

An Introduction to Simplicial Homology Theory

An introduction to simplicial homology theory

Luciano Melodia

September 29, 2023

Abstract

This paper explores the foundational concepts of simplicial structures that form the basis of simplicial homology theory. It also introduces singular homology as a means to establish the equivalence of homology groups for homeomorphic topological spaces. The paper concludes by providing a proof of the equivalence between simplicial and singular homology groups.

Contents

1	Simplicial Complexes	1
2	Homology Groups	3
4	Singular Homology	9
5	Chain Complexes	12
6	Exact Sequences	12
7	Relative Homology Groups	12
8	Equivalence of Simplicial Homology Group H_d^Δ and Singular Homology Group H_d	12

1 Simplicial Complexes

We would like to emphasize that a collection of points $X = \{x_0, x_1, \dots, x_d\}$ in \mathbb{R}^n is considered to be *affinely independent* if these points do not lie within any affine subspace of dimension lower than d .

Definition 1.1. Given a set $X = \{x_0, x_1, \dots, x_d\} \subset \mathbb{R}^n$ consisting of $d + 1$ **affinely independent** points, the d -dimensional simplex σ , also known as a d -simplex, is defined as the set of all convex combinations of these points.

$$\sigma := \left\{ \sum_{i=0}^d \lambda_i x_i \mid \sum_{i=0}^d \lambda_i = 1, \lambda_i \geq 0 \right\}. \quad (1)$$

As a convention, the empty set \emptyset is included as a face, representing the simplex formed by the empty subset of vertices. A 0-simplex represents a single point, a 1-simplex represents a line segment connecting two points, a 2-simplex represents a triangle, and a 3-simplex represents a tetrahedron. It is worth mentioning that the d -simplex is homeomorphic to the d -dimensional disk D^d .

Furthermore, it is worth noting that σ represents the convex hull of the points X , which can be defined as the smallest convex subset of \mathbb{R}^n that contains all the points x_0, x_1, \dots, x_d . The *faces* of the simplex σ with vertex set X are simplices formed by subsets of X . A d -face of a simplex refers to a subset of the vertices of the simplex with a cardinality of $d + 1$. The faces of an d -simplex with a dimension less than d are known as its *proper faces*. Two simplices are considered to be *properly situated* if their intersection is either empty or a face of both simplices. By identifying simplices along entire faces, we can construct the resulting *simplicial complexes*.

Definition 1.2. A **simplicial complex** K is a finite collection of simplices that satisfies the following properties:

1. For every simplex σ in K and every face τ of σ , it follows that τ is also in K .
2. If σ and τ are both simplices in K , then they are properly situated.

The *dimension* of K is defined as the highest dimension among its simplices. For a simplicial complex K in \mathbb{R}^n , its *underlying space* $|K|$ is the union of all the simplices in K . The topology of K is determined by the topology induced on $|K|$ by the standard topology in \mathbb{R}^n . It is important to note that when the vertex set is known, a simplicial complex in \mathbb{R}^n can be fully characterized by listing its simplices. As a result, we can describe it purely in terms of combinatorics using *abstract simplicial complexes*.

Definition 1.3. Consider a finite set $V = \{v_1, \dots, v_n\}$. An **abstract simplicial complex** \tilde{K} with vertex set V is a collection of finite subsets of V that satisfies the following two conditions:

1. All elements of V are included in \tilde{K} .
2. If σ is a subset of \tilde{K} and τ is a subset of σ , then τ is also a subset of \tilde{K} .

The abstract simplicial complex \tilde{K} associated with a simplicial complex K is commonly referred to as its *vertex scheme*. Conversely, if an abstract complex \tilde{K} serves as the vertex scheme for a complex K in \mathbb{R}^n , then K is known as a *geometric realization* of \tilde{K} .

Lemma 1.4. *Every finite abstract simplicial complex \tilde{K} can be realized geometrically in a Euclidean space.*

Proof. Let $\{v_1, v_2, \dots, v_n\}$ denote the vertex set of \tilde{K} , where n represents the number of vertices in \tilde{K} . Consider $\sigma \subset \mathbb{R}^n$, the simplex formed by the span of $\{e_1, e_2, \dots, e_n\}$, where e_i represents the i th unit vector. In this context, K refers to the subcomplex of σ such that $[e_{i_0}, \dots, e_{i_d}]$ is a d -simplex of K if and only if $[v_{i_0}, \dots, v_{i_k}]$ is a simplex of \tilde{K} . \square

Note: All realizations of an abstract simplicial complex are homeomorphic to each other. The specific realization mentioned above is referred to as the *natural realization*. Furthermore, it has been proven that any finite abstract simplicial complex of dimension n can be realized as a simplicial complex in \mathbb{R}^{2d+1} .

