# **CHAPTER 1**

# THE AVR MICROCONTROLLER: HISTORY AND FEATURES

#### **OBJECTIVES**

Upon completion of this chapter, you will be able to:

- >> Compare and contrast microprocessors and microcontrollers
- >> Describe the advantages of microcontrollers for some applications
- >> Explain the concept of embedded systems
- >> Discuss criteria for considering a microcontroller
- >> Explain the variations of speed, packaging, memory, and cost per unit and how these affect choosing a microcontroller
- >> Compare and contrast the various members of the AVR family
- >> Compare the AVR with microcontrollers offered by other manufacturers

This chapter begins with a discussion of the role and importance of microcontrollers in everyday life. In Section 1.1 we also discuss criteria to consider in choosing a microcontroller, as well as the use of microcontrollers in the embedded market. Section 1.2 covers various members of the AVR family and their features. In addition, we provide a brief discussion of alternatives to the AVR chip such as the 8051, PIC, and 68HC11 microcontrollers.

# SECTION 1.1: MICROCONTROLLERS AND EMBEDDED PROCESSORS

In this section we discuss the need for microcontrollers and contrast them with general-purpose microprocessors such as the Pentium and other x86 microprocessors. We also look at the role of microcontrollers in the embedded market. In addition, we provide some criteria on how to choose a microcontroller.

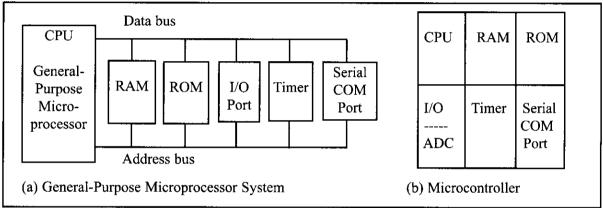


Figure 1-1. Microprocessor System Contrasted with Microcontroller System

# Microcontroller versus general-purpose microprocessor

What is the difference between a microprocessor and a microcontroller? By microprocessor is meant the general-purpose microprocessors such as Intel's x86 family (8086, 80286, 80386, 80486, and the Pentium) or Motorola's PowerPC family. These microprocessors contain no RAM, no ROM, and no I/O ports on the chip itself. For this reason, they are commonly referred to as *general-purpose microprocessors*. See Figure 1-1.

A system designer using a general-purpose microprocessor such as the Pentium or the PowerPC must add RAM, ROM, I/O ports, and timers externally to make them functional. Although the addition of external RAM, ROM, and I/O ports makes these systems bulkier and much more expensive, they have the advantage of versatility, enabling the designer to decide on the amount of RAM, ROM, and I/O ports needed to fit the task at hand. This is not the case with microcontrollers. A microcontroller has a CPU (a microprocessor) in addition to a fixed amount of RAM, ROM, I/O ports, and a timer all on a single chip. In other words, the processor, RAM, ROM, I/O ports, and timer are all embedded together on one chip; therefore, the designer cannot add any external memory, I/O, or timer to it. The fixed amount of on-chip ROM, RAM, and number of I/O ports in microcontrollers makes them ideal for many applications in which cost and space are criti-

#### Home

Appliances Intercom Telephones Security systems Garage door openers Answering machines Fax machines Home computers **TVs** Cable TV tuner **VCR** Camcorder Remote controls Video games Cellular phones Musical instruments Sewing machines Lighting control **Paging** Camera Pinball machines Toys Exercise equipment

Telephones
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Security systems
Fax machine
Microwave
Copier
Laser printer
Color printer

# Paging **Auto**

Office

Trip computer
Engine control
Air bag
ABS
Instrumentation
Security system
Transmission control
Entertainment
Climate control
Cellular phone
Keyless entry

Table 1-1: Some Embedded Products Using Microcontrollers cal. In many applications, for example, a TV remote control, there is no need for the computing power of a 486 or even an 8086 microprocessor. In many applications, the space used, the power consumed, and the price per unit are much more critical considerations than the computing power. These applications most often require some I/O operations to read signals and turn on and off certain bits. For this reason some call these processors IBP, "itty-bitty processors." (See "Good Things in Small Packages Are Generating Big Product Opportunities" by Rick Grehan, BYTE magazine, September 1994 (http://www.byte.com) for an excellent discussion of microcontrollers.)

