



Lecture 3 – State Machine Implementation Using ROMs

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Administration

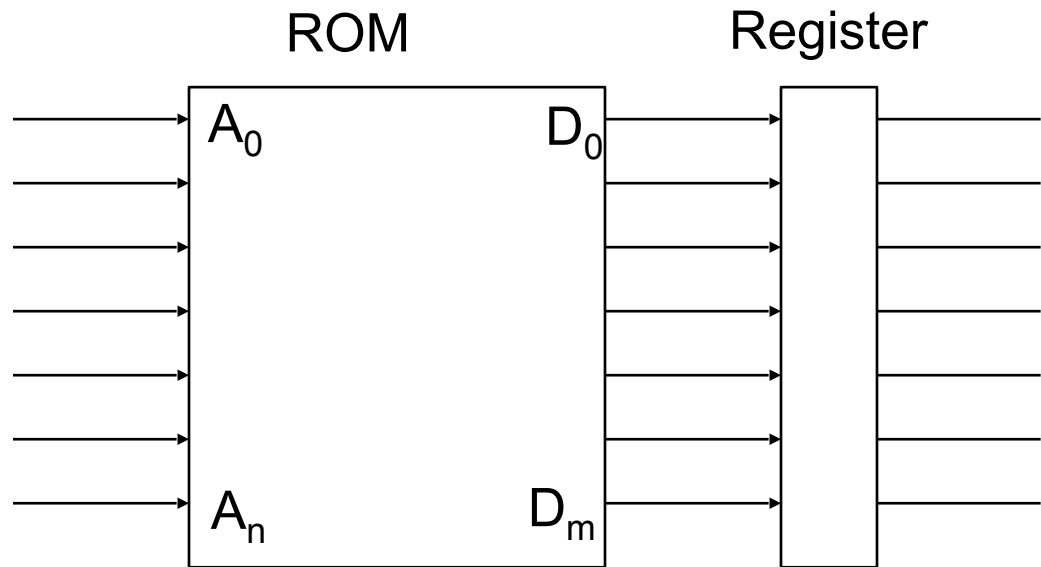
- **Next lecture Monday**
- **Laboratory Sessions Venue**
 - These are held in the Tolansky Laboratory
- **Due to a software problem, there will be NO lab session this week**
 - But there is preparation to be done!

Read Only Memories

- Typically thought of as storage for programs and data in embedded systems
 - “Firmware”
- Addresses are contiguous locations
- Data is bytes of program code or data
- But can also be regarded as general transforms of an input bit pattern (the address) to an output bit pattern (the data)