2 Homology Groups

Given a set V representing the vertices of a simplex σ , we can establish an *orientation* for the simplex by selecting a specific ordering for the vertices. If the vertex ordering differs from our chosen order by an odd permutation, it is considered *reversed*, while even permutations are said to *preserve* the orientation. Consequently, any simplex can have only two possible orientations. Moreover, the orientation of a d -simplex induces an orientation on its $(d-1)$ -faces. To be more precise, if $\sigma^{(d)} := (v_0, v_1, \dots, v_d)$ represents an oriented d -simplex, then the orientation of the $(d-1)$ -face τ of $\sigma^{(d)}$ with the vertex set $\{v_0, \dots, v_{i-1}, v_{i+1}, \dots, v_d\}$ is given by $\tau_i = (-1)^i(v_0, \dots, v_{i-1}, v_{i+1}, \dots, v_d)$.

Definition 2.1. *Given a set $\{\sigma_1^{(d)}, \dots, \sigma_k^{(d)}\}$ of arbitrarily oriented d -simplices of a complex K and an abelian group G , we define a d -chain c with coefficients $g_i \in G$ as a formal sum.*

$$c := g_1\sigma_1^{(d)} + g_2\sigma_2^{(d)} + \dots + g_k\sigma_k^{(d)} = \sum_{i=1}^k g_i\sigma_i^{(d)}. \quad (2)$$

Note: Henceforth we will assume that $G = (\mathbb{Z}, +)$.

Lemma 2.2. *The set of simplicial d -chains L_d^Δ is an abelian group $(L_d^\Delta, +)$.*

Proof. The identity element of the group is represented by the empty chain $\sum_{i=1}^k e_G\sigma_i^{(d)} = e_G$. The sum of two chains is defined as $c + c' = \sum_{i=1}^k g_i\sigma_i^{(d)} + \sum_{j=1}^l g'_j\sigma_j^{(d)} = \sum_{i=1}^k (g_i + g'_i)\sigma_i^{(d)} + \sum_{j=k+1}^l g'_j\sigma_j^{(d)}$ if $k \leq l$ and $c + c' = \sum_{i=1}^k g_i\sigma_i^{(d)} + \sum_{j=1}^l g'_j\sigma_j^{(d)} = \sum_{i=1}^k (g_i + g'_i)\sigma_i^{(d)} + \sum_{j=k+1}^l g'_j\sigma_j^{(d)}$ if $k > l$, thus, we can conclude that $c + c' \in L_d^\Delta$. The associativity of the group operation in L_d^Δ follows directly from the associativity of the group operation in G . The inverse element is defined by $e_{L_d^\Delta} = c + (-c) = \sum_{i=1}^k g_i\sigma_i^{(d)} - \sum_{i=1}^k (-g_i)\sigma_i^{(d)} = \sum_{i=1}^k (g_i - g_i)\sigma_i^{(d)}$ with $c, -c \in L_d^\Delta$. \square

Definition 2.3. Let $\sigma^{(d)}$ be an oriented d -simplex in a complex K . The **boundary** of $\sigma^{(d)}$ is defined as the simplicial $(d-1)$ -chain of K with coefficients in the abelian group $G = \mathbb{Z}$, given by

$$\partial(\sigma^{(d)}) = \sigma_0^{(d-1)} + \sigma_1^{(d-1)} + \dots + \sigma_d^{(d-1)} = \sum_{i=1}^d \sigma_i^{(d-1)} \quad (3)$$

where $\sigma_i^{(d-1)}$ is an $(d-1)$ -face of $\sigma^{(d)}$. If $d = 0$, we define $\partial(\sigma^{(0)}) = e_G = 0$.

Since $\sigma^{(d)}$ is an oriented simplex, the $\sigma_i^{(d-1)}$ -faces also have associated orientations. We can extend the definition of the boundary linearly to all elements of L_d^Δ .

Lemma 2.4. The **boundary operator** is a group homomorphism $\partial : L_d^\Delta \rightarrow L_{d-1}^\Delta$.

