

(III.) First Fundamental Form

→ introduce notion to treat metric questions (on curves/surfaces: length of curve, area of subset of surface)
 ↳ notion of distance along curve closely associated with length of a vector in Euclidean space $\mathbb{R}^2, \mathbb{R}^3$, can be used on tangent vectors to define distances (infinitesimal distances) of very close points, 'global' distance between two points along curve then obtained by integration over these local distances

Basic definitions: $\sigma: I \rightarrow \mathbb{R}^n$ smooth curve \Rightarrow speed of σ at $t \in I$ is $\|\sigma'(t)\|_{\mathbb{R}^n}$ (physical interpretation: velocity, motion of particle in n -space $\rightarrow \sigma'(t)$ velocity vec. for particle at time t)
 - distance along σ between $\sigma(t_1)$ and $\sigma(t_2)$: $\int_{t_1}^{t_2} \|\sigma'(t)\| dt \rightarrow$ Idea: vector from $\sigma(t)$ to $\sigma(t+\Delta t)$ approximately $\sigma'(t) \Delta t$ (first lin approx of σ) \rightarrow distance roughly $\|\sigma'(t)\| \Delta t \rightarrow$ Adding up all distances, taking limit $\Delta t \rightarrow 0 \rightarrow$ formula \Rightarrow no rigorous proof

39 3.1: Let $\sigma: I \rightarrow \mathbb{R}^n$ smooth curve \Rightarrow arc length of σ from $t_1 \in I$ to $t_2 \in I$ is $\int_{t_1}^{t_2} \|\sigma'(t)\| dt$
 ↳ arc-length fct for σ a primitive of the speed fct, $t \mapsto \|\sigma'(t)\|$, that is, a differentiable fct $L: I \rightarrow \mathbb{R}$ with $L'(t) = \|\sigma'(t)\|$. Arc length from t_1 to t_2 then $L(t_2) - L(t_1)$
 \Rightarrow Notice: do not require $t_1 \leq t_2$, if $t_2 < t_1$, arc length negative, also L not unique
 $P_1, P_2 \in \mathbb{R}^n \rightarrow P_1 + t(P_2 - P_1) \rightarrow$ line segment length $\|P_2 - P_1\|$ if $t_1 < t_2$ otherwise necessary

Example: $\sigma(t) = p + tq$ a straight line ($q \neq 0$) \Rightarrow arc length from $p + t_1 q$ to $p + t_2 q$ is $\int_{t_1}^{t_2} \|q\| dt = \|q\| (t_2 - t_1) = \|\sigma(t_2) - \sigma(t_1)\|$
 circle: (2) $\sigma(t) = (r \cos t, r \sin t) \Rightarrow \|\sigma'(t)\| = r \forall t \in I \rightarrow$ speed of σ constant $\Rightarrow \int_{t_1}^{t_2} \|\sigma'(t)\| dt = r(t_2 - t_1)$
 helix: (3) $\sigma(t) = (\lambda t, r \cos(\omega t), r \sin(\omega t)) \Rightarrow \|\sigma'(t)\| = \sqrt{\lambda^2 + \omega^2 r^2}$ constant arc length: constant times t for $\int_{t_1}^{t_2}$

→ reasonable geometric notions invariant under reparametrization: arc length as well; as long as they preserve orient.

0 T.3.1: $\sigma: I \rightarrow \mathbb{R}^n$ param curve, $\beta = \sigma \circ \phi: J \rightarrow \mathbb{R}^n$ a reparametrization.
 Let $u_1, u_2 \in J$ and $t_i = \phi(u_i)$ for $i \in \{1, 2\}$. If $\det \phi > 0$ (preserve a.) $\Rightarrow \int_{t_1}^{t_2} \|\sigma'(t)\| dt = \int_{u_1}^{u_2} \|\sigma'(\phi(u))\| |\phi'(u)| du$
 and if $\det \phi < 0 \rightarrow$ same absolute value, opposite signs

