Markerless LiDAR-Camera Calibration

Initial Formulation

$$r_i = I_2(x_i) - I_1(\pi(g(\delta, \pi^{-1}(x_i, d(g(G(\xi), X_i))))));$$

where,

d is the Z-coordinate selection operator, defined as

$$d: \mathbb{R}^3 \to \mathbb{R}$$
$$d(X, Y, Z) \mapsto Z$$

 r_i is the difference in intensity between the second image I_2 and the first image I_1 after warping it to the point of view of the second image, at the pixel x_i .

 δ is the known transformation between the two cameras.

 ξ is the transformation between the first camera and the LiDAR

 x_i is the 2D image coordinates of the 3D point in velodyne's coordinates, X_i

$$J = J_I.J_{\pi}.J_g.J_{\pi^{-1}}.J_d.J_g.J_G$$

$$J_I = [\nabla I_x \nabla I_y]$$

$$J_{\pi} = \begin{pmatrix} f_{x} \frac{1}{z''} & 0 & -f_{x} \frac{x''}{z''^{2}} \\ 0 & f_{y} \frac{1}{z''} & -f_{y} \frac{y''}{z''^{2}} \end{pmatrix}$$

$$J_g = \begin{pmatrix} r_{11} & r_{12} & r_{13} \\ r_{21} & r_{22} & r_{23} \\ r_{31} & r_{32} & r_{33} \end{pmatrix}$$

$$J_{\pi^{-1}} = \begin{pmatrix} \frac{(x_i - c_x)}{f_x} \\ \frac{(y_i - c_y)}{f_y} \\ 1 \end{pmatrix}$$

$$J_d = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix}$$

$$J_g = \begin{pmatrix} x & 0 & 0 & y & 0 & 0 & z & 0 & 0 & 1 & 0 & 0 \\ 0 & x & 0 & 0 & y & 0 & 0 & z & 0 & 0 & 1 & 0 \\ 0 & 0 & x & 0 & 0 & y & 0 & 0 & z & 0 & 0 & 1 \end{pmatrix}$$

$$J_G = \begin{pmatrix} 0 & 0 & 0 & 0 & R_{31} & -R_{21} \\ 0 & 0 & 0 & -R_{31} & 0 & R_{11} \\ 0 & 0 & 0 & R_{21} & -R_{11} & 0 \\ 0 & 0 & 0 & 0 & R_{32} & -R_{22} \\ 0 & 0 & 0 & -R_{32} & 0 & R_{12} \\ 0 & 0 & 0 & R_{22} & -R_{12} & 0 \\ 0 & 0 & 0 & 0 & R_{33} & -R_{23} \\ 0 & 0 & 0 & -R_{33} & 0 & R_{13} \\ 0 & 0 & 0 & R_{23} & -R_{13} & 0 \\ 1 & 0 & 0 & 0 & T_z & -T_y \\ 0 & 1 & 0 & -T_z & 0 & T_x \\ 0 & 0 & 1 & T_y & -T_x & 0 \end{pmatrix}$$

The product of all the jacobian terms, J is

$$J = \begin{pmatrix} 0 & 0 & A & B & C & 0 \end{pmatrix}$$

where,

$$A = \frac{(x_{i} - c_{x}) \left(r_{31} \left(-\frac{f_{x}g_{x}x''}{(z'')^{2}} - \frac{f_{y}g_{y}y''}{(z'')^{2}}\right) + \frac{r_{11}f_{x}g_{x}}{z''} + \frac{r_{21}f_{y}g_{y}}{z''}\right)}{f_{x}} + \frac{(y_{i} - c_{y}) \left(r_{32} \left(-\frac{f_{x}g_{x}x''}{(z'')^{2}} - \frac{f_{y}g_{y}y''}{(z'')^{2}}\right) + \frac{r_{12}f_{x}g_{x}}{z''} + \frac{r_{22}f_{y}g_{y}}{z''}\right)}{f_{y}} + r_{33} \left(-\frac{f_{x}g_{x}x''}{(z'')^{2}} - \frac{f_{y}g_{y}y''}{(z'')^{2}}\right) + \frac{r_{13}f_{x}g_{x}}{z''} + \frac{r_{23}f_{y}g_{y}}{z''}$$

