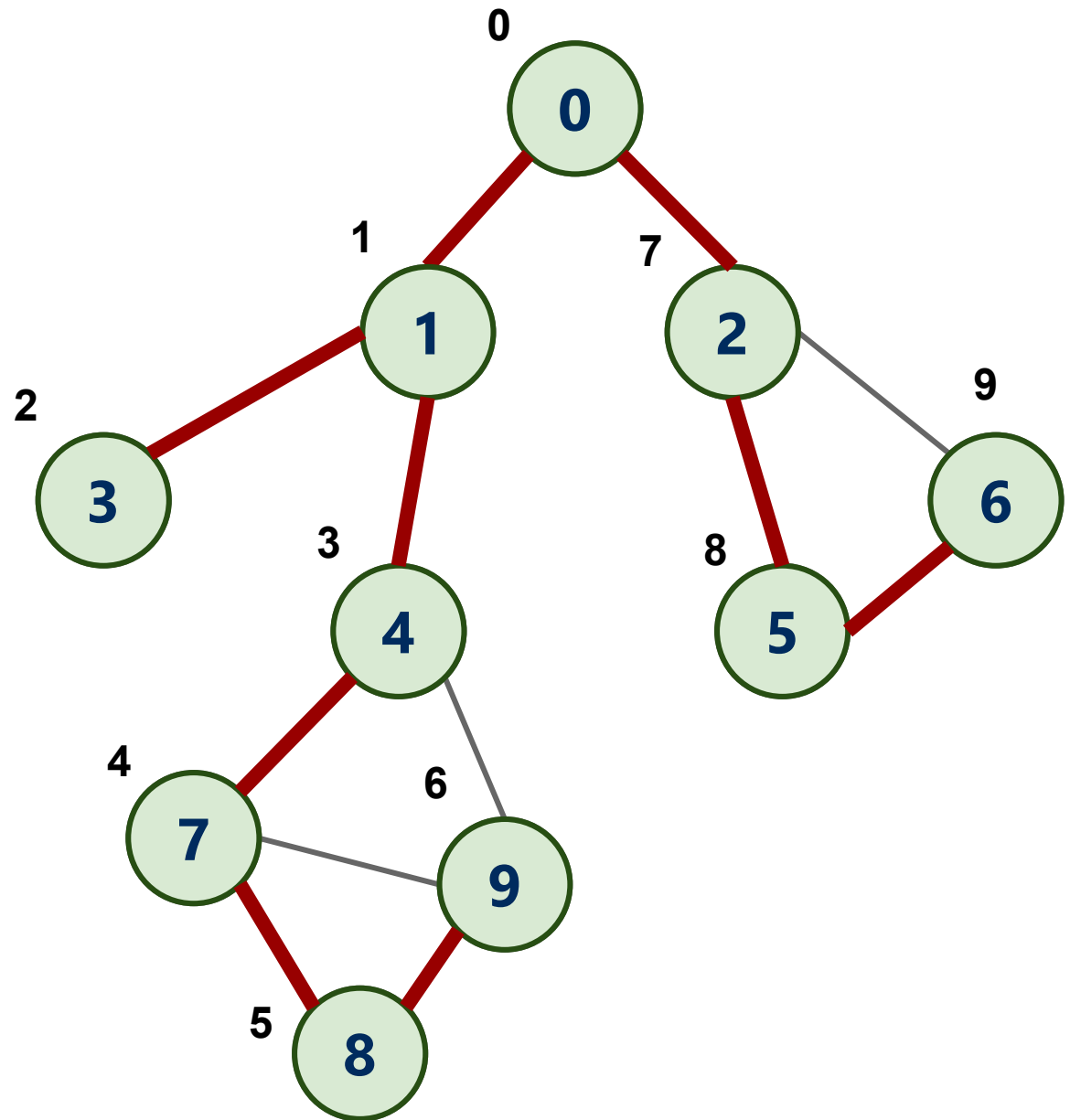
bi-connected



not bi-connected