Proof: chain rule $\int_{u_1}^{u_2} \|\beta'(u)\| du = \int_{u_1}^{u_2} \|\sigma'(\phi(u))\| \cdot |\phi'(u)| du$, then substitution $dt = \dots$ for $t = \phi(u)$

→ geometric interpret of following theo is that the linear curve from P_1 to P_2 , $t \mapsto P_1 + t(P_2 - P_1)$ is shortest from P_1 to P_2 but not unique in this respect: reparametrization

0 T.3.2: $\sigma: I \rightarrow \mathbb{R}^n$ a param. curve \Rightarrow if $t_1 < t_2$ in I and let L , arc length of σ from t_1 to $t_2 \Rightarrow L \geq \|\sigma(t_2) - \sigma(t_1)\|$

Proof: consider fct $\varphi(t) = \sigma(t) - \sigma(t_1)$ $\Rightarrow \varphi(t_2) - \varphi(t_1) = \|\varphi\|^2 = \int_{t_1}^{t_2} \varphi'(t) dt$
 $\Rightarrow \varphi'(t) = \sigma'(t) \cdot w \Rightarrow$ Cauchy: $\varphi'(t) \leq |\varphi'(t)| \leq \|\sigma'(t)\| \cdot \|w\| \Rightarrow \|w\|^2 \leq \int_{t_1}^{t_2} \|\sigma'(t)\| \cdot \|w\| dt = L \cdot \|w\|$

3.3 Unit speed parametrization

→ param curve has unit speed if $\|\sigma'(t)\| = 1 \forall t \in I \rightarrow$ common practice to replace symbol for var by s
 \Rightarrow determination of arc length simple with unit speed as $\int_{s_1}^{s_2} \|\sigma'(t)\| ds = s_2 - s_1$

0 3.3T: A regular param curve σ allows a direction-preserving reparam. with unit speed (parametrized by arc length)

Proof: $\ell(t)$ an arbitrary arc-length fct (not a unique primitive but always from 0 to t). $\ell'(t) = t \mapsto \|\sigma'(t)\|$ is smooth as σ is smooth and as regular never 0 $\Rightarrow \|\sigma'(t)\| > 0$, ℓ smooth
 $\Rightarrow \ell$ bijective onto its image, $\Phi = \ell^{-1}$ smooth $\Rightarrow \Phi'(s) = \ell^{-1}'(s) \stackrel{1}{=} \frac{1}{\ell'(t)} = \frac{1}{\|\sigma'(t)\|} > 0$ where $t = \Phi(s) \Leftrightarrow s = \ell(t)$
 $\Rightarrow (\sigma \circ \Phi)'(s) = \sigma'(\Phi(s)) \cdot \Phi'(s) = \frac{\sigma'(t)}{\|\sigma'(t)\|}$ where $t = \Phi(s) \rightarrow \sigma \circ \Phi$ unit speed

Example: (1) curve with constant speed $c \neq 0$: $\ell(t) = ct \Rightarrow \Phi(s) = \ell^{-1}(s) = \frac{s}{c} \rightarrow$ unit speed param. achieved by inserting $t = \frac{s}{c}$ into expression σ

↳ e.g. for $\sigma(t) = (c \cos t, r \sin t) \Rightarrow \ell(t) = rt \Rightarrow \beta(s) = \sigma(\frac{s}{r}) = (c \cos \frac{s}{r}, r \sin \frac{s}{r}) \rightarrow$ circle

↳ helix: $\beta(s) = (\lambda \frac{s}{c}, r \cos(\omega \frac{s}{c}), r \sin(\omega \frac{s}{c}))$ where $c = \sqrt{\lambda^2 + r^2 \omega^2} \rightarrow$ helix constant speed

First Fundamental Form:

Def: $\sigma: U \rightarrow \mathbb{R}^3$ param. surface: Three fcts on U , associated with $\sigma: E(p) = \|\sigma'_u(p)\|^2$, $F(p) = \sigma'_u(p) \cdot \sigma'_v(p)$, $G(p) = \|\sigma'_v(p)\|^2$
 ↳ three fcts together analogue for surfaces of speed $\|\sigma'(t)\|$ of curve (or rather $\|\sigma'(t)\|^2$)
 ↳ Cauchy-Schwartz-inequality: $F(p)^2 \leq E(p)G(p)$ with strict inequ. $\Leftrightarrow \sigma$ regular at $p \Leftrightarrow \sigma'_u, \sigma'_v$ lin indep.