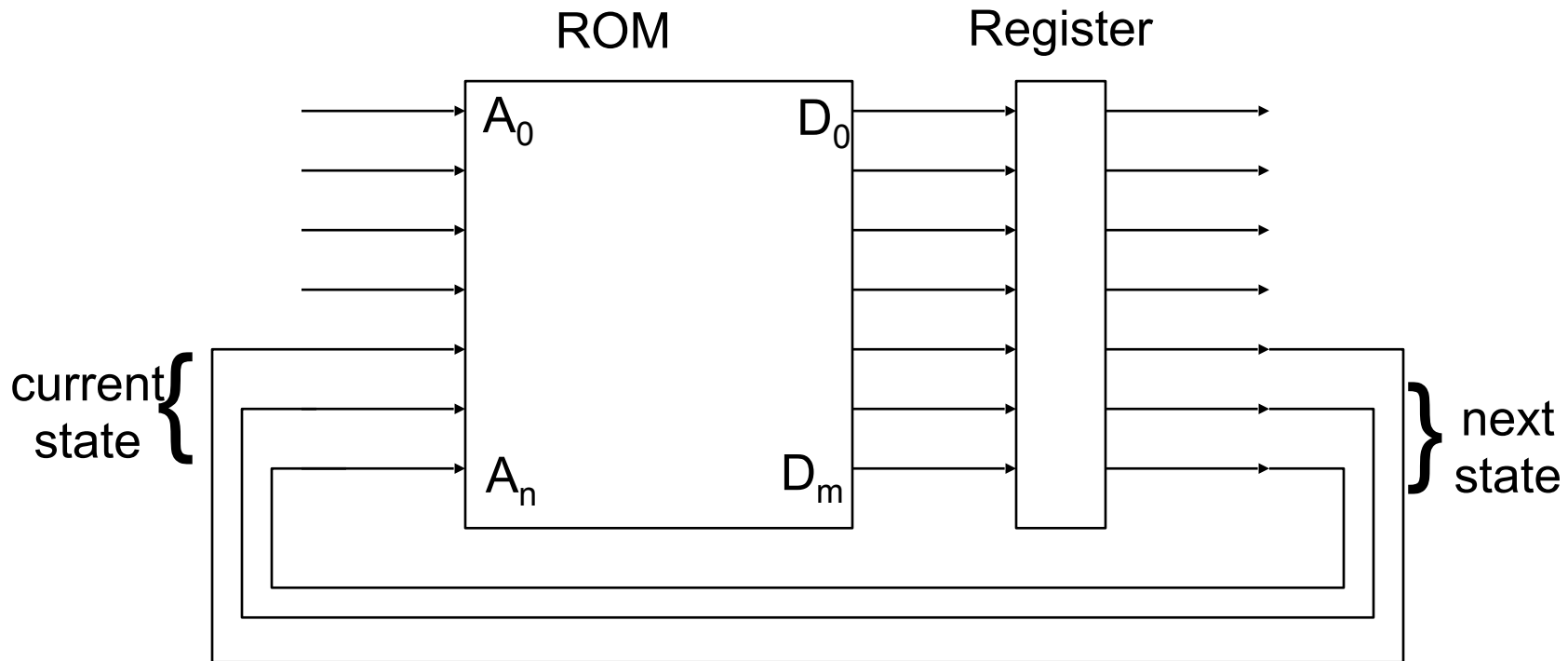
ROM for Generalised Transform

- We need to add registers (flip flops) to maintain the output states



Adding States

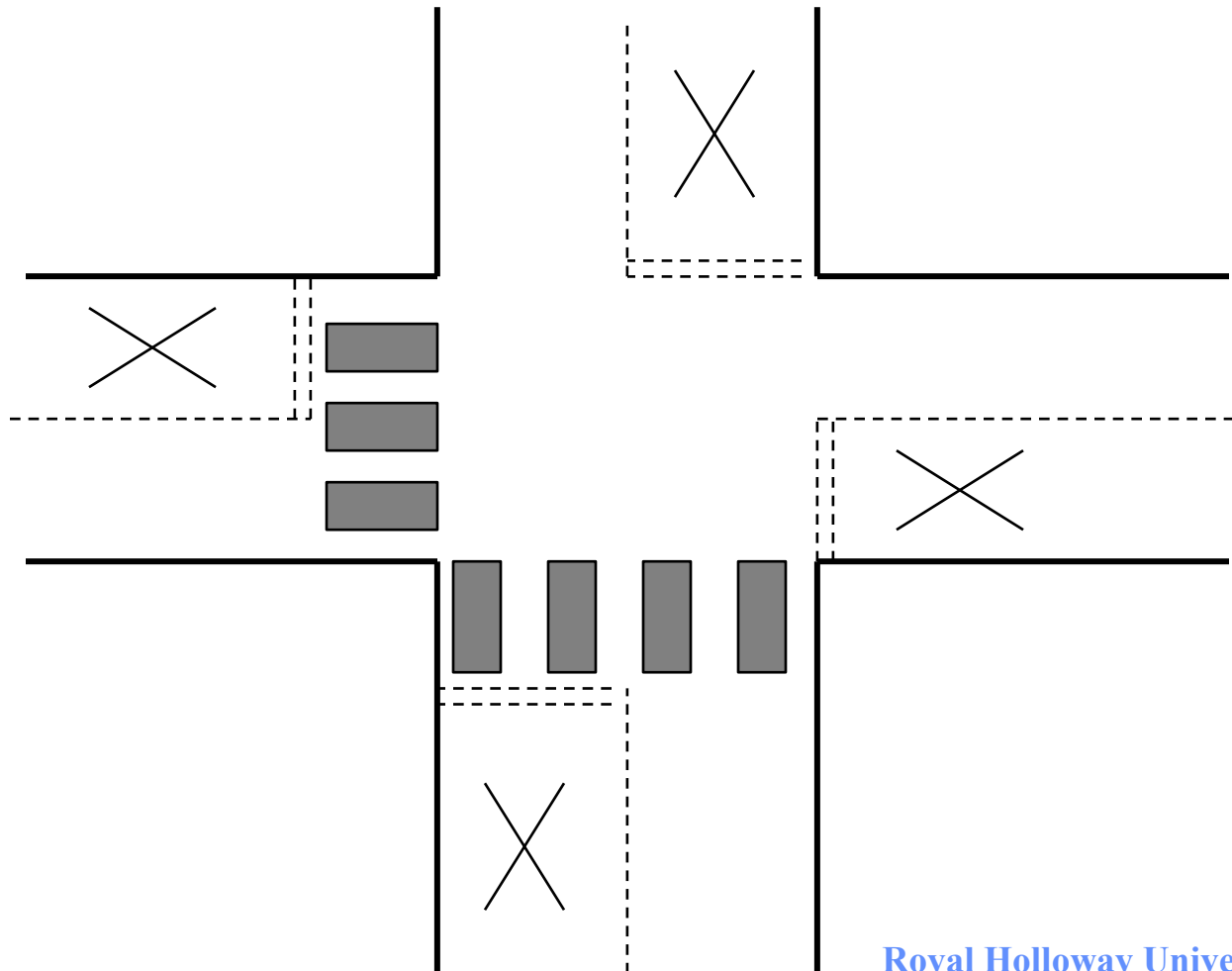
- We use some of the address and data bits to represent the current and next states



