8 Obtaining MLEs and information

8.1 Review of numerical ML estimation

We aim at maximizing $l(\beta)$ w.r. to $\beta \in \mathcal{R}^p$.

Score vector
$$U(\beta) = \begin{pmatrix} \partial l/\partial \beta_1 \\ \vdots \\ \partial l/\partial \beta_p \end{pmatrix}$$

Hessian matrix $H(\beta) = (\partial^2 l/\partial \beta_j \partial \beta_k), \ 1 \leq j, k \leq p$

Observed information $I_{\text{obs}}(\beta) = -H(\beta)$

Information $I(\beta) = E(I_{\text{obs}}(\beta))$

ML estimating equations $U(\hat{\beta}) = 0$, root $\hat{\beta}$ is MLE

Newton-Raphson iteration:

Expand score function by a multivariate Taylor expansion,

$$0 = U(\hat{\beta}) = U(\beta) + H(\beta)(\hat{\beta} - \beta) + O(\|\hat{\beta} - \beta\|^2)$$
(8.1)

$$\hat{\beta} = \beta - H^{-1}(\beta)U(\beta) + O(\cdots) \leftarrow \text{negligible under regularity conditions}$$

This motivates the Newton-Raphson iteration

Initialization $\hat{\beta}_{(0)}$ = starting value

= (for GLM) regular least squares estimate for β from multiple regression

Updating step

$$\hat{\beta}_{(l+1)} = \hat{\beta}_{(l)} - H^{-1}(\hat{\beta}_{(l)})U(\hat{\beta}_{(l)})$$
(8.2)

For acceleration of convergence, often use acceleration factors for updating (Levenberg-Marquardt). An important variant is Fisher Scoring, where we replace $I_{obs} = -H$ by I, the expected information:

$$\hat{\beta}_{(l+1)} = \hat{\beta}_{(l)} + I^{-1}(\hat{\beta}_{(l)})U(\hat{\beta}_{(l)}). \tag{8.3}$$

According to the second Bartlett identity, approximately,

$$cov(U(\beta)) = I(\beta).$$

Assume the limiting information $I_{\infty}(\beta) = \lim_{n \to \infty} n^{-1}I(\beta)$ is well-defined. By the law of large numbers, then also $n^{-1}I_{obs}(\beta) \to I_{\infty}(\beta)$ in probability. Then, using the score statistic (2.6),

$$nI_{obs}^{-1}(\beta) \to_P I_{\infty}^{-1}(\beta), \quad n^{-1/2}I^{1/2}(\beta) \to I_{\infty}^{1/2}(\beta), \quad I^{-1/2}(\beta)U(\beta) \to_D N_p(0,I_p).$$

We conclude, applying Slutsky's theorem, and ignoring terms of smaller order, from (8.1), that

$$\sqrt{n}(\hat{\beta} - \beta) = \sqrt{n}[-H^{-1}(\beta)U(\beta)]
= \sqrt{n}I_{obs}(\beta)^{-1}U(\beta)
= [nI_{obs}(\beta)^{-1}] [n^{-1/2}I^{1/2}(\beta)] [I^{-1/2}(\beta)U(\beta)]
\rightarrow_D N_p(0, I_{\infty}^{-1}(\beta)).$$
(8.4)

This result provides asymptotic normality for the MLEs and justifies the finite sample approximations

$$\hat{\beta} \sim_{approx.} N_p(\beta, I^{-1}(\hat{\beta})), \quad \hat{\beta} \sim_{approx.} N_p(\beta, I_{obs}^{-1}),$$

which are used for finite-sample inference, corresponding to the Wald statistic (2.7).

