### **Boston University Questrom School of Business**

# MF793 - Fall 2021 Eric Jacquier

#### **Introduction to GARCH Models**

AR C H: Auto Regressive Conditional Heteroskedasticity

**GARCH:** Generalized ARCH

- 1. Limitation of the log-normal distribution
- 2. Simple extensions do not work
- 3. Basic ARCH
- 4. GARCH
- 5. Testing, Estimating, Diagnostic,
- 6. Forecasting
- 7. Crucial Extensions
- 8. Contrast with SV (stochastic volatility) models

### 1 Limitation of the Lognormal distribution: Four stylized facts on asset returns

#### 1. Fat tails in the unconditional distribution of asset returns

Even it the conditional daily distribution of returns is normal with a different variance every day, the unconditional distribution is not normal:

**A mixture distribution** 
$$p(R_t) = \int N(R_t | \mu, \sigma_t) \ p(\sigma_t) \ d\sigma_t$$

One reason the **un**conditional distribution of financial returns is not normal is that the distribution of returns is a **mixture** of (possibly normal) conditional distributions.

## 2. Volatility Clustering:

"Periods of high variance tend to follow periods of high variance. (low ... low)"

Need to look at a time series plot of a measure of volatility ... Realized volatility, VIX Careful not to misinterpret the spurious autocorrelation due to overlapping data.

## 3. Leverage effect aka Volatility feedback effect

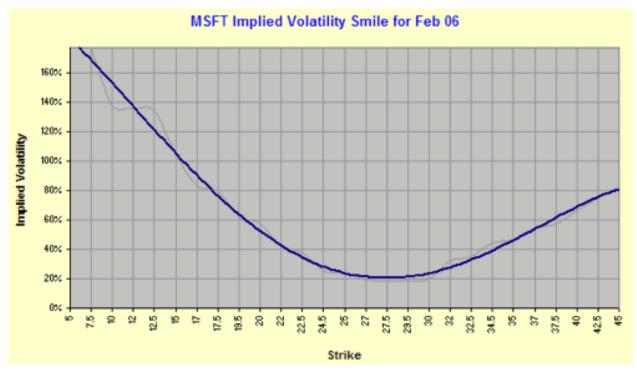
Need to plot a measure of volatility vs. returns Do we see more volatility after negative returns? 4. Non uniform information arrival – open / close – week-ends – holidays French & Roll (JFE 1986)

Daily close to close: 9:30-16:00 7.5 hrs open 16.5 hrs closed Friday close to Monday close: 7.5 hrs open 64.6 hrs closed

5. and .. a fifth not so stylized fact:

**Smile** in BSM implied volatility vs. Ln(S / PV(X))

Theoretically consistent with time-varying volatility as in Hull&White, Heston&Nandi. also consistent with other departures from BSM, e.g., illiquidity



As of Jan 2006: MSFT = 26\$

# 2. Simple extensions like the CEV Model do not help much

- $dS / S = \mu dt + \sigma S^{\alpha} dz$ ,  $-1 < \alpha < 0$
- α=0 homoskedastic returns
  - $\alpha$ <0 If S  $\uparrow$  variance  $\checkmark$ , contains Black (1976)'s inverse relationship, meant to capture a "leverage effect"
- Tests: Regression (Stan Beckers, J. Finance June 1980)  $Log(\sigma(S_{t+dt}/S_t) = \alpha_0 + \alpha \ln S_t + u_t$

Used a block sampling estimator: intra-day returns to compute daily variance

For 47 stocks: Average R<sup>2</sup>: 3.1%, max R<sup>2</sup>: 9.5%,  $\alpha$ <0 for 38 stocks

=> Specification still not flexible enough.

### **3 Basic ARCH**

• ARCH(1) model 
$$r_t = \mu + \mathbf{u}_t = \mu + \sqrt{h_t} \, \epsilon_t, \quad \epsilon_t \sim i.i.d. \, N(0, 1)$$
$$\mathbf{h}_t = \mathbf{\omega} + \mathbf{\alpha}_1 \, \mathbf{u}^2_{t-1}, \quad \mathbf{\alpha}_1, \mathbf{\omega} > \mathbf{0}$$

- ARCH is a **filter**, it writes *unobserved* volatility as function of a *past observable*  $u^2_{t-1}$  Contrast with stochastic volatility:  $\log ht = \alpha_0 + \alpha_1 \log h_{t-1} + \sigma_v v_t$ ,  $v_t \sim N(0,1)$
- ARCH(1) implies the following process on the squared innovation  $u_t^2$ .

