HW1-ECON-482

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1 Prob 1:

- (1) According to the statement, we use flat prior, so that maximizing the posterior is equivalent to maximizing likelihood ("conditional likelihood" given the initial data). There are two ways to do prediction:
 - Moving window:

$$\begin{bmatrix} 1, & 2, \cdots, & T, \cdots, & T+h \ \end{bmatrix} \\ & [2, \cdots, & T, \cdots, & T+h, & T+h+1 \] \\ & \cdots & \cdots & \cdots \\ & [T, \cdots, & T+h, & T+h+1, \cdots, & 2T+h-1 \] \\ & \cdots & \cdots & \cdots \\ \end{bmatrix}$$

• Extending window:

Here I tried both cases and get the MSFE:

According to Table 1, looks like the extending window method has smaller MSFE.

MSFE	log-real	log-real	log-GDP	log-GDP
	GDP	GDP	deflator	deflator
Average	1 quarter	4 quarters	1 quarter	4 quarters
growth rate				
Moving	2.500e - 3	3.872e - 4	1.374e - 3	4.272e - 4
window				
Extending	1.919e - 3	2.195e - 4	1.246e - 3	2.289e - 4
window				

Table 1: Mean squared forecast error for moving window and extending window.

(2) According to [1], with Minnesota prior as specified, the posterior would looks like:

$$\beta|\Sigma, Y \sim \mathcal{N}(\hat{\beta}, \Sigma \otimes \Omega) \tag{1}$$

$$\hat{B} = (X^T X + \Omega^{-1})^{-1} (X^T Y + \Omega^{-1} \hat{b})$$
 (2)

$$\hat{\beta} = vec[\hat{B}] \tag{3}$$

$$b = vec[\hat{b}] \tag{4}$$

$$b = ([0, 1, 0, \dots, 0 | 0, 0, 1, 0, \dots, 0 | \dots]^T)_{K \times 1}$$
(6)

$$\hat{\sigma}_i^2 = \frac{1}{T} \sum_{t=1}^{T} \left[(y_{i,t} - \hat{c}_i - \hat{\phi}_i y_{i,t-1})^2 \right]$$

$$= \frac{1}{T} \sum_{t=1}^{T} (y_{i,t}^2 + \hat{c}_i^2 + \hat{\phi}_i^2 y_{i,t-1}^2 + 2\hat{c}_i \hat{\phi}_i y_{i,t-1} - 2\hat{c}_i y_{i,t} - 2\hat{\phi}_i y_{i,t-1} y_{i,t})$$
 (7)

$$\begin{bmatrix} \hat{c}_i \\ \hat{\phi}_i \end{bmatrix} = \begin{bmatrix} T & \sum_{t=1}^T y_{i,t-1} \\ \sum_{t=1}^T y_{i,t-1} & \sum_{t=1}^T y_{i,t-1}^2 \end{bmatrix}^{-1} \begin{bmatrix} \sum_{t=1}^T y_{i,t} \\ \sum_{t=1}^T y_{i,t-1} y_{i,t} \end{bmatrix}$$
(8)

where K = Mp + 1, M = dim(y), p = max time lag, and the given observations are y_{-p+1}, \dots, y_0 and the values to forecast are y_1, \dots, y_T . Part of these expressions come from [2], Section 5.2. The last two equation mean the parameters $\hat{\sigma}_i^2$ are MLE based on AR(1) model, given $y_{i,0}$. Here, we don't need to know Σ because we only need a point estimation of $\hat{\beta}$. Using the same procedure as in (1), we get the MSFE as: The

MSFE	log-real	log-real	log-GDP	log-GDP
	GDP	GDP	deflator	deflator
Average	1 quarter	4 quarters	1 quarter	4 quarters
growth rate				
Extending	9.387e - 4	1.493e - 4	5.444e - 4	1.856e - 4
window				

Table 2: Mean squared forecast error for moving window and extending window.

MSFE for Minnesota priors for 1 quarter forecast is smaller than that for flat prior, but the MSEF for Minnesota priors for 4 quarter forecast is larger.

(3) The marginal likelihood is (as shown in [1] and its supplemental file):

$$P(y|\lambda) = \left(\frac{1}{\pi}\right)^{\frac{MT}{2}} \frac{\Gamma_M(\frac{T+d}{2})}{\Gamma_M(\frac{d}{2})} |\Omega|^{-\frac{M}{2}} |\Psi|^{\frac{d}{2}} |X^T X + \Omega^{-1}|^{-\frac{M}{2}}$$

$$* |\Psi + \hat{\epsilon}^T \hat{\epsilon} + (\hat{B} - \hat{b})^T \Omega^{-1} (\hat{B} - \hat{b})|^{-\frac{T+d}{2}}$$

$$\hat{\epsilon} = Y - X\hat{B}$$
(9)

Maximizing the posterior with flat prior is equivalent to maximizing the marginal likelihood. By using notation $E_{\Psi}E_{\Psi}^{T}=\Psi^{-1}$, $D_{\Omega}D_{\Omega}^{T}=\Omega$, and $\lambda^{2}\Phi=\Omega$ or $\lambda D_{\Phi}=D_{\Omega}$, the 9 can be simplified as:

$$P(y|\lambda) = \left(\frac{1}{\pi}\right)^{\frac{MT}{2}} \frac{\Gamma_{M}(\frac{T+d}{2})}{\Gamma_{M}(\frac{d}{2})} |\Psi|^{-\frac{T}{2}} |D_{\Omega}^{T}X^{T}XD_{\Omega} + I_{K}|^{-\frac{M}{2}}$$

$$* \left|I_{M} + E_{\Psi}^{T} \left[\hat{\epsilon}^{T}\hat{\epsilon} + (\hat{B} - \hat{b})^{T}\Omega^{-1}(\hat{B} - \hat{b})\right] E_{\Psi}\right|^{-\frac{T+d}{2}}$$

$$\propto |\lambda^{2}D_{\Phi}^{T}X^{T}XD_{\Phi} + I_{K}|^{-\frac{M}{2}}$$

$$* \left|\lambda^{2}I_{M} + E_{\Psi}^{T} \left[\lambda^{2}\hat{\epsilon}^{T}\hat{\epsilon} + (\hat{B} - \hat{b})^{T}\Phi^{-1}(\hat{B} - \hat{b})\right] E_{\Psi}\right|^{-\frac{T+d}{2}} \lambda^{M(T+d)} \qquad (10)$$

$$\hat{\epsilon}^{T}\hat{\epsilon} = (Y - X\hat{B})^{T}(Y - X\hat{B})$$

$$\hat{B} = (\lambda^{2}X^{T}X + \Phi^{-1})^{-1}(\lambda^{2}X^{T}Y + \Phi^{-1}\hat{b})$$

We can use gradient method to optimize 10. First we take log and then take derivative w.r.t. λ . However, the code to implement this would be much more complex. Here, I just use grid-search first. The MSFE depends on the interval we specify to do grid search.