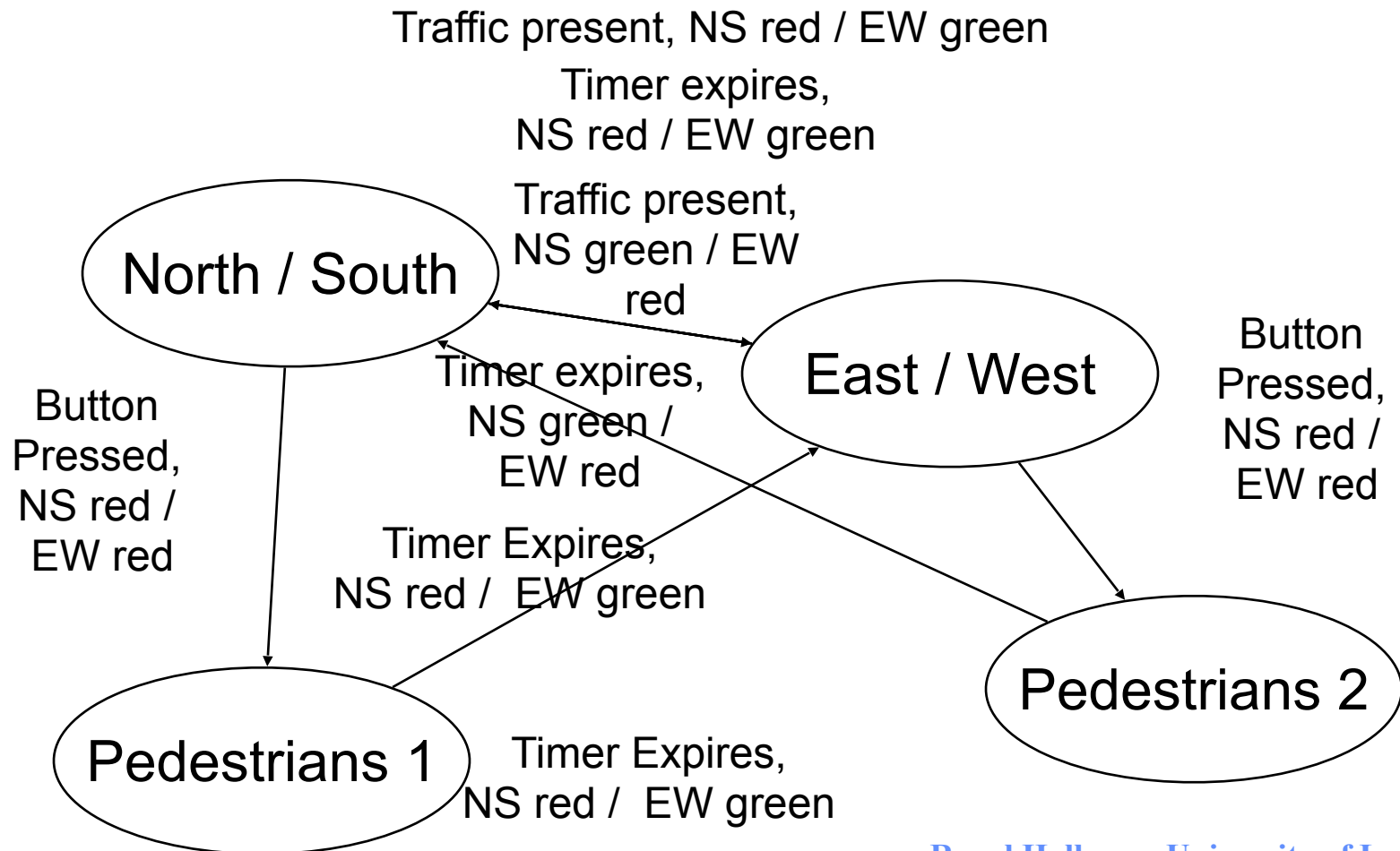
Traffic Light Example

- From previous lecture
- We will assume all timings are the same
 - We have a “timer reset” output
 - This generates a “timer expired” input after a set interval
- We will add traffic sensors
 - These generate a binary ‘1’ when vehicles are present
 - If there is traffic in the “red” direction, and no traffic in the “green” direction then
 - reset the timer
 - change the lights
- We also need a “pedestrian button” input
- And outputs for N/S and E/W lights

A Simple Traffic Light Junction