↳ fcts E, F, G useful for computing lengths of tangent vectors. Assume σ regular at p , $(\sigma'_u(p), \sigma'_v(p))$ then basis for $T_p\sigma \Rightarrow u \in T_p\sigma, u = a\sigma'_u + b\sigma'_v \Rightarrow \|u\|^2 = (a\sigma'_u + b\sigma'_v) \cdot (a\sigma'_u + b\sigma'_v) = Ea^2 + 2Fab + Gb^2$

D.3.4: σ regular at p : map $I_p: T_p\sigma \rightarrow \mathbb{R}, u \mapsto \|u\|^2 = E(p)a^2 + 2F(p)ab + G(p)b^2$ (\rightarrow associates to tangent vec the square of its length) is called first fundamental form of σ in p . E, F, G component fcts

↳ matrix form: $I_p(u) = \begin{pmatrix} a \\ b \end{pmatrix}^T \begin{pmatrix} E(p) & F(p) \\ F(p) & G(p) \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} \quad \left[\begin{pmatrix} E & F \\ F & G \end{pmatrix} = (D\sigma)^T \cdot D\sigma = \begin{pmatrix} \sigma'_u \\ \sigma'_v \end{pmatrix} \begin{pmatrix} \sigma'_u & \sigma'_v \end{pmatrix} \right]$

↳ I_p quadratic form on $T_p\sigma \forall p \in U$ (quad. f: vector space V with base $(v_1, v_2), Q: V \rightarrow \mathbb{R}, u = av_1 + bv_2 \mapsto ea^2 + 2fab + gb^2$)

Example: (1) $\sigma(u, v) = p + uq_1 + vq_2, q_1, q_2 \in \mathbb{R}^3$ assumed to be lin. independent $\Rightarrow \sigma'_u = q_1, \sigma'_v = q_2 \Rightarrow E = \|q_1\|^2, F = q_1 \cdot q_2, G = \|q_2\|^2$

↳ if q_1, q_2 orthonormal (norm 1, inner prod. 0) pair $\Rightarrow E = G = 1, F = 0$

(2) $\sigma(u, v) = (\cos v, \sin v, u)$ (cylinder) $\Rightarrow \sigma'_u = (0, 0, 1), \sigma'_v = (-\sin v, \cos v, 0) \Rightarrow E = 1, F = 0, G = 1$

(3) unit sphere: (spherical coordinates), 2.3.1 $\Rightarrow E = 1, G = \cos^2 u$ (not constant), $F = 0$

smooth fcts, vector $\in U$

T.3.4: The arc length of param curve $\gamma(t) = \sigma(u(t), v(t))$ on σ (2.4: $\gamma' = u'\sigma'_u + v'\sigma'_v$) is given with respect to coordinates $(u(t), v(t))$ as follows: $\int_{t_1}^{t_2} (Eu'^2 + 2Fu'v' + Gv'^2)^{1/2} dt$
 where E, F, G are evaluated in $(u(t), v(t))$ and derivatives u', v' are eval. in t

Proof: $\|\gamma'(t)\|^2 = I_p(\gamma'(t)) = Eu'(t)^2 + 2Fu'(t)v'(t) + Gv'(t)^2$ and rest is def. of arc length...

