Homological Inference of Embedding Dimensions in Neural Networks

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January 11, 2021

Overview

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 - The manifold of data
 - The manifold of a neural network
- 2 Simplicial structures
 - Simplicial complexes
 - Persistent homology
- 3 Counting betti numbers
 - Experiments with connected abelian Lie group assumption
 - Outlook

Manifolds and Lie groups

Smooth manifold

Let X be a topological space. A pair (X,\mathcal{A}) , consisting of a second countable Hausdorff space X and a differentiable structure on X given by $\mathcal{A}=(U_i,\phi_i)_{i\in I}$, the family of pair-wise compatible coordinate charts such that $X=\bigcup_{i\in I}U_i$, is said to be a differentiable manifold. If $\varphi(U)\subseteq\mathbb{R}^n$ for all $(U,\varphi)\in\mathcal{A}$, then we say $\dim X=n$.

Lie group

A Lie group is a smooth manifold G equipped with a group structure so that the maps $\mu:(x,y)\mapsto xy,\ G\times G\to G$ and $\iota:x\mapsto x^{-1}$ are smooth.



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The manifold of data

Manifold assumption

A set of points in Euclidean space \mathbb{R}^d is underlain by a manifold, which can be embedded in ibid. Euclidean space and on which the points lie.

Decomposition of connected abelian Lie groups

Every connected commutative (abelian) Lie group G is isomorphic to a product space $\mathbb{R}^p \times \mathbb{T}^q \cong G$ with $p+q=\dim G$.

Embedding Dimension of Neural Networks

The manifold of data



$$r = 0$$



$$r = 0.2$$



$$r = 0.4$$



r = 0.6



r = 0.8

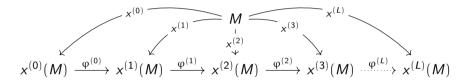
Idea:

- 1 Estimate a suitable structure.
- 2 Estimate one of its invariants.
- 3 Relate the invariant to the dimension.

How many dimensions do I need to represent the manifold that I suspect underlies the above set of points?

How many and which neurons are needed to represent this manifold?

The manifold of a neural network



Coordinate systems $x^{(I)} := \varphi^{(I-1)} \circ \cdots \circ \varphi^{(1)} \circ \varphi^{(0)} \circ x^{(0)}$ of a deep neural network induced by change of coordinate charts $\varphi^{(I)} : x^{(I)}(M) \mapsto (\varphi^{(I)} \circ x^{(I)})(M)$ learned by the neural network acting on the data.

Following Michael Hauser and Asok Ray: Principles of Riemannian Geometry in Neural Networks.



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Realise a good representation

Question: How can we adjust the neuromanifold to fit the data manifold?

- Take suitable assumptions on the dataset and its manifold.
- 2 Measure invariants on the filtration of a dataset to get a descriptor.
- 3 Infere possible manifolds from these measured invariants.
- 4 Relate the invariants to the dimension of the manifold.
- **5** Seek for approximate solutions if assumptions may not hold.



Building blocks: simplices

Consider the set of points $X := \{v_0, v_1, \dots, v_n\} \subset \mathbb{R}^d$. They are said to be **affinely independent** if the points $\{v_0 - v_n, v_1 - v_n, \dots, v_{n-1} - v_n\}$ are linearly independent. The **convex closure** of these points is a **simplex** and written as

$$[v_0, v_1, \dots, v_n] = \left\{ \sum_{i=0}^{n-1} \lambda_i (v_i - v_n) \mid \sum_{i=0}^{n-1} \lambda_i = 1 \text{ and } \lambda_i \ge 0 \right\}.$$
 (1)

The dimension of the simplex is n.

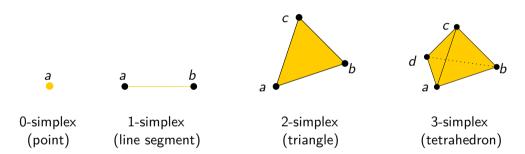
The *i*-th face of a simplex $[v_0, v_1, \ldots, v_n]$ (with an ommitted element \hat{v}_i) is defined by

$$d_i[v_0, v_1, \dots, v_n] = [v_0, v_1, \dots, \hat{v}_i, \dots, v_n].$$
 (2)



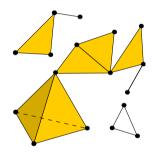
Examples

Simplicial complexes



The coefficients λ_i are chosen from the **field** $\mathbb{Z}_2 := \mathbb{Z}/2\mathbb{Z}$, such that we can **neglect the orientation** of the simplices. This is used for highly efficient computations.

