Lecture 2: Intensity Surfaces and Gradients

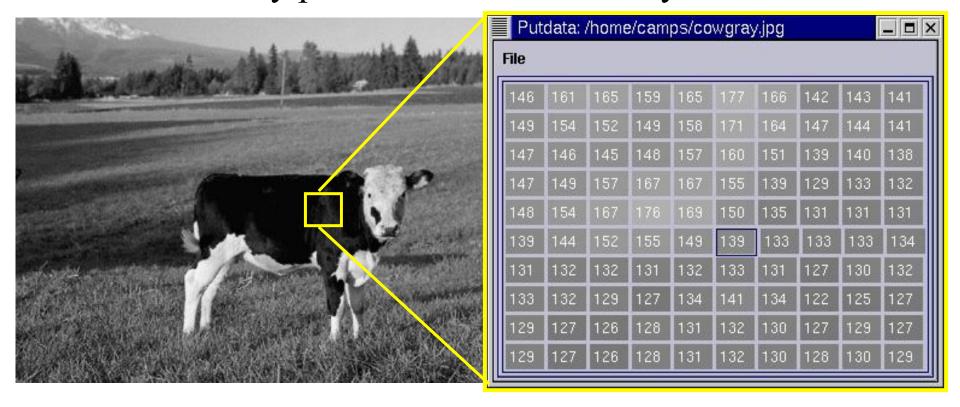
Background reading for Lectures 2-7

- Szeliski, chap 3.2 and chap 4
- Prince, chap 13
- Jain et.al., chap 4 and chap 5 (esp. chap 4.6 for Gaussian smoothing)
- Trucco&Verri, chap 3 and chap 4 (and appendix A.2 for finite diffs)

Digital Images

Intensity pattern

2d array of numbers

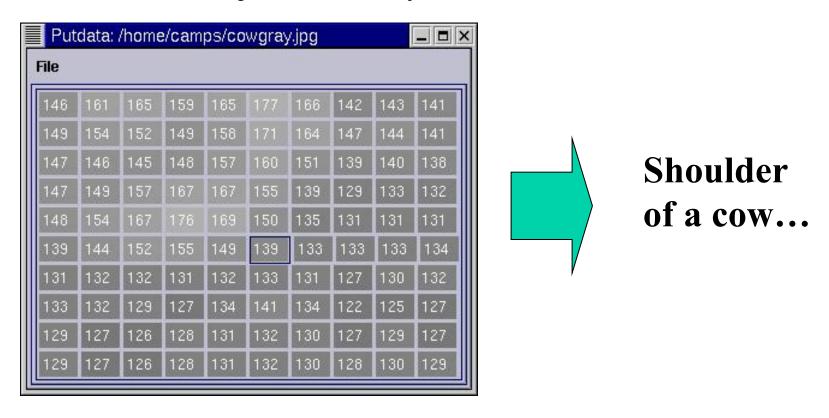


We "see it" at this level

Computer works at this level

Why is Computer Vision Hard?

We are trying to infer things about objects in the world from just an array of numbers

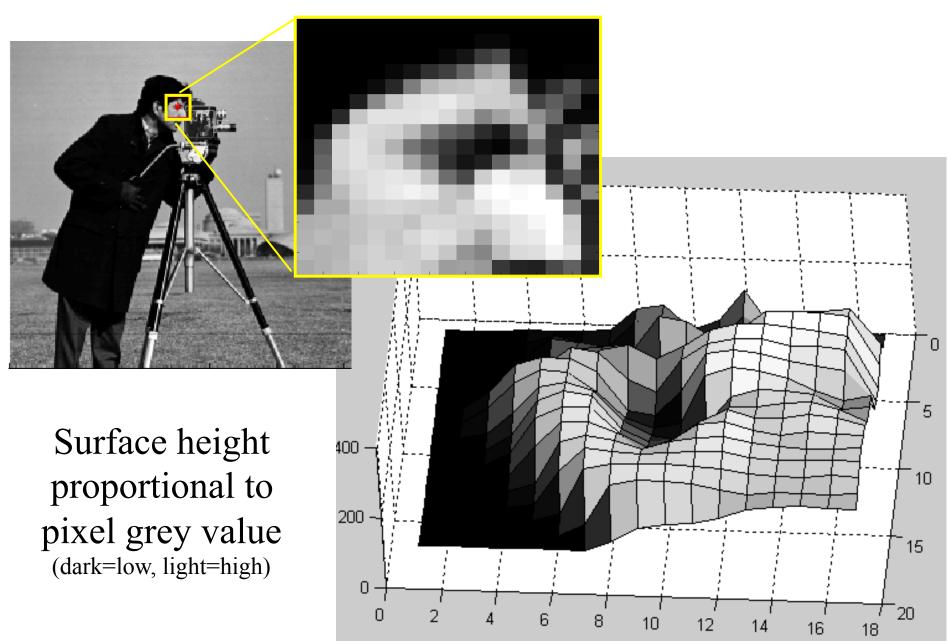


There is a mismatch between levels of abstraction.