Proof. We define the boundary operator for a d -chain $c = \sum_{i=1}^k g_i \sigma_i^{(d)}$ as follows: $\partial(c) = \sum_{i=1}^k g_i \partial(\sigma_i^{(d)}) = \sum_{i=1}^k g_i \sum_{j=1}^d \sigma_j^{(d-1)} = \sum_{i=1}^k \sum_{j=1}^d g_i \sigma_j^{(d-1)} \in L_{d-1}^\Delta$, where $\sigma_i^{(d)}$ are the d -simplices of K . We can compute this by

$$\partial(c + c') = \partial\left(\sum_{i=1}^k g_i \sigma_i^{(d)} + \sum_{j=1}^l g'_j \sigma_j^{(d)}\right) \quad (4)$$

$$= \partial\left(\sum_{i=1}^k g_i \sigma_i^{(d)}\right) + \partial\left(\sum_{j=1}^l g'_j \sigma_j^{(d)}\right) \quad (5)$$

$$= \sum_{i=1}^k g_i \partial(\sigma_i^{(d)}) + \sum_{j=1}^l g'_j \partial(\sigma_j^{(d)}) \quad (6)$$

$$= \partial(c) + \partial(c'). \quad (7)$$

□

Example 2.5. Let's consider the 2-simplex $\sigma^{(2)}$ with vertices v_0, v_1 , and v_2 . The 1-faces of this simplex are $e_0 = (v_1, v_2)$ connecting v_1 and v_2 , $e_1 = (v_2, v_0)$ connecting v_2 and v_0 , and $e_2 = (v_0, v_1)$ connecting v_0 and v_1 . Now, let's proceed with the computation.

$$\partial(\partial(\sigma^{(2)})) = \partial(e_1 + e_2 + e_3) \quad (8)$$

$$= \partial e_1 + \partial e_2 + \partial e_3 \quad (9)$$

$$= \partial(v_0, v_1) + \partial(v_1, v_2) + \partial(v_2, v_0) \quad (10)$$

$$= [(v_1) - (v_0)] + [(v_2) - (v_1)] + [(v_0) - (v_2)]. \quad (11)$$

We observe that L_0^Δ is an abelian group and that oppositely oriented simplices cancel each other out, resulting in $\partial(\partial(\sigma^{(2)})) = 0$. This property can be generalized to higher dimensions through induction. Therefore, since ∂ is a linear

operator and the chain c is a sum of d -simplices, we can conclude that $\partial^2(c) = 0$ for any d -chain c in L_d^Δ . Consequently, the boundary of the boundary is zero. Moreover, if the boundary of a simplex is zero, it is referred to as a cycle. By this definition, we can deduce that the boundary of any simplex is a cycle.

Definition 2.6. A d -chain is referred to as a **cycle** if its boundary is equal to zero. We denote the set of d -cycles of a complex K over the group \mathbb{Z} as Z_d , the simplicial **cycle group**. It is important to note that Z_d^Δ is a subgroup of L_d^Δ and can also be expressed as $Z_d^\Delta = \ker(\partial)$.

Definition 2.7. A d -cycle of a k -complex K is said to be **homologous to zero** if it can be expressed as the boundary of an $(d+1)$ -chain in K , where $d = 0, 1, \dots, k-1$. In other words, a cycle is considered a boundary if it can be „filled in“ by a higher-dimensional chain. This equivalence relation is denoted as $c \sim 0$, and the subgroup of Z_d^Δ consisting of boundaries is referred to as the simplicial **boundary group** B_d^Δ . It is worth noting that B_d^Δ is equal to the image of the boundary operator ∂ .

Since B_d^Δ is a subgroup of Z_d^Δ and Z_d^Δ is an abelian group, every subgroup of Z_d^Δ is normal. Therefore, we can construct the quotient group $H_d^\Delta = Z_d^\Delta / B_d^\Delta$.

Definition 2.8. The group H_d^Δ represents the d -dimensional simplicial **homology group** of the complex K over \mathbb{Z} . It can be expressed as the quotient group $\ker(\partial)/\text{im}(\partial)$.

Next, we want to examine the structure of this homology group by shedding light on its connection to the connected components of a simplicial complex. We will find that the homology groups of the connected components of the complex, which in turn form a complex themselves, yield the direct sum of the homology group of the entire complex.

Definition 2.9. A **subcomplex** is defined as a subset S of the simplices belonging to a complex K , where S itself forms a complex.

The collection of all simplices in a complex K with dimensions less than or equal to d is referred to as the d -skeleton of K . By definition, the d -skeleton forms a subcomplex.