Example: (1) circle $\gamma(t) = \sigma(u, t)$ on unit sphere with fixed latitude u $\Rightarrow u' = 0, v'(t) = 1 \rightarrow$ with values of E, F, G of ex. above we obtain: total length of $\gamma: \int_0^{2\pi} (Eu'^2 + 2Fu'v' + Gv'^2)^{1/2} dt = \int_0^{2\pi} \cos u dt = 2\pi \cos u$

First fundamental form can be used to determine angle between (non-zero) tangent vectors, say between

$w = a\sigma'_u(p) + b\sigma'_v(p), \tilde{w} = \tilde{a}\sigma'_u(p) + \tilde{b}\sigma'_v(p)$ in $T_p\sigma \Rightarrow \theta \in [0, \pi], \cos \theta = \frac{w \cdot \tilde{w}}{\|w\| \cdot \|\tilde{w}\|}$

$$\Rightarrow \cos \theta = \frac{Ea\tilde{a} + F(a\tilde{b} + b\tilde{a}) + Gb\tilde{b}}{(Ea^2 + 2Fab + Gb^2)^{1/2} (E\tilde{a}^2 + 2F\tilde{a}\tilde{b} + G\tilde{b}^2)^{1/2}}$$

angle between σ'_u and $\sigma'_v = \cos \theta = \frac{F}{\sqrt{EG}}$

↳ parametrized surface $\sigma(u, v)$ called orthogonal, if $F(p) = 0 \forall p \in U \Leftrightarrow \sigma'_u(p)$ and $\sigma'_v(p)$ always perpendicular $\Leftrightarrow \theta = \frac{\pi}{2} \forall p \in U$

(2) $\gamma(t)$ curve on unit sphere $\rightarrow \gamma(t) = \sigma(u(t), v(t)) \rightarrow$ determine angle between tan vect $\gamma'(t)$ an direction (North) of meridians \rightarrow meridians characterized by fixed longitude $v \rightarrow$ tan vect. of meridian has direction $\sigma'_u \Rightarrow (a = u'(t), b = v'(t)) \wedge (\tilde{a} = 1, \tilde{b} = 0) \Rightarrow$ values of E, F, G above $\rightarrow \cos \theta = \frac{u'}{(u'^2 + \cos^2 u(v')^2)^{1/2}}$

Areas and plane curves:

\rightarrow consider $D \subseteq \mathbb{R}^2$. If $D = [a, b] \times [c, d] \rightarrow$ rectangle with area $A(D) = (b-a)(d-c)$. If $f: D \rightarrow \mathbb{R}$ continuous

we define integral of f over D by $\int_D f dA = \int_a^b \int_c^d f(u, v) dv du = \int_c^d \int_a^b f(u, v) du dv$

(\rightarrow inner integral depends contin. on u)

↳ Fubini-theorem: both integrals finite \Rightarrow can change order of integration \rightarrow can always change in our course

K is a block-set

\rightarrow if D not a rectangle \rightarrow more diff. to define its area and integrals over it. By a block set we understand a finite union of closed rectangles \rightarrow by decomposing rectangles further, we can achieve that they only overlap on boundaries, such a decomposition then called partition of the block set (not unique).

\Rightarrow independant of choice of partition: $A(K)$ is sum of rectangles, $\sum_K \int_D f dA$ sum of integrals over them

area of K
 \rightarrow is integral of constant fct 1 over

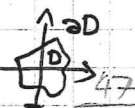
$$0 \leq \int_K f dA \leq A(K) \sup_{p \in K} |f(p)|$$

$\circ \int_{K_1 \cup K_2} f dA = \int_{K_1} f dA + \int_{K_2} f dA$ if the two block sets only overlap on their boundaries

smooth curves on closed intervals: $\gamma: [a, b] \rightarrow \mathbb{R}^2$, $-\infty < a < b < \infty \rightarrow \gamma$ smooth on (a, b) and has a continuous extension as well as all its derivatives to $[a, b]$ (that is, they have limits from left and right at the endpoints)

Gebiet

3.5.1: set $D \subset \mathbb{R}^2$ called an elementary domain if it is closed and bounded (compact) and if its boundary ∂D is a finite union of (the trace of) smooth curves def. on closed intervals



↳ block-sets are elementary domains since their boundaries are unions of line segments

3.5.2: $D \subset \mathbb{R}^2$ an elementary domain. The area of D def by: $A(D) = \sup_{K \subset D} A(K)$ where K are block-sets