Bridging the Gap

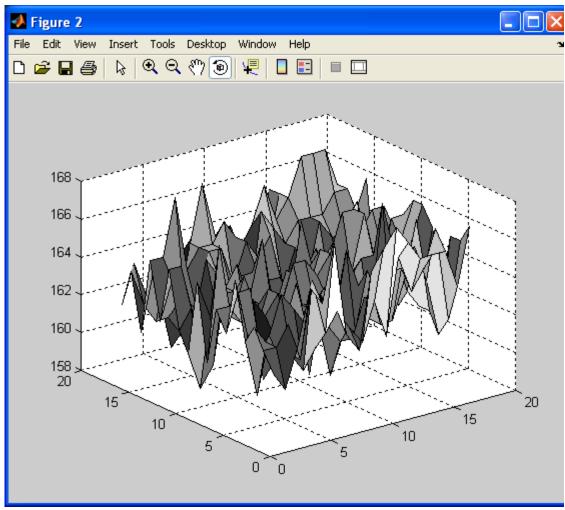
Motivation: we want to visualize images at a level high enough to retain human insight, but low enough to allow us to readily translate our insights into mathematical notation and, ultimately, computer algorithms that operate on arrays of numbers.

Images as Surfaces



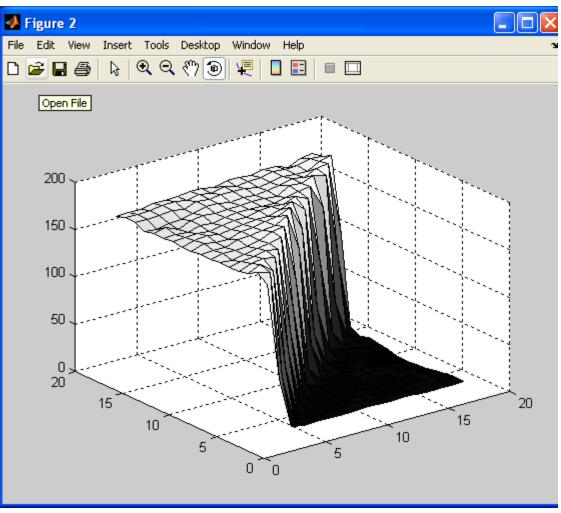


Note: see demoImSurf.m in matlab examples directory on course web site if you want to generate plots like these.

