

```
> # Initial problem:  $\frac{dy}{dx} = \frac{2y}{x} + x^2 \cos(x), \quad y(1) = 0$ 
```

```
> # range of x : [1;3], step-size :  $h = \frac{x_n - x_0}{n}$ , where n = 100
```

```
> # Explicit methods:
```

$$\begin{array}{c|cccc} 0 & 0 & 0 & 0 & 0 \\ b_2 & c_{21} & 0 & 0 & 0 \\ b_3 & c_{31} & c_{32} & 0 & 0 \\ b_4 & c_{41} & c_{42} & c_{43} & 0 \\ \hline & a_1 & a_2 & a_3 & a_4 \end{array}$$

```
> # Classic fourth-order method:
```

$$\begin{array}{c|cccc} 0 & 0 & 0 & 0 & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 & 0 & 0 \\ \frac{1}{2} & 0 & \frac{1}{2} & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ \hline & \frac{1}{6} & \frac{2}{6} & \frac{2}{6} & \frac{1}{6} \end{array}$$

```
> # 3/8-rule fourth-order method:
```

$$\begin{array}{c|cccc} 0 & 0 & 0 & 0 & 0 \\ \frac{1}{3} & \frac{1}{3} & 0 & 0 & 0 \\ \frac{2}{3} & -\frac{1}{3} & 1 & 0 & 0 \\ 1 & 1 & -1 & 1 & 0 \\ \hline & \frac{1}{8} & \frac{3}{8} & \frac{3}{8} & \frac{1}{8} \end{array}$$

```
> # Runge-Kutta-Gill method:
```

$$\begin{array}{c|cccc} 0 & 0 & 0 & 0 & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 & 0 & 0 \\ \frac{1}{2} & -\frac{1}{2} & 1 & 0 & 0 \\ 1 & 0 & \frac{1}{2} & \frac{1}{2} & 0 \\ \hline & \frac{1}{6} & \frac{3}{6} & \frac{1}{6} & \frac{1}{6} \end{array}$$

```
> #` `solving the problem using the classical method` `(the method  
can be changed by modifying the a, b vectors and c matrix)
```

```
> n := 100; X := Array(0..n); Y := Array(0..n);
                                     n := 100
```

```
X := [0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,  
      0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,  
      0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, ...,  
      ... 1 Array(0 .. 100) entries not shown]
```

$$Y := [0, \\ 0, \\ 0, \dots, \\ \cdots 1 \text{ Array}(0 .. 100) \text{ entries not shown}]$$
$$\triangleright X[0] := 1; X[n] := 3; h := \frac{X[n] - X[0]}{n};$$

$$X_0 := 1$$

$$X_{100} := 3$$

$$h := \frac{1}{50}$$

$$> f := (x, y) \rightarrow \frac{2 \cdot y}{x} + x^2 \cdot \cos(x);$$

**(1)**

**(2)**

(3)

$$f := (x, y) \mapsto \frac{2 \cdot y}{x} + x^2 \cdot \cos(x) \quad (3)$$

$$> a := \left[ \frac{1}{6}, \frac{2}{6}, \frac{2}{6}, \frac{1}{6} \right]; b := \left[ 0, \frac{1}{2}, \frac{1}{2}, 1 \right]; c := \text{Matrix} \left( \left[ \begin{bmatrix} 0, 0, 0, 0 \end{bmatrix}, \begin{bmatrix} \frac{1}{2}, 0, 0, 0 \end{bmatrix}, \begin{bmatrix} 0, \frac{1}{2}, 0, 0 \end{bmatrix}, \begin{bmatrix} 0, 0, 1, 0 \end{bmatrix} \right] \right)$$

$$a := \left[ \frac{1}{6}, \frac{1}{3}, \frac{1}{3}, \frac{1}{6} \right]$$

$$b := \left[ 0, \frac{1}{2}, \frac{1}{2}, 1 \right]$$

$$c := \begin{bmatrix} 0 & 0 & 0 & 0 \\ \frac{1}{2} & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

