

$$dW_{I} = \begin{bmatrix} -\frac{1}{2} \nu_{1} u_{1} + \frac{1}{2} \nu_{1} \left( u_{1} + \frac{d u_{1}}{d x_{1}} d x_{1} \right) \end{bmatrix}$$

$$d \mathcal{W}_{J} = \frac{1}{2} \mathcal{N}, \frac{d u_{1}}{d x_{1}} d x_{1} = \frac{1}{2} \mathcal{N}, \overline{\epsilon}, d x_{1}$$

$$\overline{\epsilon},$$

$$\mathcal{N}_{1} = S \overline{\epsilon}_{1}$$

$$a(\bar{e}_i) = \frac{1}{2} \cdot \frac{5\bar{e}_i^2}{\text{dom it landian}}$$

$$a'(v_1) = \frac{1}{2} \frac{v_1^2}{s} - Stren energy$$
den i by tun dional

Total Energies
$$A(\bar{\epsilon}_1) = \int_0^1 \alpha(\bar{\epsilon}_1) dx, = \int_0^1 2 S\bar{\epsilon}_1^2 dx_1$$

$$A'(\nu_i) = \begin{cases} \alpha'(\nu_i)dx_i = \int_0^{\ell_i} \frac{\nu_i^2}{2} dx_i \end{cases}$$

For lin our elostic morterials 
$$A(\bar{\epsilon}_i) = A'(N_i)$$

Aside: 
$$V_{1}P_{1}U_{AL}$$
  $\bar{e}_{1}$ 

$$\bar{\partial}W_{Z} = \begin{cases} V_{1}.\bar{\partial}\bar{e}_{1} = V_{1}(\bar{o}\bar{e}_{1} = V_{1}\bar{e}_{1}) \\ \bar{e}_{1} \end{cases}$$

$$\begin{cases} ecel & \bar{e}_{1} \\ dW_{Z} = \begin{cases} V_{1}.d\bar{e}_{1} = \begin{cases} \bar{e}_{1} \\ S\bar{e}_{1}.d\bar{e}_{1} = S\bar{e}_{1} \end{cases} \end{cases}$$

$$\begin{cases} ecel & \bar{e}_{1} \\ V_{0}\dot{e}_{1} = V_{1}\bar{e}_{1} \end{cases}$$

$$\begin{cases} ecel & \bar{e}_{1} \\ V_{0}\dot{e}_{1} = V_{1}\bar{e}_{1} \end{cases}$$

## Beams en Tonsion

$$\alpha(\kappa_{1}) = \frac{1}{2} \frac{H_{11} \kappa_{1}^{2}}{H_{11} \kappa_{1}^{2}} A(\kappa_{1}) = \frac{1}{2} \int_{0}^{L} \frac{H_{11} \kappa_{1}^{2} dx_{1}}{H_{11} \kappa_{1}^{2}} A(\kappa_{1}) = \frac{1}{2} \int_{0}^{L} \frac{H_{11} \kappa_{1}^{2} dx_{1}}{H_{11}}$$

## 3D Beom

$$W = \frac{1}{2} \int_{V} O^{T} E dU$$

$$O(E) = \frac{1}{2} E^{T} E E$$

$$Skillmen Watnise$$

$$a'(o) = 10^{7} \le 0$$

$$Compliance Matrixe$$

$$A = \frac{1}{2} \left( \frac{d^2 U_2(x_1)}{dx_1^2} \right)^2 dx,$$

$$T = A + \overline{Q} = \frac{1}{2} \int_{0}^{L} H_{33} \left( \frac{d^{2} u_{2}}{d x_{1}^{2}} \right)^{2} dx, - \int_{0}^{L} \rho_{2} G_{1} \left( u_{2}(x_{1}) dx_{1} \right)^{2} dx$$

$$TT = TT (U_2(x_1)) \rightarrow Ts$$
 a functional. "Function at a

\* Inlinite # od "Function at a tunotion".

DOF!

\* Need to know or approximate U2(x,)!