

Vector Space Model: Latent Semantic Indexing

(Teaching Inspired by Research)

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- ① Introduction
- ② Mathematical Formulation
- ③ Singular Value Decomposition
- ④ Conclusion

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Contents of the Course

Week	Lecture	Practical Exercises
1	(05/04) Introduction to Medical Information Retrieval (MIR)	(05/04) Introduction to Python
2	(12/04) Main Components and Classification of MIR Systems	(12/04) Introduction to Python
3	(19/04) Metadata in Medical Information Retrieval Systems	(19/04) CBIR in Medical Applications
4	(26/04) No Lecture due to a Business Trip	(26/04) CBIR in Medical Applications
5	(03/05) Set Theoretic Model: Boolean Retrieval	(03/05) CBIR in Medical Applications
6	(10/05) Set Theoretic Model: Fuzzy Retrieval	(10/05) Flask Tutorial
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11	(14/06) Text-based Retrieval of Medical Information	(14/06) Deep Learning
12	(21/06) Audio-based Retrieval of Medical Information	(21/06) Deep Learning
13	(28/06) Image-based Retrieval of Medical Information	(28/06) Relevance Feedback
14	(05/07) Demonstrators from Current Research Projects	(05/07) Relevance Feedback
15	(12/07) Summary and Conclusions	(12/07) Evaluation 

Synonymy and Polysemy in Information Retrieval

- **Synonymy**: Different words (say *car* and *automobile*) have the same meaning. The vector space representation fails to capture the relationship between synonymous terms such as *car* and *automobile*, because they correspond to separate dimensions in the term-document matrix. Consequently the computed similarity between a query *car* and a document containing both *car* and *automobile* underestimates the true similarity that a user would perceive.
- **Polysemy** refers to the case where a term such as *charge* has multiple meanings, so that the computed similarity overestimates the similarity that a user would perceive.

Transforming the Term-Document Matrix – Example

Consider the following term-document matrix \mathbf{X} :

	d_1	d_2	d_3	d_4	d_5	d_6
ship	1	0	1	0	0	0
boat	0	1	0	0	0	0
ocean	1	1	0	0	0	0
voyage	1	0	0	1	1	0
trip	0	0	0	1	0	1

Using the Singular Value Decomposition (SVD, see below), the matrix \mathbf{X} can be reformulated as follows:

$$\mathbf{X} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T .$$

Transforming the Term-Document Matrix – Example

For our example \mathbf{X} , the matrix \mathbf{U} has the following values:

ship	−0.44	−0.30	0.57	0.58	0.25
boat	−0.13	−0.33	−0.59	0.00	0.73
ocean	−0.48	−0.51	−0.37	0.00	−0.61
voyage	−0.70	0.35	0.15	−0.58	0.16
trip	−0.26	0.65	−0.41	0.58	−0.09

Transforming the Term-Document Matrix – Example

For our example \mathbf{X} , the matrix Σ has the following values:

2.16	0.00	0.00	0.00	0.00
0.00	1.59	0.00	0.00	0.00
0.00	0.00	1.28	0.00	0.00
0.00	0.00	0.00	1.00	0.00
0.00	0.00	0.00	0.00	0.39

Transforming the Term-Document Matrix – Example

For our example \mathbf{X} , the matrix \mathbf{V}^T has the following values:

d_1	d_2	d_3	d_4	d_5	d_6
−0.75	−0.28	−0.20	−0.45	−0.33	−0.12
−0.29	−0.53	−0.19	0.63	0.22	0.41
0.28	−0.75	0.45	−0.20	0.12	−0.33
0.00	0.00	0.58	0.00	−0.58	0.58
−0.53	0.29	0.63	0.19	0.41	−0.22

Transforming the Term-Document Matrix – Example

By “zeroing out” all but the two largest singular values of Σ , we obtain Σ_2 :

2.16	0.00	0.00	0.00	0.00
0.00	1.59	0.00	0.00	0.00
0.00	0.00	0.00	0.00	0.00
0.00	0.00	0.00	0.00	0.00
0.00	0.00	0.00	0.00	0.00

Transforming the Term-Document Matrix – Example

Using Σ_2 , we can compute the corresponding version of the term-document matrix \mathbf{X}_2 :

$\hat{\mathbf{d}}_1$	$\hat{\mathbf{d}}_2$	$\hat{\mathbf{d}}_3$	$\hat{\mathbf{d}}_4$	$\hat{\mathbf{d}}_5$	$\hat{\mathbf{d}}_6$
−1.62	−0.60	−0.44	−0.97	−0.70	−0.26
−0.46	−0.84	−0.30	1.00	0.35	0.65

Now, every document is described by a two dimensional vector $\hat{\mathbf{d}}_j$. In contrast to the five dimensional vectors \mathbf{d}_j of the original matrix \mathbf{X} , we do not exactly know the semantics behind the dimensions after transformation.