Definition of simplicial complexes





A **simplicial complex** K is a finite union of simplices satisfying that every face of a simplex in K is in K and that the non-empty intersection of two simplices in K is a face of each.

A **filtration** is a nested sequence of complexes K_i , which induce an ordering of the sublevel complexes. These complexes, together with the inclusion $K_i \hookrightarrow K_j$ for 0 < i < j < n are called a filtration and denoted by \mathbb{K} :

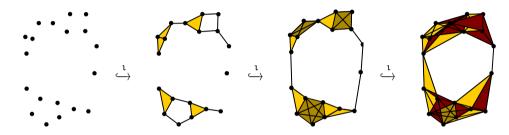
$$\mathbb{K}: \quad \emptyset = K_0 \subseteq K_1 \subseteq \cdots \subseteq K_n = K. \tag{3}$$

The inclusion on the filtration induces a homomorphism of groups $f_k^{ij}: H_k(K_i) \to H_k(K_j)$, in this case H_k are the k-th homology groups.



Simplicial complexes

Filtered simplicial complexes



Vastly used complexes to create a filtration on a point set X are:

Čech complex: $(v_0, v_1, \cdots, v_n) \in \check{\mathsf{Cech}}_r(X) \iff \bigcap_{i=0}^n B_r(x_i) \neq \emptyset.$

Vietoris-Rips complex: $(v_0, v_1, \cdots, v_n) \in \text{Rips}_r(X) \iff ||v_i - v_j|| \le r$.

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Isomorphism of homology theories

Isomorphic homology theories

For a trianguliable smooth manifold X and a simplicial complex K, forming its triangulation, the following holds for the homology groups from a field of coefficients \mathbb{F} :

$$H_k(K; \mathbb{F}) \cong H_k(X; \mathbb{F}) \cong H_k^{\infty}(X; \mathbb{F}) \cong H_{\mathsf{deRham}}^k(X; \mathbb{F}).$$
 (4)

Proof of $H_k(K; \mathbb{F}) \cong H_k(X; \mathbb{F})$: Allen Hatcher: Algebraic Topology.

Proof of $H_k(X;\mathbb{F})\cong H_k^\infty(X;\mathbb{F})$: John Lee: Introduction to smooth manifolds.

Proof of $H_k^\infty(X;\mathbb{F})\cong H_{\operatorname{deRham}}^k(X;\mathbb{F})$: John Lee: Introduction to smooth manifolds.



Persistent homology

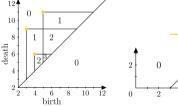
A persistence module is a family of \mathbb{F} -vectorspaces V_i for every real number i together with \mathbb{F} -linear maps $f^{ij}: V_i \to V_j$. These are called structure maps. For each pair $i \leq j$, satisfying that $k \leq i \leq j$, then $f^{kj} = f^{ij} \circ f^{ki}$.

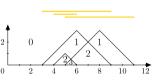
Let $\{K_i\}_{i\in\mathbb{R}}$ be a set of ordered simplicial complexes together with simplicial maps $f^{ij}:K_i\to K_j$ for each pair $i\leq j$, such that $k\leq i\leq j$ implies $f^{kj}=f^{ij}\circ f^{ki}$. An example is the aforementioned filtered simplicial complex. Then the persistence module with coefficients in \mathbb{F} is given by

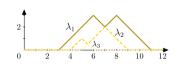
$$H_{\star}(K_i; \mathbb{F}), \quad H_{\star}(f^{ij}): H_{\star}(K_i; \mathbb{F}) \to H_{\star}(K_j; \mathbb{F}).$$
 (5)

Persistent landscapes

Functional representation of persistence diagrams as a sequence of functions $\lambda_k : \mathbb{R} \to [-\infty, \infty]$ with $\lambda_k(x)$ being the kth largest value of $\min(x - b_i, d_i - x)$. It is stable with respect to Bottleneck distance and lies in a Banach space.







Taken from Peter Bubenik: Statistical Topological Data Analysis using Persistence Landscapes.



Commutative abelian Lie groups

Main assumption: $H_k(G) \cong H_k(\mathbb{R}^p \times S_1^1 \times \cdots \times S_q^1)$ with $p + q = \dim G$.