It is interesting to note that many microcontroller manufacturers have gone as far as integrating an ADC (analog-to-digital converter) and other peripherals into the microcontroller.

# Microcontrollers for embedded systems

In the literature discussing microprocessors, we often see the term *embedded system*. Microprocessors and microcontrollers are widely used in embedded system products. An embedded system is controlled by its own internal microprocessor (or microcontroller) as opposed to an external controller. Typically, in an embedded system, the microcontroller's ROM is burned with a purpose for specific functions needed for the system. A printer is an example of an embedded system because the processor inside it performs one task only; namely, getting the data and printing it. Contrast this with a Pentium-based PC (or any x86 PC), which can be used for any number of applications such as word processor, print server, bank teller terminal, video game player, network server, or Internet terminal, A PC can also load and run software for a variety of applications. Of course, the reason a PC can perform myriad tasks is that it has RAM memory and an operating system that loads the application software into RAM and lets the CPU run it. In an embedded system, typically only one application software is burned into ROM. An x86 PC contains or is connected to various embedded products such as the keyboard, printer, modem, disk controller, sound card, CD-ROM driver, mouse, and so on. Each one of these peripherals has a microcontroller inside it that performs only one task. For example, inside every mouse a microcontroller performs the task of finding the mouse's position and sending it to the PC. Table 1-1 lists some embedded products.

# x86 PC embedded applications

Although microcontrollers are the preferred choice for many embedded systems, sometimes a microcontroller is inadequate for the task. For this reason, in recent years many manufacturers of general-purpose microprocessors such as Intel, Freescale Semiconductor (formerly Motorola), and AMD (Advanced Micro Devices, Inc.) have targeted their microprocessors for the high end of the embedded market. Intel and AMD push their x86 processors for both the embedded and desktop PC markets. In the early 1990s, Apple computer began using the PowerPC microprocessors (604, 603, 620, etc.) in place of the 680x0 for the Macintosh. In 2007 Apple switched to the x86 CPU for use in the Mac computers. The PowerPC microprocessor is a joint venture between IBM and Freescale, and is targeted for the high end of the embedded market. It must be noted that when a company targets a general-purpose microprocessor for the embedded market it optimizes the processor used for embedded systems. For this reason these processors are often called high-end embedded processors. Another chip widely used in the high end of the embedded system design is the ARM (Advanced RISC Machine) microprocessor. Very often the terms embedded processor and microcontroller are used interchangeably.

One of the most critical needs of an embedded system is to decrease power consumption and space. This can be achieved by integrating more functions into the CPU chip. All the embedded processors based on the x86 and PowerPC 6xx have low power consumption in addition to some forms of I/O, COM port, and ROM, all on a single chip. In high-performance embedded processors, the trend is to integrate more and more functions on the CPU chip and let the designer decide which features to use. This trend is invading PC system design as well. Normally, in designing the PC motherboard we need a CPU plus a chipset containing I/O, a cache controller, a Flash ROM containing BIOS, and finally a secondary cache memory. New designs are emerging in industry. For example, many companies have a chip that contains the entire CPU and all the supporting logic and memory, except for DRAM. In other words, we have the entire computer on a single chip.

Currently, because of Linux and Windows standardization, many embedded systems use x86 PCs. In many cases, using x86 PCs for the high-end embedded applications not only saves money but also shortens development time because a vast library of software already exists for the Linux and Windows platforms. The fact that Windows and Linux are widely used and well-understood platforms means that developing a Windows-based or Linux-based embedded product reduces the cost and shortens the development time considerably.

