

Courier.cpp

The most recent version

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Chapter 1

Introduction

This program create route file from a central city to all other cities. If the params aren't complete, the program will show an information about lacking params

1.1 Manual

- 1) Download all files from my repository called Courier_cpp on the GitHub;
- 2) Launch command prompt;
- 3) Use command 'cd' and go to files "Courier_cpp", "Courier", "x64", "Debug";
- 4) Then type in arguments from point at the number 5. (Remember that instead input.txt" type in data file name;
- 5) Courier.exe -i input.txt -o output.txt;
- 6) Choose a city where should the centre be.

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Date

23.02.2023

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

edge	The scructure includes a information about a given neighbouring city	7
vertex	The structure include a information about the given city	8

Chapter 3

File Index

3.1 File List

Here is a list of all files with brief descriptions:

features.cpp	Complete features file (header, and feature body)	11
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struct.h	Structures file	17

Chapter 4

Class Documentation

4.1 edge Struct Reference

The structure includes a information about a given neighbouring city.

```
#include <struct.h>
```

Public Attributes

- double [range](#)
- std::string [end](#)

4.1.1 Detailed Description

Parameters

<i>range</i>	The distance between the cities.
<i>end</i>	Neighbouring city.

Definition at line [22](#) of file [struct.h](#).

4.1.2 Member Data Documentation

4.1.2.1 end

```
std::string edge::end
```

Definition at line [24](#) of file [struct.h](#).

4.1.2.2 range

```
double edge::range
```

Definition at line 23 of file [struct.h](#).

The documentation for this struct was generated from the following file:

- [struct.h](#)

4.2 vertex Struct Reference

The structure include a information about the given city.

```
#include <struct.h>
```

Public Attributes

- std::string [previous](#)
- double [distance](#) = [max](#)
- std::vector< [edge](#) > [neighbors](#)
- bool [visited](#) = false

4.2.1 Detailed Description

Parameters

<i>previous</i>	The earlier city that was determined by the algorithm
<i>distance</i>	Dictance from the given city to the center.
<i>neighbors</i>	Vector of nieghbouring cities stcrutres.
<i>visited</i>	Bool value, that include the information about visiting the city.

Definition at line 36 of file [struct.h](#).

4.2.2 Member Data Documentation

4.2.2.1 distance

```
double vertex::distance = max
```

Definition at line 39 of file [struct.h](#).

4.2.2.2 neighbors

```
std::vector<edge> vertex::neighbors
```

Definition at line 40 of file [struct.h](#).

4.2.2.3 previous

```
std::string vertex::previous
```

Definition at line 38 of file [struct.h](#).

4.2.2.4 visited

```
bool vertex::visited = false
```

Definition at line 41 of file [struct.h](#).

The documentation for this struct was generated from the following file:

- [struct.h](#)

Chapter 5

File Documentation

5.1 features.cpp File Reference

complete features file (header, and feature body).

```
#include <iostream>
#include <cmath>
#include <vector>
#include <unordered_map>
#include <fstream>
#include <deque>
#include "features.h"
#include "struct.h"
```

Include dependency graph for features.cpp:

5.2 features.cpp

[Go to the documentation of this file.](#)

```
00001 #include <iostream>
00002 #include <cmath>
00003 #include <vector>
00004 #include <unordered_map>
00005 #include <fstream>
00006 #include <deque>
00007
00008 #include "features.h"
00009 #include "struct.h"
00010
00026 void service_cmd(std::string & input, std::string& output, int argc, char* argv[]) {
00027     for (int i = 0; argc > i; i++)
00028     {
00029         if (strcmp(argv[i], "-i") == 0) {
00030             input = argv[i + 1];
00031         }
00032         if (strcmp(argv[i], "-o") == 0) {
00033             output = argv[i + 1];
00034         }
00035     }
00036 }
00037
00048 void read_data(std::unordered_map <std::string, vertex> & cities, std::string input) {
00049
00050     std::ifstream plik(input);
00051     std::string m1, m2;
00052     double dist;
00053
00054     if(plik) {
00055
```

```

00056         while (not plik.eof())
00057         {
00058             plik » m1 » m2 » dist;
00059             cities[m1].neighbors.push_back({dist, m2});
00060             cities[m2].neighbors.push_back({ dist, m1 });
00061         }
00062     }
00063 }
00064 }
00088 void Dijkstra(std::unordered_map <std::string, vertex> & cities, std::vector <std::string> &
unavailable) {
00089
00090     for (int k = 0; k < cities.size(); k++) {
00091         double min = max;
00092         std::string current;
00093
00094         for (const auto i : cities) {
00095             if (i.second.distance < min and !i.second.visited) {
00096                 min = i.second.distance;
00097                 current = i.first;
00098             }
00099         }
00100
00101         for (int j = 0; j < cities[current].neighbors.size(); j++) {
00102
00103             double current_way = cities[current].distance + cities[current].neighbors[j].range;
00104             std::string neighbour = cities[current].neighbors[j].end;
00105
00106             if (current_way < cities[neighbour].distance) {
00107                 cities[neighbour].distance = current_way;
00108                 cities[neighbour].previous = current;
00109             }
00110         }
00111         cities[current].visited = true;
00112     }
00113
00114     for(const auto i : cities) {
00115         if (!i.second.visited) {
00116             unavailable.push_back(i.first);
00117         }
00118     }
00119 }
00135 void typing_route(std::unordered_map <std::string, vertex> cities, std::string center,
std::vector <std::string>& unavailable, std::string output) {
00136
00137     std::ofstream file(output);
00138
00139     for (const auto i : cities) {
00140
00141         if (i.second.distance < max) {
00142
00143             std::deque <std::string> queue;
00144
00145             if (i.first != center) {
00146
00147                 std::string last;
00148                 last = i.second.previous;
00149
00150                 while (last != center) {
00151                     queue.push_front(last);
00152                     last = cities[last].previous;
00153                 }
00154                 if (file) {
00155                     file « center « " -> ";
00156
00157                     for (int j = 0; j < queue.size(); j++) {
00158                         file « queue[j] « " -> ";
00159                     }
00160                     file « i.first « ": " « i.second.distance « std::endl;
00161                 }
00162             }
00163         }
00164     }
00165 }
00166
00167 if (unavailable.size() > 0) {
00168     file « std::endl « "Cities without connecting to the center: " « std::endl;
00169
00170     for (int i = 0; i < unavailable.size(); i++) {
00171         file « "- " « unavailable[i] « std::endl;
00172     }
00173 }
00174 file.close();
00175 }