Traffic Light State Diagram



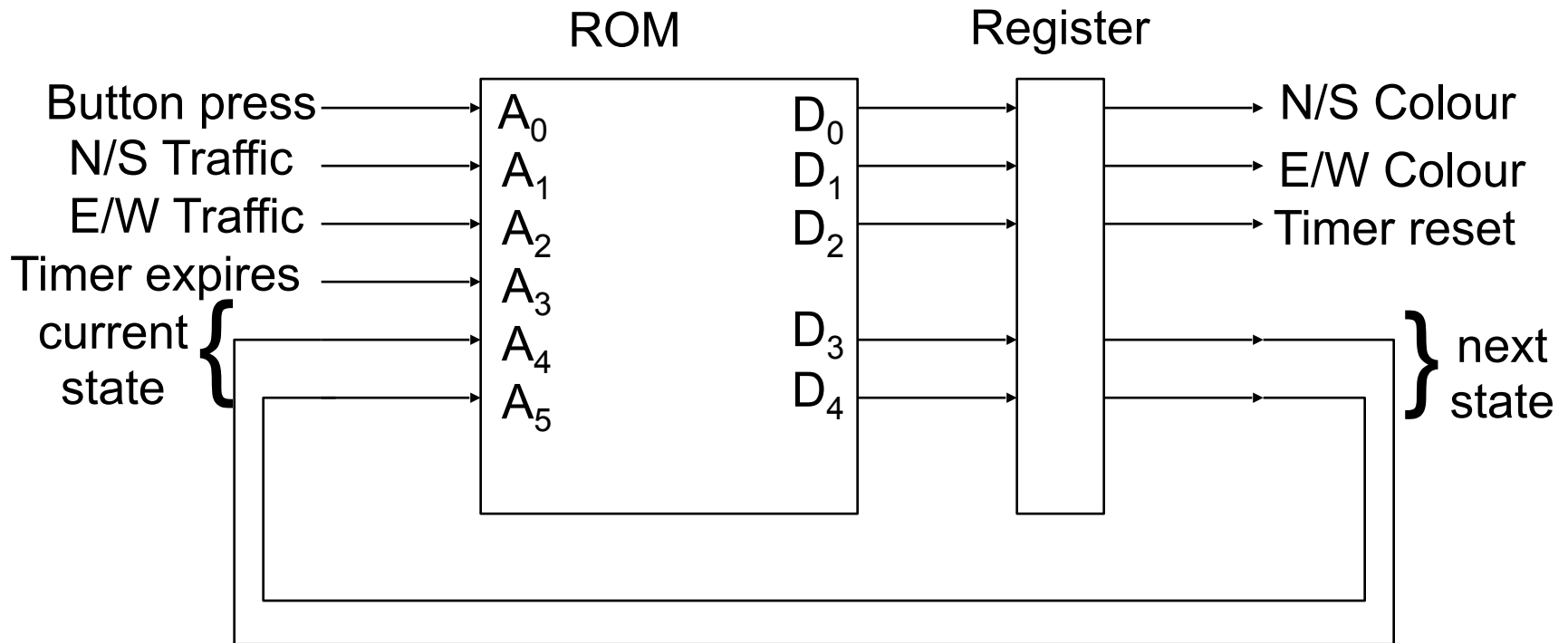
Address Assignments

- **We need an input to represent a button press**
 - Assign A_0 as “button press”
- **We need inputs from each pair of traffic sensors**
 - Assign A_1 as “NS traffic”
 - Assign A_2 as “EW traffic”
- **We need an input for the timer expiry**
 - Assign A_3 as “Timer expires”
- **We need two bits to represent the state**
 - (we have four states in total)
 - Assign A_4 and A_5 as the state bits as follows
 - 00 = North/South ▪ 10 = Pedestrians 1
 - 01 = East/West ▪ 11 = Pedestrians 2

