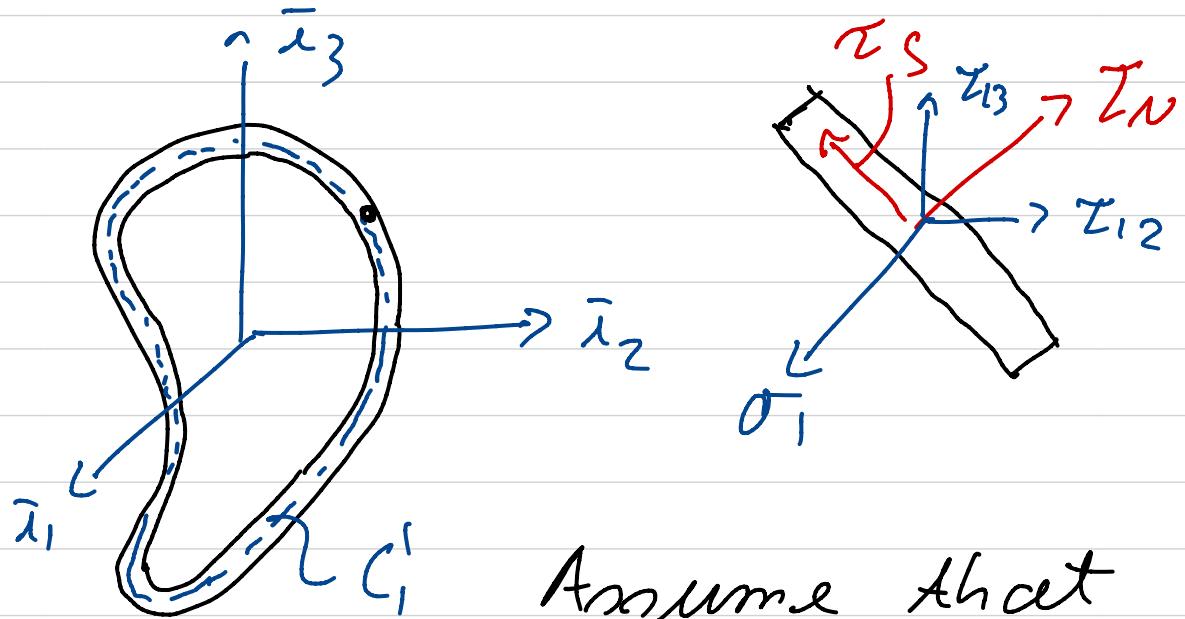



Stress in a thin-walled closed section



Assume that

$$\rightarrow \sigma_1 \gg \sigma_2, \sigma_1 \gg \sigma_3$$

$$\sigma_2 \approx 0 \quad \& \quad \sigma_3 \approx 0$$

$$\rightarrow \tau_{12}, \tau_{13} \gg \tau_{23}$$

$$\tau_{23} \approx 0$$

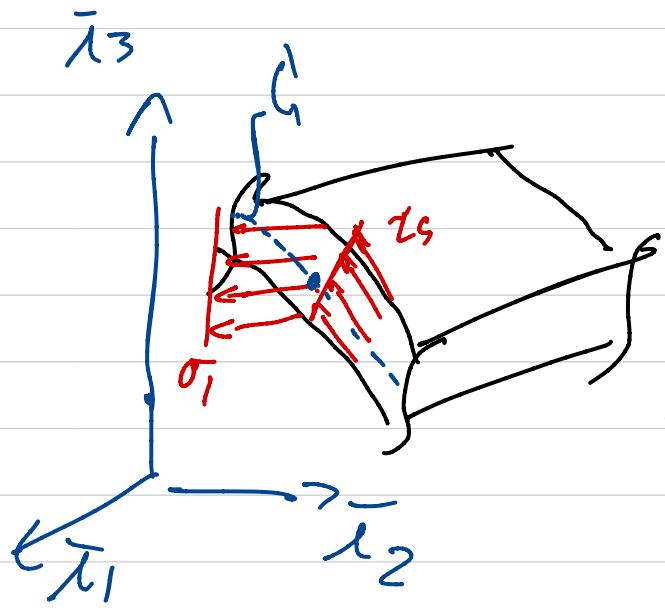
\rightarrow At the edges $\tau_N = 0$. Since the section is thin we will assume