$$\mathbf{u^{2}_{t}} = \mathbf{h_{t}} + \mathbf{u^{2}_{t}} - \mathbf{h_{t}} = \omega + \alpha_{1} \mathbf{u^{2}_{t-1}} + \mathbf{h_{t}} \varepsilon^{2}_{t} - \mathbf{h_{t}}$$

$$\mathbf{u^{2}_{t}} = \omega + \alpha_{1} \mathbf{u^{2}_{t-1}} + \mathbf{h_{t}} (\varepsilon^{2}_{t} - \mathbf{1})$$
[1]

Looks like an AR(1) in  $u^2_t$ 

•  $v_t = \frac{h_t (\epsilon^2_t - 1)}{1}$  is a noise:

$$E(v_t) = E(h_t) E(\epsilon^2_t - 1) = E(h_t) (1-1) = 0$$

Can easily show:  $Cov(v_t, v_{t-k}) = 0$ 

ARCH(1) implies that Squared return noise u2t follows an AR(1)

- $Corr(u^2_t, u^2_{t-s}) = \alpha_1^s$  by AR(1) property
- AR(1) result in  $u^2_t$ :  $E(u^2_t) = V(u_t) = \omega / (1-\alpha_1)$  Stationarity: need  $|\alpha_1| < 1$  The unconditional variance of  $r_t$ .
- Kurtosis: Can show: Kurt( $u_t$ ) =  $3(1-\alpha^2_1)/(1-3\alpha^2_1)$  exists only if  $3\alpha^2_1 < 1$  (no proof)

### Kurtosis always > 3 => fat tailed unconditional returns

- It was quickly recognized that one needed **more than one lag** of  $u^2_t$ : ARCH(q)
- ARCH(q) was not very convenient with q large, too many parameters to estimate

  A generalized model with very few lags did the trick ...

## **4 GARCH model**

• GARCH(p,q): 
$$r_t = \mu + u_t = \mu + \sqrt{h_t} \, \epsilon_t$$
,  $\epsilon_t \sim i.i.d. \, N(0, 1)$  
$$\mathbf{h}_t = \omega + \alpha_1 \, \mathbf{u}^2_{t-1} + \alpha_2 \, \mathbf{u}^2_{t-2} + ... + \alpha_q \, \mathbf{u}^2_{t-q} + \beta_1 \, \mathbf{h}_{t-1} + \beta_2 \, \mathbf{h}_{t-2} + ... + \beta_p \, \mathbf{h}_{t-p}$$
 The ARCH(q) part And now, lags in  $h_t$ 

• A GARCH(1,1) is often sufficient to explain the lag-structure of volatility.

$$\mathbf{h}_t = \mathbf{\omega} + \mathbf{\alpha} \mathbf{u}^2_{t-1} + \mathbf{\beta} \mathbf{h}_{t-1}$$

• Need  $\omega$ ,  $\alpha$ ,  $\beta > 0$  for the model to imply positive variance (otherwise makes no sense!)

• Model for 
$$u_{t}^{2}$$
:  $u_{t}^{2} = h_{t} + u_{t-1}^{2} + h_{t-1} + v_{t}$   
 $= \omega + \alpha u_{t-1}^{2} + \beta h_{t-1} + v_{t}$   
 $= \omega + \alpha u_{t-1}^{2} + \beta (h_{t-1} - u_{t-1}^{2} + u_{t-1}^{2}) + v_{t}$   
 $= \omega + \alpha u_{t-1}^{2} - \beta v_{t-1} + \beta u_{t-1}^{2} + v_{t}$   
 $u_{t}^{2} = \omega + (\alpha + \beta) u_{t-1}^{2} + v_{t} - \beta v_{t-1} \quad ARMA(1,1) \text{ in squared noise}$ 

- Stationarity of  $u^2_t$ :  $u^2_t$  is stationary if  $\sum (\alpha_i + \beta_i) < 1$ .
- The integrated IGARCH(1,1):  $\mathbf{h_t} = \boldsymbol{\omega} + \boldsymbol{\alpha} \mathbf{u^2_{t-1}} + (\mathbf{1}-\boldsymbol{\alpha}) \mathbf{h_{t-1}}$ .. is non stationary Why?