8.2 Application to GLMs

Define $n \times n$ -diagonal weight matrix

$$W = \{\operatorname{diag}(g'(\mu_1)^2 V(\mu_1) \phi, \dots, g'(\mu_n)^2 V(\mu_n) \phi)\}^{-1} = (w_{ij})_{1 \le i, j \le n}.$$

where $\eta_i = g(\mu_i)$, $\eta = g(\mu)$, $\mu = g^{-1}(\eta)$, and $V(\mu_i)$ is the variance function, ϕ is a constant. Further define the $n \times p$ design matrix

$$X = \begin{bmatrix} 1 & x_{12} & \cdots & x_{1p} \\ \vdots & \vdots & & \vdots \\ 1 & x_{n2} & \cdots & x_{np} \end{bmatrix}$$

In the GLM, the log likelihood for one observation is $l(y, \theta, \phi) = \{(y\theta - b(\theta))/\phi + c(y, \phi)\}$, and the r-th element of the score vector $U = (u_1, \dots, u_p)^{\top}$ (for one observation and in terms of β) is

$$u_r = \frac{\partial l}{\partial \beta_r} = \frac{\partial l}{\partial \theta} \frac{\partial \theta}{\partial \mu} \frac{\partial \mu}{\partial \eta} \frac{\partial \eta}{\partial \beta_r}$$
(8.5)

by the chain rule applied to the composite mapping

$$\beta \to \eta \to \mu \to \theta \to l$$
, where

$$\eta = X\beta, \ \mu = g^{-1}(\eta), \ \theta = b'^{-1}(\mu)$$
 in the exponential family.

Identifying the derivatives, denoting by x_r the r-th column of the design matrix,

$$\frac{\partial \eta}{\partial \beta_r} = x_r$$

$$\frac{\partial l}{\partial \theta} = \frac{y - b'(\theta)}{\phi} = \frac{y - \mu}{\phi}, \text{ since } \mu = b'(\theta)$$

$$\frac{\partial \theta}{\partial \mu} = \frac{\partial b'^{-1}(\mu)}{\partial \mu} = \frac{1}{b''(b'^{-1}(\mu))} = \frac{1}{V(\mu)},$$
(8.6)

noting $V(\mu) = V(\theta(\mu)) = b''(\theta(\mu)) = b''(b'^{-1}(\mu))$ and therefore

$$u_r = \frac{y - \mu}{\phi V(\mu)} \frac{\partial \mu}{\partial \eta} x_r = (y - \mu) W \frac{d\eta}{d\mu} x_r.$$
 (8.7)

8.3 Estimating equation

$$\sum_{i=1}^{n} u_{ri} = \sum_{i=1}^{n} \left(\frac{\partial l_i}{\partial \beta_r}\right) = 0$$

$$\Rightarrow \sum_{i=1}^{n} w_{ii} (y_i - \mu_i) \frac{d\eta_i}{d\mu_i} x_{ir} = 0$$

Hessian: $H = (h_{rs})_{1 \le r,s \le p}$ with elements

$$h_{rs} = \sum_{i=1}^{n} \frac{\partial^{2} l_{i}}{\partial \beta_{r} \partial \beta_{s}} = \sum_{i=1}^{n} \frac{\partial u_{ri}}{\partial \beta_{s}}$$

$$= \sum_{i=1}^{n} (y_{i} - \mu_{i}) \frac{\partial}{\partial \beta_{s}} (w_{ii} \frac{d\eta_{i}}{d\mu_{i}}) x_{ir} + \sum_{i=1}^{n} w_{ii} \frac{d\eta_{i}}{d\mu_{i}} x_{ir} \frac{\partial}{\partial \beta_{s}} (y_{i} - \mu_{i})$$

$$H = X^{\top}(y - \mu) \left[\frac{\partial}{\partial \beta_s} W \frac{d\eta}{d\mu} \right] - X^{\top} W X, \tag{8.8}$$

since

$$\frac{\partial}{\partial \beta_s} (y_i - \mu_i) = -\frac{\partial \mu_i}{\partial \eta_i} \frac{\partial \eta_i}{\partial \beta_s} = -\frac{\partial \mu_i}{\partial \eta_i} x_{is}. \tag{8.9}$$