# Choosing a microcontroller

There are five major 8-bit microcontrollers. They are: Freescale Semiconductor's (formerly Motorola) 68HC08/68HC11, Intel's 8051, Atmel's AVR, Zilog's Z8, and PIC from Microchip Technology. Each of the above microcontrollers has a unique instruction set and register set; therefore, they are not compatible with each other. Programs written for one will not run on the others. There are also 16-bit and 32-bit microcontrollers made by various chip makers. With all these different microcontrollers, what criteria do designers consider in choosing one? Three criteria in choosing microcontrollers are as follows: (1) meeting the computing needs of the task at hand efficiently and cost effectively; (2) availability of software and hardware development tools such as compilers, assemblers, debuggers, and emulators; and (3) wide availability and reliable sources of the microcontroller. Next, we elaborate on each of the above criteria.

# Criteria for choosing a microcontroller

- 1. The first and foremost criterion in choosing a microcontroller is that it must meet the task at hand efficiently and cost effectively. In analyzing the needs of a microcontroller-based project, we must first see whether an 8-bit, 16-bit, or 32-bit microcontroller can best handle the computing needs of the task most effectively. Among other considerations in this category are:
  - (a) Speed. What is the highest speed that the microcontroller supports?
  - (b) Packaging. Does it come in a DIP (dual inline package) or a QFP (quad flat package), or some other packaging format? This is important in terms of space, assembling, and prototyping the end product.
  - (c) Power consumption. This is especially critical for battery-powered products.
  - (d) The amount of RAM and ROM on the chip.
  - (e) The number of I/O pins and the timer on the chip.
  - (f) Ease of upgrade to higher-performance or lower-power-consumption versions.
  - (g) Cost per unit. This is important in terms of the final cost of the product in which a microcontroller is used. For example, some microcontrollers cost 50 cents per unit when purchased 100,000 units at a time.
- 2. The second criterion in choosing a microcontroller is how easy it is to develop products around it. Key considerations include the availability of an assembler, a debugger, a code-efficient C language compiler, an emulator, technical support, and both in-house and outside expertise. In many cases, third-party vendor (i.e., a supplier other than the chip manufacturer) support for the chip is as good as, if not better than, support from the chip manufacturer.
- 3. The third criterion in choosing a microcontroller is its ready availability in needed quantities both now and in the future. For some designers this is even more important than the first two criteria. Currently, of the leading 8-bit microcontrollers, the 8051 family has the largest number of diversified (multiple source) suppliers. (Supplier means a producer besides the originator of the microcontroller.) In the case of the 8051, which was originated by Intel, many companies also currently produce the 8051.

Notice that Freescale Semiconductor (Motorola), Atmel, Zilog, and Microchip Technology have all dedicated massive resources to ensure wide and timely availability of their products because their products are stable, mature, and single sourced. In recent years, companies have begun to sell *Field-Programmable Gate Array* (FPGA) and *Application-Specific Integrated Circuit* (ASIC) libraries for the different microcontrollers.

#### Mechatronics and microcontrollers

The microcontroller is playing a major role in an emerging field called *mechatronics*. Here is an excellent summary of what the field of mechatronics is all about, taken from the website of Newcastle University (http://mechatronics2004.newcastle.edu.au/mech2004), which holds a major conference every year on this subject:

"Many technical processes and products in the area of mechanical and

electrical engineering show an increasing integration of mechanics with electronics and information processing. This integration is between the components (hardware) and the information-driven functions (software), resulting in integrated systems called mechatronic systems.

The development of mechatronic systems involves finding an optimal balance between the basic mechanical structure, sensor and actuator implementation, automatic digital information processing and overall control, and this synergy results in innovative solutions. The practice of mechatronics requires multidisciplinary expertise across a range of disciplines, such as: mechanical engineering, electronics, information technology, and decision making theories."

#### **Review Questions**

- 1. True or false. Microcontrollers are normally less expensive than microprocessors.
- 2. When comparing a system board based on a microcontroller and a general-purpose microprocessor, which one is cheaper?
- 3. A microcontroller normally has which of the following devices on-chip?
  - (a) RAM
- (b) ROM
- (c) I/O
- (d) all of the above
- 4. A general-purpose microprocessor normally needs which of the following devices to be attached to it?
  - (a) RAM
- (b) ROM
- (c) I/O
- (d) all of the above
- 5. An embedded system is also called a dedicated system. Why?
- 6. What does the term embedded system mean?
- 7. Why does having multiple sources of a given product matter?