Definition 2.10. A complex K is considered **connected** if it cannot be expressed as the disjoint union of two or more non-empty subcomplexes. A geometric complex is **path-connected** if there exists a path consisting of 1-simplices connecting any vertex to any other vertex.

Lemma 2.11. Path-connectedness \iff connectedness.

Proof. „ \implies “: Let us assume that K is not connected. In this case, we can choose two separate subcomplexes, namely L and M , which do not share any common elements, but when combined, they form the entire complex $L \cup M = K$. Now, let's suppose that there exists a path between a vertex l_0 in L and

a vertex m_0 in M . However, if we consider the last vertex l_i in this path that belongs to L , we observe that the 1-simplex connecting l_i to the next vertex in the path cannot be a part of either L or M . If it were, then L and M would have a nonempty intersection, which contradicts our initial assumption that K is not connected.

„ \Leftarrow “: Now, let's consider the other direction. Suppose there are two points, namely l_0 and m_0 , in K that do not have a path connecting them. In this case, we can define L as the path-connected subcomplex of K that contains l_0 , and M as the path-connected subcomplex that contains m_0 . If there exists a vertex v_0 in the intersection of L and M (i.e., $v_0 \in L \cap M \neq \emptyset$), then we can find a path from l_0 to v_0 and another path from v_0 to m_0 . By concatenating these paths, we obtain a path from l_0 to m_0 , which contradicts our initial assumption that there is no path between l_0 and m_0 . Therefore, we conclude that L and M must have an empty intersection ($L \cap M = \emptyset$), indicating that K is not connected. \square

Theorem 3. *Let K_1, \dots, K_p be the collection of all connected components of a complex K . Furthermore, let H_{d_i} represent the d th homology group of K_i , and H_d denote the d th homology group of K . In this context, we can establish that H_d is isomorphic to the direct sum $H_{d_1} \oplus \dots \oplus H_{d_p}$.*

Proof. Let L_d represent the group of d -chains of K , and K_i denote the i th component of K . We can define L_{d_i} as the group of d -chains of K_i . It is evident that L_{d_i} is a subgroup of L_d . Furthermore, we observe that L_d can be expressed as the direct sum of L_{d_1}, \dots, L_{d_p} :

$$L_d = L_{d_1} \oplus \dots \oplus L_{d_p}. \quad (12)$$

Our goal is to demonstrate that a similar decomposition can be applied to the groups B_d and Z_d . By considering B_{d_i} as the image of ∂ restricted to the subgroup L_{d_i} , we can represent the group B_d as the direct sum of these restrictions:

$$B_d = B_{d_1} \oplus \dots \oplus B_{d_p}. \quad (13)$$

Thus, for any element $c \in L_{d+1}$, which can be represented as:

$$c = c_1 + \dots + c_p, \quad \partial(c) = \partial c_1 + \dots + \partial c_p \in B_d, \quad (14)$$

where $c_i \in L_{(d+1)_i}$. Let us define Z_{d_i} as the intersection of the kernel of ∂ and L_{d_i} . It follows that Z_d can be expressed as the direct sum of Z_{d_1}, \dots, Z_{d_p} :

$$Z_d = Z_{d_1} \oplus \dots \oplus Z_{d_p}. \quad (15)$$

To verify this, we observe that for an element $c \in L_d$ to belong to Z_d , we require $\partial(c) = 0$. However, we can express $\partial(c)$ as $\partial(c_1) + \dots + \partial(c_p)$. Therefore, for $\partial(c) = 0$ to hold, it implies that $\partial(c_i) = 0$, indicating that $c_i \in Z_{d_i}$. Since both Z_d and B_d can be decomposed componentwise, we can conclude that:

$$Z_d/B_d = Z_{d_1}/B_{d_1} \oplus \dots \oplus Z_{d_p}/B_{d_p}, \quad (16)$$

and consequently:

$$H_d = H_{d_1} \oplus \cdots \oplus H_{d_p}. \quad (17)$$

□

Definition 3.1. The *index* of a chain $c = \sum_{i=1}^k g_i \sigma_i^{(n)}$ is defined as the sum of the coefficients $I(c) = \sum_{i=1}^k g_i$.

Proposition 3.2. If K is a connected complex and c is a 0-chain with $I(c) = 0$, then the condition $I(c) = 0$ is equivalent to $c \sim 0$, where \sim denotes homology equivalence. Furthermore, in this case, the zeroth simplicial homology group $H_0^\Delta(K, \mathbb{Z})$ is isomorphic to the integers \mathbb{Z} .