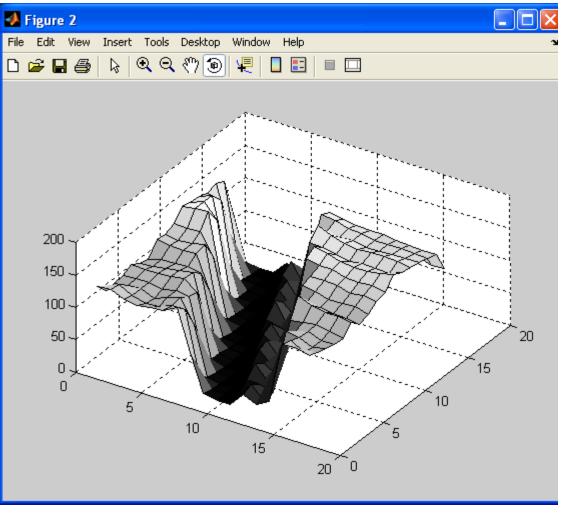


Mean = 164 Std = 1.8

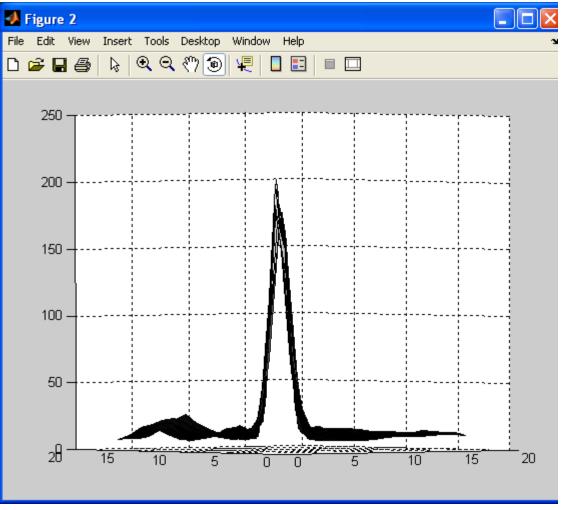




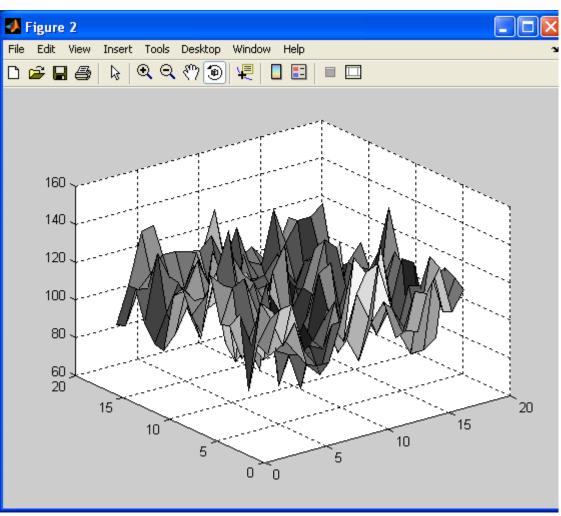






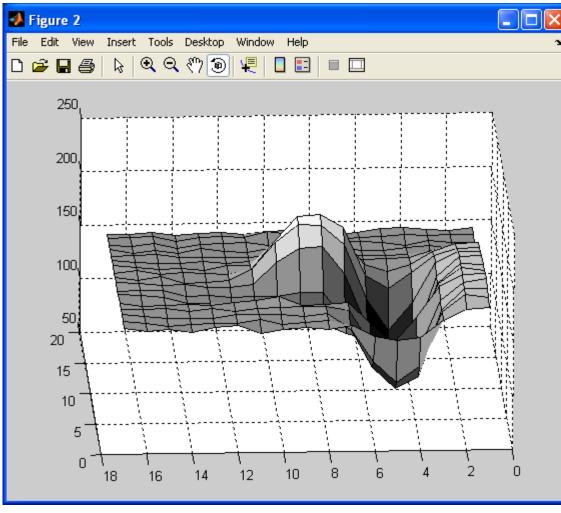




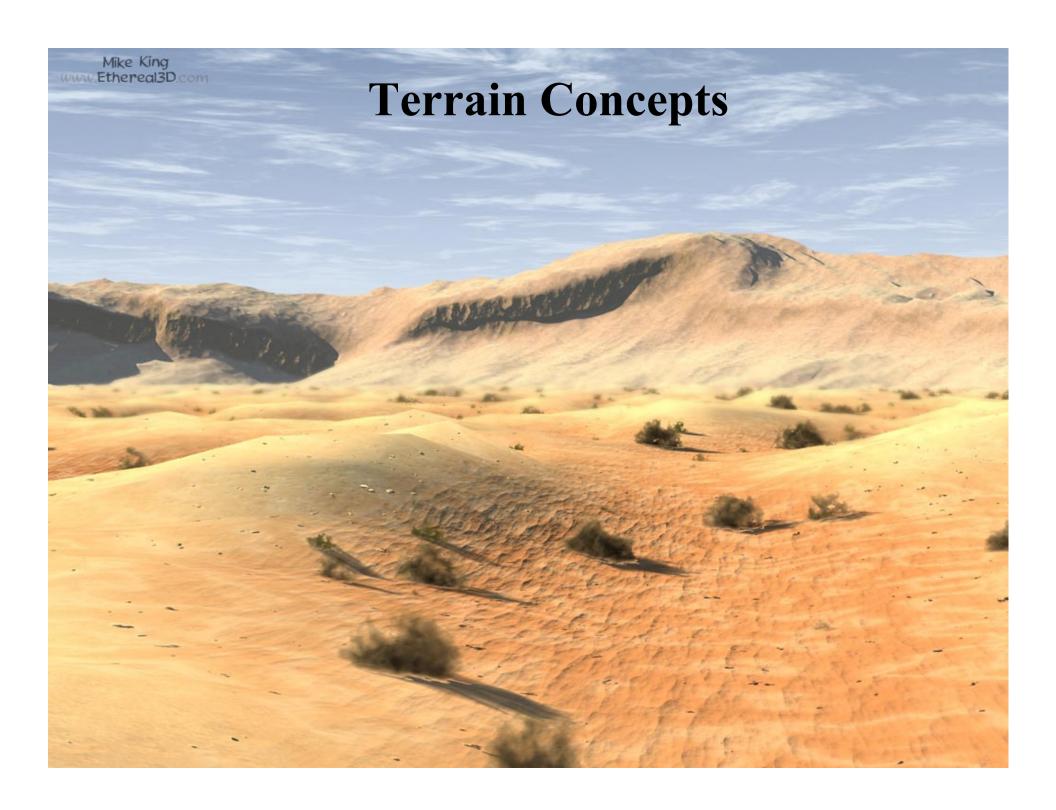


Mean = 111 Std = 15.4





How does this visualization help us?