MSFE	log-real	log-real	log-GDP	log-GDP
	GDP	GDP	deflator	deflator
Average	1 quarter	4 quarters	1 quarter	4 quarters
growth rate				
[0.0001, 1]	9.524e - 4	1.748e - 4	5.020e - 4	2.014e - 4
[0.05, 1]	9.063e - 4	1.604e - 4	4.995e - 4	1.934e - 4

Table 3: Mean squared forecast error for moving window and extending window.

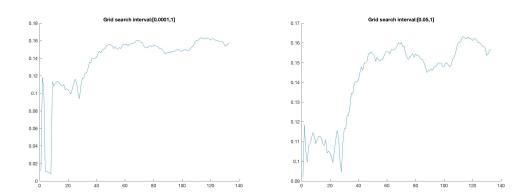


Figure 1: The optimal λ with extending windows and two different search intervals. I am not sure why when λ is near 0 the path has a big jump. From MSFE, we see they are comparable with those obtained by setting $\lambda = 0.2$.

2 Prob 2:

(1) First use the whole data set to get MLE for parameters by maximizing likelihood (conditional likelihood conditioning on the first p observations). Then, use the obtained coefficients to do projection from p+1 to T, based on the given initial observations and later projected values.

Name	Observed data	Flat prior	Minnesota prior	SOC (1)	SOC (5)
GDP	3.35E+00	3.26E+00	3.23E+00	3.27E+00	3.33E+00
pri-infla	5.65E-04	1.38E-04	1.38E-04	6.88E-05	3.13E-05
federal	1.07E-03	2.71E-04	2.16E-04	1.55E-04	6.32E-05
wage-infla	1.02E-03	1.44E-04	1.24E-04	8.18E-05	3.31E-05
labor	5.96E-02	6.23E-02	5.53E-02	7.04E-02	6.76E-02
cons	2.27E-02	2.20E-02	2.13E-02	1.93E-02	1.74E-02

As shown in above form, the variance for log-real GDP, log-labor share, and log-consumption ratio are mostly explained by the deterministic components, but for quarterly price inflation, federal funds rate, and quarterly wage inflation, most of variance cannot be explained by the deterministic components. I think it makes sense because the former three variables are more stable, while the later three variables can be easily affected by the time and current economical situation.

- (2) Repeat the same exercise for Minnesota priors.
 - The difference is very small. They are comparable.
- (3) Repeat the same exercise for SOC priors.

The plot is following:

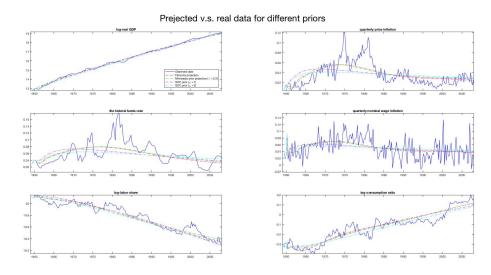


Figure 2: The projections based on the whole data set with flat prior, Minnesota prior, SOC with $\mu = 1$, and SOC with $\mu = 5$.