↳ continuous fct $f: D \rightarrow \mathbb{R}$, $f(p) \geq 0 \forall p \in D$ def by: $\int_D f dA = \sup_{K \subset D} \int_K f dA$

↳ supremums are finite: since D is bounded, it is contained in a sufficiently large square with side-length $N \Rightarrow \int_D f dA \leq A(K) \sup_{p \in K} f(p) \leq A(D) \sup_{p \in D} f(p)$ which is finite since f continuous (max on compact domain)

split function into positive and negative part

⇒ remove assumption $f \geq 0 \Rightarrow f: U \rightarrow \mathbb{R}$ continuous, $f_+(x) = \max\{0, f(x)\}$, $f_-(x) = \max\{0, -f(x)\}$ so that $f_+, f_- \geq 0$ and $f = f_+ - f_- \Rightarrow \int_D f dA = \int_D f_+ dA - \int_D f_- dA$

o $\int_D f + g dA = \int_D f dA + \int_D g dA$ o $\int_D c f dA = c \int_D f dA$ o $|\int_D f dA| \leq \int_D |f| dA$

o $\int_{D_1 \cup D_2} f dA = \int_{D_1} f dA + \int_{D_2} f dA$ where D_1, D_2 only intersect with their boundaries

Null sets:

→ theorem below shows that we don't 'miss' parts of D by forming supremum over blocksets $K \subset D$

→ say that a closed bounded set is a null set if $\forall \epsilon > 0 \exists K$ block set of area $< \epsilon$ such that $D \subset K$

0 L.3.6: $\gamma: [a, b] \rightarrow \mathbb{R}^2$ smooth, the trace $\gamma([a, b])$ is a null set.

Proof: using the continuous arc length fct → divide γ in N pieces of equal length $\frac{L}{N}$, L total length of curve. (finite as $[a, b]$) → cover trace with squares of side-length $\frac{L}{N}$ → union of areas $N(\frac{L}{N})^2 = \frac{L^2}{N} \leq \epsilon$ for sufficiently large N

→ follows that boundaries of elementary domains are null sets:

0 T.3.6: $U \subset \mathbb{R}^2$ open set, $f: U \rightarrow [0, \infty]$ be a continuous fct with $D \subset U$ an elementary domain

⇒ $\int_D f dA = \inf_{D \subset K \subset U} \int_K f dA$ where K are block-sets

↳ can also approximate from the outside

Double integrals:

→ Let $\Phi, \Psi: [a, b] \rightarrow \mathbb{R}$ smooth fcts with $\Phi(u) < \Psi(u) \forall u \in (a, b)$. The set $D = \{(u, v) \mid a \leq u \leq b, \Phi(u) \leq v \leq \Psi(u)\}$ of points between graphs is an elementary domain

0 3.7.T: set D from above has area $A(D) = \int_a^b [\Psi(u) - \Phi(u)] du$ and the plane integral of a continuous fct f over D is $\int_D f dA = \int_a^b \int_{\Phi(u)}^{\Psi(u)} f(u, v) dv du$

↳ more complicated sets are treated by means of a disjoint division into subsets of this form

Example: triangle $D = \{(u, v) \mid 0 \leq u, 0 \leq v, 2u + v \leq 2\}$ → $v = 2 - 2u$, $\Psi(u) = 2 - 2u$, $\Phi(u) = 0 \Rightarrow A(D) = \int_0^1 \Psi(u) du = \frac{1}{2}$

→ $f(u, v) = v \Rightarrow \int_D v dA = \int_0^1 \int_0^{2-2u} v dv du = \int_0^1 \frac{1}{2} (2-2u)^2 du = \frac{2}{3}$

→ D can also be regarded as set $0 \leq v \leq 2, 0 \leq u \leq 1 - \frac{1}{2}v \Rightarrow A(D) = \int_0^2 (1 - \frac{1}{2}v) dv = 1$

$\int_D v dA = \int_0^2 \int_0^{1-\frac{1}{2}v} v du dv = \int_0^2 v (1 - \frac{1}{2}v) dv = \frac{2}{3}$

Transformation of integrals

→ generalization of the formula for substitution of variables in ordinary integrals.