$$\tau_N \approx 0$$

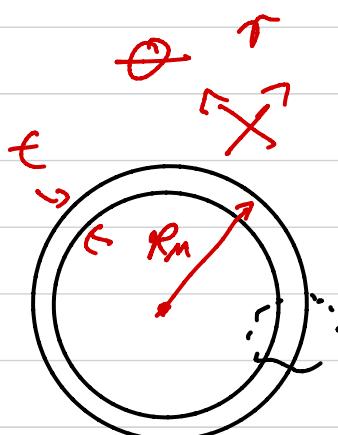
→ Because the section is thin, we will assume that

I_S and σ_1

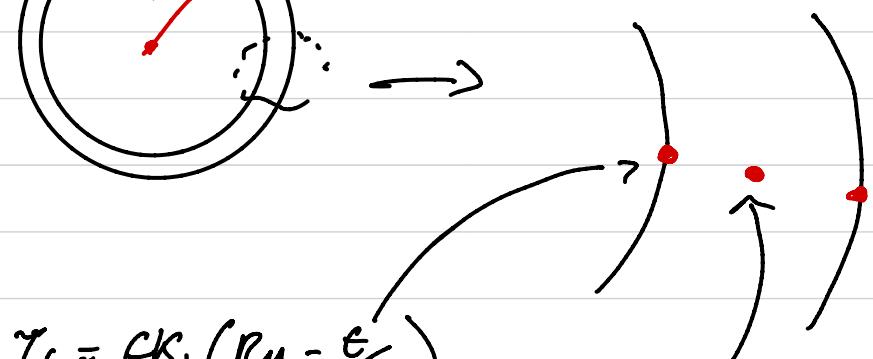
are uniformly distributed across the thickness



Aside: Thin-walled circular cylinder



$$I_S = G K_1 r$$



$$I_S = G K_1 (R_M - \frac{t}{2})$$

$$I_S = G K_1 R_M \left(1 - \frac{1}{2} \frac{t}{R_M}\right)$$

$$\approx 1 \quad I_S = G K_1 R_M$$

Stress Flow

Define

$$n(x_1, s) = \sigma_1(x_1, s) \cdot e(s)$$

$$\tau(x_1, s) = \tau_s(x_1, s) \cdot e(s)$$

n - Axial Stress Flow

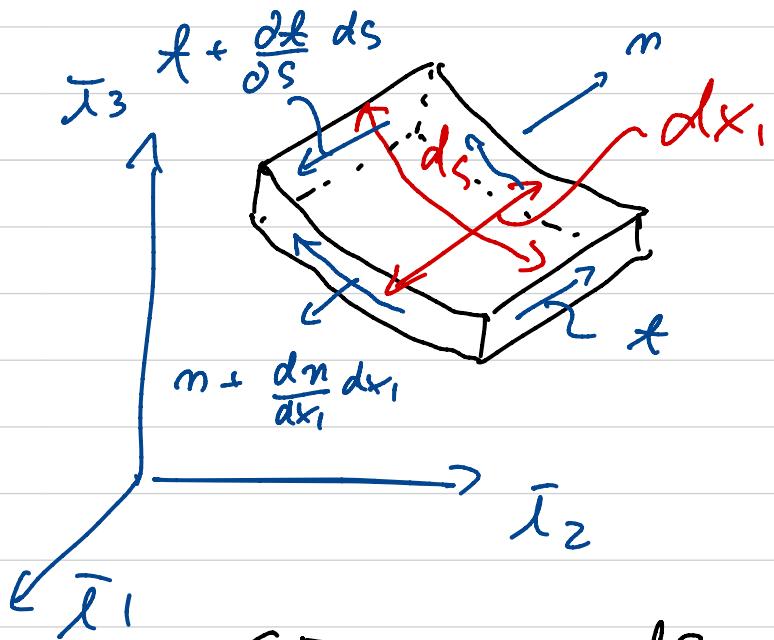
τ - Shear Stress Flow

$$\underline{m}_0 = \int_{C'_1} \underline{\tau}_p \times \underline{e} \, ds$$

$$\rightarrow M_{10} = \int_{C'_1} r_0 \tau \, ds$$

$$\tau_0 = \left(x_2 \frac{dx_3}{ds} - x_3 \frac{dx_2}{ds} \right)$$

Local Equilibrium



$$EF_i: -m dS + \left(m + \frac{\partial m}{\partial x_1} dx_1 \right) dS$$

$$-\ell \cdot dx_1 + \left(\ell + \frac{\partial \ell}{\partial S} dS \right) dx_1 = 0$$

