

# Eigenvals/vecs

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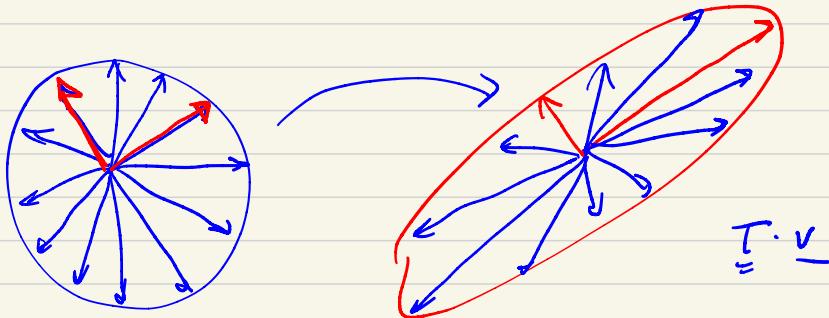


## Eigenvalues & Eigenvectors of rank 2 tensors.

Let  $\underline{T}$  be a rank 2 tensor,  $\underline{v}$  a vector, and  $\lambda$  a scalar.

If  $\underline{T} \cdot \underline{v} = \lambda \underline{v}$ ;  $\underline{v} \neq 0$ , then:

- $\lambda$  is called an eigenvalue of  $\underline{T}$
- $\underline{v}$  is called an eigenvector of  $\underline{T}$  associated w/  $\lambda$ .



(note, the red ones didn't change direction)

- Eigen {values/vectors} are also called proper, principal, characteristic {values/vectors}
- How do we find  $\lambda$ 's &  $\underline{v}$ 's?

$$\underline{T} \cdot \underline{v} = \lambda \underline{v} = \lambda \underline{\underline{I}} \cdot \underline{v} \Rightarrow \underline{T} \cdot \underline{v} - \lambda \underline{\underline{I}} \cdot \underline{v} = 0$$

$$\Rightarrow (\underline{T} - \lambda \underline{\underline{I}}) \cdot \underline{v} = 0 \quad (1)$$

We can express (1) in matrix form, in terms of components in a basis  $e^{\alpha} = \{e_1^{\alpha}, e_2^{\alpha}, e_3^{\alpha}\}$

$$\Rightarrow ([T]^{\alpha} - \lambda [I]^{\alpha})\{v\}^{\alpha} = [0]^{\alpha}$$

which has a nontrivial solution for

$$\det([T]^{\alpha} - \lambda [I]^{\alpha}) = 0$$

$$\det \begin{vmatrix} T_{11}^{\alpha} - \lambda & T_{12}^{\alpha} & T_{13}^{\alpha} \\ T_{21}^{\alpha} & T_{22}^{\alpha} - \lambda & T_{23}^{\alpha} \\ T_{31}^{\alpha} & T_{12}^{\alpha} & T_{33}^{\alpha} - \lambda \end{vmatrix} = 0$$

which can be written as

$$\boxed{\lambda^3 - I_1 \lambda^2 + I_2 \lambda - I_3 = 0} \quad (2)$$

where

characteristic equation.

$$I_1, I_2, I_3$$

are real numbers given by:

$$I_1 = T_{kk}^{\alpha} = \text{Trace}(T)$$

$$I_2 = \frac{1}{2} (T_{ii}^{\alpha} T_{jj}^{\alpha} - T_{ij}^{\alpha} T_{ji}^{\alpha})$$

$$I_3 = \frac{1}{6} \epsilon_{ijk} \epsilon_{pqr} T_{ip}^{\alpha} T_{jq}^{\alpha} T_{kr}^{\alpha} = \det(I)$$

Equation (2) is called the characteristic equation

$I_1, I_2, I_3$  are called principal invariants  
of tensor  $T$

The following questions arise:

- Does the solution of (2) hold for other basis?
- why do we call  $I_1, I_2, I_3$  invariants?

To answer the first question, let's write  
the components of  $T$  in a different basis

$e^P = \{e_1^P, e_2^P, e_3^P\}$ . Then eq. (1) can  
be written as:

$$[(T)^P - \lambda(I)^P] \{v\}^P = \{0\}^P$$

which has non-trivial solution for :

$$\det[(T)^P - \lambda(I)^P] = 0 \quad (3)$$

If  $[Q]$  is a rotation that relates the basis  $e^L$  &  $e^P$  then we can write:

$$[T]^P = [e]^T [T]^L [e] \text{ and}$$

$$[I]^P = [e]^T [I]^L [e]$$

$$\Rightarrow \det([e]^T [T]^L [e] - \lambda [e]^T [I]^L [e]) = 0$$

$$\Rightarrow \det([e]^T (([T]^L - \lambda [I]^L) [e])) = 0$$

$$\Rightarrow \underbrace{\det([e]^T)}_1 \det([T]^L - \lambda [I]^L) \underbrace{\det([e])}_\text{because they are rotations!} = 0$$

$$\Rightarrow \det([T]^L - \lambda [I]^L) = 0$$

which leads again to eq (2)

Central question:

properties of rotation matrices.

$\det = 1$ , inverse = Transpose

That is, the values of  $\lambda$  that satisfies eq (2) are independent of the basis chosen to represent  $T$

Since the invariants are the coefficients of the unique characteristic equation, they must be independent of the chosen basis as well

This can also be shown by writing

$$T_{ij}^P = \alpha_{ip} \alpha_{pj} T_{pq}^L$$

and using orthogonality properties of  $\underline{\alpha}$ , for ex:

$$T_{ii}^P = \underbrace{(\alpha_{ip} \alpha_{iq})}_{\delta_{pq}} T_{pq}^L = \delta_{pq} T_{pq}^L = T_{pp}^L = I,$$

The same procedure can be repeated for the other invariants.

## Properties of symmetric tensors

Let  $\underline{\underline{T}}$  be a symmetric tensor, then:

- 1) All roots of its characteristic equation are real, i.e.: we can find three real eigenvalues  $\lambda_1, \lambda_2, \lambda_3$
- 2) Out of the associated eigenvectors, we can always form an orthonormal right-handed set of eigenvectors  $\underline{\underline{e}} = \{\underline{\underline{v}}_1, \underline{\underline{v}}_2, \underline{\underline{v}}_3\}$
- 3) In the eigenbasis  $\underline{\underline{e}}$ , the matrix representing the components of  $\underline{\underline{T}}$  is diagonal, with the eigenvalues in the diagonal

$$\begin{bmatrix} T_{11} & T_{12} & T_{13} \\ T_{12} & T_{22} & T_{23} \\ T_{13} & T_{23} & T_{33} \end{bmatrix} \xrightarrow{\text{diag}} \underbrace{\lambda_1, \lambda_2, \lambda_3}_{\text{real}} \quad e_{\beta} = \{\underline{\underline{v}}_1, \underline{\underline{v}}_2, \underline{\underline{v}}_3\}$$

(Try to interpret in terms of physics, i.e. cavity - green's law stretch.)  $\Rightarrow \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}$