Terrain Concepts

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Basic notions:
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Uphill / downhill

Contour lines (curves of constant elevation)

Steepness of slope

Peaks/Valleys (local extrema)

More mathematical notions:

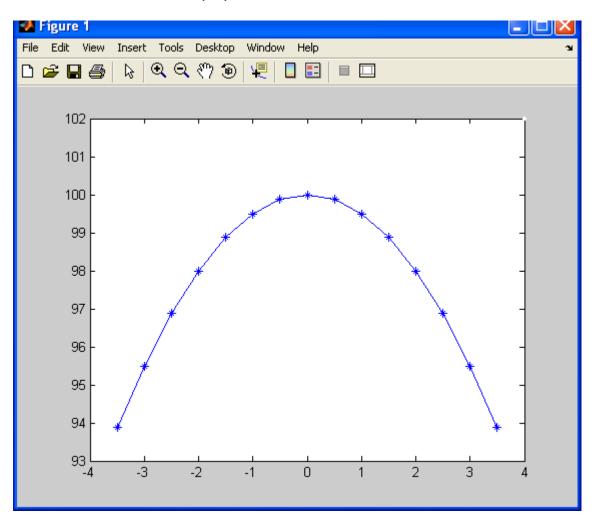
Tangent Plane

Normal vectors

Curvature

Gradient vectors (vectors of partial derivatives) will help us define/compute all of these.

Consider function $f(x) = 100 - 0.5 * x^2$

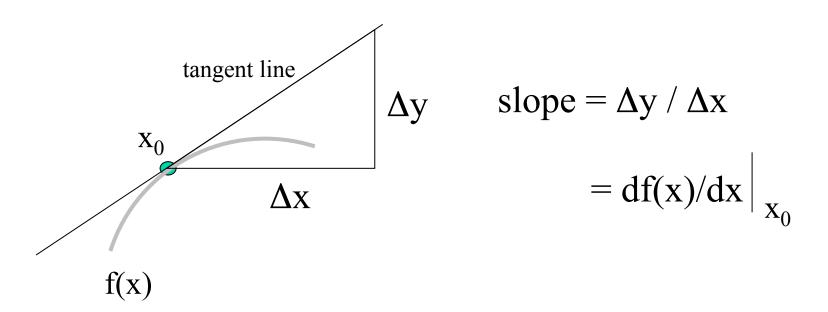


Consider function $f(x) = 100 - 0.5 * x^2$

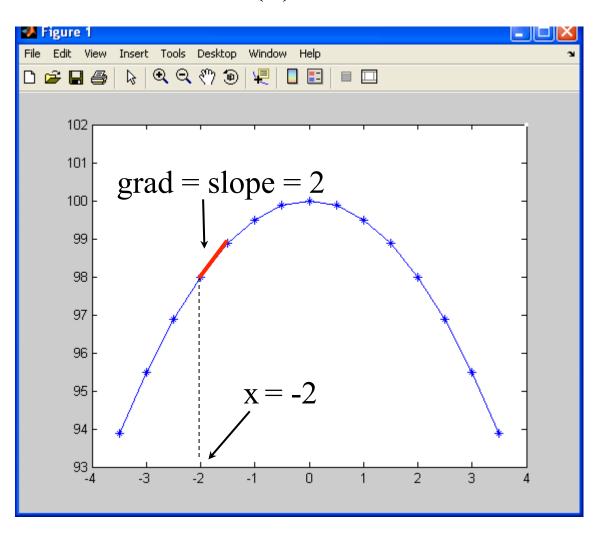
Gradient is df(x)/dx = -2 * 0.5 * x = -x

Geometric interpretation:

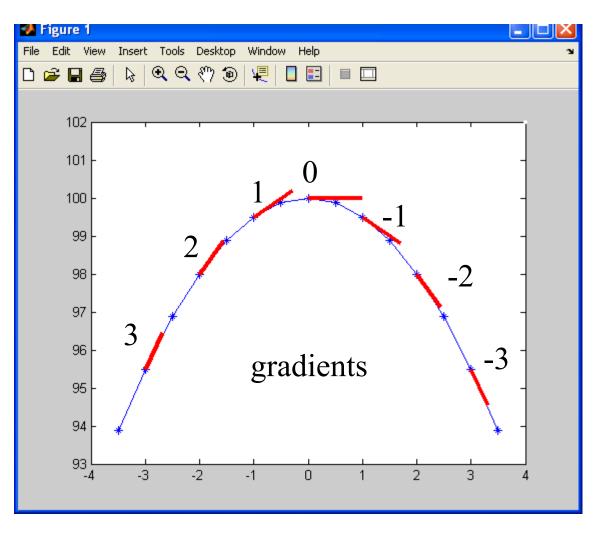
gradient at x_0 is slope of tangent line to curve at point x_0



