

• Feedback voltage circuit (V_{ref})

$$R_1 = 11.4 \text{ k}\Omega \quad R_2 = 1 \text{ k}\Omega$$

$$1) \quad V_{out} = (V_f - V_{ref}) \times \frac{R_1 + R_2}{R_2} + V_{ref}$$

$$V_{out} = \frac{R_1 + R_2}{R_2} \cdot V_f - \frac{R_1}{R_2} V_{ref} = 15.3 - 11.4 V_{ref}$$

$$V_{out}|_{min} = 12 \text{ V} \rightarrow V_{ref}|_{max} = 0.29 \text{ V} \leftarrow \text{small} \text{ :/}$$

2) Solution: greater $V_{out}|_{max}$

$$V_{out}|_{max} = 42 \text{ V} \quad R_1 = 33 \text{ k}\Omega \quad R_2 = 1 \text{ k}\Omega$$

$$V_{out} = 42 - 33 V_{ref} \quad V_{out}|_{min} = 12 \text{ V} \rightarrow \underline{V_{ref}|_{max} = 0.91 \text{ V}}$$

$$V_{out} = 0 \text{ V} \rightarrow \underline{V_{ref} = 1.27 \text{ V}}$$

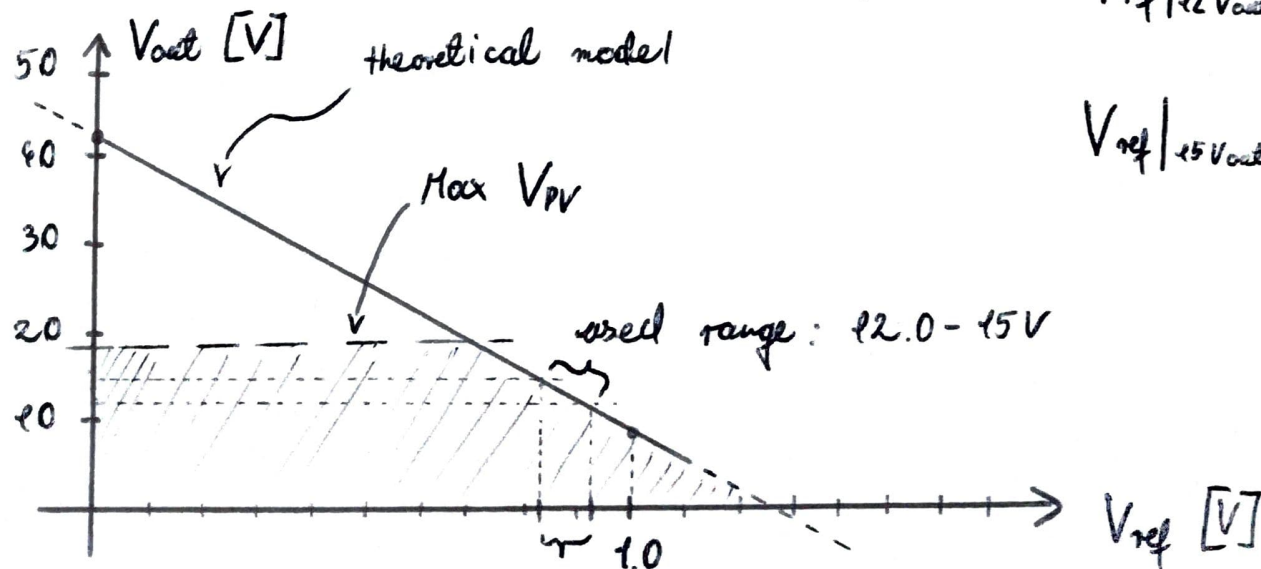
• Attention: Very high input resistance!