[2]

# 5 Testing, Estimating, Diagnostic

- **Testing:** The ACF of the squared returns.
- Estimation done by numerical maximum likelihood, no analytical results available

$$\Rightarrow \widehat{\alpha}, \ \widehat{h_t}, \ t = 2, ..., T$$
 Why t=2?

• **Diagnostic:** To be successful, ARCH should explain the non-normality of unconditional returns

If 
$$R_t \mid h_t \sim N(\mu, h_t)$$
  $\Longrightarrow \frac{R_t - \widehat{\mu}}{\sqrt{\widehat{h}_t}} \sim i.i.dN(0, 1)$  [3]

Diagnostic: Check the normality of the standardized residuals as in [3]

Note the asymptotics: h<sub>t</sub> supposedly estimated in large sample, Student-t assumed approximately normal.

- Empirical Results: GARCH models
  - 1) explain a lot of, but not all the fat-tailness of financial returns.
  - 2) have been quite successful at forecasting variance in the short to medium term.

# 6 Forecasting: why it matters for risk management

• VaR before time-varying volatility ... used the unconditional variance:

 $Prob[R_{t+1} < \mu - 1.65 \sigma] = 0.05$  Naïve VaR [4]

Could be ... very ... very wrong:

Period of high volatility: VaR is optimistic Period of low volatility: VaR is pessimistic

• Volatility varies with time:

One must use the relevant conditional distribution to make conditional forecasts

Conditioning: information I at time t about t+1  $R_{t+1} \mid I_t \sim N(\mu, \mathbf{h_{t+1}})$ 

• VaR with time-varying volatility ARCH(1)

$$h_{t+1} = \omega + \alpha u_t^2 + \beta h_t$$

Prob[ 
$$R_{t+1} < \mu - 1.65\sqrt{h_{t+1}}$$
 ] = 0.05 GARCH based VaR [4']

• GARCH and other filters for time-varying volatility allow the use of the relevant **conditional distribution** of stock returns for **conditional volatility forecasts**.

• Multiperiod (multi step ahead) forecast borrows from stationary AR method

ARCH(1) 
$$\begin{array}{l} h_{t+1} = \omega + \alpha \ u^2_t & t+1 \ known \\ h_{t+2} = \omega + \alpha \ u^2_{t+1} \\ E_t(h_{t+2}) = \omega + \alpha \ E_t(u^2_{t+1}) = \omega + \alpha \ h_{t+1} \\ = \omega + \alpha \ (\omega + \alpha \ u^2_t) = \omega \ (1+\alpha) + \alpha^2 \ u^2_t \\ \\ Or: \\ E_t(h_{t+k}) = E_t(u^2_{t+k}) & recall \ E_t(u^2_{t+k}) = E_t(\epsilon^2_t) \ E_t(h^2_{t+k}) \\ E_t(h_{t+k}) = \omega \ (1+\alpha + ... \ \alpha^{k-1}) + \alpha^k \ u^2_t & per \ stationary \ AR(1) \ in \ u^2_t \ in \ [1] \\ \\ GARCH(1,1) \ E_t(h_{t+k}) = E_t(u^2_{t+k}) = \omega \ [1+(\alpha+\beta) + ... \ (\alpha+\beta)^{k-1}] + (\alpha+\beta)^k \ u^2_t \\ \end{array}$$

Compare with Risk Metrics:

Using RM to forecast variance for tomorrow  $s^2_{t+1} = \lambda s^2_t + u^2_{t+1}$ ? We don't know  $u_{t+1}$ 

$$s^{2}_{t+1} = \lambda s^{2}_{t} + (1-\lambda) \underbrace{E_{t}(u^{2}_{t+1})}_{t+1} = \lambda s^{2}_{t} + (1-\lambda) s^{2}_{t}$$

$$s^{2}_{t+1} = \lambda s^{2}_{t} + (1-\lambda) s^{2}_{t}$$

$$=> s^{2}_{t+1} = s^{2}_{t} \qquad s^{2}_{t+k} = s^{2}_{t}$$

Risk–Metrics forecasts are similar to a random walk with no drift RM can not recognize a term-structure of volatility

RM is similar to an IGARCH with no intercept

# 7 Crucial extensions

- Model :  $R_t = \mu + u_t \ , \ u_t \sim N(0, \sqrt{h_t})$   $h_t = \omega + \alpha_1 \ u^2_{t\text{-}1} + \beta_1 \ h_{t\text{-}1} \ a \ GARCH(1,1)$
- Estimate  $\Rightarrow \hat{\mu}, \hat{\omega}, \hat{\alpha}, \hat{\beta}, \hat{h_t}, t = 2, ..., T \Rightarrow \hat{u_t} \quad t = 2, ..., T$
- If model is correct:  $\hat{u}_t / \sqrt{\hat{h}_t} \sim \text{i.i.d. N}(0,1)$  the GARCH standardized residuals

• We test that there is no autocorrelation left in squares or absolute values of residuals One rarely needs more than 1 lag of each GARCH(1,1)

• We test normality of the "standardized residuals" of the GARCH model Residuals are more normal that ut's but most often not quite normal yet.