$$f(x) = 100 - 0.5 * x^2$$
 $df(x)/dx = -x$

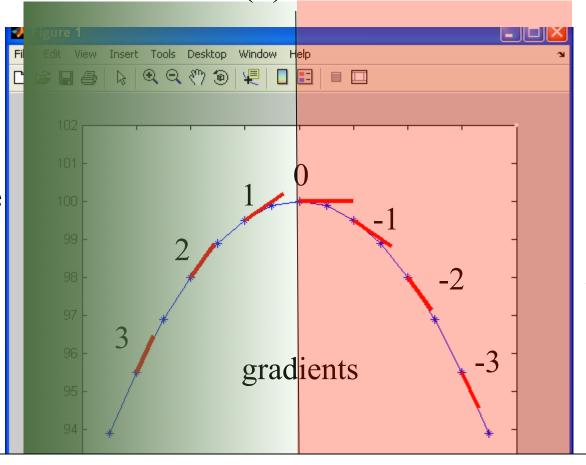


$$f(x) = 100 - 0.5 * x^2$$
 $df(x)/dx = -x$



$$f(x) = 100 - 0.5 * x^2$$
 $df(x)/dx = -x$

Gradients on this side of peak are positive

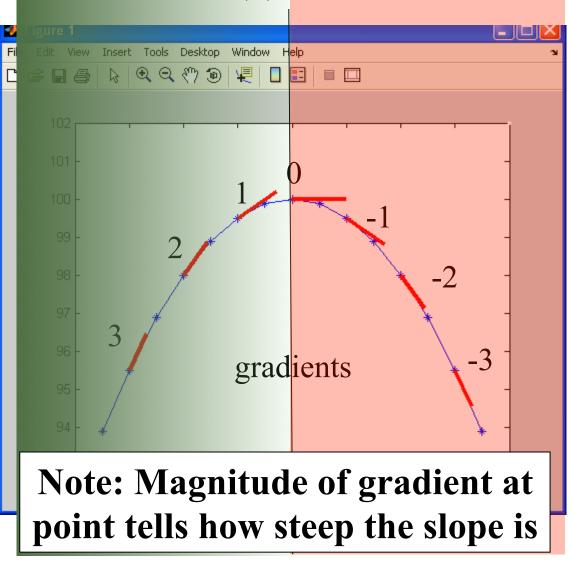


Gradients on this side of peak are negative

Note: Sign of gradient at point tells you what direction to go to travel "uphill"

$$f(x) = 100 - 0.5 * x^2$$
 $df(x)/dx = -x$

Gradients on this side of peak are positive

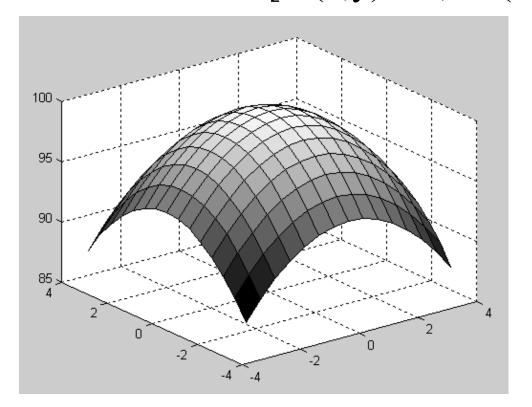


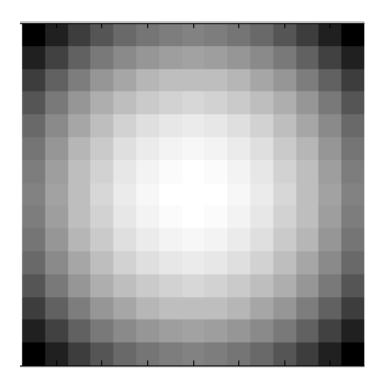
Gradients on this side of peak are negative

$$f(x,y) = 100 - 0.5 * x^2 - 0.5 * y^2$$

$$df(x,y)/dx = -x df(x,y)/dy = -y$$

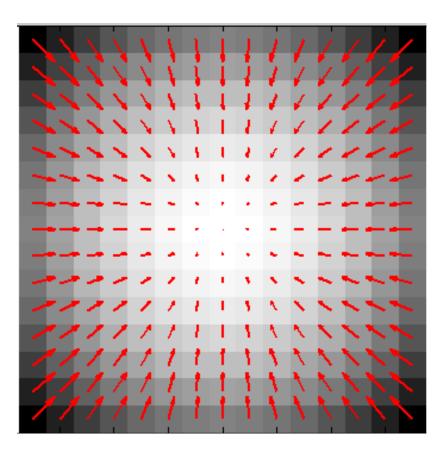
$$Gradient = [df(x,y)/dx, df(x,y)/dy] = [-x, -y]$$