```


5.3 features.h File Reference

Header file.

```
#include <iostream>
#include <cmath>
#include <vector>
#include <unordered_map>
#include <fstream>
#include "struct.h"
```

Include dependency graph for features.h: This graph shows which files directly or indirectly include this file:

Functions

- void [service_cmd](#) (std::string &input, std::string &output, int argc, char *argv[])
Feature assign a proper params to variables input and output.
- void [read_data](#) (std::unordered_map< std::string, [vertex](#) > &cities, std::string input)
Feature reads a data from a data file and writes it to the unordered map.
- void [Dijkstra](#) (std::unordered_map< std::string, [vertex](#) > &cities, std::vector< std::string > &unavailable)
The feature executes the Dijkstra algorithm.
- void [typing_route](#) (std::unordered_map< std::string, [vertex](#) > cities, std::string center, std::vector< std::string > &unavailable, std::string output)
The feature sorts the cities and previous citis, then the feature saves the program result to the new create file.

5.3.1 Function Documentation

5.3.1.1 Dijkstra()

```
void Dijkstra (
    std::unordered_map< std::string, vertex > & cities,
    std::vector< std::string > & unavailable )
```

Good to know, that at the beginning of the program:

- The city which was choosen the center is assigned the value zero. Whereas all other cities is assigned the distance variable equal to a maximal posible value;
- Every city includes a bool value equal to "false" in the structure variable called "visited", (The value "false" means that given city hasn't been visited by algorithm .

The algorithm execuution:

- 1) The closest unvisited city (from center) is serached and saved to a variable called "current";
- 2) The routes from center to all other cities are cheacked, If the distance are shorter than current saved way, the distance is overwritten and city from variable "current" are assigned to structure variable "previaus";
- 3) Then city from the variable "current" is marked as visited, and value true is assigned to variable "visited" of structere given city;
- 4) The points from 1 to 3 are executed as many time as there are saved a cities in the container (unordered↵_map);
- 5) The unvisited cities are saved in the vector called "unavailable".

Parameters

<i>cities</i>	The unordered map, there are saved the cities structures, with information about a given cities.
<i>unavailable</i>	The cities, which haven't got any route connecting to the center.

Definition at line 88 of file [features.cpp](#).

5.3.1.2 read_data()

```
void read_data (
    std::unordered_map< std::string, vertex > & cities,
    std::string input )
```

First, Data are saved to proper structures

If the structures don't exist then the feature creates them.

Second, Structures are saved to the unordered map.

Parameters

<i>cities</i>	unordered map, include structures with a information about cities from the database
<i>input</i>	the variable includes a file name with input data.

Definition at line 48 of file [features.cpp](#).

5.3.1.3 service_cmd()

```
void service_cmd (
    std::string & input,
    std::string & output,
    int argc,
    char * argv[] )
```

Param "-i" inform the feature that a next argument will be assign to the variable "input". The program will do similar with a param "-o", and the variable "output".

Parameters

<i>input</i>	the variable includes a input file name with data
<i>output</i>	the variable includes output file name with a program result

Definition at line 26 of file [features.cpp](#).

5.3.1.4 typing_route()

```
void typing_route (
    std::unordered_map< std::string, vertex > cities,
    std::string center,
    std::vector< std::string > & unavailable,
    std::string output )
```

- 1) A queue is created, then next city and previous cities are saved to the first position the queue until the center is saved;
- 2) Then, Route from the center, through previous cities and finished on the last city (saved in the variable "i"), the distance information is saved in the end;
- 3) The points from 1 to 2 are performed for each city from the unordered map;
- 4) All cities which haven't got connected with the center are saved type in to the file with a short information (about not connected);
- 5) The file is closed.