↳ $U, W \subset \mathbb{R}^2$ open, $\Phi: W \rightarrow U$ a diffeomorphism

o T.3.8: $D \subset \mathbb{R}^2$ closed and bounded and contained in W . If D is an elementary domain, then so is its image $\Phi(D) \subset U$. Moreover $\int_{\Phi(D)} f dA = \int_D (f \circ \Phi) \cdot |\det(D\Phi)| dA$ for $f: U \rightarrow \mathbb{R}$ continuous

$\hookrightarrow f=1: A(\Phi(D)) = \int_D |\det(D\Phi)| dA$

o D.3.9: The area of the surface $\sigma: U \rightarrow \mathbb{R}^3$ over $D \subset \mathbb{R}^2$ elementary domain with $D \subset U$ is

$A(\sigma(D)) = A(\sigma, D) = \int_D \|\sigma'_u \times \sigma'_v\| dA$

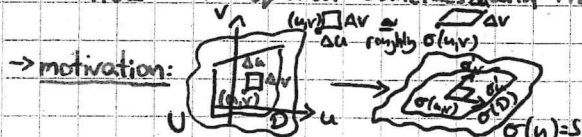
Recall that $\sigma'_u \times \sigma'_v$ is a normal vec to tangent plane $\Rightarrow \|\sigma'_u \times \sigma'_v\| = (EG - F^2)^{1/2}$ as general rule of vec.

calculus: $\|a \times b\|^2 = \|a\|^2 \|b\|^2 - (a \cdot b)^2$

\hookrightarrow often denote $A(\sigma(D))$ although not legitimate as depends on both σ and D and not just $\sigma(D)$

\hookrightarrow if we consider (x, y) -plane as $\sigma(u, v) = (u, v, 0) \Rightarrow E = G = 1, F = 0 \Rightarrow A(\sigma, D) = \int_D 1 dA$

\Rightarrow new notion of area coincides with the previous one for plane sets



area of parallelogram, spanned by $\Delta u \sigma'_u, \Delta v \sigma'_v$ is roughly (linear approx of σ) the same as of $\Delta u \Delta v$

$\|\Delta u \sigma'_u \times \Delta v \sigma'_v\| = \Delta u \Delta v \|\sigma'_u \times \sigma'_v\|$

\rightarrow adding up all these areas and taking limit $(\Delta u, \Delta v) \rightarrow (0, 0)$ leads to 3.9

o T.3.9: Surface area invariant under reparametrization $\tau = \sigma \circ \Phi: W \rightarrow \mathbb{R}^3$ where $\Phi: V \rightarrow U$ diffeo

Proof: let $E \subset U$ elementary domain $\Rightarrow D = \Phi^{-1}(E) \subset W$ elementary domain (\rightarrow preimage of compact domain under diffeo

\Rightarrow since $\tau = \sigma \circ \Phi \Rightarrow \tau(D) = \sigma(E) \rightarrow$ appears to be tautology but it is not as area defined by both

parametrization and image, not just their image. $A(\tau, D) = \int_D \|\tau'_s \times \tau'_t\| dA \stackrel{(*)}{=} A(\sigma, E) = \int_E \|\sigma'_u \times \sigma'_v\| dA$

(*) 2.8: $\tau'_s(q) \times \tau'_t(q) = \det(D\Phi)(q) \sigma'_u(\Phi(q)) \times \sigma'_v(\Phi(q)) \rightarrow$ insert into $A(\tau, D)$, then use 3.8

Example: compute surface area of unit sphere (param. with spherical coordinates) Let D be rectangle where $-\frac{\pi}{2} \leq u \leq \frac{\pi}{2}$ and $-\pi \leq v \leq \pi$ $\Rightarrow \sigma$ injective on interior of D (overlap on a line which is not important as it's a null set)

$E=1, F=0, G=\cos^2 u \Rightarrow (EG - F^2)^{1/2} = \cos u \Rightarrow \int_{-\pi}^{\pi} \int_{-\pi/2}^{\pi/2} \cos u du dv = 4\pi$