#### 7.1 Crucial Extension 1: Fat-tailed conditional returns

- For financial returns:  $\hat{u}_t / \sqrt{\hat{h}_t}$  still has fat tails after GARCH modeling:
- That is, in  $R_t = \mu_t + \sqrt{h_t} \varepsilon_t$ ,  $\varepsilon_t$  is **not** normally distributed, it has fat tails.
- $\varepsilon_t$  is fat-tail => shortfall probabilities, VAR are incorrect:

i.e., 
$$Prob[R_{t+1} < \mu_{t+1} - 1.65 \sqrt{h}_{t+1}] \neq 0.05$$

Instead: 
$$\varepsilon_t \sim \text{Student}(\nu)$$
  
 $\text{Prob}[R_{t+1} < \mu_{t+1} - 1.81 \sqrt{h_{t+1}}] = 0.05 \text{ for } \nu = 10$ 

- v must be estimated for best fit.
- Results: Evidence of non normality of the conditional distributions, v found to be below 10 or 20.
- Normal-based GARCH VaRs and confidence intervals are optimistic since  $\varepsilon_t$  has fat tails.

# 7.2 Crucial Extension 2: Asymmetric volatility

• EGARCH: 
$$R_t = \mu + u_t$$
,  $u_t = \sqrt{h_t} \, \epsilon_t$ ,  $\epsilon_t \sim N(0,1)$  (Dan Nelson)

$$\log h_t = \omega + \varphi \varepsilon_{t-1} + \alpha \left[ \varepsilon^2_{t-1} - E(\varepsilon^2_{t-1}) \right] + \beta \log h_{t-1}$$

Parameters to estimate:  $\omega$ ,  $\alpha$ ,  $\beta$ ,  $\varphi$ ,

Why log formulation?

No restriction needed on parameters to enforce  $h_t > 0$ Volatility cycles are possible with GARCH(1,2) and < 0 parameters

If  $\phi < 0$ ,  $h_t$  rises after a < 0 shock more than after a positive shock.

Recall: The leverage effect is a misnomer, better term: Volatility Feedback

• Asymmetric GARCH (Glosten, Jagannathan, Runkle GJR):

$$R_t = \mu_t + u_t$$
,  $u_t \sim N(0,h_t)$ 

$$h_t = \omega + \alpha_1 D_{t-1} u^2_{t-1} + \alpha_2 u^2_{t-1} + \beta_1 h_{t-1}$$
 where  $D_t = 0$  if  $\epsilon_t < 0$ 

## 8 Stochastic Volatility Model (SV), contrast with GARCH

$$\begin{split} SV(1): & R_t = \sqrt{h_t} \epsilon_t, \\ & Log \ h_t = \alpha + \delta \ log \ h_{t-1} + v_t \ , \qquad v_t \sim N(0,\sigma_v) \end{split}$$

- Why logarithm? Discrete time model with unbounded noise, need to force positivity of h<sub>t</sub>
- SV: close to continuous time models used in option and asset pricing (Hull & White, Heston)
- SV: More flexible than GARCH: v<sub>t</sub> is an **un**observable noise, it adds variability to h<sub>t</sub> Can induce more kurtosis than GARCH.

GARCH kurtosis and persistence are linked via  $\alpha$ ,  $\beta$ . They can't be modeled separately SV: kurtosis is modeled via  $\sigma_v$ , persistence via  $\delta$ .

Less need for conditional fat-tail return  $\varepsilon_t$ 

- SV: Variance remains an unobservable state variable More difficult to estimate than GARCH, requires Bayesian methods
- Why does GARCH work relatively well?

Nelson & Foster show that GARCH filters, even if mis-specified, have good filtering properties for the true continuous time model: asymptotically consistent estimation of ot

Among other things, Nelson shows that GARCH filters are asymptotically (in continuous time) more efficient than the Kalman filter