

# CAS 741: Module Interface Specification

Dynamical Systems: MPSim

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December 21, 2018

# 1 Revision History

Date	Version	Notes
November 26, 2018	1.0	First full draft for submission
December 17, 2018	2.0	All GitHub issues and comments addressed
December 18, 2018	3.0	MIS & bibliography fixed, & program name fixed

## 2 Symbols, Abbreviations and Acronyms

See SRS Documentation at:

<https://github.com/karolserkis/CAS-741-Pendula/blob/master/docs/SRS/SRS.pdf>

The symbols are listed in alphabetical order.

symbol	description
A	Assumption
DD	Data Definition
GD	General Definition
GS	Goal Statement
IM	Instance Model
LC	Likely Change
NF	Non-Functional Requirement
MIS	Module Interface Specification
PS	Physical System Description
R	Requirement
SRS	Software Requirements Specification
T	Theoretical Model

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### 3 Introduction

The following document details the Module Interface Specifications for the solution for a Multi-Pendulum Simulation ( MPSim ) program and tracking the chaotic motion of the system in a simulation.

Complementary documents include the System Requirement Specifications and Module Guide. The full documentation and implementation can be found at:

<https://github.com/karolserkis/CAS-741-Pendula>.

### 4 Notation

The structure of the MIS for modules comes from [Hoffman and Strooper \(1995\)](#), with the addition that template modules have been adapted from [Ghezzi et al. \(2003\)](#). The mathematical notation comes from Chapter 3 of [Hoffman and Strooper \(1995\)](#). For instance, the symbol  $:=$  is used for a multiple assignment statement and conditional rules follow the form  $(c_1 \Rightarrow r_1 | c_2 \Rightarrow r_2 | \dots | c_n \Rightarrow r_n)$ .

(Karol) I am also using <https://proofwiki.org/wiki/Symbols:R> for notation reference

The following table summarizes the primitive data types used by MPSim and the symbols used in this document. The choice of symbols was made to be consistent with calculus, ordinary differentials (ODE), the Lagrangian, kinematics etc. The standard mathematical spaces are used (e.g.  $\mathbb{N}$ ,  $\mathbb{Z}$ ,  $\mathbb{R}$ , etc.)

Data Type	Notation	Description
character	char	a single symbol or digit
integer	$\mathbb{Z}$	a number without a fractional component in $(-\infty, \infty)$
natural number	$\mathbb{N}$	a number without a fractional component in $[1, \infty)$
real	$\mathbb{R}$	any number in $(-\infty, \infty)$

The specification of MPSim uses some derived data types: sequences, strings, and tuples. Sequences are lists filled with elements of the same data type. Strings are sequences of characters. Tuples contain a list of values, potentially of different types. In addition, MPSim uses functions, which are defined by the data types of their inputs and outputs. Local functions are described by giving their type signature followed by their specification.

### 5 Module Decomposition

The following table is taken directly from the Module Guide document for this project.

Level 1	Level 2
Hardware-Hiding	
	MPSim Control Module
	MPSim GUI Module
	User Input Parameters Module
Behaviour-Hiding	Data Structure Module
	Generic Trajectory Simulation GUI Module
Software Decision	Generic GUI/Plot Module
	Lagrangian Module

Table 1: Module Hierarchy

## 6 MIS of MPSim Control Module (M2)

Execution flow of MPSim . Calls the different modules in the appropriate order. The general steps of the module are:

1. Read in and verify mps\_input.
2. Calculate Lagrangian module, iterate over the whole time frame (use data structure).
3. Generate a Plot
4. Return the trajectory plot output as per the output/simulation module specifications.

### 6.1 Module

mps\_control

### 6.2 Uses

mps\_gui (M3, Section 7)

mps\_input (M4, Section 8)

Processing modules: [\[what are processing modules? I'm not sure about this terminology —SS\]](#)

mps\_lagrang (M5, Section 9)

mps\_datastruct (M7, Section 11)

generic\_plot (M8, Section 12), mps\_trajplotsim (M9, Section 13)



## 6.3 Syntax

### 6.3.1 Exported Constants

None

### 6.3.2 Exported Access Programs

Name	In	Out	Exceptions
run_mps	int, str	None	None

## 6.4 Semantics

The MPSim is designed to have the input and initialization controlled by the user directly through the GUI. The MPSim Control Module uses the events in the MPSim GUI to use the processing modules in order.

### 6.4.1 State Variables

- mps\_input\_init : init (see Section 8)
- mps\_datastruct\_init : init (see Section 11)
- mps\_lagrang : calc (see Section 9)

[init is not a type, either is calc? How am I supposed to read this? State variables are specified as a name and a type. —SS]

### 6.4.2 Environment Variables

[This section is not necessary for all modules. Its purpose is to capture when the module has external interaction with the environment, such as for a device driver, screen interface, keyboard, file, etc. —SS]

### 6.4.3 Assumptions

[Try to minimize assumptions and anticipate programmer errors via exceptions, but for practical purposes assumptions are sometimes appropriate. —SS]

### 6.4.4 Access Routine Semantics

run\_mps(mps\_input) [This doesn't match the int, str specified above? —SS]:

- transition: The Multi Pendulum Simulation is initialized and the data structure is passed through the Lagrangian module for calculation (The result is then passed to the plot/simulation/output modules.)

