

SiwiR 2 - Assignment 3

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- 1 Recapitulation of LBM
 - Discrete Lattice Boltzmann equation
 - Moments of the probability functions
 - Boundary conditions
- 2 Incompressible LBM
- 3 Assignment sheet 4
- 4 The VTK/Paraview visualization
- 5 The Grid class
 - Possible data layouts
 - C++ data layout implementation
- 6 A FileReader Implementation
- 7 Verbose Mode
- 8 LBM Input Parameters
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Recapitulation of LBM

Discrete Lattice Boltzmann equation

$$f_{\alpha}(x + \vec{c}_{\alpha}\Delta t, t + \Delta t) - f_{\alpha}(x, t) = -\omega(f_{\alpha} - f_{\alpha}^{eq})$$

collide step

$$\tilde{f}_{\alpha}(x, t + \Delta t) = f_{\alpha}(x, t) - \omega(f_{\alpha} - f_{\alpha}^{eq})$$

stream step

$$\tilde{f}_{\alpha}(x + \vec{c}_{\alpha}\Delta t, t + \Delta t) = \tilde{f}_{\alpha}(x, t + \Delta t)$$

Moments of the probability functions

- 0 density: $\rho = \sum_{\alpha} f_{\alpha}$
- 1 momentum density: $\rho \vec{u} = \sum_{\alpha} f_{\alpha} \vec{c}_{\alpha}$

no-slip: bounce-back

$$f_{\bar{\alpha}}(x, t) = f_{\alpha}(x, t), \quad \vec{c}_{\alpha} = -\vec{c}_{\bar{\alpha}}$$

moving no-slip: modified bounce-back

$$f_{\bar{\alpha}}(x, t) = f_{\alpha}(x, t) - 2t_{\alpha}\rho\frac{3}{c^2}\vec{c}_{\alpha} \cdot \vec{u}_w, \quad t_{\alpha} : \text{weighting factor}$$

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- Standard formulation of the equilibrium distribution:

$$f_{\alpha}^{eq} = t_{\alpha} \rho \left(1 + \frac{3}{c^2} \vec{c}_{\alpha} \cdot \vec{u} + \frac{9}{2c^4} (\vec{c}_{\alpha} \cdot \vec{u})^2 - \frac{3\vec{u}^2}{2c^2} \right)$$

- Special formulation for incompressible fluids:

$$f_{\alpha}^{eq} = t_{\alpha} \left(\rho + \frac{3}{c^2} \vec{c}_{\alpha} \cdot \vec{u} + \frac{9}{2c^4} (\vec{c}_{\alpha} \cdot \vec{u})^2 - \frac{3\vec{u}^2}{2c^2} \right)$$

For incompressible fluids it is advisable to adapt the moving wall boundary conditions:

- Compressible fluids:

$$f_{\bar{\alpha}}(x, t) = f_{\alpha}(x, t) - 2t_{\alpha}\rho\frac{3}{c^2}\vec{c}_{\alpha} \cdot \vec{u}_w$$

- Incompressible fluids ($\rho = 1$):

$$f_{\bar{\alpha}}(x, t) = f_{\alpha}(x, t) - 2t_{\alpha}\frac{3}{c^2}\vec{c}_{\alpha} \cdot \vec{u}_w$$

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The VTK/Paraview Visualization

VTK File Formats

<http://www.vtk.org/VTK/img/file-formats.pdf>

VTK File Format

```
# vtk DataFile Version 4.0
SiwiRVisFile
ASCII
DATASET STRUCTURED_POINTS
DIMENSIONS 50 50 1
ORIGIN 0 0 0
SPACING 1 1 1
POINT_DATA 2500
```

...