Different priors give very similar results.

```
1 clear();
2 % Load data into the working space
3 load ('dataVARmedium', '-mat');
4 p = 5;
5 T = 64-5;
_{6} N = size(y,1);
7 M = 7;
8 \text{ K} = M*p+1;
9 h = 4;
11 % (1) OLS solution for prediction
12 % Moving window prediction
13 tic
z_{comp} = z_{comp} = (N-(T+p+h)+1,8); % the first four columns are predicted z (
      average growth rate of GDP) and the second four columns is the real \boldsymbol{z}
  for i = 1: (N-(T+p+h)+1)
16
      % design matrix
      X = zeros(T,K);\% a T*K matrix
17
       for j = 1:T
18
           X(j,:) = [1, reshape(y((i+j+p-2:-1:i+j-1),:)',1,K-1)];\% have to
19
      transpose because the reshape function operate in column
      % OLS solution for coefficients
21
       B_{-hat} = (X'*X) \setminus X'*y((i+p:i+p+T-1),:);\% \text{ a } K*M \text{ matrix}
22
      \% \text{ for } h = 1 \& 4
23
       pred_y = zeros(h,M);\% a h*M matrix
24
       y_{-}lag = [1, reshape(y(i+p+T-1:-1:i+T,:)', 1, K-1)]; % lag of y for the
25
       prediction
       for k = 1:h
27
           % forecast
           pred_y(k,:) = y_lag*B_hat;
28
           if k<h
29
                % reform the lag for y of prediction
30
                y_{lag} = [1, reshape(pred_y(k:-1:1,:)', 1, k*M), reshape(y(i+p+T-1:-1:
31
      i+T+k,:) ',1,K-1-k*M)];
32
           end
       end
33
       z_{\text{comp}}(i,1:2) = \text{pred}_y(1,1:2) - y(i+p+T-1,1:2);%predicted average growth
34
      rates for one quarter of (i) log-real GDP and (ii) log-GDP delector
       z_{\text{-comp}}(i, 3:4) = (pred_y(h, 1:2) - y(i+p+T-1, 1:2))/h; %predicted average
35
      growth rates for h quarters of (i) log-real GDP and (ii) log-GDP delector
       z_{-comp}(i,5:6) = y(i+p+T,1:2)-y(i+p+T-1,1:2); %average growth rates for one
       quarter of (i) log-real GDP and (ii) log-GDP delector
37
       z_{\text{comp}}(i,7:8) = (y(i+p+T+h-1,1:2)-y(i+p+T-1,1:2))/h;%average growth rates
        for h quarters of (i) log-real GDP and (ii) log-GDP delector
38 end
39 % Calculate the average squared forecast error
40 MSFE1 = sum((z_{comp}(:,1:4)-z_{comp}(:,5:8)).^2,1)/size(z_{comp},1)
41 csvwrite ('mse_ex1-1-moving.csv', MSFE1)
```

```
42 toc
43 % Expanding window prediction
44 tic
z_{comp} = z_{comp} = z_{comp} (N-(T+p+h)+1.8); \% the first four columns are predicted z (
      average growth rate of GDP) and the second four columns is the real z
  for i = 1:(N-(T+p+h)+1)
46
       if i ==1
47
           % design matrix
48
           X = zeros(T,K);\% a T*K matrix
49
           for j = 1:T
50
               X(j,:) = [1, reshape(y((j+p-1:-1:j),:)',1,K-1)];\% have to
      transpose because the reshape function operate in column
52
           end
       else
53
           new\_row = [1, reshape(y((i+T+p-2:-1:i+T-1),:)',1,K-1)];
           X = [X; new\_row]; \% a (T+i-1)*K matrix
56
      % OLS solution for coefficients
       B_{-hat} = (X'*X) X'*y((p+1:p+T+i-1),:);\% \text{ a } K*M \text{ matrix}
58
      \% for h = 1 \& 4
59
       pred_y = zeros(h,M); % a h*M matrix
60
       y_{-}lag = [1, reshape(y(T+i+p-1:-1:T+i,:)', 1, K-1)];\% lag of y for the
61
      prediction
       for k = 1:h
           % forecast
64
           pred_y(k,:) = y_lag*B_hat;
           if k<h
65
               % reform the lag for y of prediction
66
               y_{lag} = [1, reshape(pred_y(k:-1:1,:)', 1, k*M), reshape(y(T+i+p-1:-1:
67
      T+i+k,:) ',1,K-1-k*M];
           end
      end
69
       z_{\text{comp}}(i,1:2) = \text{pred}_y(1,1:2) - y(i+p+T-1,1:2);%predicted average growth
      rates for one quarter of (i) log-real GDP and (ii) log-GDP delector
      z_{\text{-comp}}(i, 3:4) = (pred_y(h, 1:2) - y(i+p+T-1, 1:2))/h;%predicted average
71
      growth rates for h quarters of (i) log-real GDP and (ii) log-GDP delector
       z_{-comp}(i,5:6) = y(i+p+T,1:2)-y(i+p+T-1,1:2);%average growth rates for one
72
       quarter of (i) log-real GDP and (ii) log-GDP delector
73
       z_{\text{comp}}(i,7:8) = (y(i+p+T+h-1,1:2)-y(i+p+T-1,1:2))/h;%average growth rates
       for h quarters of (i) log-real GDP and (ii) log-GDP delector
75 % Calculate the average squared forecast error
76 MSFE2 = sum((z_{comp}(:,1:4)-z_{comp}(:,5:8)).^2,1)/size(z_{comp},1)
77 csvwrite ('mse_ex1-1-extending.csv', MSFE2)
79 % (2) Minnesota prior with a given lambda
80 % Expanding window prediction
81 tic
z_{\text{comp}} = z_{\text{eros}}(N-(T+p+h)+1,8); % the first four columns are predicted z (
      average growth rate of GDP) and the second four columns is the real z
```

```
83 % Given lambda
84 \text{ lam} = 0.2;
85 % Estimate b
  b_hat = [zeros(M,1), eye(M,M*p)];
   for i = 1:(N-(T+p+h)+1)
       if i ==1
88
           % design matrix
89
           X = zeros(T,K);\% a T*K matrix
90
           for j = 1:T
91
               X(j,:) = [1, reshape(y((j+p-1:-1:j),:)',1,K-1)];% have to
92
       transpose because the reshape function operate in column
93
94
       else
           new\_row = [1, reshape(y((i+T+p-2:-1:i+T-1),:)',1,K-1)];
95
           X = [X; new\_row]; \% a (T+i-1)*K matrix
96
97
       % Estimate elements of Omega
98
       % The first observation is given (regarded as index 0) and the rest of
       observation up to the
       % end of current window (index 1 to T) are for prediction as stated in
100
       the problem
       % statement
101
       % Follow Hamilton 1994 to get the MLE for variance
102
       sum1 = sum(y(1:p+T+i-2,:),1); %sum_1^T y_(t-1)
       sum2 = sum(y(2:p+T+i-1,:),1); %sum_1^T y_(t)
       sum3 = sum(y(1:p+T+i-2,:).^2,1); %sum_1^T y_(t-1)^2
       sum4 = sum(y(2:p+T+i-1,:).^2,1); %sum_1^T y_(t)^2
106
       sum5 = sum(y(2:p+T+i-1,:).*y(1:p+T+i-2,:),1); sum_1^T y_(t) y_(t-1)
       sigma2-hat = zeros(1,M);
108
109
       for m = 1:M
           c_phi_hat = [p+T+i-2,sum1(m);sum1(m),sum3(m)] \setminus [sum2(m);sum5(m)];\%
110
       c_{phi}hat = [c_{hat}, phi_{hat}]
           sigma2-hat(m) = 1.0/(p+T+i-2)*(sum4(m)+c-phi-hat(2)^2*sum3(m)+2*
111
       c_phi_hat(1)*c_phi_hat(2)*sum1(m)...
                             -2*c_phi_hat(1)*sum2(m)-2*c_phi_hat(2)*sum5(m)+
112
       c_phi_hat (1) ^2;
113
       end
       omega_d = [10^6];
115
       for j = 1:p
           omega_d = [omega_d, (sigma2_hat*j^2).^(-1)];
116
117
       end
       % Times the lambda^2
118
       omega_d = lam^2 * omega_d;
119
       % MAP solution for coefficients
       B_{hat} = (X'*X+diag(omega_d.^(-1)))(X'*y((p+1:p+T+i-1),:)+diag(omega_d
121
       .^{(-1)}*b_hat');\% a K*M matrix
       \% for h = 1 \& 4
       pred_y = zeros(h,M);\% a h*M matrix
123
       y_{-}lag = [1, reshape(y(T+i+p-1:-1:T+i,:)', 1, K-1)]; % lag of y for the
       prediction
```

```
for k = 1:h
125
           % forecast
126
           pred_y(k,:) = y_lag*B_hat;
127
            if k<h
                % reform the lag for y of prediction
                y_{lag} = [1, reshape(pred_y(k:-1:1,:)', 1, k*M), reshape(y(T+i+p-1:-1:
130
      T+i+k,:) ',1,K-1-k*M)];
           end
131
       end
132
       z_{\text{-comp}}(i,1:2) = \text{pred}_{y}(1,1:2) - y(i+p+T-1,1:2);%predicted average growth
133
       rates for one quarter of (i) log-real GDP and (ii) log-GDP delector
       z_{\text{-comp}}(i, 3:4) = (\text{pred}_{y}(h, 1:2) - y(i+p+T-1, 1:2))/h;%predicted average
       growth rates for h quarters of (i) log-real GDP and (ii) log-GDP delector
       z_{-comp}(i, 5:6) = y(i+p+T, 1:2)-y(i+p+T-1, 1:2);%average growth rates for one
        quarter of (i) log-real GDP and (ii) log-GDP delector
       z_{\text{comp}}(i,7:8) = (y(i+p+T+h-1,1:2)-y(i+p+T-1,1:2))/h;%average growth rates
136
        for h quarters of (i) log-real GDP and (ii) log-GDP delector
138 % Calculate the average squared forecast error
139 MSFE3 = sum((z_{comp}(:,1:4)-z_{comp}(:,5:8)).^2,1)/size(z_{comp},1)
csvwrite ('mse_ex1-1-lambda_given.csv', MSFE3)
141 toc
142 W (3) Minnesota prior without a given lambda (optimize marginal likelihood to
        get lambda each time)
143 % Expanding window prediction
145 %Cannot set lambda = 0, because when take log of lambda, 0 is not
146 %meaningful
lam_bd = [0.0001, 1];
148 \text{ N_-try} = 1000;
149 d = M + 2;
150 z-comp = zeros (N-(T+p+h)+1.8); % the first four columns are predicted z (
       average growth rate of GDP) and the second four columns is the real z
151 % Record optimal value of lambda
rec_lam_opt = zeros(N-(T+p+h)+1,1);
153 % Estimate b
b_hat = [zeros(M,1), eye(M,M*p)];
   for i = 1:(N-(T+p+h)+1)
156
       if i ==1
           % design matrix
157
           X = zeros(T,K);\% a T*K matrix
158
           for j = 1:T
159
                X(j,:) = [1, reshape(y((j+p-1:-1:j),:)',1,K-1)];\% have to
160
       transpose because the reshape function operate in column
       else
162
           new\_row = [1, reshape(y((i+T+p-2:-1:i+T-1),:)',1,K-1)];
163
           X = [X; new\_row]; \% a (T+i-1)*K matrix
164
165
       % Estimate elements of Omega
```

```
% The first observation is given and the rest of observation up to the
167
       % end of current window are for prediction as stated in the problem
168
       % statement
169
       % Follow Hamilton 1994 to get the MLE for variance
170
       sum1 = sum(y(1:p+T+i-2,:),1);%sum_1^T y_(t-1)
171
       sum2 = sum(y(2:p+T+i-1,:),1); %sum_1^T y_(t)
172
       sum3 = sum(y(1:p+T+i-2,:).^2,1); %sum_1^T y_(t-1)^2
173
       sum4 = sum(y(2:p+T+i-1,:).^2,1);%sum_1^T y_(t)^2
174
       sum5 = sum(y(2:p+T+i-1,:).*y(1:p+T+i-2,:),1);%sum_1^T y_(t)y_(t-1)
175
       sigma2-hat = zeros(1,M);
176
       for m = 1:M
177
            c_phi_hat = [p+T+i-2,sum1(m);sum1(m),sum3(m)] \setminus [sum2(m);sum5(m)];\%
       c_{phi}hat = [c_{hat}, phi_{hat}]
            temp\_sum = 0;
179
            sigma2-hat(m) = 1.0/(p+T+i-2)*(sum4(m)+c-phi-hat(2)^2*sum3(m)+2*
180
       c_phi_hat(1)*c_phi_hat(2)*sum1(m)...
                             -2*c_phi_hat(1)*sum2(m)-2*c_phi_hat(2)*sum5(m)+
181
       c_phi_hat (1) ^2;
       end
182
       omega_d = [10^6];
183
       for j = 1:p
184
            omega_d = [omega_d, (sigma2_hat*j^2).^(-1)];
185
186
       end
       % Optimize in terms of lambda
187
       % Use grid-search method
189
       %options_optim = optimoptions(@fminunc, 'Display', 'iter-detailed', '
       Algorithm', 'quasi-newton', 'SpecifyObjectiveGradient', true, 'MaxIterations
       ',1000);
       rec_lam_opt(i) = lam_mle_grid(@logmlikelih, lam_bd, N_try, X, y((p+1:p+T+i-1))
190
       ,:), sigma2_hat, omega_d, b_hat', M, T+i-1,d);
       % Times the lambda^2
191
       omega_d = rec_lam_opt(i)^2 * omega_d;
       % MAP solution for coefficients
193
       B_{hat} = (X'*X+diag(omega_d.^(-1)))(X'*y((p+1:p+T+i-1),:)+diag(omega_d
194
       .^{(-1)}*b_hat');\% a K*M matrix
       \% \text{ for } h = 1 \& 4
195
       pred_y = zeros(h,M);\% a h*M matrix
196
       y_{-}lag = [1, reshape(y(T+i+p-1:-1:T+i,:)', 1, K-1)];\% lag of y for the
       prediction
       for k = 1:h
198
           % forecast
199
            pred_y(k,:) = y_lag*B_hat;
200
            if k<h
201
                % reform the lag for y of prediction
202
                y_{-}lag = [1, reshape(pred_y(k:-1:1,:)', 1, k*M), reshape(y(T+i+p-1:-1:
203
      T+i+k,:) ',1,K-1-k*M)];
           end
204
       end
205
       z_{\text{comp}}(i,1:2) = \text{pred}_y(1,1:2) - y(i+p+T-1,1:2); %predicted average growth
206
       rates for one quarter of (i) log-real GDP and (ii) log-GDP delector
```

```
z_{\text{-comp}}(i, 3:4) = (\text{pred_y}(h, 1:2) - y(i+p+T-1, 1:2))/h;%predicted average
       growth rates for h quarters of (i) log-real GDP and (ii) log-GDP delector
       z_{-comp}(i,5:6) = y(i+p+T,1:2)-y(i+p+T-1,1:2);%average growth rates for one
208
        quarter of (i) log-real GDP and (ii) log-GDP delector
       z_{-comp}(i,7:8) = (y(i+p+T+h-1,1:2)-y(i+p+T-1,1:2))/h;%average growth rates
        for h quarters of (i) log-real GDP and (ii) log-GDP delector
210 end
211 % Calculate the average squared forecast error
212 MSFE4 = sum((z_{comp}(:,1:4)-z_{comp}(:,5:8)).^2,1)/size(z_{comp},1)
csvwrite ('mse_ex1-1-lambda_opt.csv', MSFE4)
csvwrite('lambda_opt.csv', rec_lam_opt)
215 figure();
216 hold on;
plot (rec_lam_opt);
int_str = ['[', num2str(lam_bd(1)),',',num2str(lam_bd(2)),']'];
title (['Grid search interval:',int_str]);
220 cwd = '/Users/kungangzhang/Documents/OneDrive/Northwestern/Study/Courses/ECON
       -482/HW1/;
221 saveas(gca,[cwd,['lambda_opt_1']],'fig');
222 saveas(gca,[cwd,['lambda_opt_1']],'jpg');
223 toc
```