(4)

$$> r := 4 \# \text{ fourth-order method}$$

$$r := 4$$

(5)

```
> for i from 0 to n - 1 do:
  k[1] := f(X[i], Y[i]);
  for j from 2 to r do:
    k[j] := f(X[i] + h·b[j], Y[i] + h·add(c[j, l]·k[l], l = 1..j - 1));
  end do;
  Y[i + 1] := evalf(X[i] + h);
  X[i + 1] := evalf(Y[i] + h·add(a[j]·k[j], j = 1..4));
end do;
```

$$k_1 := \cos(1)$$

$$Y_1 := 1.020000000$$

$$X_1 := 0.01106677293$$

$$k_1 := 184.3357019$$

$$Y_2 := 0.03106677293$$

$$X_2 := 7.554831200$$

$$k_1 := 16.82885060$$

$$Y_3 := 7.574831200$$

$$X_3 := 0.3584394087$$

$$k_1 := 42.38592938$$

$$Y_4 := 0.3784394087$$

$$X_4 := 8.446397783$$

$$k_1 := -39.74521058$$

$$Y_5 := 8.466397783$$

$X_5 := -0.4320793817$   
 $k_1 := -39.01954991$   
 $Y_6 := -0.4120793817$   
 $X_6 := 7.703854419$   
 $k_1 := 8.769544677$   
 $Y_7 := 7.723854419$   
 $X_7 := -0.2475771771$   
 $k_1 := -62.33610309$   
 $Y_8 := -0.2275771771$   
 $X_8 := 6.527363299$   
 $k_1 := 41.27287928$   
 $Y_9 := 6.547363299$   
 $X_9 := 0.6008248919$   
 $k_1 := 22.09235082$   
 $Y_{10} := 0.6208248919$   
 $X_{10} := 6.996824217$   
 $k_1 := 37.18711476$   
 $Y_{11} := 7.016824217$   
 $X_{11} := 1.362314643$   
 $k_1 := 10.68545146$   
 $Y_{12} := 1.382314643$   
 $X_{12} := 7.231898401$   
 $k_1 := 30.85923667$   
 $Y_{13} := 7.251898401$   
 $X_{13} := 1.994297798$   
 $k_1 := 5.638173042$   
 $Y_{14} := 2.014297798$   
 $X_{14} := 7.363994722$   
 $k_1 := 26.06773789$   
 $Y_{15} := 7.383994722$   
 $X_{15} := 2.528788148$   
 $k_1 := 0.608781629$   
 $Y_{16} := 2.548788148$   
 $X_{16} := 7.394230592$

$k_1 := 24.94990722$   
 $Y_{17} := 7.414230592$   
 $X_{17} := 3.040548538$   
 $k_1 := -4.320877263$   
 $Y_{18} := 3.060548538$   
 $X_{18} := 7.325529305$   
 $k_1 := 27.89252046$   
 $Y_{19} := 7.345529305$   
 $X_{19} := 3.612025348$   
 $k_1 := -7.562226978$   
 $Y_{20} := 3.632025348$   
 $X_{20} := 7.193138629$   
 $k_1 := 32.76773323$   
 $Y_{21} := 7.213138629$   
 $X_{21} := 4.282687537$   
 $k_1 := -4.272511229$   
 $Y_{22} := 4.302687537$   
 $X_{22} := 7.129791238$   
 $k_1 := 34.88592061$   
 $Y_{23} := 7.149791238$   
 $X_{23} := 4.996521089$   
 $k_1 := 9.860270498$   
 $Y_{24} := 5.016521089$   
 $X_{24} := 7.353055694$   
 $k_1 := 27.32970176$   
 $Y_{25} := 7.373055694$   
 $X_{25} := 5.556409973$   
 $k_1 := 25.72644875$   
 $Y_{26} := 5.576409973$   
 $X_{26} := 7.895109464$   
 $k_1 := -1.150264374$   
 $Y_{27} := 7.915109464$   
 $X_{27} := 5.540665103$   
 $k_1 := 25.47508117$

