## Model 1

Model layer : 5

• Full connect layer: 3

• Activation function : ReLU

• Optimizer function : SGD

· Nesterov 加速算法

• Learning rate: 0.013

```
self.conv1 =
              nn. Conv2d (128, 256,
                                     kernel size=3, stride=1)
self.conv2 =
              nn. Conv2d (256,
                               256,
                                     kernel_size=3,
                                                     stride=1)
self.conv4 =
                                     kernel_size=3,
                                                     stride=1)
self. conv5 = nn. Conv2d(512, 512,
                                    kernel_size=3,
                                                     stride=1)
self.relu = nn.ReLU()
self.maxpool = nn.MaxPool2d(kernel size=2)
self. dropout = nn. Dropout (p=0. 2)
self. fc1 = nn. Linear (12800, 5000)
self. fc2 = nn. Linear (5000,
                              1000)
self. fc3 = nn. Linear (1000,
```

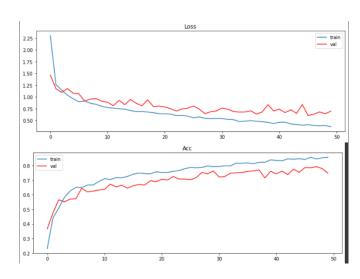
```
self.conv1(x)
       self.relu(out)
       self.maxpool(out)
       self.conv2(out)
       self.relu(out)
    = self.maxpool(out)
    = self.conv3(out)
    = self.relu(out)
    = self.maxpool(out)
    = self. conv4(out)
    = self.relu(out)
    = self.maxpool(out)
    = self.conv5(out)
    = self.relu(out)
    = self.maxpool(out)
    = out.view(out.size(0),
out = self.fcl(out)
out = self.dropout(out)
out = self.fc3(out)
```

```
criterion = nn.CrossEntropyLoss()
optimizer = optim.SGD(model.parameters(), lr=0.013, momentum=0.9, nesterov=True)
```

# 執行結果:

• Epoch: 50





• Kaggle 測試結果: 0.77076

## Model 2

- Model layer: 4
- Full connect layer: 3
- Activation function : ReLU
- Optimizer function : SGD + Schedular
- · Nesterov 加速算法
- Learning rate: 0.0015

```
self.conv1 = nn.Conv2d(3, 128, 3, stride=1)
self.conv2 = nn.Conv2d(128, 256, 3, stride=1)
self.batch2 = nn.BatchNorm2d(256)
self.conv3 = nn.Conv2d(256, 256, 3, stride=1)
self.conv4 = nn.Conv2d(256, 512, 3, stride=1)
self.batch4 = nn.BatchNorm2d(512)

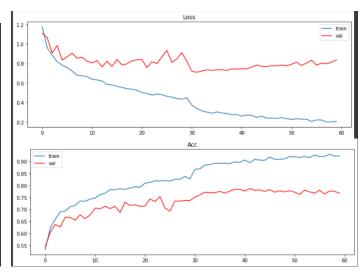
self.relu = nn.ReLU()
self.maxpool = nn.MaxPool2d(kernel_size=2)
self.dropout = nn.Dropout(p=0.2)
self.fc1 = nn.Linear(73728, 1024)
self.fc2 = nn.Linear(1024, 128)
self.fc3 = nn.Linear(128, 5)
```

```
self.conv1(x)
        self.relu(out)
        self.maxpool(out)
        self.conv2(out)
        self.relu(out)
        self.maxpool(out)
        self.batch2(out)
        self.conv3(out)
        self.maxpool(out)
        self.conv4(out)
        self.relu(out)
        self.maxpool(out)
        self.batch4(out)
        out. view(out. size (0), -1)
        self.fcl(out)
       self.fcl(out)
out = self.dropout(out)
out = self. fc2(out)
out = self.fc3(out)
```

```
criterion = nn.CrossEntropyLoss()
optimizer = optim.SGD(model.parameters(), 1r=0.0015, momentum=0.9, nesterov=True)
scheduler = optim.1r_scheduler.StepLR(optimizer, step_size=30, gamma=0.1)
```

#### 執行結果:

- Epoch: 60
- Kaggle 測試結果: 0.80730



#### Model 1 與 Model 2 的差異

- 1. Model Layer 減少 (5 → 4)
- 2. 加入 2 層 batch, 更新參數
- 3. Optimizer 搭配 schedular
- 4. Learning rate 調小  $(0.013 \rightarrow 0.0015)$