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Term-Document Matrix – Notation

$$\mathbf{t}_i^T \rightarrow \begin{matrix} & & \mathbf{d}_j & & \\ & & \downarrow & & \\ \begin{bmatrix} x_{1,1} & \dots & x_{1,j} & \dots & x_{1,n} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ x_{i,1} & \dots & x_{i,j} & \dots & x_{i,n} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ x_{m,1} & \dots & x_{m,j} & \dots & x_{m,n} \end{bmatrix} \end{matrix}$$

Term-Document Matrix – Notation

- A row in this matrix is a vector corresponding to a term, giving its relation to each document:

$$\mathbf{t}_i = (x_{i,1}, \dots, x_{i,j}, \dots, x_{i,n})^T \quad .$$

- A column in this matrix is a vector corresponding to a document, giving its relation to each term:

$$\mathbf{d}_j = (d_{1,j}, \dots, d_{i,j}, \dots, d_{m,j})^T \quad .$$

Term-Document Matrix – Correlations

- The dot product $\mathbf{t}_i^T \mathbf{t}_p$ gives the correlation between the terms over the set of all documents.
- The matrix product $\mathbf{X}\mathbf{X}^T$ contains all the dot products. The Element (i, p) equal to the element (p, i) contains the dot product $\mathbf{t}_i^T \mathbf{t}_p = \mathbf{t}_p^T \mathbf{t}_i$.
- Likewise, the matrix $\mathbf{X}^T \mathbf{X}$ contains the dot products between all document vectors, giving their correlation over the terms $\mathbf{d}_j^T \mathbf{d}_q = \mathbf{d}_q^T \mathbf{d}_j$.

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SVD – Main Statement

From the theory of linear algebra, there exists the following decomposition of the matrix \mathbf{X} :

$$\mathbf{X} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T$$

where \mathbf{U} and \mathbf{V} are orthogonal matrices and $\mathbf{\Sigma}$ is a diagonal matrix.

SVD – Term and Document Correlations

The term and document correlations can be now reformulated:

$$\mathbf{X}\mathbf{X}^T = (\mathbf{U}\Sigma\mathbf{V}^T)(\mathbf{U}\Sigma\mathbf{V}^T)^T = (\mathbf{U}\Sigma\mathbf{V}^T)(\mathbf{V}\Sigma^T\mathbf{U}^T) = \mathbf{U}\Sigma\Sigma^T\mathbf{U}^T$$

$$\mathbf{X}^T\mathbf{X} = (\mathbf{U}\Sigma\mathbf{V}^T)^T(\mathbf{U}\Sigma\mathbf{V}^T) = (\mathbf{V}\Sigma^T\mathbf{U}^T)(\mathbf{U}\Sigma\mathbf{V}^T) = \mathbf{V}\Sigma\Sigma^T\mathbf{V}^T$$

Since $\Sigma\Sigma^T$ and $\Sigma^T\Sigma$ are diagonal, \mathbf{U} must contain the eigenvectors of $\mathbf{X}\mathbf{X}^T$, while \mathbf{V} must be the eigenvectors of $\mathbf{X}^T\mathbf{X}$.

SVD – Full Notation

$$\begin{array}{c}
 X \\
 (\mathbf{d}_j) \\
 \downarrow \\
 \begin{bmatrix} x_{1,1} & \dots & x_{1,j} & \dots & x_{1,n} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ x_{i,1} & \dots & x_{i,j} & \dots & x_{i,n} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ x_{m,1} & \dots & x_{m,j} & \dots & x_{m,n} \end{bmatrix}
 \end{array}
 = (\hat{\mathbf{t}}_i^T) \rightarrow \left[\begin{bmatrix} \mathbf{u}_1 \end{bmatrix} \dots \begin{bmatrix} \mathbf{u}_l \end{bmatrix} \right] \cdot \begin{bmatrix} \sigma_1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma_l \end{bmatrix} \cdot \begin{array}{c} V^T \\ (\hat{\mathbf{d}}_j) \\ \downarrow \\ \left[\begin{bmatrix} \mathbf{v}_1 \end{bmatrix} \\ \vdots \\ \begin{bmatrix} \mathbf{v}_l \end{bmatrix} \end{array} \right]$$

- $\sigma_1, \dots, \sigma_l$ – singular values
- $\mathbf{u}_1, \dots, \mathbf{u}_l$ – left singular vectors
- $\mathbf{v}_1, \dots, \mathbf{v}_l$ – right singular vectors

SVD – Dimensionality Reduction

- Selecting k largest singular values and their corresponding singular vectors from \mathbf{U} and \mathbf{V} , we get the rank k approximation of \mathbf{X} with the smallest error.
- The vector $\hat{\mathbf{t}}_i$ is a result of mapping (approximation) the vector \mathbf{t}_i into a k -dimensional space.
- The vector $\hat{\mathbf{d}}_j$ is a result of mapping (approximation) the vector \mathbf{d}_j into a k -dimensional space.
- The full approximation can be expressed as follows:

$$\mathbf{X}_k = \mathbf{U}_k \mathbf{\Sigma}_k \mathbf{V}_k^T .$$

SVD Applied in Information Retrieval

- First, all documents in the database are transformed into the k -dimensional space using SVD:

$$\hat{\mathbf{d}}_j = \Sigma_k^{-1} \mathbf{U}_k^T \mathbf{d}_j \quad .$$

- Then, the query vector \mathbf{q} is transformed using the same transformation:

$$\hat{\mathbf{q}} = \Sigma_k^{-1} \mathbf{U}_k^T \mathbf{q} \quad .$$

- The inverse of the diagonal matrix Σ_k can be found by inverting each nonzero value within the matrix.

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Final Statements

- LSI is a powerful technique to cope with the problems of synonymy and polysemy in information retrieval.
- LSI is able to extract a “non-visible” (latent) semantics from text documents.
- Although LSI reduces the dimensionality of the vector space drastically, it usually leads to a better performance (precision, recall) of information retrieval systems.