Proof. We begin by proving that $c \sim 0 \implies I(c) = 0$. Let $\sigma^{(1)} = (v_0, v_1)$ be a 1-simplex. Then, for a chain $c = \partial(g\sigma^{(1)}) = gv_1 - gv_0$, we have $c \sim 0$. It is clear that $I(c) = I(g\sigma^{(1)}) = g - g = 0$. Since $I(c + c') = I(c) + I(c')$, I is a group homomorphism. For any $c \in L_1$ of the form $\sum_{i=1}^k g_i \sigma_i^{(1)}$, where $\sigma_i^{(1)} = (v_i, v_{i+1})$, we have $c = \partial(c) \sim 0 \implies I(c) = I(\partial(c)) = 0$.

To prove the forward direction, $I(c) = 0 \implies c \sim 0$, we consider two vertices v and w of K . Since K is connected, there exists a path between v and w consisting of 1-simplices $\sigma_i^{(1)} = (v_i, v_{i+1})$, $i = 1, \dots, k-1$, where $v_0 = v$ and $v_k = w$. We consider the boundary of the chain $c = \sum_{i=1}^k g \sigma_i^{(1)}$, given by $\partial(c) = \sum_{i=1}^k g \partial(\sigma_i^{(1)}) = \sum_{i=1}^k g[(v_{i+1}) - (v_i)] = gw - gv$. The index of the chain $c = \sum_{i=1}^k g_i \sigma_i^{(1)}$ is defined as $I(c) = \sum_{i=1}^k g_i$. Since $\partial(c)$ is a boundary, we have $c = \partial(c) \sim 0$. This implies that $(gw - gv) \sim 0$, which further implies $gw \sim gv$. Therefore, any 0-chain c in K is homologous to the chain gv . We observe that homologous chains have equal indices, i.e., $I(c) = I(gv) = g$. Thus, we have $c \sim gv \implies c \sim I(c)v$. This shows that if $I(c) = 0$, then $c \sim 0$. Hence, $I(c) = 0$ is equivalent to $c \sim 0$.

As mentioned, I is a homomorphism from $L_0 = Z_0$ to \mathbb{Z} . For a 0-simplex c and $g \in \mathbb{Z}$, the chain $gc \in L_0$ is a cycle with $I(gc) = g$. Therefore, $I(Z_0) = \mathbb{Z}$. Since $I(c) = 0$ is equivalent to $c \sim 0$, we have $B_0 = \ker(I)$. This implies that $H_0^\Delta = Z_0/B_0 \cong \mathbb{Z}$. □

At this point, we can deduce the following corollary from Theorem 2.11 and Proposition 3.2:

Corollary 3.3. The zero-dimensional homology group of a complex K over \mathbb{Z} can be represented as $\mathbb{Z}^p = \bigoplus_p \mathbb{Z}$, where p denotes the number of connected components present in K .

Example 3.4.

- This implies that the zeroth homology group of the circle is isomorphic to \mathbb{Z} . If we consider a simplicial representation of the circle using four one-simplices, $v_1 = (w, v)$, $v_2 = (v, y)$, $v_3 = (y, x)$, and $v_4 = (x, w)$, the

group Z_0 consists of sums over the four zero-simplices v, w, x , and y with coefficients in \mathbb{Z} . Let c be a zero-chain with non-zero coefficients given by

$$c = g_1v + g_2w + g_3x + g_4y. \quad (18)$$

In order to reduce it to an element of H_0^Δ , we subtract from it the chain $c' = g_4x - g_4y \sim 0$, resulting in

$$c - c' = g_1v + g_2w + (g_3 - g_4)x. \quad (19)$$

By repeating this process, we obtain a new chain

$$c'' = (g_1 - g_2 + g_3 - g_4)v. \quad (20)$$

Since $c'' \sim c$, it represents an element of H_0^Δ . Moreover, since $g_i \in \mathbb{Z}$, we can write $(g_1 - g_2 + g_3 - g_4) \in \mathbb{Z}$ as $c'' = gv$, where g is an element of \mathbb{Z} . Therefore, we can choose any g , which implies that $H_0^\Delta \cong \mathbb{Z}$.

