

INTERESTS	SLAM, 3D Computer Vision, Robot Perception	
EDUCATION	International Institute of Information Technology , Hyderabad, India (IIIT-H)	2018 - 2021
	M.S. by Research in Computer Science & Engineering Thesis: Robust Plane-based Visual-Inertial Odometry for Dynamic Environments CGPA: 9.50/10	
	Anna University , SSN College of Engineering, Chennai, India (SSN-CE)	2013 - 2017
	B.Eng. in Electronics & Communication Engineering (ECE)	
PUBLICATIONS	RP-VIO: Robust Plane-based Visual-Inertial Odometry for Dynamic Environments 📄	
	Karnik Ram , Chaitanya Kharyal, Sudarshan S. Harithas, K. Madhava Krishna <i>In proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems, 2021</i>	
	Learnable Spatio-Temporal Map Embeddings for Deep Inertial Localization	
	Dennis Melamed, Karnik Ram , Vivek Roy, Kris Kitani <i>In proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems, 2022</i>	
	INFER: Intermediate Representations for Future Prediction 📄	
WORK EXPERIENCE	Shashank Srikanth, Junaid Ahmed Ansari, Karnik Ram , Sarthak Sharma, J. Krishna Murthy, K. Madhava Krishna <i>In proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems, 2019</i>	
	CalibNet: Geometrically-Supervised LiDAR-Camera Extrinsic Calibration using 3D Spatial Transformer Networks 📄	
	Ganesh Iyer, Karnik Ram , J. Krishna Murthy, K. Madhava Krishna <i>In proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems, 2018</i>	
	Research Associate , Robotics Institute, Carnegie Mellon University	Aug 2021 - Present
	Working on deep inertial-only navigation algorithms for indoor smartphone localization, towards blind person navigation. Advisor: Prof. Kris Kitani.	
	Graduate Research Assistant , Robotics Research Center, IIIT Hyderabad	
	Aug 2018 - Aug 2021	
	Researched algorithms for improving the robustness of visual SLAM algorithms in dynamic environments. In particular, developed and evaluated a visual-inertial odometry algorithm for dynamic environments using only planar features and their induced planar homographies. Also worked on a deep auto-regressive model for the trajectory prediction of vehicles in a dynamic scene. Advisor: Prof. K. Madhava Krishna. Outcome: 2 research papers and open-source code.	
	Google Summer of Code Student Developer , Mobile Robot Programming Toolkit Summer 2018	
	Developed a GUI app for the extrinsic calibration of range sensors. The app includes implementations of algorithms for estimating the extrinsics between RGB-D / LiDAR sensors based on plane-matching and line-matching, within a user-friendly GUI. Outcome: Open-source code. 📄	
	Research Intern , Robotics Research Center, IIIT Hyderabad	
	May 2017 - April 2018	
	Researched algorithms for markerless LiDAR-camera extrinsic calibration for an autonomous car. In particular, we developed and evaluated an approach to estimate the extrinsics using direct photometric error minimization, as well as a geometrically-supervised deep network using spatial transformer networks. Advisor: Prof. K. Madhava Krishna, J. Krishna Murthy. Outcome: 1 research paper.	
	Computer Vision Intern , Navstik Autonomous Systems, Pune, India	
	Summer 2016	
	Worked on person detection algorithms for a drone, and in particular, evaluated the performance of a HOG feature-based detector on an Nvidia Jetson embedded board.	

RELEVANT COURSEWORK	<p><i>Graduate:</i> Mobile Robotics, Computer Vision, Machine Learning, Topics in Applied Optimization.</p> <p><i>Undergraduate:</i> Robotics & Automation, Digital Image Processing, OOP & Data Structures, Computer Architecture, Probability & Random Processes, Embedded & Real Time Systems</p>
ADDITIONAL COURSES	<p>ETH Robotics Summer School, ETH Zürich 🦉 July 2019</p> <p>2-week all-expenses-paid summer school, contained lectures and hands-on exercises on autonomous navigation, and talks by renowned researchers. Also worked in a team of six on a semi-autonomous ground robot for search-and-rescue applications. Approx. 50 selected participants from 15 countries.</p>
TEACHING	<p>Head Teaching Assistant, Mobile Robotics, IIIT-H 🦉 Fall 2019</p> <p>Designed 5 new assignments and 2 exams on topics including single-view geometry, epipolar geometry, stereo reconstruction, bundle adjustment, EKF localization. Responsibilities also included conducting tutorial classes, office hours, and grading. Approx. 80 students.</p> <p>Teaching Assistant, 3D Computer Vision Workshop, IIIT-H Feb 2020</p> <p>Conducted a tutorial session on multiple-view geometry concepts including epipolar geometry and bundle adjustment with hands-on exercises for a professional audience from industry. Approx. 80 participants.</p> <p>Event Coordinator, SSN-ECE Tech Club, SSN-CE Spring, 2017</p> <p>Taught introductory concepts in robotics and computer vision to approx. 20 sophomores and juniors over a semester. Also organized an Internet-of-Things themed inter-college hackathon for approx. 40 participants.</p>
AWARDS & GRANTS	<ul style="list-style-type: none"> • Top 2 out of 134 teams in the ARTPARK Robotics Challenge, IISc 2021 • ETH Robotics Summer School Travel Grant, ETH Zürich 2019 • Research Fellowship, covered tuition fees and living expenses, IIIT-H 2018-21 • Best Senior Year Project, ECE Department, SSN-CE 2017 • First place, inter-college image processing based robotics event, Anna University 2016 • Top 10 out of 144 teams in the “Apps for Chennai Challenge” 2015 • SSN Trust Funding for Student Projects, SSN-CE 2014, 2015
SERVICES	<ul style="list-style-type: none"> • Lab Systems Administrator for the compute cluster at RRC, IIIT Hyderabad. 2020-21 • Served as a reviewer in the SLAM track for IROS. 2021, 22 • Served as a co-chair for the VI-SLAM session at IROS. 2021 • Conceived, developed, and maintained The SSN App, the official Android app of SSN-CE. 2014-17
TECHNICAL SKILLS	<p><i>Tools & Libraries:</i> OpenCV, ROS, Ceres Solver, PyTorch, Eigen, Git, AirSim Familiar: Qt, Android</p> <p><i>Programming Languages:</i> C++, Python Familiar: Java</p>
REFERENCES	<p>Prof. K. Madhava Krishna, Lab Head at RRC, IIIT Hyderabad Relation: Master’s thesis advisor and course instructor. Email: mkrishna@iiit.ac.in</p> <p>Prof. Kris Kitani, Associate Research Professor at RI, CMU Relation: Research project advisor. Email: kkitani@cmu.edu</p> <p>Krishna Murthy Jatavallabhula, PhD Candidate at Mila, Montréal Relation: Research collaborator and mentor. Email: krrish94@gmail.com</p>