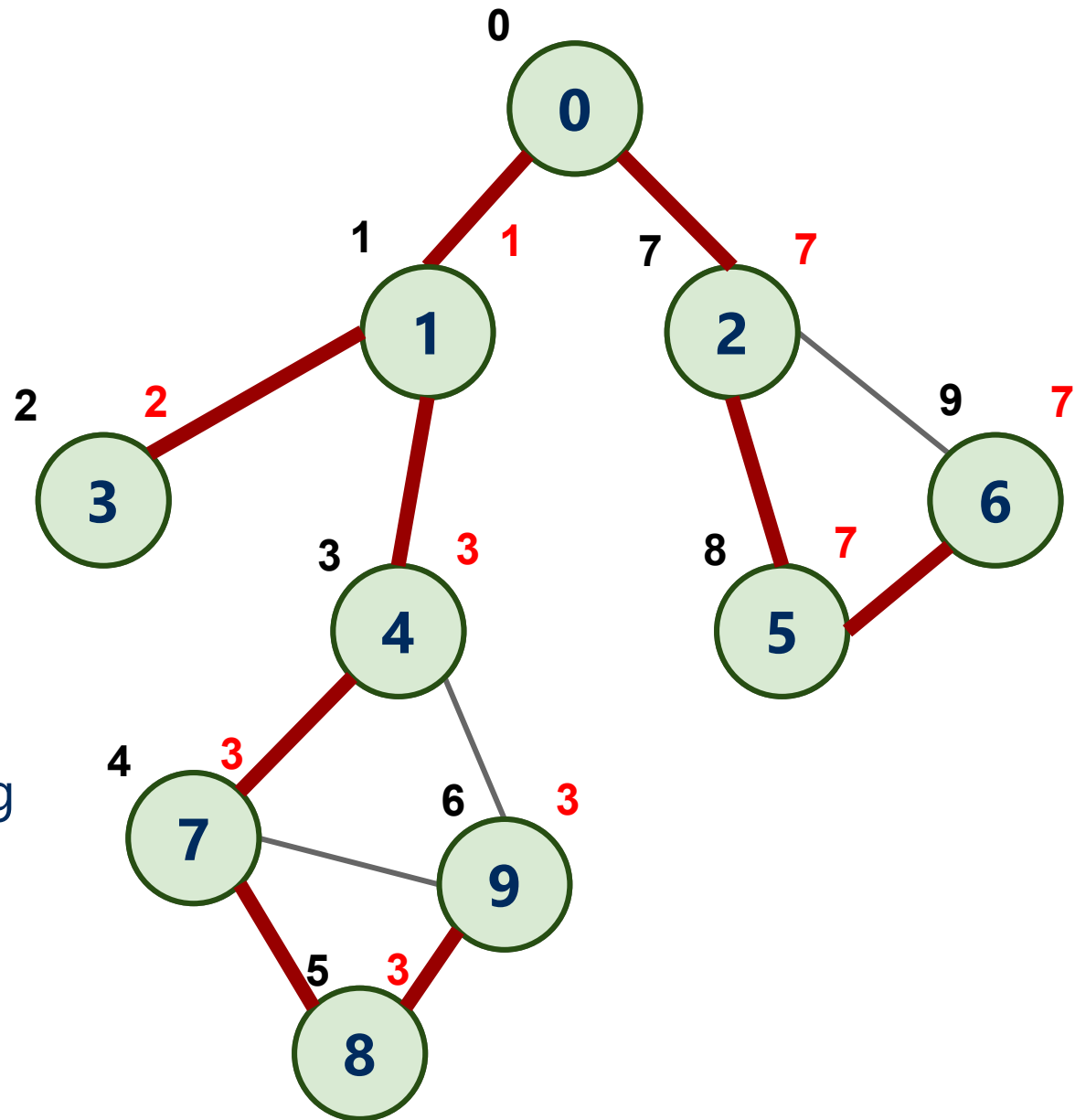
# Finding articulation points of a graph