• Input R of LM5276 \gg few $\text{M}\Omega$ \uparrow no problem

3) Graph of V_{out} (V_{ref}) for this configuration

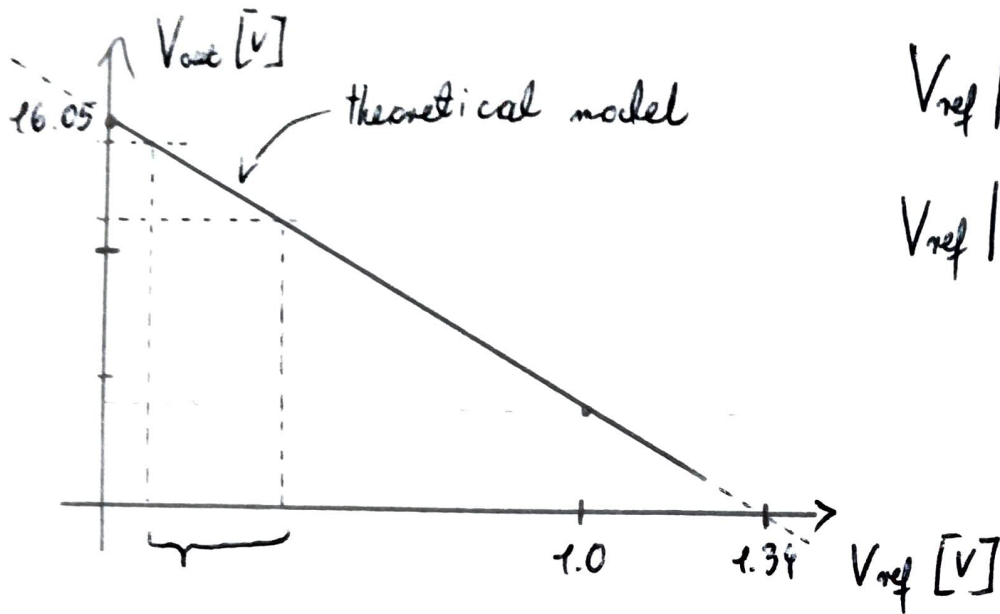
$$V_{ref}|_{12 \text{ V}_{out}} = 0.91 \text{ V}$$

$$V_{ref}|_{15 \text{ V}_{out}} = 0.82 \text{ V}$$



4) Final choice $R_1 = 1.8 k\Omega$ $R_2 = 1 k\Omega$

$$V_{out} = \frac{R_1 + R_2}{R_2} V_f - \frac{R_1}{R_2} V_{ref} = 2.8 V_f - 1.2 V_{ref}$$



$$V_{ref} / 12 V_{out} = 0.338 V$$

$$V_{ref} / 15 V_{out} = 0.086 V$$

$$\Delta V = 0.25 V$$

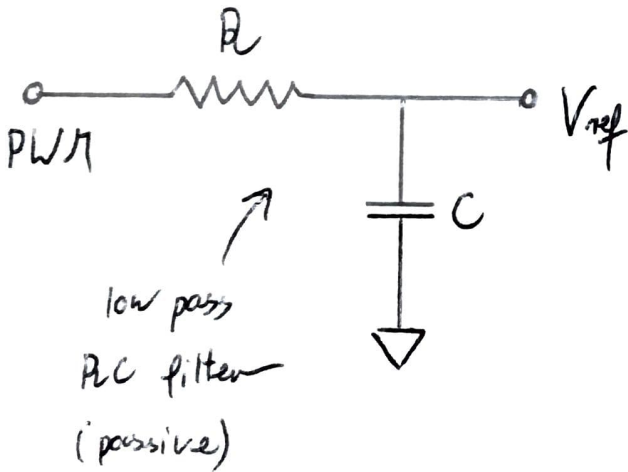
$$\Delta V = 5\% \text{ DC (duty cycle)}$$

5) RC filter design

$$f_c = \frac{1}{2\pi RC}$$

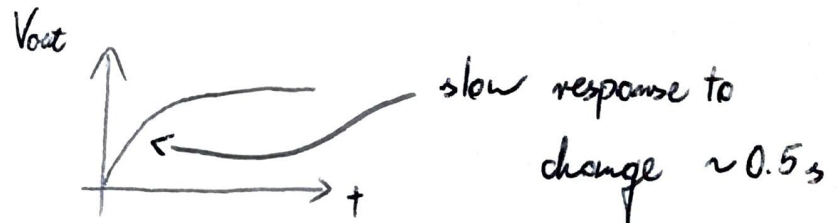
$$f_{PWM} = 7800 \approx 8 \text{ kHz}$$

$$f_{PWM} = 62.5 \text{ kHz}$$



$$R = 33 k\Omega \quad C = 10 \mu F$$

$$f_c = 0.48 \text{ Hz}$$



- lower Arduino PWM frequencies (e.g. 100-500 Hz) gives V_{out} closer to $V_{in} \times DC$, however for frequencies $< 100 \text{ Hz}$ large voltage ripple ($\pm 10 \text{ mV}$) can be observed

5) Further tests:

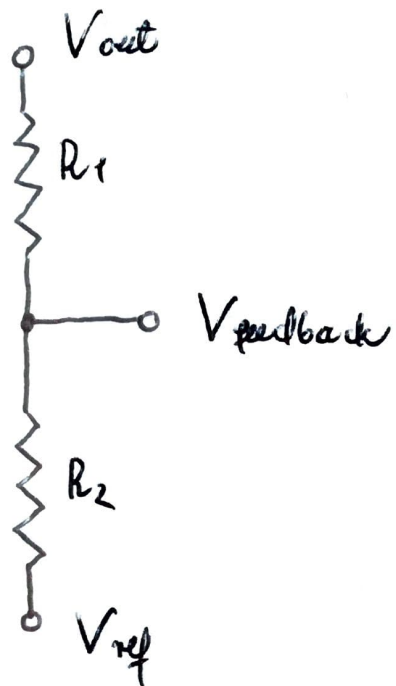
- Final thoughts:

1) 490 Hz as PWM frequency gives the best results for generating voltages $0 < V_{out} < 500 \text{ mV}$;

2) The best RC filter for this frequency and voltages turned out to be $R = 33 \text{ k}\Omega$, $C = 10 \mu\text{F}$, $f_c = 0.48 \text{ Hz}$, and response to change $0 \rightarrow 500 \text{ mV}$ faster than a second;

3) Before the final assembly, calibration is necessary:

- V_{out} for 20 DC settings, and vice versa DC set. for 20 given V_{out}



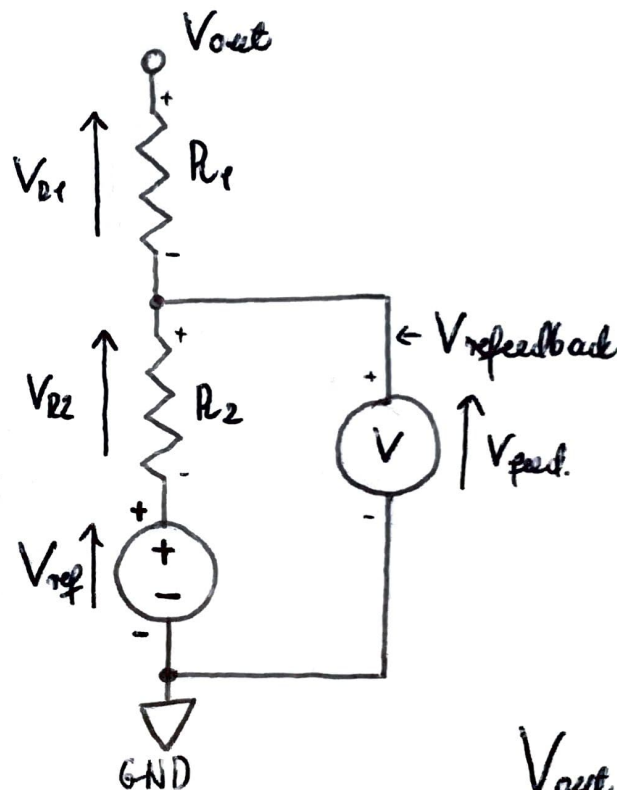
$$V_{\text{feedback}} = (V_{\text{out}} - V_{\text{ref}}) \cdot \frac{R_2}{R_1 + R_2} \Rightarrow V_f = 9.4 \times (V_{\text{out}} - V_{\text{ref}})$$

\uparrow
 $\frac{1}{10.4} = 0.096$

$$V_{\text{out}} = \frac{R_1 + R_2}{R_2} \cdot V_{\text{feedback}} + V_{\text{ref}}$$

Corrected

Feedback Voltage



$$\begin{cases} V_f = V_{R2} + V_{\text{ref}} \\ V_{R2} = (V_{\text{out}} - V_{\text{ref}}) \cdot \frac{R_2}{R_1 + R_2} \end{cases}$$

\Downarrow

$$V_f - V_{\text{ref}} = (V_{\text{out}} - V_{\text{ref}}) \cdot \frac{R_2}{R_1 + R_2}$$

$$(V_f - V_{\text{ref}}) \cdot \frac{R_1 + R_2}{R_2} + V_{\text{ref}} = V_{\text{out}}$$

$$V_{\text{out}} = (V_f - V_{\text{ref}}) \times \frac{R_1 + R_2}{R_2} + V_{\text{ref}}$$

1) $R_1 = 8.7 \times 2 = 9.4 \text{ k}\Omega$ ($9.2 \text{ k}\Omega$)

$R_2 = 1 \text{ k}\Omega$

$$V_{\text{out}} = \frac{10}{9.4} \times 1.235 + V_{\text{ref}}$$

$$V_{\text{out}} = 12.8 + V_{\text{ref}}$$