## **SECTION 1.2: OVERVIEW OF THE AVR FAMILY**

In this section, we first look at the AVR microcontrollers and their features and then examine the different families of AVR in more detail.

# A brief history of the AVR microcontroller

The basic architecture of AVR was designed by two students of Norwegian Institute of Technology (NTH), Alf-Egil Bogen and Vegard Wollan, and then was bought and developed by Atmel in 1996.

You may ask what AVR stands for; AVR can have different meanings for different people! Atmel says that it is nothing more than a product name, but it might stand for Advanced Virtual RISC, or Alf and Vegard RISC (the names of the AVR designers).

There are many kinds of AVR microcontroller with different properties. Except for AVR32, which is a 32-bit microcontroller, AVRs are all 8-bit microprocessors, meaning that the CPU can work on only 8 bits of data at a time. Data larger than 8 bits has to be broken into 8-bit pieces to be processed by the CPU. One of the problems with the AVR microcontrollers is that they are not all 100% compatible in terms of software when going from one family to another family. To run programs written for the ATtiny25 on a ATmega64, we must recompile the program and possibly change some register locations before loading it into the ATmega64. AVRs are generally classified into four broad groups: Mega, Tiny,

Special purpose, and Classic. In this book we cover the Mega family because these microcontrollers are widely used. Also, we will focus on ATmega32 since it is powerful, widely available, and comes in DIP packages, which makes it ideal for educational purposes. For those who have mastered the Mega family, understanding the other families is very easy and straightforward. The following is a brief description of the AVR microcontroller.

#### **AVR** features

The AVR is an 8-bit RISC single-chip microcontroller with Harvard architecture that comes with some standard features such as on-chip program (code) ROM, data RAM, data EEPROM, timers and I/O ports. See Figure 1-2. Most AVRs have some additional features like ADC, PWM, and different kinds of serial interface such as USART, SPI, I2C (TWI), CAN, USB, and so on. See Figures 1-3 and 1-4. Due to the importance of these peripherals, we have dedicated an entire chapter to many of them. The details of the RAM/ROM memory and I/O features of the Mega are given in the next few chapters.

#### AVR microcontroller program ROM

In microcontrollers, the ROM is used to store programs and for that reason it is called *program* or *code ROM*. Although the AVR has 8M (megabytes) of program (code) ROM space, not all family members come with that much ROM installed. The program ROM size can vary from 1K to 256K at the time of this writing, depending on the family member. The AVR was one of the first microcontrollers to use on-chip Flash memory for program storage. The Flash memory is