- We will demonstrate that $H_n^\Delta(S^n) \cong \mathbb{Z}$. It is worth noting that the n -simplex $\sigma^{(n)}$ and the n -ball are homeomorphic. Consequently, their boundaries, which consist of $(n-1)$ -simplices, and the n -sphere are also homeomorphic. Therefore, the appropriate simplicial structure to impose on S^n is that of the boundary of the $(n+1)$ -simplex $\sigma^{(n+1)}$. Let v_0, \dots, v_{n-1} denote the set of vertices of $\sigma^{(n+1)}$. It is important to note that this set is not oriented, and the orientations of the $(n-1)$ -simplices can be arbitrarily determined. We will utilize their numbering to establish orientations. Consequently, all n -chains on this structure can be expressed as:

$$c = \sum_{i=0}^{n+1} g_i(v_0, \dots, v_{i-1}, v_{i+1}, \dots, v_n), \quad (21)$$

where $g_i \in \mathbb{Z}$. Since $\sigma^{(n+1)}$ itself is not part of the structure, there are no boundaries in Z_n , the group of cycles. Therefore, $H_n = Z_n/B_n$ represents the group of cycles. If $c \in Z_n$, then $\partial(c) = 0$. By using Eq. 21, we have:

$$\partial(c) = \partial \left(\sum_{i=0}^{n+1} g_i(v_0, \dots, v_{i-1}, v_{i+1}, \dots, v_n) \right) \quad (22)$$

$$= \sum_{i=0}^{n+1} g_i \left(\sum_{j=1}^{n+1} (-1)^j (v_0, \dots, v_{i-1}, v_{i+1}, \dots, v_{j-1}, v_{j+1}, \dots, v_n) \right). \quad (23)$$

By rearranging this sum, we obtain terms of the form:

$$(g_k - g_l)(v_0, \dots, v_{j-1}, v_{j+1}, \dots, v_{i-1}, v_{i+1}, \dots, v_n) \quad (24)$$

where $k, l = 0, \dots, n+1$ for all $i, j = 0, \dots, n$. Each pair of n -simplices of $\sigma^{(n+1)}$ intersect along an $(n-1)$ -face. Therefore, we obtain terms of the form given in Eq. 24 for each of these faces. From this, we can deduce

that if $\partial(c) = 0$, we must have $g_k = g_l$ for all $k, l = 0, \dots, n+1$. In other words, $g_0 = g_1 = \dots = g_{n+1}$. Consequently, our original n -chain can be rewritten as:

$$c = \sum_{i=0}^{n+1} g_0(v_0, \dots, v_{i-1}, v_{i+1}, \dots, v_n), \quad (25)$$

allowing us to choose g_0 from \mathbb{Z} . Thus, we conclude that $H_n^\Delta(S^n) \cong \mathbb{Z}$.

- We demonstrate that $H_n^\Delta(D^n) = 0$. To do so, we employ the simplest simplicial structure for D^n , which is that of the n -simplex $\sigma^{(n)}$. Consequently, all n -chains can be expressed as $c = g\sigma^{(n)}$, where $g \in \mathbb{Z}$. It is important to note that this form is never a boundary, thus implying that $H_n = Z_n$. However, $\partial(c) = 0$ only when $g = 0$. Consequently, we can conclude that $H_n^\Delta(D^n) \cong 0$.

4 Singular Homology

In the realm of lower dimensions, we possess an intuitive understanding of when two topological spaces are fundamentally „equivalent“. To formalize and solidify this intuition, we have devised various methods, one of which is the concept of homeomorphism. It would be highly desirable to establish a relationship between the homology groups of homeomorphic spaces. Remarkably, it has been discovered that if two topological spaces are homeomorphic, their homology groups are isomorphic. This fact begs for verification.

To accomplish this task, we require a means of comparing homology groups. However, it is not immediately evident how we can achieve this using the tools we have developed thus far. In fact, it proves to be quite a challenging problem. To circumvent this difficulty, we introduce the notion of *singular homology*. The fundamental principles underlying this concept are analogous to those we have already explored. To compute $Z_n(X)$, we need to find the group of n -cycles in X . Since X is obtained by identifying opposite faces of $\partial\sigma^{(n)}$, an n -cycle in X corresponds to an n -cycle in $\partial\sigma^{(n)}$ that is not a boundary of any $(n+1)$ -dimensional simplex in $\sigma^{(n)}$. In other words, an n -cycle in X corresponds to an n -cycle in $\partial\sigma^{(n)}$ that is not a boundary of any $(n+1)$ -dimensional face of $\sigma^{(n)}$.