Gradient is vector of partial derivs wrt x and y axes

$$f(x,y) = 100 - 0.5 * x^2 - 0.5 * y^2$$
Gradient = $[df(x,y)/dx, df(x,y)/dy] = [-x, -y]$



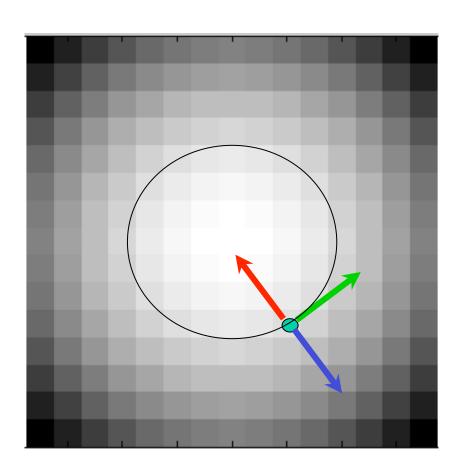
Plotted as a vector field, the gradient vector at each pixel points "uphill"

The vector indicates direction and steepness of ascent.

The gradient is 0 at the peak (also at any flat spots, and local minima,...but there are none of those for this function)

$$f(x,y) = 100 - 0.5 * x^2 - 0.5 * y^2$$

Gradient = [df(x,y)/dx, df(x,y)/dy] = [-x, -y]



Let $g=[g_x,g_y]$ be the gradient vector at point/pixel (x_0,y_0)

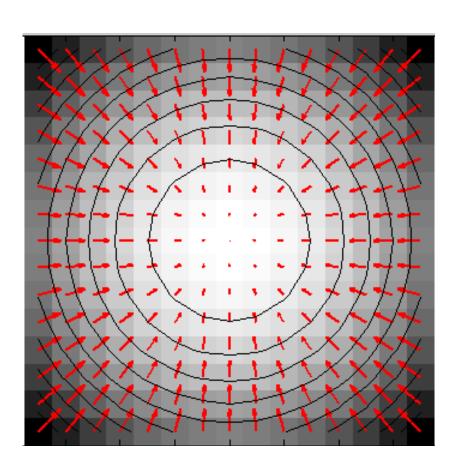
Vector g points uphill

(direction of steepest ascent)

Vector - g points downhill (direction of steepest descent)

Vector $[g_y, -g_x]$ is perpendicular, and denotes direction of constant elevation. i.e. tangent to contour line passing through point (x_0, y_0)

$$f(x,y) = 100 - 0.5 * x^2 - 0.5 * y^2$$
 Gradient = $[df(x,y)/dx, df(x,y)/dy] = [-x, -y]$

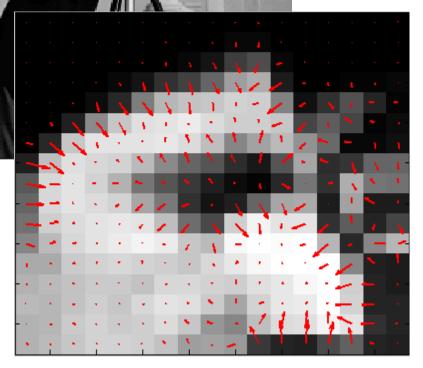


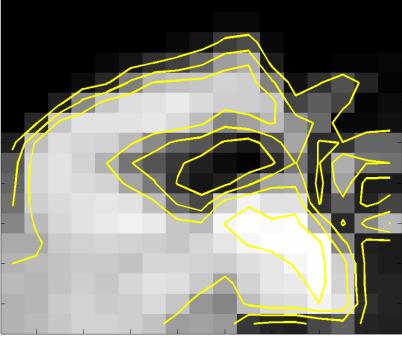
And so on for all points

Image Gradient

The same is true of 2D image gradients.

However, the underlying function is numerical(tabulated) rather than algebraic. So need numerical derivatives.