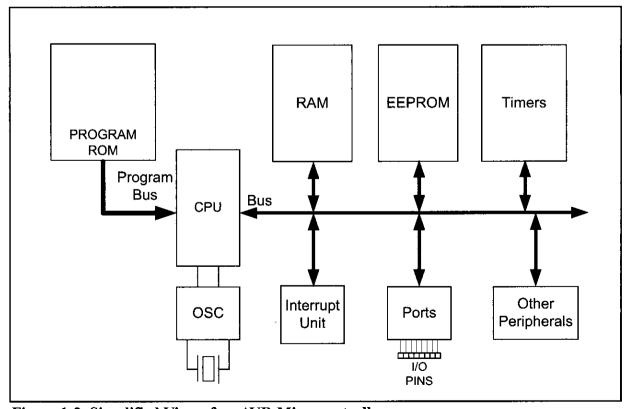


Figure 1-2. Simplified View of an AVR Microcontroller

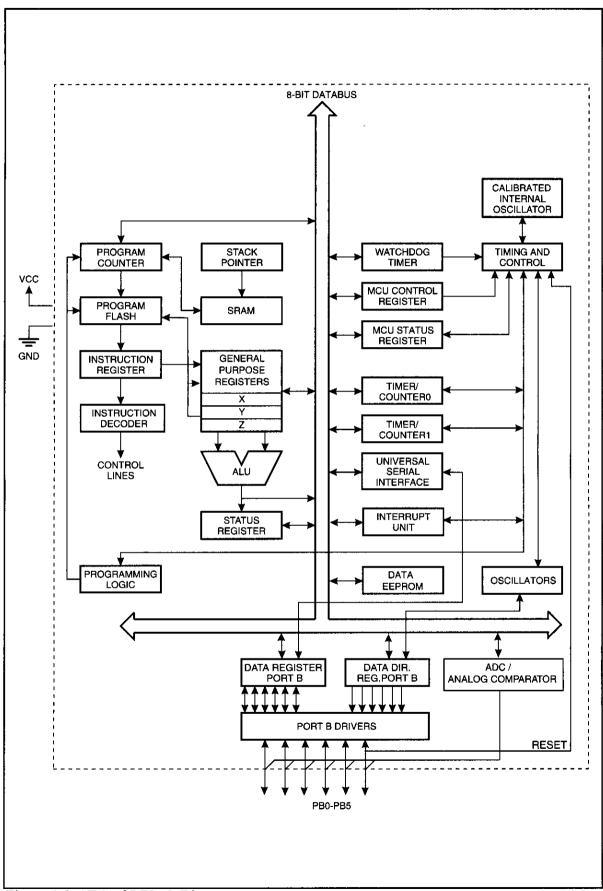


Figure 1-3. ATtiny25 Block Diagram

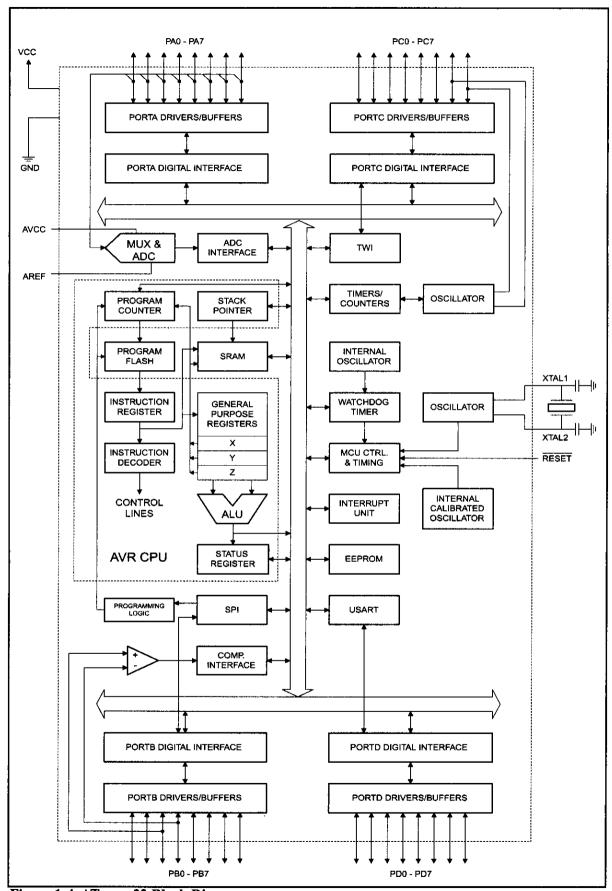


Figure 1-4. ATmega32 Block Diagram

ideal for fast development because Flash memory can be erased in seconds compared to the 20 minutes or more needed for the UV-EPROM. A discussion of the various types of ROM is given in Chapter 0, if you need to refresh your memory on these important memory technologies.

# AVR microcontroller data RAM and EEPROM

While ROM is used to store program (code), the RAM space is for data storage. The AVR has a maximum of 64K bytes of data RAM space. Not all of the family members come with that much RAM. As we will see in the next chapter, the data RAM space has three components: general-purpose registers, I/O memory, and internal SRAM. There are 32 general-purpose registers in all of the AVRs, but the SRAM's size and the I/O memory's size varies from chip to chip. On the Atmel website, whenever the size of RAM is mentioned the internal SRAM size is meant. The internal SRAM space is used for a read/write scratch pad, as we will see in Chapter 2. In AVR, we also have a small amount of EEPROM to store critical data that does not need to be changed very often. You will see more about EEPROM in Chapter 6.