Goal: Sufficiently good representation of the topological structure of input space.

Künneth's Theorem

$$H_k(X \times Y) \cong \bigoplus_{i+j=k} H_i(X) \otimes H_j(Y)),$$
 thus

$$H_k(\mathbb{R}^p \times S^1_1 \times \cdots \times S^1_q) \cong \bigoplus_{i_1 + \cdots + i_r = k} H_{i_1}(\mathbb{R}^p) \otimes H_{i_2}(S^1_1) \otimes \cdots \otimes H_{i_r}(S^1_q).$$



Computing dimensions

We get

$$H_0(S^1) = H_1(S^1) = \mathbb{Z},$$
 (6)

$$H_i(S^1) = 0$$
, for all $i \ge 2$. (7)

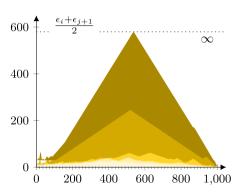
Applying Künneth's formula only indices for $i_i \in \{0, 1\}$ remain, thus we get

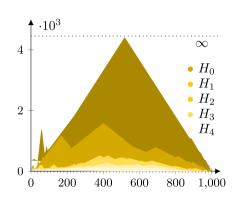
$$H_0(\mathbb{R}^p) \cong \mathbb{Z},$$
 (8)

$$H_k(\mathbb{T}^q) \cong H_k(S_1^1 \times \cdots S_q^1) \cong \mathbb{Z}^{\binom{q}{k}}.$$
 (9)

Experiments with connected abelian Lie group assumption

Experimental results on cifar10 & cifar100





Experiments with connected abelian Lie group assumption

Results for the Betti numbers

	ŀ	Homology groups						pprox embedding dimension						
	H_0	H_1	H_2	<i>H</i> ₃	H ₄		р	$q H_1$	$q H_2$	$q H_3$	$q H_4$	$\dim U$		
cifar10	12	16	40	59	50		12	16	9±4	8±3	7±15	92±44		
cifar100	13	18	34	46	48		13	18	$9{\pm}2$	8 ± 10	$7{\pm}13$	$97{\pm}50$		

Problem: It becomes apparent, that this can't be a torus. Further, it might be, that the components are not connected. Our theory does give us results for *connected* abelian Lie groups.



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Experiments with connected abelian Lie group assumption

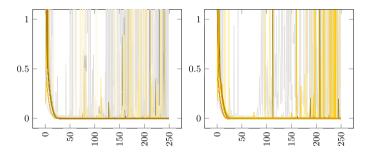
Results for the Betti numbers

	ŀ	Homology groups						pprox embedding dimension						
	H_0	H_1	H_2	<i>H</i> ₃	H_4		р	$q H_1$	$q H_2$	$q H_3$	$q H_4$	$\dim U$		
cifar10	12	16	40	59	50		12	16	9±4	8±3	7±15	92±44		
cifar100	13	18	34	46	48		13	18	$9{\pm}2$	8 ± 10	$7{\pm}13$	$97{\pm}50$		

Workaround: Choose a dimension being capable of embedding *n*-tori according to the rank of *every single* persistent homology group.



Losses on cifar10 & cifar100



cifar10: $\bullet \in [2, 148], \bullet \in [150, 198], \bullet \in [200, 270] \text{ and } \bullet \in [272, 784],$ (10)

cifar100: $\bullet \in [2, 148], \bullet \in [150, 198], \bullet \in [200, 292] \text{ and } \bullet \in [294, 784].$ (11)



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Outlook

Outlook

- Sliding window embeddings investigated by Jose Perea et al. [PersHS2016, SliWi2015] – embed time series as a curve on or a curve dense on a torus. For these embeddings our method is an accurate estimate.
- 2 For arbitrary datasets we do not yield an exact solution for the binomial coefficient. The assumption of a connected structure fails. How could one generalize this?
- We use vanilla neural networks. If we know the homology groups we want to represent, we can assign a commutative Lie group structure to the neural network itself, so that the **neuromanifold** has the same invariants as the **data manifold**.



References



Jose Perea (2016)
Persistent Homology of Toroidal Sliding Window Embeddings

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Sliding Windows and Persistence: An Application of Topological Methods to Signal Analysis
Foundations of Computational Mathematics.

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Thank you.

Got interested?

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or follow karhunenloeve on GitHub

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