See also T&V, Appendix A.2

Taylor Series expansion

$$f(x+h) = f(x) + hf'(x) + \frac{1}{2}h^2f''(x) + \frac{1}{3!}h^3f'''(x) + O(h^4)$$

Manipulate:

$$f(x+h) - f(x) = hf'(x) + \frac{1}{2}h^2f''(x) + O(h^3)$$
$$\frac{f(x+h) - f(x)}{h} = f'(x) + O(h)$$

Finite forward difference

See also T&V, Appendix A.2

Taylor Series expansion

$$f(x-h) = f(x) - hf'(x) + \frac{1}{2}h^2f''(x) - \frac{1}{3!}h^3f'''(x) + O(h^4)$$

Manipulate:

$$f(x) - f(x-h) = hf'(x) - \frac{1}{2}h^2f''(x) + O(h^3)$$
$$\frac{f(x) - f(x-h)}{h} = f'(x) + O(h)$$

Finite backward difference

See also T&V, Appendix A.2

Taylor Series expansion

$$f(x+h) = f(x) + hf'(x) + \frac{1}{2}h^2f''(x) + \frac{1}{3!}h^3f'''(x) + O(h^4)$$
subtract
$$-\left[f(x-h) = f(x) - hf'(x) + \frac{1}{2}h^2f''(x) - \frac{1}{3!}h^3f'''(x) + O(h^4)\right]$$

$$f(x+h) - f(x-h) = 2hf'(x) + \frac{2}{3!}h^3f'''(x) + O(h^4)$$
$$\frac{f(x+h) - f(x-h)}{2h} = f'(x) + O(h^2)$$

Finite central difference

See also T&V, Appendix A.2

Finite forward difference

$$\frac{f(x+h) - f(x)}{h} = f'(x) + O(h)$$

Finite backward difference

$$\frac{f(x) - f(x-h)}{h} = f'(x) + O(h)$$

Finite central difference

$$\frac{f(x+h) - f(x-h)}{2h} = f'(x) + O(h^2)$$
More accurate

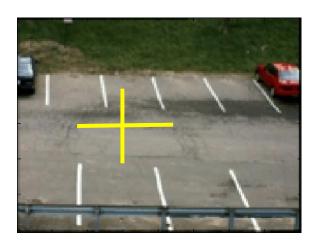
Example: Temporal Gradient

A video is a sequence of image frames I(x,y,t).

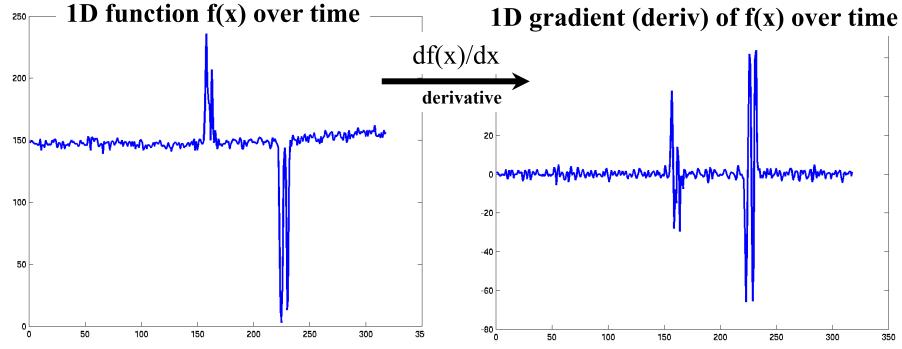


Each frame has two spatial indices x, y and one temporal (time) index t.

Example: Temporal Gradient

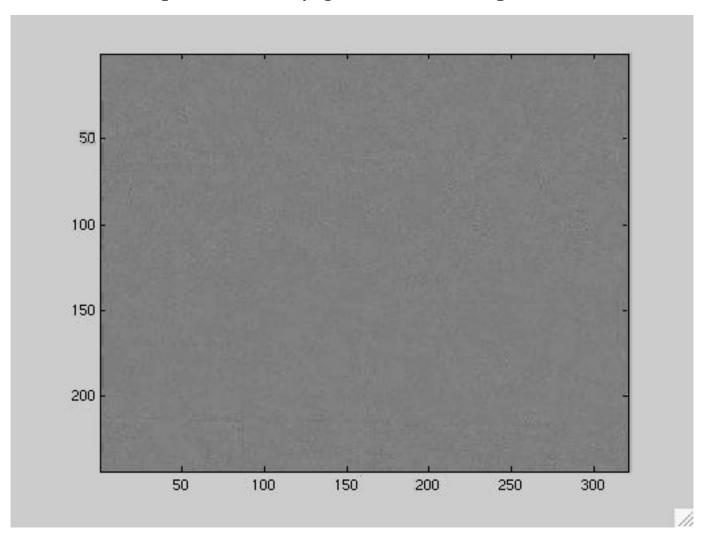


Consider the sequence of intensity values observed at a single pixel over time.