Parameters

<i>cities</i>	The unordered map, there are saved the cities structures, with information about a given cities.
<i>center</i>	A city that chose as the center.
<i>unavailable</i>	The cities, which haven't got any route connecting to the center.
<i>output</i>	the variable includes output file name with a program result

Definition at line 135 of file [features.cpp](#).

5.4 features.h

[Go to the documentation of this file.](#)

```
00001 #pragma once
00002
00003 #include <iostream>
00004 #include <cmath>
00005 #include <vector>
00006 #include <unordered_map>
00007 #include <fstream>
00008
00009 #include "struct.h"
00013 void service_cmd(std::string& input, std::string& output, int argc, char* argv[]);
00014
00015 void read_data(std::unordered_map <std::string, vertex> & cities, std::string input);
00016
00017 void Dijkstra(std::unordered_map <std::string, vertex> & cities, std::vector <std::string> &
    unavailable);
00018
00019 void typing_route(std::unordered_map <std::string, vertex> cities, std::string center, std::vector
    <std::string>& unavailable,
00020                  std::string output);
```

5.5 main.cpp File Reference

File with main feature.

```
#include <iostream>
#include <cmath>
#include <vector>
```

```
#include <unordered_map>
#include <fstream>
#include <deque>
#include "features.h"
#include "struct.h"
Include dependency graph for main.cpp:
```

Functions

- int [main](#) (int argc, char *argv[])

5.5.1 Detailed Description

Parameters

<i>argc</i>	number of typed arguments.
<i>argv</i>	params contents.

Definition in file [main.cpp](#).

5.5.2 Function Documentation

5.5.2.1 main()

```
int main (
    int argc,
    char * argv[ ] )
```

Definition at line 38 of file [main.cpp](#).

5.6 main.cpp

[Go to the documentation of this file.](#)

```
00001 #include <iostream>
00002 #include <cmath>
00003 #include <vector>
00004 #include <unordered_map>
00005 #include <fstream>
00006 #include <deque>
00007
00008 #include "features.h"
00009 #include "struct.h"
00010
00038 int main(int argc, char* argv[]) {
00039     std::string input;
00040     std::string output;
00041
00042     service_cmd(input, output, argc, argv);
00043
00044     if (input.empty() || output.empty()) {
00045         std::cout << "no parameters" << std::endl;
```

```

00046
00047     }
00048
00049     else {
00050         std::unordered_map<std::string, vertex> cities;
00051         std::vector<std::string> unavailable;
00052         std::string centre;
00053
00054         read_data(cities, input);
00055
00056         std::cout << "The program calculate the shortest route between centre and all different cities"
00057     << std::endl << std::endl;
00058         std::cout << "Available cities: " << std::endl;
00059         for (const auto i : cities) {
00060             std::cout << "- " << i.first << std::endl;
00061         }
00062
00063         std::cout << std::endl << "Type city name where should the centre be: ";
00064         bool exist = false;
00065         do
00066         {
00067             std::cin >> centre;
00068             std::cout << std::endl;
00069
00070             for (const auto i : cities) {
00071
00072                 if (i.first == centre) {
00073                     exist = true;
00074                 }
00075             }
00076             if (!exist)
00077                 std::cout << "This city was not found, type in correct a city name: ";
00078
00079         } while (!exist);
00080         cities[centre].distance = 0;
00081
00082         Dijkstra(cities, unavailable);
00083
00084         typing_route(cities, centre, unavailable, output);
00085     }
00086 }

```

5.7 struct.h File Reference

Structures file.

```

#include <iostream>
#include <cmath>
#include <vector>
#include <unordered_map>

```

Include dependency graph for struct.h: This graph shows which files directly or indirectly include this file:

Classes

- struct [edge](#)
The structure includes a information about a given neighbouring city.
- struct [vertex](#)
The structure include a information about the given city.

Variables

- const double [max](#) = std::numeric_limits<double>::max()

5.7.1 Detailed Description

Parameters

<i>max</i>	The maximal value mean a infinity
------------	-----------------------------------

Definition in file [struct.h](#).

5.7.2 Variable Documentation

5.7.2.1 max

```
const double max = std::numeric_limits<double>::max()
```

Definition at line 13 of file [struct.h](#).

5.8 struct.h

[Go to the documentation of this file.](#)

```
00001 #pragma once
00002
00003 #include <iostream>
00004 #include <cmath>
00005 #include <vector>
00006 #include <unordered_map>
00007
00013 const double max = std::numeric_limits<double>::max();
00014
00015
00022 struct edge {
00023     double range;
00024     std::string end;
00025 };
00026
00027
00036 struct vertex {
00037
00038     std::string previous;
00039     double distance = max;
00040     std::vector <edge> neighbors;
00041     bool visited = false;
00042 };
```

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