- Edges not included in the spanning tree are called **back edges**
  - e.g., (4, 9) and (2, 6)
- A pre-order DFS traversal visits the vertices in some order
  - let's number the vertices with their traversal order
  - $\text{num}(v)$



# Finding articulation points of a graph

- For each non-root vertex  $v$ , find the lowest numbered vertex reachable from  $v$ 
  - **not through  $v$ 's parent**
  - **using 0 or more tree edges then at most one back edge**
- move down the tree looking for a back edge that goes backwards the furthest

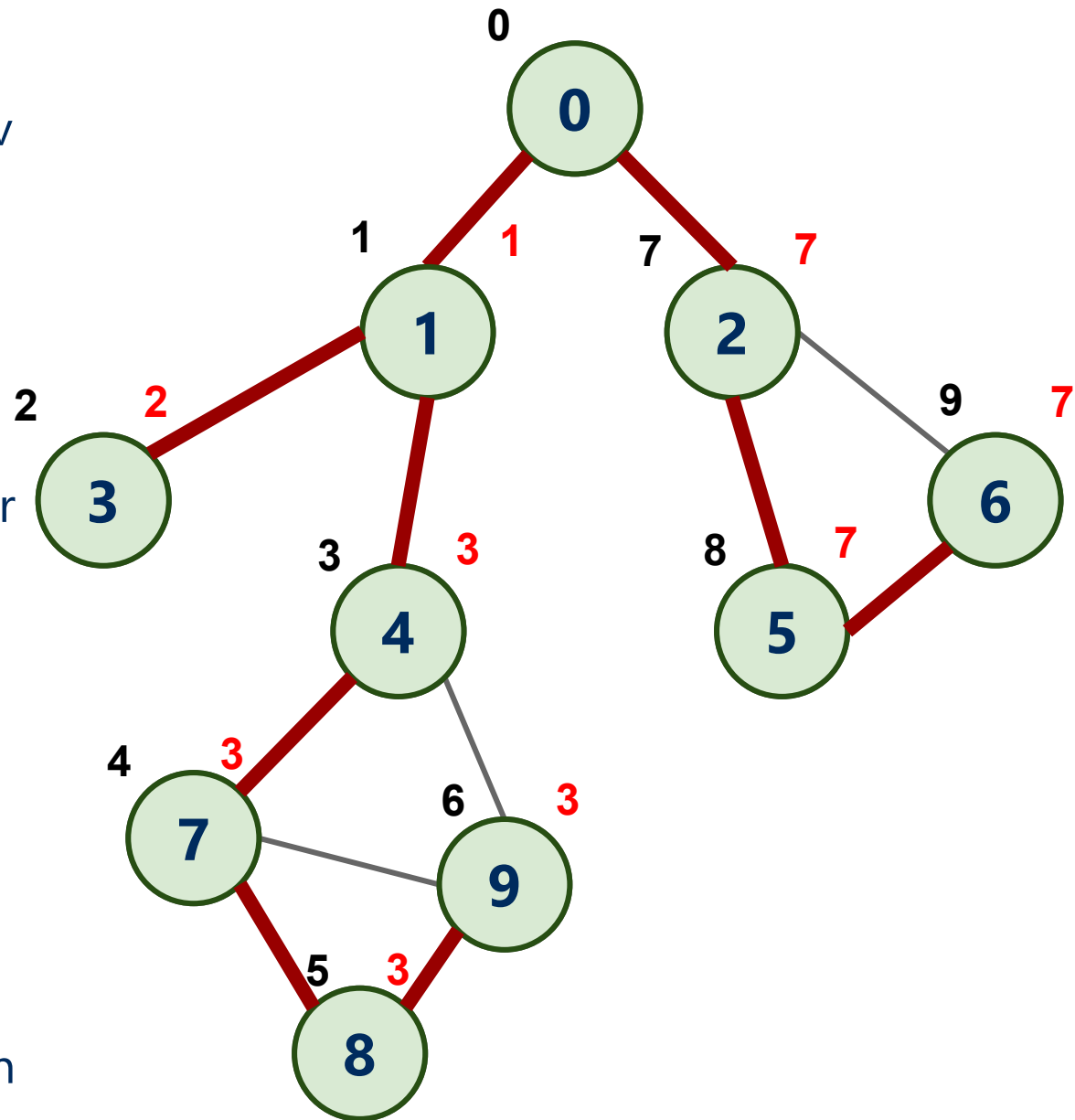


# low(v)

- $\text{low}(v)$  = lowest-numbered vertex reachable from  $v$  using 0 or more spanning tree edges and then **at most one** back edge
  - Min of:
    - $\text{num}(v)$  (the vertex is reachable from itself)
    - Lowest  $\text{num}(w)$  of all back edges  $(v, w)$
    - Lowest  $\text{low}(w)$  of all children of  $v$  (the lowest-numbered vertex reachable through a child)

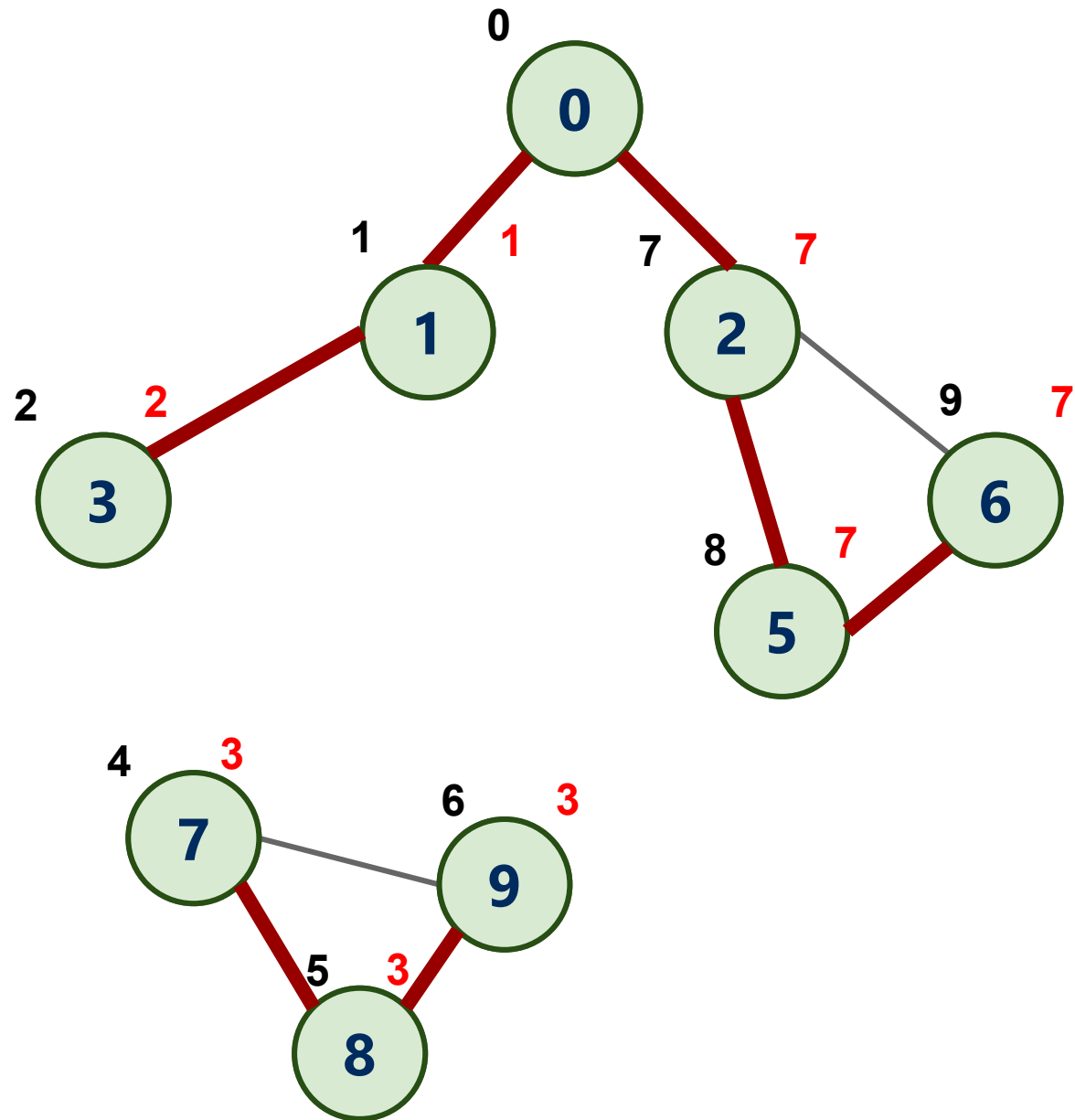
# Finding articulation points of a graph