$$\begin{split} C &= -R_{11}x \left(\frac{\left(x_i - c_x\right) \left(r_{31} \left(-\frac{f_x g_x x''}{(z'')^2} - \frac{f_y g_y y''}{(z'')^2} \right) + \frac{r_{11}f_x g_x}{x''} + \frac{r_{21}f_y g_y}{z''}}{f_x} \right)}{f_x} \right) \\ &- R_{11}x \left(\frac{\left(y_i - c_y\right) \left(r_{32} \left(-\frac{f_x g_x x''}{(z'')^2} - \frac{f_y g_y y''}{(z'')^2} \right) + \frac{r_{12}f_x g_x}{z''} + \frac{r_{22}f_y g_y}{z''}}{f_y} \right) + r_{33} \left(-\frac{f_x g_x x''}{(z'')^2} - \frac{f_y g_y y''}{(z'')^2} \right) + \frac{r_{13}f_x g_x}{z''} + \frac{r_{23}f_y g_y}{z''} \right) \\ &- R_{12}y \left(\frac{\left(x_i - c_x\right) \left(r_{31} \left(-\frac{f_x g_x x''}{(z'')^2} - \frac{f_y g_y y''}{(z'')^2} \right) + \frac{r_{11}f_x g_x}{z''} + \frac{r_{21}f_y g_y}{z''}}{f_x} \right) \right) \\ &- R_{12}y \left(\frac{\left(y_i - c_y\right) \left(r_{32} \left(-\frac{f_x g_x x''}{(z'')^2} - \frac{f_y g_y y''}{(z'')^2} \right) + \frac{r_{12}f_x g_x}{z''} + \frac{r_{22}f_y g_y}{z''}}{f_y} \right) \\ &- R_{12}y \left(\frac{\left(x_i - c_x\right) \left(r_{31} \left(-\frac{f_x g_x x''}{(z'')^2} - \frac{f_y g_y y''}{z''} \right) + \frac{r_{11}f_x g_x}{z''} + \frac{r_{23}f_y g_y}{z''}}{f_y} \right) \right) \\ &- R_{12}y \left(\frac{\left(x_i - c_x\right) \left(r_{31} \left(-\frac{f_x g_x x''}{(z'')^2} - \frac{f_y g_y y''}{(z'')^2} \right) + \frac{r_{11}f_x g_x}{z''} + \frac{r_{23}f_y g_y}{z''}}{f_y} \right) \right) \\ &- R_{13}z \left(\frac{\left(y_i - c_y\right) \left(r_{32} \left(-\frac{f_x g_x x''}{(z'')^2} - \frac{f_y g_y y''}{(z'')^2} \right) + \frac{r_{11}f_x g_x}{z''} + \frac{r_{23}f_y g_y}{z''}}{f_y} \right) \right) \\ &- T_x \left(\frac{\left(x_i - c_x\right) \left(r_{31} \left(-\frac{f_x g_x x''}{(z'')^2} - \frac{f_y g_y y''}{z''} \right) + \frac{r_{11}f_x g_x}{z''} + \frac{r_{23}f_y g_y}{z''}}{f_x} \right) \right) \\ &- T_x \left(\frac{\left(y_i - c_y\right) \left(r_{32} \left(-\frac{f_x g_x x''}{(z'')^2} - \frac{f_y g_y y''}{(z'')^2} \right) + \frac{r_{11}f_x g_x}{z''} + \frac{r_{23}f_y g_y}{z''}}{f_x} \right) \\ &- T_x \left(\frac{\left(y_i - c_y\right) \left(r_{32} \left(-\frac{f_x g_x x''}{(z'')^2} - \frac{f_y g_y y''}{(z'')^2} \right) + \frac{r_{12}f_x g_x}{z''} + \frac{r_{22}f_y g_y}{z''}}{f_x} \right) \\ &- T_x \left(\frac{\left(y_i - c_y\right) \left(r_{32} \left(-\frac{f_x g_x x''}{(z'')^2} - \frac{f_y g_y y''}{(z'')^2} \right) + \frac{r_{12}f_x g_x}{z''} + \frac{r_{22}f_y g_y}{z''}}{f_x} \right) \\ &- T_x \left(\frac{\left(y_i - c_y\right) \left(r_{32} \left(-\frac{f_x g_x x''}{(z'')^2} - \frac{f_y g_y y''}{(z'')^2} \right) + \frac{r_{12}f_x g_x}{z''} + \frac{r_{22}f_y g_y}{z''} \right)}{f_x} \right) \\ &- T_x \left(\frac{\left(y_i - c_y\right) \left(r_{32} \left(-\frac{f_x g_x x''}{(z'')^2}$$