VTK File Format (cont'd)

```
SCALARS flags double 1
```

```
LOOKUP_TABLE default
```

```
1
```

```
...
```

```
SCALARS density double 1
```

```
LOOKUP_TABLE default
```

```
1
```

```
...
```

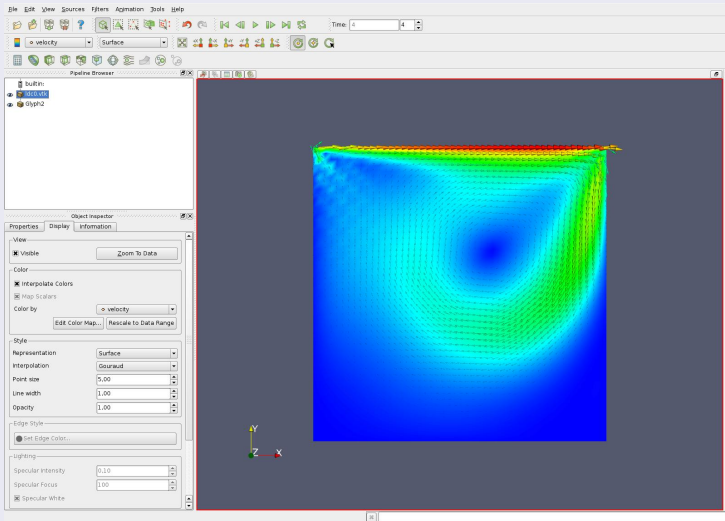
```
VECTORS velocity double
```

```
-7.00552e-07 1.90304e-08 0
```

```
...
```

The VTK/Paraview Visualization

Paraview

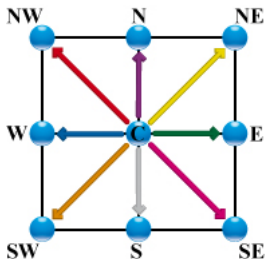


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Data layouts

- D2Q9-model:



- Collision-optimized data layout:



- Propagation-optimized data layout:



Abstraction from the actual data layout via a wrapper class

```
namespace lbm {  
  
    // A convenient type definition  
    typedef unsigned int  uint;  
  
    ...  
  
} // namespace lbm
```

The Grid class

```
namespace lbm {  
  
    template< typename Type, uint Cellsize >  
    class Grid  
    {  
    public:  
        inline Grid();  
        inline Grid( uint xsize, uint ysize );  
        inline ~Grid();  
  
        ...  
    };  
  
} // namespace lbm
```

```
public:  
  
...  
  
inline Type& operator()( uint x, uint y, uint f );  
inline Type  operator()( uint x, uint y, uint f ) const;  
  
...
```

The Grid class

```
...

private:

    uint xsize_; // Number of nodes in x-dimension
    uint ysize_; // Number of nodes in y-dimension

    Type* data_; // Linearized, 1-dimensional representation
                 // of the 2D data grid
};
```

The Grid class

```
// Implementation of the default constructor
template< typename Type, uint Cellsize >
Grid<Type,Cellsize>::Grid()
    : xsize_(0)
    , ysize_(0)
    , data_(0)
{}

```

```
// Implementation of the initialization constructor
template< typename Type, uint Cellsize >
Grid<Type,Cellsize>::Grid( uint xsize, uint ysize )
    : xsize_(xsize)
    , ysize_(ysize)
    , data_( new Type[Cellsize*xsize*ysize] )
{}

```

The Grid class

```
// Implementation of the function call operator
template< typename Type, uint Cellsize >
inline Type&
Grid<Type,Cellsize>::operator()( uint x, uint y, uint f )
{
    assert( x < xsize_ && y < ysize_ && f < Cellsize );
    return data_[y*xsize_*Cellsize+x*Cellsize+f];
}

// Implementation of the const function call operator

// ... Same as non-const version
```

The Grid class

```
// Partial template specialization for Cellsize = 1
template< typename Type >
class Grid<Type,1>
{
public:
    ...
    inline Type& operator()( uint x, uint y );
    inline Type  operator()( uint x, uint y ) const;
    ...
};
```

The Grid class

```
// Partial template specialization for Cellsize = 0  
// No class definition => compile time error  
template< typename Type >  
class Grid<Type,0>;
```


The Grid class

```
// Convenient type definitions
namespace lbm {

    ...

    typedef Grid<double,9>   PDF_Field;
    typedef Grid<double,2>   V_Field;
    typedef Grid<double,1>   D_Field;
    typedef Grid<uint,1>     Flags;

    ...

} // namespace lbm
```

Swapping Two Grids

Due to the data dependencies in the stream step (propagation step), it is favorable to use two grids: source (`src`) and destination (`dst`). After every time step, these two grids have to be swapped.