# AVR microcontroller I/O pins

The AVR can have from 3 to 86 pins for I/O. The number of I/O pins depends on the number of pins in the package itself. The number of pins for the AVR package goes from 8 to 100 at this time. In the case of the 8-pin AT90S2323, we have 3 pins for I/O, while in the case of the 100-pin ATmega1280, we can use up to 86 pins for I/O. We will study I/O pins and programming in Chapter 4.

## AVR microcontroller peripherals

Most of the AVRs come with ADC (analog-to-digital converter), timers, and USART (Universal Synchronous Asynchronous Receiver Transmitter) as standard peripherals. As we will see in Chapter 13, the ADC is 10-bit and the number of ADC channels in AVR chips varies and can be up to 16, depending on the number of pins in the package. The AVR can have up to 6 timers besides the watchdog timer. We will examine timers in Chapter 9. The USART peripheral allows us to connect the AVR-based system to serial ports such as the COM port of the x86 IBM PC, as we will see in Chapter 11. Most of the AVR family members come with the I<sup>2</sup>C and SPI buses and some of them have USB or CAN bus as well.

Table 1-2: So	ome Meml	bers of the	Classic Fam	ily			
Part Num.	Code ROM	Data RAM	Data EEPROM	I/O pins	ADC	Tin	ners Pin numbers & Package
AT90S2313	2K	128	128	15	0	2	SOIC20, PDIP20
AT90S2323	2K	128	128	3	0	1	SOIC8, PDIP8
AT90S4433	4K	128	256	20	6	2	TQFP32, PDIP28

#### Notes:

- 1. All ROM, RAM, and EEPROM memories are in bytes.
- Data RAM (general-purpose RAM) is the amount of RAM available for data manipulation (scratch pad) in addition to the register space.

# **AVR family overview**

AVR can be classified into four groups: Classic, Mega, Tiny, and special purpose.

#### Classic AVR (AT90Sxxxx)

This is the original AVR chip, which has been replaced by newer AVR chips. Table 1-2 shows some members of the Classic AVR that are not recommended for new designs.

#### Mega AVR (ATmegaxxxx)

These are powerful microcontrollers with more than 120 instructions and lots of different peripheral capabilities, which can be used in different designs. See Table 1-3. Some of their characteristics are as follows:

- Program memory: 4K to 256K bytes
- Package: 28 to 100 pins
- Extensive peripheral set
- Extended instruction set: They have rich instruction sets.

Table 1-3: So	me Meml	ers of the	ATmega Fa	amily			
Part Num.	Code ROM	Data RAM	Data EEPROM	I/O pins	ADC	Timers	s Pin numbers & Package
ATmega8	8K	1K	0.5K	23	8	3	TQFP32, PDIP28
ATmega16	16K	1K	0.5K	32	8	3	TQFP44, PDIP40
ATmega32	32K	2K	1K	32	8	3	TQFP44, PDIP40
ATmega64	64K	4K	2K	54	8	4	TQFP64, MLF64
ATmega1280	128K	8K	4K	86	16	6	TQFP100, CBGA

#### Notes:

- 1. All ROM, RAM, and EEPROM memories are in bytes.
- Data RAM (general-purpose RAM) is the amount of RAM available for data manipulation (scratch pad) in addition to the register space.
- 3. All the above chips have USART for serial data transfer.

# Tiny AVR (ATtinyxxxx)

As its name indicates, the microcontrollers in this group have less instructions and smaller packages in comparison to mega family. You can design systems with low costs and power consumptions using the Tiny AVRs. See Table 1-4. Some of their characteristics are as follows:

- Program memory: 1K to 8K bytes
- Package: 8 to 28 pins
- Limited peripheral set
- Limited instruction set: The instruction sets are limited. For example, some of them do not have the multiply instruction.