Listing 1: Matlab code for problem 1.

```
1 clear();
2 % Load data into the working space
3 load ('dataVARmedium', '-mat');
_{5} \operatorname{lgGDP} = y(:,1); \% \operatorname{log-real GDP}
6 qpriinf = diff(y(:,2)); %quarterly price inflation
7 fedfr = y(:,3); % federal funds rate
s \text{ qnomwainf} = \text{diff}(y(:,7)+y(:,2)); % \text{quarterly nominal wage inflation}
9 lglabsh = y(:,7)+y(:,6)-y(:,1);\%log-labor share
10 \operatorname{lgcomra} = y(:,4)-y(:,1);\%\log-\operatorname{consumption} ratio
11
12 p = 5;
13 N = size(y,1);
14 T = N-p; %Initial time horizon for forecasting
15 M = 7;
16 \text{ K} = M*p+1;
17 h = 0; The maximum horizon of out-of-sample forecast
19 % (1) OLS solution for prediction
20 tic
  for i = 1:(N-(T+p+h)+1)
21
       if i ==1
22
           % design matrix
23
           X = zeros(T,K);\% a T*K matrix
24
25
            for j = 1:T
26
                X(j,:) = [1, reshape(y((j+p-1:-1:j),:)',1,K-1)];\% have to
       transpose because the reshape function operate in column
```

```
end
       else
28
           new\_row = [1, reshape(y((i+T+p-2:-1:i+T-1),:)',1,K-1)];
29
           X = [X; new\_row]; \% a (T+i-1)*K matrix
30
       end
31
      % OLS solution for coefficients
32
       B_{-hat} = (X'*X) \setminus X'*y((p+1:p+T+i-1),:);\% \text{ a } K*M \text{ matrix}
33
      % Do projection based on MLE of coefficients
34
       yproj1 = y(1:p,:);
35
       for i = p+1:N
36
           yproj1(i,:) = [1, reshape(yproj1(i-1:-1:i-p,:)',1,K-1)]*B_hat;
37
38
39
       lgGDP1 = yproj1(:,1);
       qpriinf1 = diff(yproj1(:,2));
40
       fedfr1 = yproj1(:,3);
41
       qnomwainf1 = diff(yproj1(:,7)+yproj1(:,2));
42
       lglabsh1 = yproj1(:,7)+yproj1(:,6)-yproj1(:,1);
43
       lgcomra1 = yproj1(:,4)-yproj1(:,1);
44
45 end
46 xt = ((1959+0.25): 0.25: (2008+1));
47 figure();
48 hold on;
49 box on;
50 %title('Prejected v.s. real data');
  annotation ('textbox', [0 0.9 1 0.1], ...
       'String', 'Prejected v.s. real data for different priors', ...
53
       'EdgeColor', 'none',
54
       'HorizontalAlignment', 'center')
57 legendinfo{1} = ['Observed data'];
  handle(1) = plot_all([xt, lgGDP], [xt(2:end), qpriinf], [xt, fedfr], [xt(2:end),
      qnomwainf], [xt, lglabsh], [xt, lgcomra], '-b', 'Observed data');
xt1 = xt(1:end);
60 legendinfo {2} = ['Flat prior projection'];
61 handle (2) = \text{plot\_all}([xt1, \lg GDP1], [xt1(2:end), qpriinf1], [xt1, fedfr1], [xt1(2:end)]
      end), qnomwainf1], [xt1, lglabsh1], [xt1, lgcomra1], '-.r', 'Flat prior
      projection ');
62 toc
63
64 % (2) Minnesota prior with a given lambda
65 tic
66 % Given lambda
67 \text{ lam} = 0.2;
68 % Estimate b
b_{-}hat = [zeros(M,1), eye(M,M*p)];
70 for i = 1:(N-(T+p+h)+1)
       if i ==1
71
           % design matrix
           X = zeros(T,K);\% a T*K matrix
```

```
for i = 1:T
74
                X(j,:) = [1, reshape(y((j+p-1:-1:j),:)',1,K-1)];% have to
75
       transpose because the reshape function operate in column
           end
76
       else
77
            new\_row = [1, reshape(y((i+T+p-2:-1:i+T-1),:)',1,K-1)];
78
           X = [X; new\_row]; \% a (T+i-1)*K matrix
79
80
       % Estimate elements of Omega
81
       % The first observation is given (regarded as index 0) and the rest of
82
       observation up to the
83
       % end of current window (index 1 to T) are for prediction as stated in
       the problem
       % statement
84
       % Follow Hamilton 1994 to get the MLE for variance
85
       sum1 = sum(y(1:p+T+i-2,:),1); %sum_1^T y_(t-1)
86
       sum2 = sum(y(2:p+T+i-1,:),1); %sum_1^T y_(t)
87
       sum3 = sum(y(1:p+T+i-2,:).^2,1); %sum_1^T y_(t-1)^2
       sum4 = sum(y(2:p+T+i-1,:).^2,1); %sum_1^T y_-(t)^2
89
       sum5 = sum(y(2:p+T+i-1,:).*y(1:p+T+i-2,:),1);%sum_1^T y_(t)y_(t-1)
90
       sigma2-hat = zeros(1,M);
91
       for m = 1:M
92
            c_phi_hat = [p+T+i-2,sum1(m);sum1(m),sum3(m)] \setminus [sum2(m);sum5(m)];\%
93
       c_phi_hat = [c_hat, phi_hat]
            sigma2-hat(m) = 1.0/(p+T+i-2)*(sum4(m)+c-phi-hat(2)^2*sum3(m)+2*
       c_{phi_{hat}}(1) * c_{phi_{hat}}(2) * sum1(m) ...
                             -2*c_phi_hat(1)*sum2(m)-2*c_phi_hat(2)*sum5(m)+
95
       c_phi_hat (1) ^2;
       end
96
       omega_d = [10^6];
97
       for j = 1:p
            omega_d = [omega_d, (sigma2-hat*j^2).^(-1)];
100
       % Times the lambda^2
101
       omega_d = lam^2 * omega_d;
102
       \% MAP solution for coefficients
103
       B_{hat} = (X'*X+diag(omega_d.^(-1)))(X'*y((p+1:p+T+i-1),:)+diag(omega_d.^(-1)))(X'*y((p+1:p+T+i-1),:)+diag(omega_d.^(-1)))
       .^{(-1)}*b_hat');\% a K*M matrix
       % Do projection based on MLE of coefficients
       yproj2 = y(1:p,:);
106
       for i = p+1:N
107
            yproj2(i,:) = [1, reshape(yproj2(i-1:-1:i-p,:)',1,K-1)]*B_hat;
108
109
       lgGDP2 = yproj2(:,1);
110
       qpriinf2 = diff(yproj2(:,2));
111
112
       fedfr2 = yproj2(:,3);
       qnomwainf2 = diff(yproj2(:,7)+yproj2(:,2));
113
       lglabsh2 = yproj2(:,7)+yproj2(:,6)-yproj2(:,1);
114
       lgcomra2 = yproj2(:,4)-yproj2(:,1);
115
116 end
```

```
xt2 = xt(1:end);
118 legendinfo{3} = ['Minnesota prior projection (\lambda = 0.2)'];
handle(3) = plot_all([xt2,lgGDP2],[xt2(2:end),qpriinf2],[xt2,fedfr2],[xt2(2:end),qpriinf2]
       end), qnomwainf2], [xt2, lglabsh2], [xt2, lgcomra2], '-.g', 'Minnesota prior
       projection (\lambda = 0.2);
120
121 toc
122 % (3) Minnesota prior without a given lambda (optimize marginal likelihood to
        get lambda each time)
123 tic
124 % Given lambda
125 \text{ lam} = 0.2;
126 \text{ mu} = 1;
127 % Estimate b
b_{hat} = [zeros(M,1), eye(M,M*p)];
   for i = 1:(N-(T+p+h)+1)
       if i ==1
130
           % design matrix
132
           X = zeros(T,K);\% a T*K matrix
            for j = 1:T
133
                X(j,:) = [1, reshape(y((j+p-1:-1:j),:)',1,K-1)];% have to
134
       transpose because the reshape function operate in column
           end
135
       else
136
           new\_row = [1, reshape(y((i+T+p-2:-1:i+T-1),:)',1,K-1)];
138
           X = [X; new\_row]; \% a (T+i-1)*K matrix
139
       % Estimate elements of Omega
140
       % The first observation is given (regarded as index 0) and the rest of