- output: None [if appropriate —SS]
- exception: None [if appropriate —SS]

[A module without environment variables or state variables is unlikely to have a state transition. In this case a state transition can only occur if the module is changing the state of another module. —SS]

[Modules rarely have both a transition and an output. In most cases you will have one or the other. —SS]

#### **6.4.5 Local Functions**

[As appropriate —SS] [These functions are for the purpose of specification. They are not necessarily something that is going to be implemented explicitly. Even if they are implemented, they are not exported; they only have local scope. —SS]

[A new page between modules makes the document a more convenient reference document. —SS]

## 7 MIS of MPSim GUI (M3)

[Use labels for cross-referencing —SS]

[You can reference SRS labels, such as R??. —SS]

[It is also possible to use  $\LaTeX$  for hyper-links to external documents. —SS]

Methods to interact with user and display & run MPSim . Serves as interface between the user and the software through the hardware by outputting calculation results and collecting user information (user inputs) for the calculation modules.

### 7.1 Module

mps\_gui

### 7.2 Uses

mps\_datastruct (M7, Section 11)

generic\_plot (M8, Section 12), mps\_trajplotsim (M9, Section 13)

### 7.3 Syntax

#### 7.3.1 Exported Constants

None

#### 7.3.2 Exported Access Programs

Name	In	Out	Exceptions
mps_input	int, str	-	-
gui_trajsim	-	GUI object	-
gui_plot	-	GUI object (Poincaré)	-

### 7.4 Semantics

The MPSim process flow is initialized by user through the GUI. The user triggered the events that start the selected processing step.

#### 7.4.1 State Variables

None

### 7.4.2 Environment Variables

Plot\_TrajSim: GUI object

button\_Input: GUI object

button\_TrajSim: GUI object

[More words to describe these environment variables would be helpful. —SS]

[This section is not necessary for all modules. Its purpose is to capture when the module has external interaction with the environment, such as for a device driver, screen interface, keyboard, file, etc. —SS]

### 7.4.3 Assumptions

[Try to minimize assumptions and anticipate programmer errors via exceptions, but for practical purposes assumptions are sometimes appropriate. —SS]

### 7.4.4 Access Routine Semantics

mps\_input():

- transition: Trigger mps\_input when button\_Input pressed.
- output: [if appropriate —SS]
- exception: WarnOutOfBounds (warn when mps\_input are invalid) [if appropriate —SS]

gui\_trajsims():

- transition: Trigger gui\_trajsims when button\_TrajSim pressed.
- output: [if appropriate —SS]
- exception: [if appropriate —SS]

gui\_plot():

- transition: Trigger gui\_plot when button\_Poincaré pressed.
- output: [if appropriate —SS]
- exception: [if appropriate —SS]

[A module without environment variables or state variables is unlikely to have a state transition. In this case a state transition can only occur if the module is changing the state of another module. —SS]

[Modules rarely have both a transition and an output. In most cases you will have one or the other. —SS]

### 7.4.5 Local Functions

[As appropriate —SS] [These functions are for the purpose of specification. They are not necessarily something that is going to be implemented explicitly. Even if they are implemented, they are not exported; they only have local scope. —SS]

## 8 MIS of User Input Module (M4)

[Use labels for cross-referencing —SS]

[You can reference SRS labels, such as R??. —SS]

[It is also possible to use  $\LaTeX$  for hyperlinks to external documents. —SS]

The format and structure of the input data. Loads, verifies and stores the input data into the appropriate data and object structure.

### 8.1 Module

mps\_input

### 8.2 Uses

mps\_gui (M3, Section 7)

mps\_datastruct (M7, Section 11) [The modules in the uses section should actually be used in the specification. I don't see where these are actually invoked. —SS]

### 8.3 Syntax

#### 8.3.1 Exported Constants

None

#### 8.3.2 Exported Access Programs

Name	In	Out	Exceptions
verify_Input	int, str	-	-
data_struct	int, str	-	-
gui_trajsim	-	GUI object	-
gui_plot	-	GUI object	-

## 8.4 Semantics

### 8.4.1 State Variables

data : object

### 8.4.2 Environment Variables

Plot\_TrajSim: GUI object

[Describe this enviro variable. Are you taking the data fields from corresponding fields in the GUI object? —SS] [You have really integrated the GUI into your design. It is better if you almost don't mention the GUI with the idea that the modules can be implemented by any interface. Maybe a model view controller pattern would work in your case? —SS]