From $E y_i = \mu_i$, we obtain

$$I = -E(H) = X^{\top} W X \tag{8.10}$$

For the case of a canonical link function, $\theta = \eta$, for one observation, using $\partial \theta / \partial \eta \equiv \mathrm{id}$,

$$\theta = \eta \implies_{(8.5)} u_r = \frac{\partial l}{\partial \beta_r} = \frac{\partial l}{\partial \theta} \frac{\partial \theta}{\partial \mu} \frac{\partial \mu}{\partial \eta} \frac{\partial \eta}{\partial \beta_r} = \frac{\partial l}{\partial \theta} \frac{\partial \eta}{\partial \beta_r} = x_r \frac{y - \mu}{\phi}$$

$$h_{rs} = \sum_{i=1}^{n} \frac{\partial^{2} l_{i}}{\partial \beta_{r} \partial \beta_{s}} = \sum_{i=1}^{n} \frac{\partial u_{ri}}{\partial \beta_{s}} =_{(8.9)} \frac{1}{\phi} \sum_{i=1}^{n} \left(-\frac{\partial \mu_{i}}{\partial \eta_{i}} x_{is} x_{ir}\right) = (-X^{\top} W X)_{rs}$$
(8.11)

as

$$w_{ii} = \frac{1}{g'(\mu_i)^2 \phi V(\mu_i)} = \frac{1}{\phi} \frac{\partial \theta_i}{\partial \mu_i} \left(\frac{\partial \mu_i}{\partial \eta_i}\right)^2 = \frac{1}{\phi} \frac{\partial \mu_i}{\partial \eta_i}$$

in the canonical case, using $\frac{\partial \theta_i}{\partial \mu_i} = 1/V(\mu_i)$, by (8.6). This implies

$$I = I_{\text{obs}} = X^{\top} W X. \tag{8.12}$$

Conclusion: For the canonical link $(\theta = \eta)$, $I_{obs} = I$ and Fisher scoring is the same as Newton-Raphson with observed information. For any link, the Fisher information in a GLM is $I = X^{\top}WX$.

9 Iterated weighted least squares

Define auxiliary variables

$$Z = \eta + (y - \mu) \frac{d\eta}{d\mu} = \begin{bmatrix} \eta_1 + (y_1 - \mu_1)g'(\mu_1) \\ \vdots \\ \eta_n + (y_n - \mu_n)g'(\mu_n) \end{bmatrix} \qquad n \times 1 - \text{vector}$$

Iterated weighted least squares algorithm to obtain MLE $\hat{\beta}$:

- 1. Starting value for β , Z, W: $\hat{\beta}_{(0)}$, often obtained by regular (unweighted) multiple regressions: $Z_{(0)} = g(Y)$; $W_{(0)} = I_{n \times n}$, where $I_{n \times n}$ is the identity matrix.
- 2. Updating step: Given $\hat{\beta}_{(l)}$, obtain $\hat{\beta}_{(l+1)}$ by a weighted multiple linear regression step:

$$\hat{\beta}_{(l+1)} = \operatorname{argmin}_{\beta} \sum_{i=1}^{n} \{ Z_{(l)i} - \sum_{j=1}^{p} x_{ij} \beta_{(l)j} \}^{2} W_{(l)ii}$$

$$= \operatorname{argmin}_{\beta} (Z_{(l)} - X\beta)^{\top} W_{(l)} (Z_{(l)} - X\beta), \tag{9.1}$$

then update

$$\hat{\eta}_{(l+1)} = X \hat{\beta}_{(l+1)},
\hat{\mu}_{(l+1)} = g^{-1}(\hat{\eta}_{(l+1)}),
W_{(l+1)} = \{ \operatorname{diag}(g'(\hat{\mu}_{1(l+1)})^2 V(\hat{\mu}_{1(l+1)}) \hat{\phi}, \dots, g'(\hat{\mu}_{n(l+1)})^2 V(\hat{\mu}_{n(l+1)}) \hat{\phi}) \}^{-1},
Z_{(l+1)} = \hat{\eta}_{(l+1)} + (y - \hat{\mu}_{(l+1)}) \frac{d\eta}{d\mu}|_{\mu = \hat{\mu}_{(l+1)}}.$$

Once β is updated, then update η, μ, W and Z.

3. Stopping criterion: Stop the iteration, if

$$\frac{\|\hat{\beta}_{(\ell+1)} - \hat{\beta}_{(\ell)}\|}{\|\hat{\beta}_{(\ell)}\|} \le \varepsilon$$

for a suitably chosen small constant ε , or if the number of iterations is larger than a pre-specified number N.