$Y_{28} := 5.560665103$   
 $X_{28} := 8.432136769$   
 $k_1 := -37.53630349$   
 $Y_{29} := 8.452136769$   
 $X_{29} := 4.794366429$   
 $k_1 := 5.408081474$   
 $Y_{30} := 4.814366429$   
 $X_{30} := 8.565377582$   
 $k_1 := -46.77571143$   
 $Y_{31} := 8.585377582$   
 $X_{31} := 3.863297800$   
 $k_1 := -6.759370854$   
 $Y_{32} := 3.883297800$   
 $X_{32} := 8.450101766$   
 $k_1 := -39.16978965$   
 $Y_{33} := 8.470101766$   
 $X_{33} := 3.084304323$   
 $k_1 := -4.004936501$   
 $Y_{34} := 3.104304323$   
 $X_{34} := 8.387790282$   
 $k_1 := -35.05755242$   
 $Y_{35} := 8.407790282$   
 $X_{35} := 2.387629726$   
 $k_1 := 2.887030436$   
 $Y_{36} := 2.407629726$   
 $X_{36} := 8.463934625$   
 $k_1 := -40.46751224$   
 $Y_{37} := 8.483934625$   
 $X_{37} := 1.582665426$   
 $k_1 := 10.69134216$   
 $Y_{38} := 1.602665426$   
 $X_{38} := 8.698587544$   
 $k_1 := -56.20726744$   
 $Y_{39} := 8.718587544$

$X_{39} := 0.463300448$   
 $k_1 := 37.82888184$   
 $Y_{40} := 0.4833004480$   
 $X_{40} := 9.491729726$   
 $k_1 := -89.78924995$   
 $Y_{41} := 9.511729726$   
 $X_{41} := -1.318735880$   
 $k_1 := -13.99180421$   
 $Y_{42} := -1.298735880$   
 $X_{42} := 9.234146417$   
 $k_1 := -84.00607374$   
 $Y_{43} := 9.254146417$   
 $X_{43} := -2.989257941$   
 $k_1 := -15.02378461$   
 $Y_{44} := -2.969257941$   
 $X_{44} := 8.956719971$   
 $k_1 := -72.25757893$   
 $Y_{45} := 8.976719971$   
 $X_{45} := -4.428000983$   
 $k_1 := -9.555716522$   
 $Y_{46} := -4.408000983$   
 $X_{46} := 8.783057808$   
 $k_1 := -62.79976855$   
 $Y_{47} := 8.803057808$   
 $X_{47} := -5.678848360$   
 $k_1 := 23.43699145$   
 $Y_{48} := -5.658848360$   
 $X_{48} := 9.264500841$   
 $k_1 := -85.95250808$   
 $Y_{49} := 9.284500841$   
 $X_{49} := -7.387887271$   
 $k_1 := 22.01524613$   
 $Y_{50} := -7.367887271$   
 $X_{50} := 9.731887476$

$k_1 := -91.79247304$   
 $Y_{51} := 9.751887476$   
 $X_{51} := -9.205326247$   
 $k_1 := -84.82450419$   
 $Y_{52} := -9.185326247$   
 $X_{52} := 8.066406318$   
 $k_1 := -15.99552954$   
 $Y_{53} := 8.086406318$   
 $X_{53} := -9.519420735$   
 $k_1 := -91.91275182$   
 $Y_{54} := -9.499420735$   
 $X_{54} := 6.254174756$   
 $k_1 := 36.06045782$   
 $Y_{55} := 6.274174756$   
 $X_{55} := -8.773123594$   
 $k_1 := -62.62591037$   
 $Y_{56} := -8.753123594$   
 $X_{56} := 5.036637687$   
 $k_1 := 4.606291909$   
 $Y_{57} := 5.056637687$   
 $X_{57} := -8.655013093$   
 $k_1 := -54.95889854$   
 $Y_{58} := -8.635013093$   
 $X_{58} := 3.972902701$   
 $k_1 := -14.98389556$   
 $Y_{59} := 3.992902701$   
 $X_{59} := -8.934687051$   
 $k_1 := -71.32580797$   
 $Y_{60} := -8.914687051$   
 $X_{60} := 2.580280675$   
 $k_1 := -12.54610971$   
 $Y_{61} := 2.600280675$   
 $X_{61} := -9.168611257$   
 $k_1 := -81.88751680$