Divide through by $ds dx_1$,

$$\frac{\partial m}{\partial x_1} + \frac{\partial \ell}{\partial S} = 0$$

TORSION OF A CLOSED THIN-WALLED SECTION

Axial strain/stress vanishes

$$\epsilon(s) = 0$$

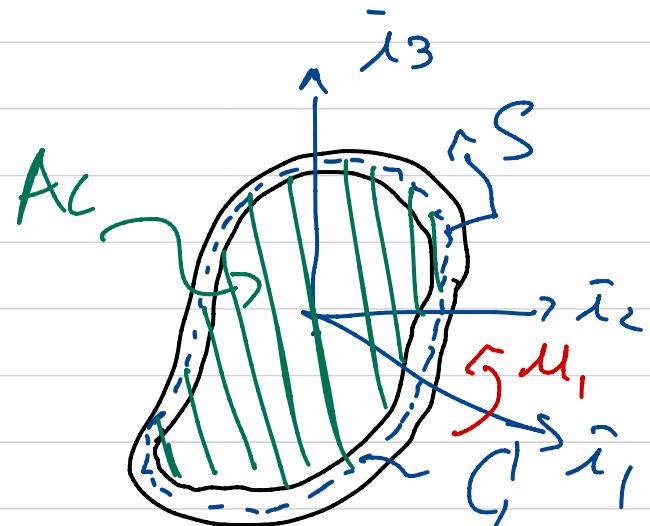
Equilibrium

$$\frac{\partial t}{\partial s} = 0 \rightarrow t = \text{constant}.$$

$$M_1 = \int_{C_1^l} t r_0 ds$$

$$M_1 = t \underbrace{\int_{C_1^l} r_0 ds}_{A_C}$$

Purely geometric



$$= 2 \cdot A_C t \quad A_C - \text{Area enclosed by } C_1^l$$

$$M_1 = 2 A_C t$$

\rightarrow Bredt - Batho Formulae

$$T_S(s) = \frac{M_1}{2 A_C \cdot t(s)}$$

Need to relate K_1 and M_1 to find H_{11}

Energy Argument

$$M_1 \cdot K_1 = \int_{C_1} T_S \cdot f_S \cdot t ds$$

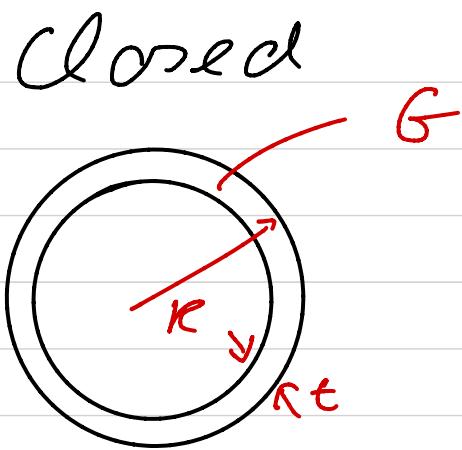
Work Done on System *Strain Energy*

$$K_1 = \frac{M_1}{4 A_c^2} \int_{C_1} \frac{ds}{E(s) t(s)}$$

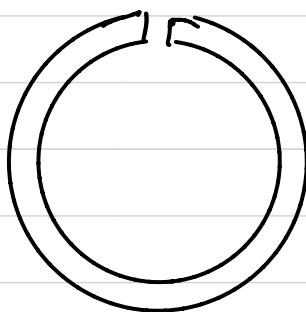
$$H_{11} = \frac{4 A_c^2}{\int_{C_1} \frac{ds}{G \cdot t}}$$

