

for Ma:

$$0 = m_1 x_1 + B_1 x_1 + B_3 \dot{x}_1 + k_1 x_1 + k_2 x_1 - B_3 \dot{x}_3 - k_2 x_2$$

$$f(t) = m_2 \dot{x}_2 + B_2 \dot{x}_2 + B_4 \dot{x}_2 + k_2 x_2 - B_4 \dot{x}_3 - k_2 x_1$$

$$0 = m_3 \ddot{x}_3 + B_3 \dot{x}_3 + B_4 \dot{x}_3 - B_1 \dot{x}_1 - B_2 \dot{x}_2$$

$$X_{2}=X_{1}(t)$$
 $X_{3}=X_{2}(t)$ $X_{5}=X_{3}(t)$
 $X_{2}=X_{1}(t)$ $X_{4}=X_{3}(t)$ $X_{4}=X_{3}(t)$
 $X_{1}=X_{1}(t)=X_{2}$ $X_{3}=X_{2}(t)=X_{4}$ $X_{5}=X_{3}(t)=X_{4}$
 $X_{2}=X_{1}(t)$ $X_{4}=X_{2}(t)$ $X_{5}=X_{3}(t)=X_{4}$
 $X_{1}=X_{2}(t)$ $X_{1}=X_{3}(t)$

 $0 = m_1 \dot{x}_2 + B_1 \dot{x}_2 + B_3 \dot{x}_2 + K_1 \dot{x}_1 + K_2 \dot{x}_1 - B_3 \dot{x}_4 - K_2 \dot{x}_3$ $U_1 = m_2 \dot{x}_4 + B_2 \dot{x}_4 + B_4 \dot{x}_4 + K_2 \dot{x}_3 - B_4 \dot{x}_4 - K_2 \dot{x}_1$ $0 = m_3 \dot{x}_4 + B_3 \dot{x}_4 + B_4 \dot{x}_4 - B_1 \dot{x}_2 - B_2 \dot{x}_4$

$$\dot{X}_{2} = -\left(\frac{K_{1} + K_{2}}{m_{1}}\right) X_{1} - \left(\frac{B_{4} - B_{5}}{m_{1}}\right) X_{2} + \left(\frac{K_{2}}{m_{1}}\right) X_{5} + \frac{0}{2} \times \frac{B_{5}}{m_{1}} \times \frac{1}{2} + \frac{B_{5}}{m_{1}} \times$$

$$\dot{X}_{4} = \left(\frac{K_{2}}{m_{2}}\right) X_{1} + O X_{2} - \left(\frac{K_{2}}{m_{2}}\right) X_{3} - \left(\frac{B_{2} + B_{4}}{m_{2}}\right) X_{4} - O X_{5} + \left(\frac{B_{4}}{m_{2}}\right) X_{6} + \frac{U_{1}}{m_{2}}$$

$$\dot{x}_{u} = 0x_{1} + \left(\frac{B_{1}}{m_{3}}\right)x_{2} - 0x_{3}\left(\frac{B_{2}}{m_{3}}\right)x_{4} + 0x_{5} - \left(\frac{B_{3}+B_{4}}{m_{3}}\right)x_{4} + 0u_{1}$$

$$y = \begin{bmatrix}
x_1 & x_2 & x_3 & x_4 & x_5 & x_6 \\
1 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 1 & 0
\end{bmatrix}
\begin{bmatrix}
x_1 \\
x_2 \\
x_3 \\
x_4 \\
x_5 \\
x_6
\end{bmatrix}
+
\begin{bmatrix}
0 \\
0 \\
0 \\
3x_1 \\
0
\end{bmatrix}$$

$$0 \\
0 \\
0 \\
0 \\
0$$

$$\frac{C(5)}{R(5)} = \frac{16}{5^5 + 215^4 + 195^3 + 65^2 + 1}$$

$$C(s)[s^5 + 2|s^4 + |9s^3 + 6s^2 + 1] = |6R(s)$$

 $L^5(s^5C(s) + 2|s^4C(s) + |9s^3C(s) + 6s^2C(s) + C(s) = |6R(s)|^2$

$$X_1 = C$$
 $X_1 = C = X_2$ $U_1 = C$

$$X_2 = C \qquad X_2 = C = X_3$$

$$X_2 = \dot{C}$$
 $\dot{X}_2 = \dot{C} = \dot{X}_3$
 $\dot{X}_3 = \dot{C}$ $\dot{X}_3 = \dot{C} = \dot{X}_4$