$Y_{62} := -9.148611257$   
 $X_{62} := 0.973979660$   
 $k_1 := -18.25289640$   
 $Y_{63} := 0.9939796600$   
 $X_{63} := -9.517248529$   
 $k_1 := -90.39991752$   
 $Y_{64} := -9.497248529$   
 $X_{64} := -0.8079869450$   
 $k_1 := 23.95950585$   
 $Y_{65} := -0.7879869450$   
 $X_{65} := -9.024229347$   
 $k_1 := -74.81613444$   
 $Y_{66} := -9.004229347$   
 $X_{66} := -2.271250889$   
 $k_1 := 4.603830496$   
 $Y_{67} := -2.251250889$   
 $X_{67} := -8.910905615$   
 $k_1 := -68.64370917$   
 $Y_{68} := -8.890905615$   
 $X_{68} := -3.610072545$   
 $k_1 := -6.702822280$   
 $Y_{69} := -3.590072545$   
 $X_{69} := -9.023813743$   
 $k_1 := -74.17497446$   
 $Y_{70} := -9.003813743$   
 $X_{70} := -5.060522935$   
 $k_1 := 12.29477956$   
 $Y_{71} := -5.040522935$   
 $X_{71} := -8.764225098$   
 $k_1 := -59.50430451$   
 $Y_{72} := -8.744225098$   
 $X_{72} := -6.215642202$   
 $k_1 := 41.35973467$   
 $Y_{73} := -6.195642202$



$X_{73} := -7.922643326$   
 $k_1 := -2.742356456$   
 $Y_{74} := -7.902643326$   
 $X_{74} := -6.237628298$   
 $k_1 := 41.40149969$   
 $Y_{75} := -6.217628298$   
 $X_{75} := -7.080075104$   
 $k_1 := 36.79218512$   
 $Y_{76} := -7.060075104$   
 $X_{76} := -5.478704475$   
 $k_1 := 23.39307660$   
 $Y_{77} := -5.458704475$   
 $X_{77} := -6.599662676$   
 $k_1 := 43.04671307$   
 $Y_{78} := -6.579662676$   
 $X_{78} := -4.600190541$   
 $k_1 := 0.491267122$   
 $Y_{79} := -4.580190541$   
 $X_{79} := -6.573716534$   
 $k_1 := 42.79622601$   
 $Y_{80} := -6.553716534$   
 $X_{80} := -3.726933510$   
 $k_1 := -8.060725190$   
 $Y_{81} := -3.706933510$   
 $X_{81} := -6.714144300$   
 $k_1 := 42.06210950$   
 $Y_{82} := -6.694144300$   
 $X_{82} := -2.866907608$   
 $k_1 := -3.241087772$   
 $Y_{83} := -2.846907608$   
 $X_{83} := -6.756641928$   
 $k_1 := 41.47305227$   
 $Y_{84} := -6.736641928$   
 $X_{84} := -2.018190537$

$k_1 := 4.913830540$   
 $Y_{85} := -1.998190537$   
 $X_{85} := -6.637609633$   
 $k_1 := 41.92158972$   
 $Y_{86} := -6.617609633$   
 $X_{86} := -1.161764630$   
 $k_1 := 11.92914436$   
 $Y_{87} := -1.141764630$   
 $X_{87} := -6.381115909$   
 $k_1 := 40.88139951$   
 $Y_{88} := -6.361115909$   
 $X_{88} := -0.3284827834$   
 $k_1 := 38.83241679$   
 $Y_{89} := -0.3084827834$   
 $X_{89} := -5.608285554$   
 $k_1 := 24.66745166$   
 $Y_{90} := -5.588285554$   
 $X_{90} := 0.1774306836$   
 $k_1 := -62.96020940$   
 $Y_{91} := 0.1974306836$   
 $X_{91} := -6.918326859$   
 $k_1 := 38.47225115$   
 $Y_{92} := -6.898326859$   
 $X_{92} := 0.9680237808$   
 $k_1 := -13.72113952$   
 $Y_{93} := 0.9880237808$   
 $X_{93} := -7.175412268$   
 $k_1 := 32.04167858$   
 $Y_{94} := -7.155412268$   
 $X_{94} := 1.633195382$   
 $k_1 := -8.928800093$   
 $Y_{95} := 1.653195382$   
 $X_{95} := -7.335688591$   
 $k_1 := 26.20779706$

```

Y96 := -7.315688591
X96 := 2.183722726
k1 := -9.443427122
Y97 := 2.203722726
X97 := -7.506971081
k1 := 18.57841876
Y98 := -7.486971081
X98 := 2.583783972
k1 := -11.45933492
Y99 := 2.603783972
X99 := -7.719076905
k1 := 7.339187916
Y100 := -7.699076905
X100 := 2.761492160