Data Assignments

- **We need an output to represent the state of the N/S lights**
 - Assign D_0 as “n/s colour” (0 = red, 1 = green)
- **Similarly for the E/W lights**
 - Assign D_1 as “e/w colour” (0 = red, 1 = green)
- **We will assume that if $D_0 = 0$ and $D_1 = 0$ then**
 - Pedestrian lights are green
- **We also need an output to reset the timer**
 - Assign D_2 as “timer reset”
- **And two output bits to represent the next state**
 - Assign D_3 and D_4 as per previous slide

ROM Schematic



ROM Truth Table (extract)

| Address Lines | | | | | | Data Lines | | | | Next Stat |
|---------------|----------|----------|---------|------------|-----------|------------|-----|---------|---|-----------|
| Btn prs | N/S traf | E/W traf | Tmr Exp | Crnt State | | N/S | E/W | Tmr rst | | |
| 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 1 | 0 | 0 | 0 | 1 | 1 | 0 | 1 |
| 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 |
| 0 | 0 | 1 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 1 |
| 0 | 1 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |
| 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 |
| 1 | 0 | Etc.. | 1 | 0 | 0 | 0 | 0 | 1 | 1 | 0 |
| CS232 | 1 | 1 | 1 | 0 | Lecture 3 | 0 | 0 | 1 | 1 | 0 |

ROM Implementation

- **ALL combinations of inputs need to be explicitly specified**
 - However, this does make plain conflicting priorities
 - e.g. What happens when a button press coincides with the traffic sensor?
- **ROM size must be a minimum of n words each of m bits long**
 - This can get large quickly!

Logic Implementation

- In most situations there are many “don’t care” combinations of inputs
 - In fact, the *majority* of inputs may be “don’t care”
- We can implement the truth table using combinatorial logic
 - But we need to minimise the hardware required
- Rather than discrete logic we can use programmable arrays of logic
 - More on these next week

Laboratory Tools

- **We will be using the Tkgate simulation package**
 - This runs under under X Windows on Linux / Unix and is available from <http://www.cs.cmu.edu/~hansen/tkgate>
 - It has also been installed on aspasia in C103
 - There is a tutorial available for those interested
- **Tkgate is a graphical simulation package**
 - “Draw” logic circuits using graphical components
 - Run the simulation, view outputs, timing diagrams etc.
- **Much less dangerous than soldering!**

Laboratory Preparation

- **A circuit will be provided**
 - As per previously shown ROM schematic
 - With the addition of clock signals etc.
 - Switches for the traffic sensors
 - LEDs for the traffic lights
- **You will need to provide the ROM contents**
 - 64 entries, as per previous table
 - Probably easier to provide this in address order

ROM Contents Format

- You will need to provide a text file as input
- Must have extension “.mem”
- Blank lines and those beginning with # ignored
- Other lines must be composed of:
 - A hexadecimal address
 - A forward slash
 - one or more hexadecimal data bytes
- e.g.

```
# Start loading at position 100
100/ e1 f0 0 0 e1 e0 0 0
108/ 81 0 0 0 12 1 bd 0
```

Possible Extensions

- **What is the effect on our ROM implementation of the following changes?**
 - **Having different timer values for each direction?**
 - **Additional output required**
 - **Adding “filter lanes” for particular directions**
 - **Additional states (therefore more bits to represent them)**
 - **Additional outputs**
 - **Correctly modelling the traffic light sequence (red -> red / amber -> green -> amber)**
 - **Lots more states and outputs**

Summary

- **State Machines can easily be implemented using ROMs**
 - But need to fully specify ROM contents
 - ROM size can become large quickly
- **Using programmable arrays of logic allows us to take advantage of “don’t care” states**
 - But we need a mechanism to do this

Next Week

- **We will look at how State Machines can be implemented in programmable logic**
- **A more general minimisation method than Karnaugh maps**