141
       observation up to the
       % end of current window (index 1 to T) are for prediction as stated in
142
       the problem
       % statement
143
       % Follow Hamilton 1994 to get the MLE for variance
144
       sum1 = sum(y(1:p+T+i-2,:),1); %sum_1^T y_(t-1)
145
       sum2 = sum(y(2:p+T+i-1,:),1); %sum_1^T y_(t)
146
       sum3 = sum(y(1:p+T+i-2,:).^2,1); %sum_1^T y_(t-1)^2
147
       sum4 = sum(y(2:p+T+i-1,:).^2,1); %sum_1^T y_(t)^2
149
       sum5 = sum(y(2:p+T+i-1,:).*y(1:p+T+i-2,:),1); %sum_1^T y_(t)y_(t-1)
       sigma2-hat = zeros(1,M);
150
       for m = 1:M
151
            c_{phi-hat} = [p+T+i-2,sum1(m);sum1(m),sum3(m)] \setminus [sum2(m);sum5(m)];
       c_{phi}hat = [c_{hat}, phi_{hat}]
            sigma2_hat(m) = 1.0/(p+T+i-2)*(sum4(m)+c_phi_hat(2)^2*sum3(m)+2*
       c_{phi-hat}(1)*c_{phi-hat}(2)*sum1(m)...
                             -2*c_phi_hat(1)*sum2(m)-2*c_phi_hat(2)*sum5(m)+
154
       c_phi_hat (1) ^2;
       end
155
       omega_d = [10^6];
       for j = 1:p
```

```
omega_d = [omega_d, (sigma2-hat*j^2).^(-1)];
158
        end
159
       \% Times the lambda \hat{\,}2
160
        omega_d = lam^2 * omega_d;
161
       %stack the artificial observations at the bottom to get soc prior
163
        Xplus = [\underline{zeros}(M,1), \underline{repmat}(\underline{diag}(\underline{mu*mean}(y(1:p,:),1)), [1 p])];
164
       X= [X; Xplus]; % stack x at the bottom
165
        yplus = diag(mu*mean(y(1:p,:),1));
166
        ynew = [y((p+1:p+T+i-1),:);yplus];
167
       % MAP solution for coefficients
        B_{hat} = (X'*X+diag(omega_d.^(-1))) \setminus (X'*ynew+diag(omega_d.^(-1))*b_{hat}');\%
170
        a K*M matrix
       % Do projection based on MLE of coefficients
171
        yproj3 = y(1:p,:);
172
        for j = p+1:N
173
            yproj3(j,:) = [1, reshape(yproj3(j-1:-1:j-p,:)',1,K-1)]*B_hat;
175
        lgGDP3 = yproj3(:,1);
176
        qpriinf3 = diff(yproj3(:,2));
177
        fedfr3 = yproj3(:,3);
178
        qnomwainf3 = diff(yproj3(:,7)+yproj3(:,2));
179
        lglabsh3 = yproj3(:,7)+yproj3(:,6)-yproj3(:,1);
180
        lgcomra3 = yproj3(:,4)-yproj3(:,1);
183 \text{ xt3} = \text{xt} (1:\text{end});
legendinfo \{4\} = ['SOC prior (\mu = 1)'];
185 handle (4) = plot_all ([xt3, lgGDP3], [xt3 (2:end), qpriinf3], [xt3, fedfr3], [xt3 (2:
       end), qnomwainf3], [xt3, lglabsh3], [xt3, lgcomra3], '-m', 'SOC prior (\mu = 1)
        <sup>'</sup>);
186
187
   toc
188
189 tic
190 % Given lambda
191 \text{ lam} = 0.2;
192 \text{ mu} = 5;
193 % Estimate b
194 b_hat = [zeros(M,1), eye(M,M*p)];
   for i = 1:(N-(T+p+h)+1)
        if i ==1
196
            % design matrix
197
            X = zeros(T,K);\% a T*K matrix
            for j = 1:T
199
                 X(j,:) = [1, reshape(y((j+p-1:-1:j),:)',1,K-1)];% have to
200
       transpose because the reshape function operate in column
            end
201
202
            new\_row = [1, reshape(y((i+T+p-2:-1:i+T-1),:)',1,K-1)];
```

```
X = [X; new\_row]; \% a (T+i-1)*K matrix
204
       end
205
       % Estimate elements of Omega
206
       % The first observation is given (regarded as index 0) and the rest of
207
       observation up to the
       % end of current window (index 1 to T) are for prediction as stated in
208
       the problem
       % statement
209
       % Follow Hamilton 1994 to get the MLE for variance
       sum1 = sum(y(1:p+T+i-2,:),1);%sum_1^T y_(t-1)
211
       sum2 = sum(y(2:p+T+i-1,:),1); %sum_1^T y_(t)
212
       sum3 = sum(y(1:p+T+i-2,:).^2,1);%sum_1^T y_(t-1)^2
214
       sum4 = sum(y(2:p+T+i-1,:).^2,1); %sum_1^T y_(t)^2
       sum5 = sum(y(2:p+T+i-1,:).*y(1:p+T+i-2,:),1);%sum_1^T y_(t)y_(t-1)
215
       sigma2-hat = zeros(1,M);
       for m = 1:M
217
            c_phi_hat = [p+T+i-2,sum1(m);sum1(m),sum3(m)] \setminus [sum2(m);sum5(m)];\%
218
       c_{phi}hat = [c_{hat}, phi_{hat}]
            sigma2-hat(m) = 1.0/(p+T+i-2)*(sum4(m)+c-phi-hat(2)^2*sum3(m)+2*
       c_{phi}hat(1)*c_{phi}hat(2)*sum1(m)...
                             -2*c_phi_hat(1)*sum2(m)-2*c_phi_hat(2)*sum5(m)+
       c_phi_hat (1) ^2;
       end
221
       omega_d = [10^6];
222
223
       for j = 1:p
224
           omega_d = [omega_d, (sigma2_hat*j^2).^(-1)];
225
       % Times the lambda<sup>2</sup>
226
       omega_d = lam^2 * omega_d;
227
228
       %stack the artificial observations at the bottom to get soc prior
229
230
       Xplus = [zeros(M,1), repmat(diag(mu*mean(y(1:p,:),1)),[1 p])];
       X= [X; Xplus]; % stack x at the bottom
231
       yplus = diag(mu*mean(y(1:p,:),1));
232
       ynew = [y((p+1:p+T+i-1),:);yplus];
233
234
       % MAP solution for coefficients
235
236
       B_{hat} = (X'*X+diag(omega_d.^(-1))) \setminus (X'*ynew+diag(omega_d.^(-1))*b_{hat}');\%
       a K*M matrix
       % Do projection based on MLE of coefficients
237
       yproj4 = y(1:p,:);
238
       for j = p+1:N
239
           yproj4(j,:) = [1, reshape(yproj4(j-1:-1:j-p,:)', 1, K-1)] *B_hat;
240
241
       lgGDP4 = yproj4(:,1);
       qpriinf4 = diff(yproj4(:,2));
243
       fedfr4 = yproj4(:,3);
244
       qnomwainf4 = diff(yproj4(:,7)+yproj4(:,2));
245
       lglabsh4 = yproj4(:,7)+yproj4(:,6)-yproj4(:,1);
246
       lgcomra4 = yproj4(:,4)-yproj4(:,1);
```

```
248 end
249 \text{ xt4} = \text{xt} (1:\text{end});
legendinfo\{5\} = ['SOC prior (\mu = 5)'];
251 \text{ handle}(5) = \text{plot\_all}([xt4, lgGDP4], [xt4(2:end), qpriinf4], [xt4, fedfr4], [xt4(2:end), qpriinf4]
       end), qnomwainf4], [xt4, lglabsh4], [xt4, lgcomra4], '-.c', 'SOC prior (\mu = 5)
252
   toc
253
254
var1 = [var(lgGDP), var(lgGDP1), var(lgGDP2), var(lgGDP3), var(lgGDP4)];
256 var2=[var(qpriinf), var(qpriinf1), var(qpriinf2), var(qpriinf3), var(qpriinf4)];
257 var3=[var(fedfr), var(fedfr1), var(fedfr2), var(fedfr3), var(fedfr4)];
258 var4=[var(qnomwainf), var(qnomwainf1), var(qnomwainf2), var(qnomwainf3), var(
       qnomwainf4)];
259 var5=[var(lglabsh), var(lglabsh1), var(lglabsh2), var(lglabsh3), var(lglabsh4)];
260 var6=[var(lgcomra), var(lgcomra1), var(lgcomra2), var(lgcomra3), var(lgcomra4)];
var_all = [var1; var2; var3; var4; var5; var6];
legend(handle, legendinfo, 'Location', 'southeast');
```