Proper implementation of the swap functionality

- Add a swap **function member** to the Grid class
- Add an **overload** for the standard swap function for the Grid class that uses the Grid function member

The swap member function

```
namespace lbm {

    template< typename Type, uint Cellsize >
    class Grid {
    public:
        // ...
        void swap( Grid& grid ) /* throw() */ {
            std::swap( y_, grid.y_ );
            std::swap( x_, grid.x_ );
            std::swap( v_, grid.v_ );
        }
        // ...
    };

} // namespace lbm
```

The Grid class

The global swap function

```
template< typename Type, size_t N >
inline void swap( Grid<Type,N>& a,
                 Grid<Type,N>& b ) /* throw() */
{
    a.swap( b );
}
```

Use of the swap function

```
Grid<double,9> a, b;
// ... proper initialization
swap( a, b );
```



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A FileReader Implementation

An Example Parameter File

```
size_x 70  
size_y 80  
timesteps 100  
omega 1.9  
vtk_file vtk/ldc.vtk  
vtk_step 50
```

The Task...

... is to write a `FileReader` class that parses this parameter file, stores the parameters, and converts the parameters to the desired data type.



A FileReader Implementation

Example

```
// Parsing the parameter file
FileReader reader;
reader.readParameters( argv[1] );

// Converting the 'timesteps' parameter to a size_t value
const size_t timesteps(
    reader.getParameter<size_t>( "timesteps" )
);

// Checking the value
if( timesteps == 0 || timesteps > 1000000 ) {
    std::cerr << " Invalid 'timesteps' parameter!\n";
    return EXIT_FAILURE;
}
```

Task

Think about ...

- ... a suitable implementation for FileReader
- ... a fitting internal data structure
- ... the differences between individual data types (int, unsigned int, ...)
- ... a working implementation for a `getParameter()` function:

```
template< typename Type >  
Type FileReader::getParameter(const std::string& key) c
```


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Add a verbose mode to your programm such that ...

- ... it is possible to switch the verbose mode on and off very easily
- ... you make debugging easier for you
- ... the compiler can optimize away all outputs in case you switch the verbose mode off
- ... no preprocessor functionality is used

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Parameterization for LBM

Normalization of basic physical values (\cdot_p) to the lattice parameters

$$\Delta t = \frac{\Delta t_p}{\Delta t_p} = 1$$

$$\Delta x = \frac{\Delta x_p}{\Delta x_p} = 1$$

$$\rho = \frac{\rho_p}{\rho_p} = 1$$

Normalization of velocity and kinematic viscosity

$$u \left[\frac{m}{s} \right] :$$

$$u = \frac{\Delta t_p}{\Delta x_p} u_p$$

$$\nu \left[\frac{m^2}{s} \right] :$$

$$\nu = \frac{\Delta t_p}{\Delta x_p^2} \nu_p$$

Physical parameters from lattice parameters by multiplication with inverse factors

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Debugging of the lid-driven cavity

- The total mass in the system should not change, i.e. the total sum of all distribution functions should not change
- During collision, the macroscopic density and velocity of a node should not change
- The macroscopic density of a node should be close to 1 (i.e. in the range $[0.9..1.1]$)
- The absolute value of the norm of the macroscopic velocity should not be larger than 0.1 (i.e. in the range $[0..0.1]$)
- The individual particle distribution functions should be in the range $[0..0.5]$

Debugging of the lid-driven cavity

- Start with the most simple test case possible: a single lattice node surrounded by no-slip boundary nodes
- Perform obstacle / leak check: Set f_i on nodes that are never accessed to 999
- Explicitly set the macroscopic velocity via equilibrium distribution functions
 - First test case: $\mathbf{v} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow$ No changes may occur
 - Second test case: $\mathbf{v} = \begin{pmatrix} 0.1 \\ 0 \end{pmatrix} \Rightarrow$ Relaxation towards $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$

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- implement the Lattice Boltzmann method
- use a suitable data structure
- implement a parameter reader
- visualize with paraview
- debug using a strategy