$$X_4 = C$$
 $X_4 = C = X_5$
 $X_5 = C$ $X_5 = C$

$$\dot{X}_1 = OX_1 + X_2 + OX_3 + OX_4 + OX_5 + OU_1$$

 $\dot{X}_2 = OX_1 + OX_2 + X_3 + OX_4 + OX_5 + OU_1$
 $\dot{X}_3 = OX_1 + OX_2 + OX_3 + X_4 + OX_5 + OU_1$
 $\dot{X}_4 = OX_1 + OX_2 + OX_3 + OX_4 + X_5 + OU_1$
 $\dot{X}_5 = -X_1 + OX_2 - GX_3 - IQX_4 - 2IX_5 + IGU_1$

STATE SPACE EQUATION
$$\begin{bmatrix}
\dot{x}_1 \\
\dot{x}_2 \\
\dot{x}_3 \\
\dot{x}_4 \\
\dot{x}_5
\end{bmatrix} = \begin{bmatrix}
\dot{x}_1 \\
\dot{x}_2 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0$$

$$\forall = C = X_1$$

$$\forall = \begin{bmatrix} 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ X_3 \\ X_4 \\ X_5 \end{bmatrix} + \begin{bmatrix} 0 \end{bmatrix} U_1$$

$$\frac{R(6)}{6^{2} + 26^{2} + 116 + 6} = \frac{C(6)}{6^{2} + 26^{2} + 116 + 6} = \frac{1}{6^{3} + 26^{2} + 116 + 6} = \frac{1}{6^{3} + 26^{2} + 116 + 6} = \frac{1}{8(5)} = \frac{1}{6^{3} + 26^{2} + 116 + 6} = \frac{1}{8(5)} = \frac$$

$$X_1 = X_1$$
 $\dot{X}_1 = \dot{X}_1 - X_2$ $V_1 = r$
 $X_2 < \dot{X}_1$ $\dot{X}_2 = \ddot{X}_1 = \dot{X}_3$
 $X_3 = \ddot{X}_1$ $\dot{X}_3 = \ddot{X}_1$

X3 X3 X2 X1 U1

$$\dot{X}_1 = X_2$$
 $\dot{X}_2 = X_3$
 $\dot{X}_3 = -6X_1 - 11X_2 - 2X_3 + V_1$

STATE EQUATION:
$$\begin{bmatrix}
\dot{x}_1 \\
\dot{x}_2 \\
\dot{x}_3
\end{bmatrix} :
\begin{bmatrix}
0 & 1 & 0 \\
0 & 0 & 1 \\
-6 & -11 & -2
\end{bmatrix}
\begin{bmatrix}
x_1 \\
x_2 \\
x_3
\end{bmatrix} =
\begin{bmatrix}
0 \\
0 \\
1
\end{bmatrix}
U_1$$

CONTINUATION:

$$C = \{ s^2 X_1 (s) + 3 s x_1 (s) + 3 x_1 (s) \}$$

 $C = \{ x_1 + 3 x_1 + 3 x_1 \}$
 $Y = \{ x_1 + 3 x_1 + 3 x_1 \}$
 $Y = \{ x_2 + 3 x_2 + 3 x_1 \}$
 $Y = \{ x_3 + 3 x_2 + 3 x_1 \}$
 $Y = \{ x_3 + 3 x_2 + 3 x_1 \}$

OUTPUT EQUATION:

$$\frac{X_{1(6)}}{S^{2} + 36 + 3} = \frac{C_{66}}{C_{66}}$$
,

 $\frac{C_{60}}{X_{1(6)}} = S^{2} + 3s + 3$
 $C_{60} = S^{2} \times C_{60} + 3s \times C_{60} + 3x + 6s$