Motivation: Note that for

$$Z = \eta + (y - \mu)g'(\mu) \approx g(y),$$

one has

$$Z - \eta = (y - \mu)g'(\mu)$$

and

$$(Z - \eta)^2 \frac{1}{g'(\mu)^2 V(\mu) \phi} = \frac{(y - \mu)^2}{V(\mu) \phi} = P,$$

where the l.h.s. can be rewritten as $(Z - X\beta)^{\top}W(Z - X\beta)$. Therefore, weighted least squares aims at minimizing the Pearson distance P. Note that $\hat{\phi}$ may or may not be updated.

Analyzing this iteration, we obtain

$$\hat{\beta}_{(l+1)} = (X^{\top} W_{(l)} X)^{-1} X^{\top} W_{(l)} Z_{(l)}$$
(9.2)

as the weighted least squares solution from normal equations.

Inserting $Z_{(l)}$, noting that by (8.7)

$$U(\hat{\beta}) = X^{\top} W(y - \hat{\mu}) \frac{\partial \eta}{\partial u},$$

$$\hat{\beta}_{(l+1)} = (X^{\top} W_{(l)} X)^{-1} X^{\top} W_{(l)} (X \hat{\beta}_{(l)} + (y - \hat{\mu}_{(l)}) \frac{d\eta}{d\mu}|_{\mu = \hat{\mu}_{(l)}})$$

$$= \hat{\beta}_{(l)} + (X^{\top} W_{(l)} X)^{-1} X^{\top} W_{(l)} (y - \hat{\mu}_{(l)}) \frac{d\eta}{d\mu}|_{\mu = \hat{\mu}_{(l)}}$$

$$= \hat{\beta}_{(l)} + (X^{\top} W_{(l)} X)^{-1} U(\hat{\beta}_{(l)}) = \hat{\beta}_{(l)} + I^{-1} U(\hat{\beta}_{(l)}).$$

Result: For ML estimation in the GLM, Fisher scoring and iterated weighted least squares are equivalent. For the canonical link, Fisher scoring and Newton-Raphson iteration with observed information are equivalent.

Notes: (1) Inference is usually based on expected information

$$E(I_{obs}) = I = X^{\top} W X,$$

and on the approximate distribution

$$\hat{\beta} \sim N_p(\beta, (X^\top W X)^{-1}), \quad W = W(\beta)$$
(9.3)

for large samples, from which we obtain simultaneous inference or inference for individual components as described previously.

- (2) The linearization through IWLS is a key device to extend arguments and tools that are available for (weighted) least squares to GLMs.
- (3) An underlying regularity condition for the asymptotics to work is:

$$I_{\infty} = \lim_{n \to \infty} \frac{1}{n} (X^{\top} W X)$$

exists and is invertible. This being an asymptotic condition, it has no direct bearing on the finite sample situation.

Example for inference: To test

$$H_0: A\beta = \zeta, \text{ where } A \text{ is } q \times p, \beta \in \mathbb{R}^p \text{ and } \zeta \in \mathbb{R}^q,$$

note that by (9.3), approximately,

$$A\hat{\beta} \sim N_q(A\beta, A(X^\top W X)^{-1} A^\top),$$

and that under H_0 we have, approximately,

$$(A\hat{\beta} - \zeta)^{\top} [A(X^{\top}WX)^{-1}A^{\top}]^{-1} (A\hat{\beta} - \zeta) \sim \chi_q^2,$$

if $A(X^{\top}WX)^{-1}A^{\top}$ is of full rank q. Can also construct confidence ellipsoid for parameter vector β , and for $\zeta = A\beta$, the latter based on the spectral decomposition of $[A(X^TWX)^{-1}A^T]$ (rather than that of $[X^TWX]^{-1}$).

Computational note: Implementing weighted least squares of Z on X with weight matrix W requires nothing more than a simple least squares step. Setting

$$X' = W^{1/2}X, \quad Z' = W^{1/2}Z, \tag{9.4}$$

the weighted least squares solution $\hat{\beta}$ is the same as the least squares solution for regressing Z' on predictors X'. Note that the hat matrix H of the transformed regression is defined by $W^{1/2}\hat{Z} = HW^{1/2}Z$ for

$$H = W^{1/2}X(X^TWX)^{-1}X^TW^{1/2}. (9.5)$$

Note that when applying (9.4), one has to do this for each iteration step as the matrices W are updated for each iteration. The hat matrix H to be used for diagnostics is the one obtained at the last iteration.