- What does it mean if a vertex  $v$  has a child  $w$  such that
  - $\text{low}(w) \geq \text{num}(v)$
- e.g., 4 and 7
- It means the child has no other way except through its parent to reach at least one other vertex
- e.g., 7 cannot reach 0, 1, and 3 except through 4
- So, the parent is an articulation point!



# Finding articulation points of a graph

- So, the parent is an articulation point!
  - e.g., if 4 is removed, the graph becomes disconnected
- Each non-root vertex  $v$  that has a child  $w$  with  $\text{low}(w) \geq \text{num}(v)$  is an articulation point



# Finding articulation points of a graph: The Algorithm

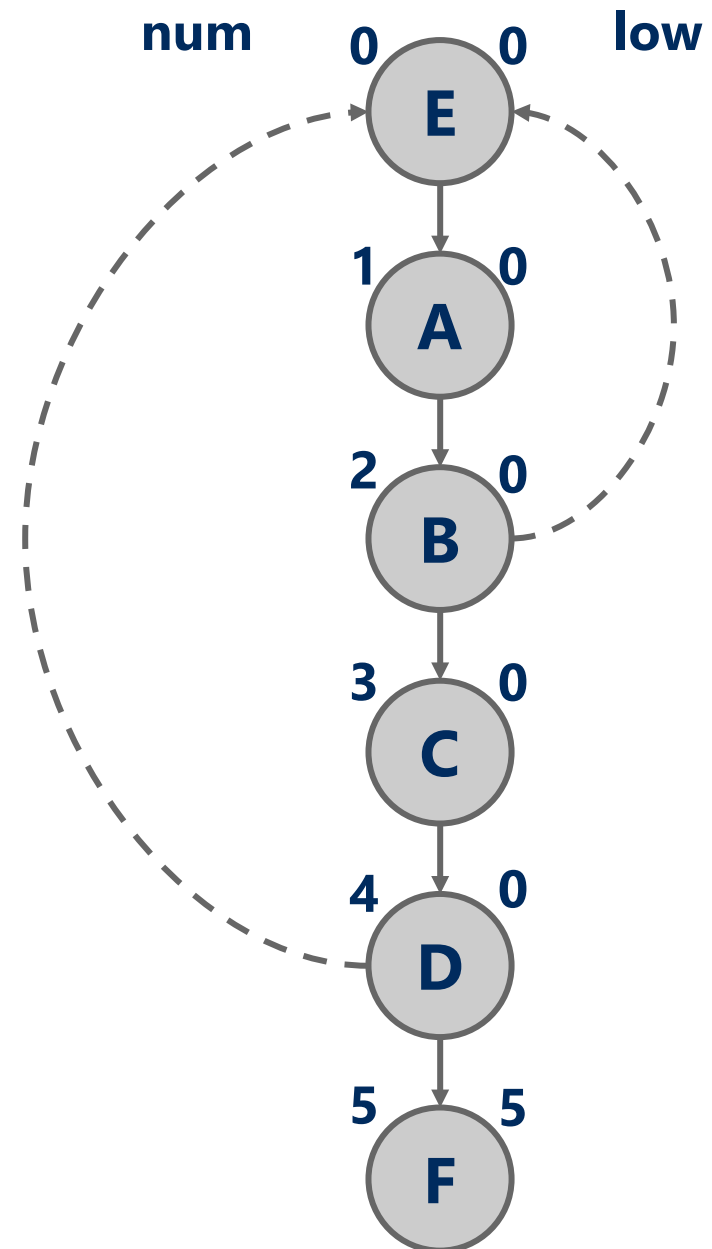
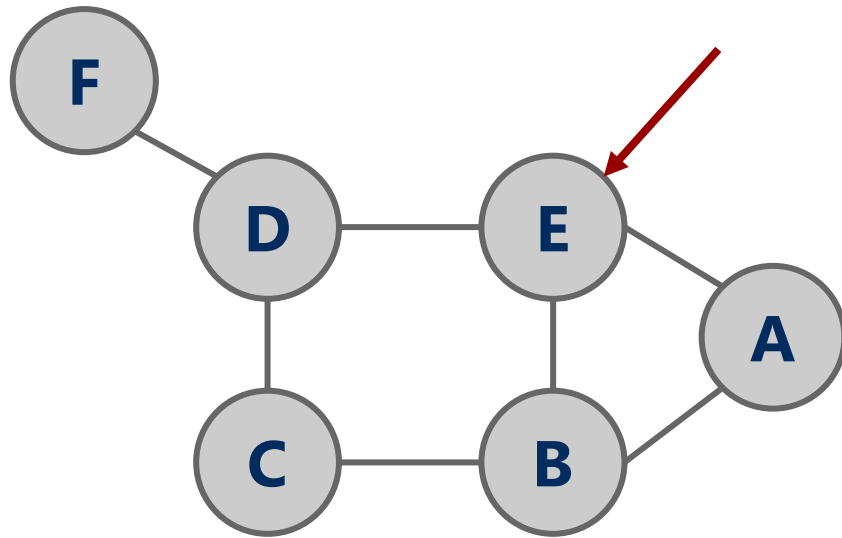
- Build a DFS spanning tree
  - Think of it as directed
  - Create back edges when considering a vertex that has already been visited
  - Label each vertex  $v$  with with two numbers:
    - $\text{num}(v)$  = pre-order traversal order
    - $\text{low}(v)$  = lowest-numbered vertex reachable from  $v$  using 0 or more spanning tree edges and then at most one back edge

# when to compute $\text{num}(v)$ and $\text{low}(v)$

- $\text{num}(v)$  is computed as we move down the tree
  - pre-order DFS
- $\text{low}(v)$  is computed as we move up the tree
- Recursive DFS is convenient to compute both
  - why?



# Finding articulation points example



# Using DFS to find the articulation points of a connected undirected graph

```
int num = 0
```

```
DFS(vertex v) {
```

```
    num[v] = num++
```

```
    low[v] = num[v] //initially
```

```
    seen[v] = true //mark v as seen
```

```
    for each neighbor w
```

```
        if(w unseen){
```

```
            parent[w] = v
```

```
            DFS(w) //after the call returns low[w] is computed, why?
```

```
            low[v] = min(low[v], low[w])
```

```
        } else { //seen neighbor
```

```
            if(w != parent[v]) //and not the parent, so back edge
```

```
                low[v] = min(low[v], num[w])
```

```
        }
```

```
}
```

# What about the root of the spanning tree?

- What if we start DFS at an articulation point?
  - The starting vertex becomes the root of the spanning tree
  - If the root of the spanning tree has more than one child, the root is an articulation point