Listing 2: Matlab code for problem 2.

```
1 function val = logmlikelih (lam, X, Y, d_psi, d_phi, b_hat, M, T, d)
2 % Calculate the log marginal likelihood
з % Input:
4 % lam: lambda value which we are optimizing in terms of
5 % X: matrix X in time series (lag);
6 % Y: matrix Y which are to be forecasted;
7 % d-psi: diagnoal elements of Psi matrix (which is diagonal);
8 % d.ome: diagonal elements of Omega matrix (which is diagonal);
9 % M: the dimension of y
10 % T: time horizon to be forecasted
11 % d: some constant specified in prior
12 % Output:
13 % val: the log marginal likelihood up to adding a constant
tempm1 = X*diag(d_phi.^0.5);
eig1 = eig(tempm1'*tempm1);
16 B_hat = (lam^2*(X'*X)+diag(d_phi.^(-1)))(lam^2*X'*Y+diag(d_phi.^(-1))*
      b_hat);
eps_hat = Y - X*B_hat;
18 \text{ tempm2} = B_hat-b_hat;
eig2 = eig(diag(d_psi.^(-0.5))*(lam^2*(eps_hat'*eps_hat) + tempm2'*diag(d_phi))
      .^{(-1)} *tempm2 *diag(d_psi.^{(-0.5)});
val = (-M/2)*sum(log(1+lam^2*eig1))+(-(T+d)/2)*sum(log(lam^2+eig2))+M*(T+d)*
      log(lam);
21 end
```