If $G = \text{constant}$ and $t = \text{constant}$

$$H_{11} = \frac{4 G t A_c^2}{l}$$



Open



$$H_{11}^{CL} = \frac{4 G \epsilon A_c^2}{\ell}$$

$$= \frac{4 G \epsilon (\pi k^2)^2}{2 \pi R}$$

$$H_{11}^{OP} = \frac{1}{3} G \ell \epsilon^3$$

$$= \frac{1}{3} G (2 \pi R) \epsilon^3$$

$$H_{11}^{CL} = 2 \pi G \epsilon R^3$$

$$H_{11}^{OP} = \frac{2}{3} \pi G \epsilon^3 R$$

$$\frac{H_{11}^{CL}}{H_{11}^{OP}} = 3 \left(\frac{R}{\ell} \right)^2 \approx 1200 \text{ for}$$

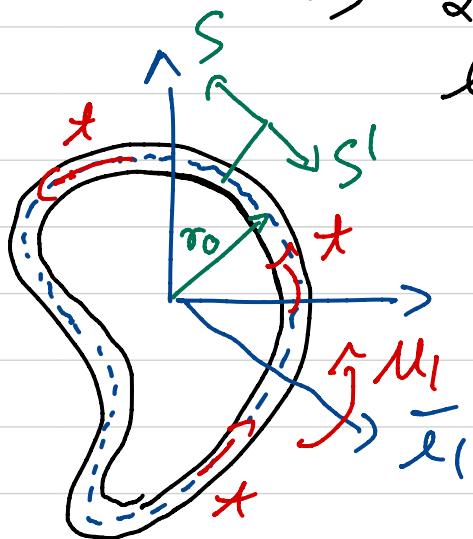
$$\frac{R}{\ell} = 20$$

Notes

→ $\ell = \int_{C_i} ds$ is the perimeter at the curve C_i .

→ The cross-section at max torsional stiffness is the thin-walled circular tube

→ Largest $A_c = \pi R^2$ for a given $\ell = 2\pi R$.



→ τ_0 is an algebraic quantity whose sign depends on the direction at s

→ A_c is an algebraic area

$$s \rightarrow M_1 = 2A_c \tau$$

$$\tau = \frac{M_1}{2A_c}$$

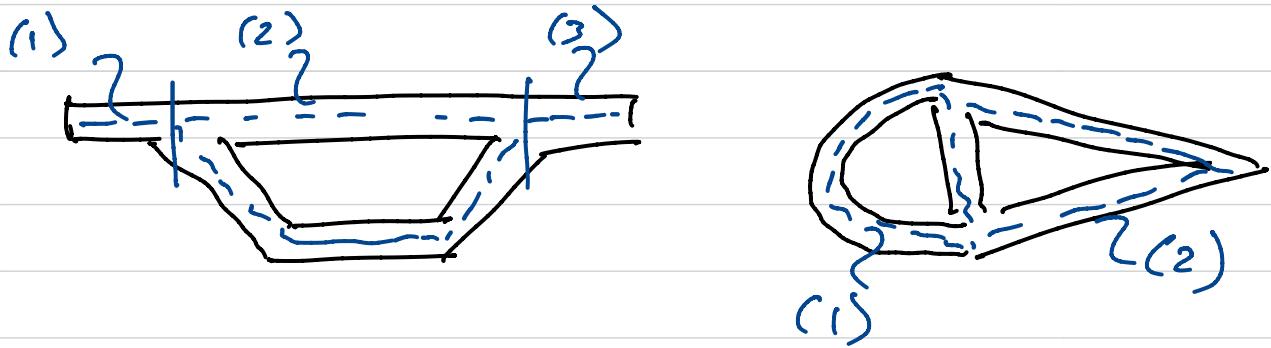
$$A_c > 0 \rightarrow \tau > 0$$

$$s' \rightarrow A_c < 0$$

$$\rightarrow \tau < 0$$

→ $A_c > 0$ when the circular variable describes C_i with A_c to the left.

Torsion at Multi-Component & Multi-Cellular Structures



→ The total torque M_t carried by the cross-section is the sum of torques carried by each segment

$$M_t = \sum_i M_t^{(i)}$$

→ The twist rate at all segments is equal

$$\kappa_t = \kappa_t^{(1)} = \dots = \kappa_t^{(i)}$$

For a given applied torque Q we can solve for $M_t^{(i)}$ and κ_t

→ Solve for shear stress in each segment

→ Solve for twist angle.