MLRF Lecture 02

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Agenda for lecture 2

- 1. Introduction
- 2. Global image descriptors
- 3. Clustering
- 4. Texture descriptors
- 5. Local feature detectors

Introduction

Lecture 02 part 01

Previously, in MLRF...

Summary of last lecture

Machine learning

- Machine learning = searching for the best model in a hypothesis space
- Inductive machine learning, optimization-based
- Inductive bias, biais/variance compromise
- Supervised, reinforcement, unsupervised learning
- Regression, classification, density estimation
- Model validation: test generalisation, separate/decorrelate test & training sets

Template matching

- Sum of squared differences (T-I)², or correlation-based methods (T×I)
- Normalization needed for correlation-based methods
- Tolerates translation and small noise, but not rotation, intensity shift, ...

Debriefing of practice session 1

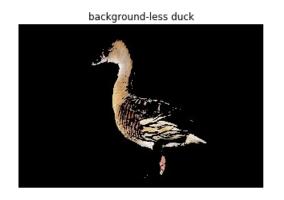
PS1 content

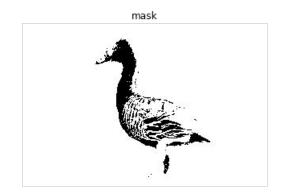
- 1. Jupyter tricks
- 2. NumPy reminders
- 3. Intro to image manipulations
- 4. Twin it! part 1: Template matching
- 5. (Bonus level: segmentation)

Discussion

- Who completed part 1? 2? 3? 4? 5?
- Any remarks, comments, questions?
- Things to keep, change, remove?

Practice session 1: Take home messages (1/2)





How annoying was it to manually adjust color thresholds to select the duck?

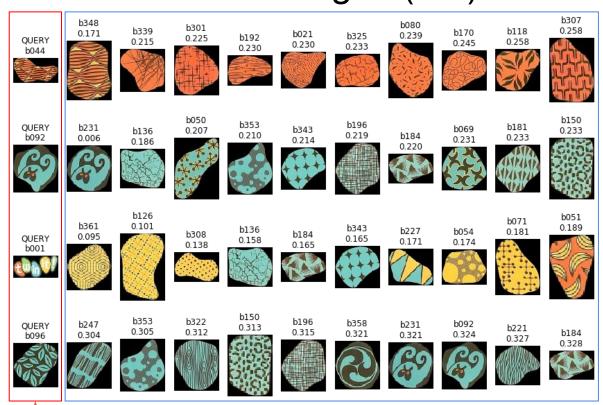
How could we have <u>automated</u> it?

Practice session 1: Take home messages (2/2)

Results with method SQDIFF_NORMED → (lower is better)

Strengths and weaknesses of template matching for the Twin it! case?

Effects of <u>normalization</u>?

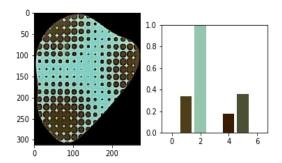


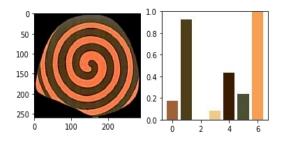
Next practice session(s)

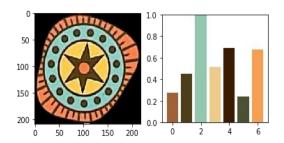
Next practice session

Twin it!, again, with a slightly more elaborated approach:

1. Pre-select bubbles based on their colors ⇒ Color histograms



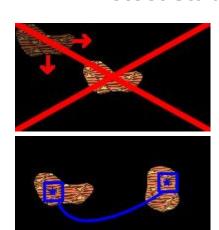


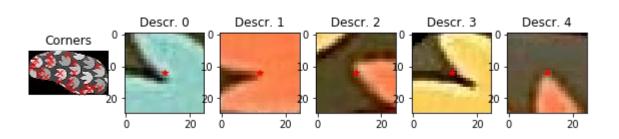


Next practice session

Twin it!, again, with a slightly more elaborated approach:

- 1. Pre-select bubbles based on their colors ⇒ Color histograms
- For the pre-selected bubbles, check their content is similar
 ⇒ Detect stable points and extract the patches around them

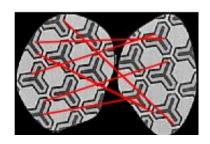




Next practice session

Twin it!, again, with a slightly more elaborated approach:

- 1. Pre-select bubbles based on their colors ⇒ Color histograms
- 2. For the pre-selected bubbles, check their content is similar
 - ⇒ Detect stable points and extract the patches around them
 - ⇒ Compare (match) those patches



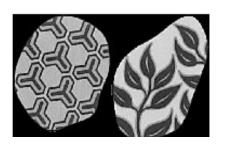


Image descriptors

Issues with methods based on pixel comparison

What is important? What do they consider? Raw pixels!

⇒ We want to be able to make use of **domain knowledge**!

Like sensitivity to shape, or dominant color information.

They are terribly **slow** and works **only for small images**.

⇒ We want to **summarize an image** to a much smaller vector.

They are **sensible to rotation, scaling**, and many other perturbations.

⇒ We want to adjust sensitivity/invariance to perturbations.

Do we tolerate translation? Rotation? Intensity shift?

How can we compare different pairs of images? Metric issues.

⇒ We want to be able to achieve more than 1 vs all comparisons.

Image descriptors: Overview

Different sizes and contents ⇒ Different kind of descriptors

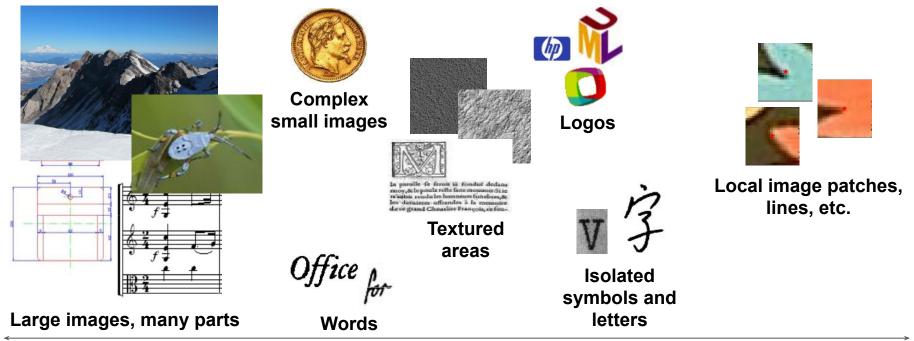


Image descriptors: Overview

Different sizes and contents ⇒ Different kind of descriptors

Different problems ⇒ **Different choices**

- Computation / memory constraints
- Which perturbations to we have to tolerate?
 rotation, translation...
- What is the expected output? classification, detection, ranking, segmentation...

Many, many approaches ⇒ Impossible to list them all

- Examples of several categories
- Focus on very useful or instructive ones