Definition 4.1. In the context of a topological space X , we define a **singular n -simplex** as a map $\tilde{\sigma}^{(n)} : \sigma^{(n)} \rightarrow X$, where $\tilde{\sigma}^{(n)}$ is continuous.

We define the boundary map ∂_n in a similar manner as before:

Definition 4.2. The boundary map, denoted as ∂_n , is a function that operates on the chain group $C_n(X)$ and maps it to the chain group $C_{n-1}(X)$. It is defined as follows: For any singular n -simplex $\tilde{\sigma}^{(n)}$ in X , the boundary map $\partial_n(\tilde{\sigma}^{(n)})$ is obtained by summing over all the $(n-1)$ -simplices that are obtained by removing one vertex from $\tilde{\sigma}^{(n)}$. Each term in the sum is multiplied by $(-1)^i$, where i

represents the index of the removed vertex. In other words, if v_i represents the 0-simplex (vertex) of $\tilde{\sigma}^{(n)}$, then the boundary map can be expressed as:

$$\partial_n(\tilde{\sigma}^{(n)}) = \sum_i (-1)^i \tilde{\sigma}^{(n)}|_{[v_0, \dots, v_{i-1}, v_{i+1}, \dots, v_n]}. \quad (26)$$

Here, v_i is a map that takes the 0-simplex $\sigma^{(0)}$ to the corresponding vertex in X , s.t. $v_i : \sigma^{(0)} \rightarrow X$ is continuous.

As mentioned earlier, when we apply the boundary map twice to an n -chain c , denoted as $\partial^2(c)$ or $\partial(\partial(c))$, the result is always zero. This observation leads us to the idea of defining the singular homology groups in a similar way to the simplicial homology groups.

Definition 4.3. The *singular homology group* $H_n(X)$ is defined to be the quotient $H_n(X) = \ker(\partial_n) / \text{im}(\partial_{n+1})$.

In the following section, we will explore how this definition of homology allows us to establish a simple relationship between homeomorphic spaces and their corresponding homology groups. This relationship becomes apparent when we consider the fact that the definitions of H_d and H_d^Δ are analogous. Intuitively, we would expect these two groups to be the same. However, this is not immediately obvious. One reason for this is that H_d^Δ is finitely generated, while the chain group $C_d(X)$, from which we derived H_d , is uncountable.

Interestingly, for spaces where both simplicial and singular homology groups can be calculated, these two groups are indeed equivalent. We will provide a proof for this later on. But before we do, let us present some facts about singular homology that support the intuition that H_d is isomorphic to H_d^Δ .

Proposition 4.4. In the context of a topological space X , it can be observed that $H_d(X)$ is isomorphic to the direct sum $H_d(X_1) \oplus \dots \oplus H_d(X_p)$, where X_i represents the path-connected components of X . This equivalence serves as the counterpart to Theorem 3.

Proof. As the maps $\tilde{\sigma}^{(d)}$ exhibit continuity, it can be deduced that a singular simplex always possesses a path-connected image within X . Consequently, $C_d(X)$ can be expressed as the direct sum of subgroups $C_d(X_1) \oplus \dots \oplus C_d(X_p)$. The boundary map ∂ functions as a homomorphism, thereby preserving this decomposition. Consequently, $\ker(\partial_d)$ and $\text{im}(\partial_{d+1})$ also undergo a split, leading to the conclusion that $H_d(X) \cong H_d(X_1) \oplus H_d(X_2) \oplus \dots \oplus H_d(X_p)$. \square

Proposition 4.5. The zero-dimensional homology group of a space X can be expressed as the direct sum of \mathbb{Z} copies, with each copy corresponding to a distinct path-component of X . This correspondence serves as the parallel to Corollary 3.3.

Proof. To establish the isomorphism $H_0(X) \cong \mathbb{Z}$, it is sufficient to consider the case where X is path-connected. For a 0-chain c , the boundary operator $\partial_0(c)$

is always zero since the boundary of any 0-simplex vanishes. Consequently, $\ker(\partial_0) = C_0(X)$, which implies that $H_0(X) = C_0(X)/\text{im}(\partial_1)$ by definition.