```

(6)

```
> # exact solution
```

```
> unassign('x','y');
```

```
ODE := diff(y(x), x) =  $\frac{2 \cdot y(x)}{x} + x^2 \cdot \cos(x)$ ;
```

```
ODE :=  $\frac{d}{dx} y(x) = \frac{2 y(x)}{x} + x^2 \cos(x)$ 
```

(7)

```
> ICs := y(1) = 0;
```

```
ICs := y(1) = 0
```

(8)

```
> sol := dsolve( {ODE, ICs}, y(x) )
```

```
sol := y(x) = (sin(x) - sin(1)) x2
```

(9)

```
> # Relative percent error between the obtained solution (
    for each set of coefficients) and the exact solution
```

```
> for i from 1 to n do:
```

```
    result :=  $\frac{\text{evalf}(\text{eval}(\text{rhs}(\text{sol}), x = X[i])) - Y[i]}{\text{evalf}(\text{eval}(\text{rhs}(\text{sol}), x = X[i]))} \cdot 100$ ;
```

```
    printf("%.8f%%\n", result);
```

```
end do:
```

```

1003025.12700000 %
99.52302104 %
12116.07991000 %
144.66293220 %
3698.49940400 %
104.71430640 %
11697.71564000 %
99.10934347 %
6667.93543900 %
106.78578190 %
-2662.23504100 %
191.75686040 %
-2497.94447000 %

```

9.11064887 %  
533.59451670 %  
14.76383924 %  
208.28772970 %  
-157.86130120 %  
143.48484670 %  
235.00285610 %  
122.46540300 %  
191.56933480 %  
115.89840180 %  
-160.13388010 %  
115.85816560 %  
43.26481846 %  
116.98911280 %  
2055.82279200 %  
120.00469480 %  
178.10244160 %  
138.29425170 %  
489.83082360 %  
213.53757140 %  
-127.38833510 %  
1039.76643000 %  
254.19402380 %  
-2037.48623600 %  
111.93662800 %  
10394.34960000 %  
100.59055780 %  
402.20113710 %  
97.66393408 %  
204.27143480 %  
90.51728974 %  
-286.80129600 %  
76.47505674 %  
199.89548330 %  
90.33111131 %  
109.80546750 %  
93.19844880 %  
110.86541910 %  
203.76018190 %  
111.94625230 %  
72.10029797 %  
105.62972890 %  
80.71660092 %  
104.39065120 %  
65.38124119 %  
103.81186570 %  
-333.08157740 %  
102.82527280 %  
-67142.26940000 %  
101.46486040 %  
-829.92944480 %  
99.21421898 %  
-8.68392379 %  
97.87312385 %  
-74.95074403 %  
96.42076017 %  
456.79876960 %

95.48998237 %  
70.75712873 %  
94.63292944 %  
74.48129273 %  
92.03187427 %  
-94.38699064 %  
89.12741268 %  
304.22989040 %  
90.60322995 %  
-63.26961451 %  
93.46968460 %  
26.80459543 %  
95.19353818 %  
5.11235414 %  
96.18401695 %  
-178.74340230 %  
97.01458736 %  
-4964.37545700 %  
95.47302473 %  
-26594.34156000 %  
100.28749640 %  
-41481.42783000 %  
101.18460640 %  
1813.22439100 %  
101.79643490 %  
-6427.37444600 %  
102.19458680 %  
-259.28626910 %  
102.38483020 %  
-114.60059220 %