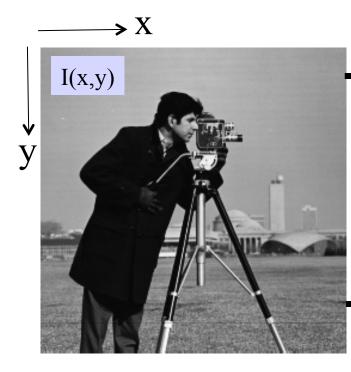


Temporal Gradient (cont)

What does the temporal intensity gradient at each pixel look like over time?



Example: Spatial Image Gradients

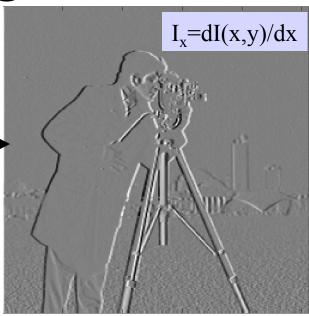


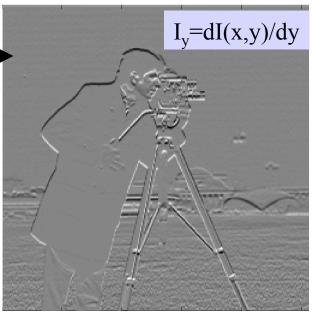
$$\frac{I(x+1,y) - I(x-1,y)}{2}$$

Partial derivative wrt x

$$\frac{I(x,y+1) - I(x,y-1)}{2}$$

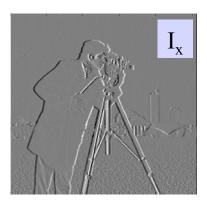
Partial derivative wrt y

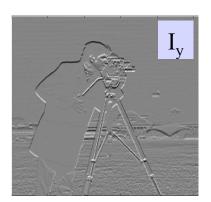




Functions of Gradients







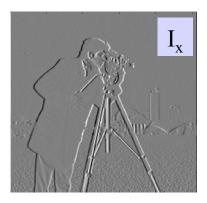
Magnitude of gradient sqrt(Ix.^2 + Iy.^2)

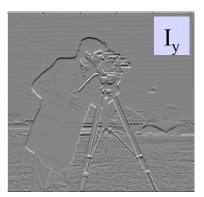
Measures steepness of slope at each pixel



Functions of Gradients

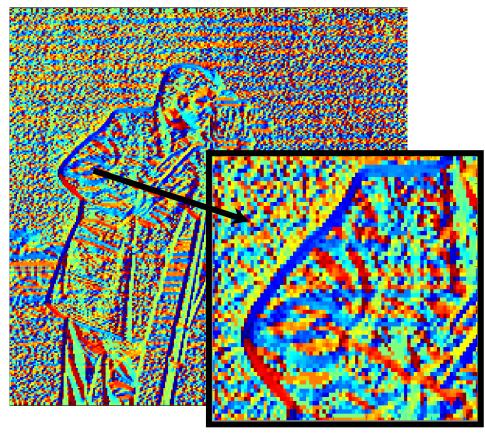






Angle of gradient atan2(Iy, Ix)

Denotes similarity of orientation of slope

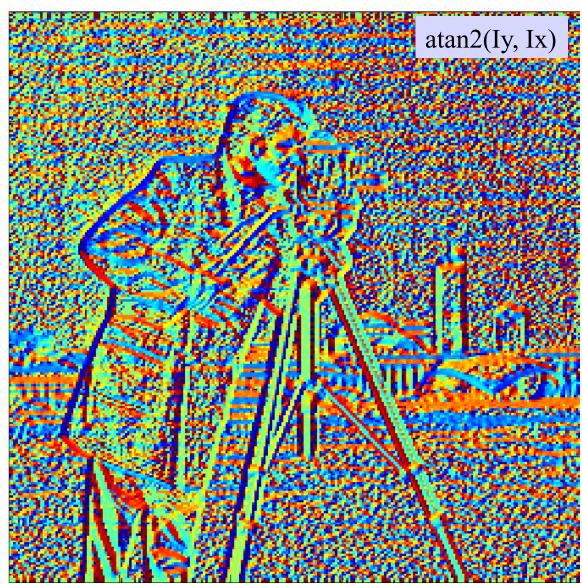


Functions of Gradients



What else do we observe in this image?

Enhanced detail in low contrast areas (e.g. folds in coat; imaging artifacts in sky)



Next Time: Linear Operators

Gradients are an example of linear operators, i.e. value at a pixel is computed as a linear combination of values of neighboring pixels.