Listing 3: Matlab code for evaluate the log marginal likelihood.

```
2 % Use grid search to find the optimal solution for lam with several starting
      points
з % Input:
4 % objFunc: objective function which return kernel of marginal likelihood
5 % (or log of it)
      % Calculate the marginal likelihood
      % Input:
8
      % lam: lambda value which we are optimizing in terms of
9
      % X: matrix X in time series (lag);
      % Y: matrix Y which are to be forecasted;
      \% d_psi: diagnoal elements of Psi matrix (which is diagonal);
12
13
      % d_ome: diagonal elements of Omega matrix (which is diagonal);
      % M: the dimension of v
14
      % T: time horizon to be forecasted
      % d: some constant specified in prior
16
      % Output:
17
      % val: the marginal likelihood up to a constant factor
18
19 %
20 % lam_bd: lambda value upper and lower bound for initial value exploring
21 %
      % [lam_lower_bound, lam_upper_bound]
22
23 %
24 % N_try: how many initial tries to do inside the lam_bd
25 % X: matrix X in time series (lag);
26 % Y: matrix Y which are to be forecasted;
27 % d_psi: diagnoal elements of Psi matrix (which is diagonal);
28 % d_ome: diagonal elements of Omega matrix (which is diagonal);
29 % M: the dimension of y
_{30} % T: time horizon to be forecasted
31 % d: some constant specified in prior
32 % options_optim: options when calling the fminunc function
33 % Output:
34 % opt_lam: optimal lambda that maximizing the marginal likelihood
36 % code
37 %options_optim = optimoptions(@fminunc, 'Display', 'iter-detailed', 'Algorithm
      ', 'trust-region', 'SpecifyObjectiveGradient', true);
39 %fun = @(lam)objFunc(lam, X, Y, d_psi, d_phi, b_hat, M, T, d);
40
41
lam_{try} = lam_{bd}(1) : (lam_{bd}(2) - lam_{bd}(1)) / N_{try} : lam_{bd}(2);
rec_lam = zeros(length(lam_try), 2);
  for i = 1:length(lam_try)
      %rec_lam(i,:)=fminunc(fun,lam_init(i),options_optim);
      rec_lam(i,:) = [lam_try(i),objFunc(lam_try(i),X,Y,d_psi,d_phi,b_hat,M,T,d
46
      )];
48 [ , opt_ind ] = \max(\text{rec_lam}(:,2));
```

```
lam_opt = rec_lam(opt_ind,1);
end
```