Let us define the map $I : C_0(X) \rightarrow \mathbb{Z}$, where $I(c) = \sum_i g_i$ for $c = \sum_i g_i \tilde{\sigma}_i^{(0)} \in C_0(X)$. Our goal is to demonstrate that $\ker(I) = \text{im}(\partial_1)$, or in other words, for any 0-chain c , $I(c) = 0$ if and only if $c \sim 0$. The proof follows a similar line of reasoning as Proposition 3.2. \square

Example 4.6. *Alternative proof that $H_d(S^d) \cong \mathbb{Z}$. To prove that the d th homology group of the d -sphere is isomorphic to \mathbb{Z} , we will use the singular homology approach. The d th singular chain group $C_d(S^d)$ consists of formal linear combinations of singular d -simplices in S^d with integer coefficients. First, we note that S^d is a connected and compact topological space. Therefore, by the Hurewicz theorem, we have $H_d(S^d) \cong \pi_d(S^d)$, where $\pi_d(S^d)$ denotes the d th homotopy group of S^d . Since S^d is simply connected for $d \geq 2$, we have $\pi_d(S^d) = 0$ for $d \geq 2$. However, for $d = 1$, we have $\pi_1(S^1) \cong \mathbb{Z}$.*

Now, we need to establish the isomorphism between $\pi_1(S^1)$ and $H_1(S^1)$. To do this, we consider the singular 1-chain group $C_1(S^1)$, which consists of formal linear combinations of singular 1-simplices in S^1 with integer coefficients. Let c be a singular 1-chain in $C_1(S^1)$. We can write c as $c = \sum_i g_i \tilde{\sigma}_i^{(1)}$, where $g_i \in \mathbb{Z}$ and $\tilde{\sigma}_i^{(1)}$ are singular 1-simplices. The boundary of c is given by $\partial(c) = \sum_i g_i \partial(\tilde{\sigma}_i^{(1)})$. Since S^1 is a 1-dimensional manifold, the boundary of any singular 1-simplex $\tilde{\sigma}_i^{(1)}$ is a formal linear combination of two points in S^1 , each with opposite orientations. Therefore, $\partial(\tilde{\sigma}_i^{(1)}) = p - q$, where p and q are points in S^1 . Hence, we have $\partial(c) = \sum_i g_i (p - q) = (p - q) \sum_i g_i$. Since p and q are fixed points in S^1 , the sum $\sum_i g_i$ is an integer. Therefore, the boundary of any singular 1-chain c in $C_1(S^1)$ is of the form $(p - q)k$, where k is an integer. This implies that $H_1(S^1) = Z_1(S^1)/B_1(S^1) \cong \mathbb{Z}$, where $Z_1(S^1)$ is the group of 1-cycles and $B_1(S^1)$ is the group of 1-boundaries. In conclusion, we have shown that $H_d(S^d) \cong \pi_d(S^d) = 0$ for $d \geq 2$, and $H_1(S^1) \cong \pi_1(S^1) \cong \mathbb{Z}$. Therefore, the d th homology group of the d -sphere is isomorphic to \mathbb{Z} . \square

5 Chain Complexes

6 Exact Sequences

7 Relative Homology Groups

**8 Equivalence of Simplicial Homology Group H_d^Δ
and Singular Homology Group H_d**

References

- [1] Boissonnat, J. D., Chazal, F., Yvinec, M. (2018). Geometric and Topological Inference (Vol. 57). Cambridge University Press.
- [2] Edelsbrunner, H., Harer, J. L. (2022). Computational Topology: An Introduction. American Mathematical Society.
- [3] Hatcher, A. (2005). Algebraic Topology. Cambridge University Press.
- [4] Jonsson, J. (2011). Introduction to Simplicial Homology. Königliche Technische Hochschule. URL: <https://people.kth.se/~jakobj/doc/homology/homology.pdf>.
- [5] Khoury, M. (2022). Lecture 6: Introduction to Simplicial Homology. Topics in Computational Topology: An Algorithmic View. Ohio State University. URL: <http://web.cse.ohio-state.edu/~wang.1016/courses/788/Lecs/lec6-marc.pdf>.
- [6] Melodia, L., Lenz, R. (2021). Estimate of the Neural Network Dimension Using Algebraic Topology and Lie Theory. In Pattern Recognition. ICPR International Workshops and Challenges.
- [7] Nadathur, P. (2007). An Introduction to Homology. University of Chicago. URL: <https://www.math.uchicago.edu/~may/VIGRE/VIGRE2007/REUPapers/FINALFULL/Nadathur.pdf>.
- [8] Pontryagin L. S. (1952): Foundations of Combinatorial Topology. Graylock Press.