Table 1-4: So Part Num.	Code ROM	Data RAM	Data EEPROM	I/O pins	ADC	Timers	s Pin numbers & Package
ATtiny13	1K	64	64	6	4	1	SOIC8, PDIP8
ATtiny25	2K	128	128	6	4	2	SOIC8, PDIP8
ATtiny44	4K	256	256	12	8	2	SOIC14, PDIP14
ATtiny84	8 <b>K</b>	512	512	12	8	2	SOIC14, PDIP14

#### Special purpose AVR

The ICs of this group can be considered as a subset of other groups, but their special capabilities are made for designing specific applications. Some of the special capabilities are: USB controller, CAN controller, LCD controller, Zigbee, Ethernet controller, FPGA, and advanced PWM. See Table 1-5.

Table 1-5: Son	ne Mem	bers of th	ne Special Pu	urpose Fa	amily		
Part Num.	Code ROM	Data RAM	Data EEPROM	Max I/C	Special Capabilities	Time	rs Pin numbers & Package
AT90CAN128	128K	4K	4K	53	CAN	4	LQFP64
AT90USB1287	128K	8K	4K	48	USB Host	4	TQFP64
AT90PWM216	16K	1K	0.5K	19 /	Advanced PWN	<i>I</i> 2	SOIC24
ATmega169	16K	1K	0.5K	54	LCD	3	TQFP64, MLF64

## **AVR** product number scheme

All of the product numbers start with AT, which stands for Atmel. Now, look at the number located at the end of the product number, from left to right, and find the biggest number that is a power of 2. This number most probably shows the amount of the microcontroller's ROM. For example, in ATmega1280 the biggest power of 2 that we can find is 128; so it has 128K bytes of ROM. In ATtiny44, the amount of memory is 4K, and so on. Although this rule has a few exceptions such as AT90PWM216, which has 16K of ROM instead of 2K, it works in most of the cases.

## Other microcontrollers

There are many other popular 8-bit microcontrollers besides the AVR chip. Among them are the 8051, HCS08, PIC, and Z8. The AVR is made by Atmel Corp, as seen in Table 1-6. Microchip produces the PIC family. Freescale (formerly Motorola) makes the HCS08 and many of its variations. Zilog produces the Z8 microcontroller. The 8051 family is made by Intel and a number of other companies. To contrast the ATmega32 with the 8052 chip and PIC, examine Table 1-7.

For a comprehensive treatment of the 8051, HCS12, and PIC microcontrollers, see "The 8051 Microcontroller and Embedded Systems," "HCS12 Microcontroller and Embedded Systems," and "PIC Microcontroller and Embedded Systems" by Mazidi, et al.

Company	Web Site	Architecture
Atmel	http://www.atmel.com	AVR and 8051
Microchip	http://www.microchip.com	PIC16xxx/18xxx
Intel	http://www.intel.com/design/mcs51	8051
Philips/Signetics	http://www.semiconductors.philips.com	8051
Zilog	http://www.zilog.com	Z8 and Z80
Dallas Semi/Maxim	http://www.maxim-ic.com	8051
Freescale Semi	http://www.freescale.com	68HC11/HCS08

Table 1-7: Comparison of 8051, PIC18	Family, and AVR (4	0-pin packag	(e)
Feature	8052	PIC18F452	ATmega32
Program ROM	8K	32K	32K
Data RAM (maximum space)	256 bytes	2K	2K
EEPROM	0 bytes	256 bytes	1 <b>K</b>
Timers	3	4	3
I/O pins	32	35	32

# **Review Questions**

- 1. Name three features of the AVR.
- 2. The AVR is a(n) \_\_\_\_\_-bit microprocessor.
- 3 Name the different groups of the AVR chips.
- 4. Which group of AVR has smaller packages?
- 5. Give the size of RAM in each of the following:
  - (a) ATmega32
    - (b) ATtiny25
- 6. Give the size of the on-chip program ROM in each of the following:
  - (a) ATtiny84
- (b) ATmega32
- (c) ATtiny25