Listing 4: Matlab code for find the optimal λ using grid search.

```
1 function h=plot_all(dat1, dat2, dat3, dat4, dat5, dat6, pattern, text)
       subplot(3,2,1);
2
       hold on;
3
4
      box on;
      h=plot(dat1(:,1),dat1(:,2),pattern);
       axis([1959,2008,-inf,inf])
6
      % legend ('Observed Data', 'DC Prediction')
      %legend(h,text)
       title('log-real GDP')
9
10
       subplot(3,2,2);
       hold on;
12
      box on;
13
       plot(dat2(:,1),dat2(:,2),pattern);
14
       axis ([1959,2008, -inf, inf])
15
      % legend('Observed Data', 'DC Prediction')
16
       title('quarterly price inflation')
17
18
       subplot(3,2,3);
19
       hold on;
20
      box on;
21
       plot(dat3(:,1),dat3(:,2),pattern);%,xt,rt2.predgdp,'-.m',xt,rt3.predgdp
22
      ,'--c', xt, rt4.predgdp, ':r'
      axis([1959,2008,-inf,inf])
23
      \% legend('Observed Data','DC Prediction')
24
       title ('the federal funds rate')
25
26
       subplot(3,2,4);
27
       hold on;
28
29
      box on;
      plot (dat4(:,1), dat4(:,2), pattern); %, xt, rt2.predgdp, '-.m', xt, rt3.predgdp
30
      ,'--c', xt, rt4. predgdp, ':r')
      axis([1959,2008,-inf,inf])
31
      % legend('Observed Data', 'DC Prediction')
32
       title ('quarterly nominal wage inflation')
33
34
35
       subplot(3,2,5);
       hold on;
37
       box on;
       plot (dat5 (:,1), dat5 (:,2), pattern); %, xt, rt2. predgdp, '-.m', xt, rt3. predgdp
38
      ,'--c', xt, rt4.predgdp, ':r')
      axis([1959,2008,-inf,inf])
39
      \% legend ( 'Observed Data', 'DC Prediction ')
40
41
       title ('log-labor share')
42
      subplot (3,2,6);
43
```

```
hold on;
box on;
plot(dat6(:,1),dat6(:,2),pattern);%,xt,rt2.predgdp,'-.m',xt,rt3.predgdp
,'--c',xt,rt4.predgdp,':r')
axis([1959,2008,-inf,inf])
% legend('Observed Data','DC Prediction')
title('log-consumption ratio')
```

Listing 5: Matlab code for plot data.

References

- [1] D. Giannone, M. Lenza, and G. E. Primiceri, Priors for the long run, (2016).
- [2] J. D. Hamilton, *Time series analysis*, volume 2, Princeton university press Princeton, 1994.