See the following websites for AVR microcontrollers and AVR trainers:

http://www.Atmel.com

http://www.MicroDigitalEd.com

http://www.digilentinc.com

#### SUMMARY

This chapter discussed the role and importance of microcontrollers in everyday life. Microprocessors and microcontrollers were contrasted and compared. We discussed the use of microcontrollers in the embedded market. We also discussed criteria to consider in choosing a microcontroller such as speed, memory, I/O, packaging, and cost per unit. The second section of this chapter described various families of the AVR, such as Mega and Tiny, and their features. In addition, we discussed some of the most common AVR microcontrollers such as the ATmega32 and ATtiny25.

#### **PROBLEMS**

#### SECTION 1.1: MICROCONTROLLERS AND EMBEDDED PROCESSORS

- 1. True or False. A general-purpose microprocessor has on-chip ROM.
- 2. True or False. Generally, a microcontroller has on-chip ROM.
- 3. True or False. A microcontroller has on-chip I/O ports.
- 4. True or False. A microcontroller has a fixed amount of RAM on the chip.
- 5. What components are usually put together with the microcontroller onto a single chip?
- 6. Intel's Pentium chips used in Windows PCs need external \_\_\_\_ and \_\_\_\_ chips to store data and code.
- 7. List three embedded products attached to a PC.
- 8. Why would someone want to use an x86 as an embedded processor?
- 9. Give the name and the manufacturer of some of the most widely used 8-bit microcontrollers.
- 10. In Question 9, which one has the most manufacture sources?
- 11. In a battery-based embedded product, what is the most important factor in choosing a microcontroller?
- 12. In an embedded controller with on-chip ROM, why does the size of the ROM matter?
- 13. In choosing a microcontroller, how important is it to have multiple sources for that chip?
- 14. What does the term "third-party support" mean?
- 15. Suppose that a microcontroller architecture has both 8-bit and 16-bit versions. Which of the following statements is true?
  - (a) The 8-bit software will run on the 16-bit system.
  - (b) The 16-bit software will run on the 8-bit system.

#### SECTION 1.2: OVERVIEW OF THE AVR FAMILY

16. What is the advantag	ge of Flash memory over the other kinds of ROM?
17. The ATmega32 has	pins for I/O.
18. The ATmega32 has _	bytes of on-chip program ROM.
19. The ATtiny44 has	bytes of on-chip data RAM.
20. The ATtiny44 has	ADCs.

21.	The ATmega64 has bytes of on-chip data RAM.
22.	The ATmega1280 has on-chip timer(s).
	The ATmega32 has bytes of on-chip data RAM.
	Check the Atmel website to see if there is a RAMless version of the AVR. Give
	the part number if there is one.
25.	Check the Atmel website to see if there is a ROMless version of the AVR. Give
	the part number if there is one.
26.	Check the Atmel website to find three members of the AVR family that have
	USB controllers.
27.	Check the Atmel website to find two members of the AVR family that have
	CAN controllers.
28.	Give the amount of program ROM and data RAM for the following chips:
	(a) ATmega32 (b) ATtiny44 (c) ATtiny84 (d) 90CAN128
29.	What are the main differences between the ATmega16 and the ATmega32?
<b>30</b> .	The ATmega16 has bytes of data EEPROM.
Αl	NSWERS TO REVIEW QUESTIONS
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	NSWERS TO REVIEW QUESTIONS  CTION 1.1: MICROCONTROLLERS AND EMBEDDED PROCESSORS
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SE0 1. 2. 3. 4. 5.	True A microcontroller-based system (d) (d) It is dedicated because it is does only one type of job. Embedded system means that the application and the processor are combined into a single system.
SE0 1. 2. 3. 4. 5.	True A microcontroller-based system (d) (d) It is dedicated because it is does only one type of job. Embedded system means that the application and the processor are combined into a single system. Having multiple sources for a given part means you are not hostage to one supplier. More
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(c) 2K bytes

(b) 32K bytes

(b) 128 bytes

6. (a) 8K bytes