[This section is not necessary for all modules. Its purpose is to capture when the module has external interaction with the environment, such as for a device driver, screen interface, keyboard, file, etc. —SS]

### 8.4.3 Assumptions

[Try to minimize assumptions and anticipate programmer errors via exceptions, but for practical purposes assumptions are sometimes appropriate. —SS]

### 8.4.4 Access Routine Semantics

verify\_Input():

- transition: [if appropriate —SS]
- output: [if appropriate —SS]
- exception: Check if positive integer

data\_struct(mps\_input):

- transition: mps\_input is the user input that is entered into the GUI. The input is used to initialize the data structure. [What is the data structure? The MIS is where you make decisions about this. —SS]
- output: [if appropriate —SS]
- exception: [if appropriate —SS]

gui\_trajsim(mps\_datastruct, mps\_input):

- transition: mps\_datastruct is a module that takes the mps\_input and thus the program gui\_trajsim will be prepared for the Lagrangian and Hamiltonian calculations done by their corresponding modules.

- output: [if appropriate —SS]
- exception: [if appropriate —SS]

`gui_plot(mps_datastruct, mps_input):`

- transition: `mps_datastruct` is a module that takes the `mps_input` and thus the program `gui_plot` will be prepared for the Lagrangian calculations done by their corresponding modules.
- output: [if appropriate —SS]
- exception: [if appropriate —SS]

[A module without environment variables or state variables is unlikely to have a state transition. In this case a state transition can only occur if the module is changing the state of another module. —SS]

[Modules rarely have both a transition and an output. In most cases you will have one or the other. —SS]

#### 8.4.5 Local Functions

[As appropriate —SS] [These functions are for the purpose of specification. They are not necessarily something that is going to be implemented explicitly. Even if they are implemented, they are not exported; they only have local scope. —SS]

## 9 MIS of Lagrangian Module (M5)

[Use labels for cross-referencing —SS]

[You can reference SRS labels, such as R??. —SS]

[It is also possible to use L<sup>A</sup>T<sub>E</sub>X for hyperlinks to external documents. —SS]

Lagrangian calculation/algorithm. Calculates the variation of Lagrangian for each pendulum in the chain (each element of the array).

### 9.1 Module

`mps_lagrang`

### 9.2 Uses

`mps_input` (M4, Section 8)

Processing modules:

`mps_lagrang` (M5, Section 9)

mps\_datastruct (M7, Section 11)

## 9.3 Syntax

### 9.3.1 Exported Constants

None

### 9.3.2 Exported Access Programs

Name	In	Out	Exceptions
mps_input	int	-	-
calc_lagrang	int	float(python)	-

## 9.4 Semantics

### 9.4.1 State Variables

### 9.4.2 Environment Variables

[This section is not necessary for all modules. Its purpose is to capture when the module has external interaction with the environment, such as for a device driver, screen interface, keyboard, file, etc. —SS]

### 9.4.3 Assumptions

[Try to minimize assumptions and anticipate programmer errors via exceptions, but for practical purposes assumptions are sometimes appropriate. —SS]

### 9.4.4 Access Routine Semantics

mps\_input():

- transition: mps\_input passed to calc\_lagrang (which in turn the module utilizes mps\_datastruct).
- output: [if appropriate —SS]
- exception: WarnOutOfBounds (warn when mps\_input are invalid) [if appropriate —SS]

calc\_lagrang(mps\_input):

- transition: Utilizing the mps\_datastruct the mps\_input is calculated and passed to the gui\_trajsim and gui\_plot [if appropriate —SS]
- output: To gui\_trajsim and gui\_plot [if appropriate —SS]



- exception: WarnOutOfBounds (warn when mps\_input are invalid) [if appropriate —SS]

[A module without environment variables or state variables is unlikely to have a state transition. In this case a state transition can only occur if the module is changing the state of another module. —SS]

[Modules rarely have both a transition and an output. In most cases you will have one or the other. —SS]

#### 9.4.5 Local Functions

[As appropriate —SS] [These functions are for the purpose of specification. They are not necessarily something that is going to be implemented explicitly. Even if they are implemented, they are not exported; they only have local scope. —SS]

[For the Lagrangian and Hamiltonian modules, I expected to see equations, like those from your SRS. —SS]

## 10 MIS of Data Structure Module (M7)

[Use labels for cross-referencing —SS]

[You can reference SRS labels, such as R??. —SS]

[It is also possible to use  $\LaTeX$  for hyperlinks to external documents. —SS]

Data format for an image. Provides convenient format to store, read and manipulate all OpenGL elements. Also the points to plot on a graph (where the image is constructed by an python libraries).

### 10.1 Module

mps\_datastruct

### 10.2 Uses

mps\_gui (M3, Section 7)

mps\_input (M4, Section 8)

Processing modules:

mps\_lagrang (M5, Section 9)

mps\_datastruct (M7, Section 11)

## 10.3 Syntax

### 10.3.1 Exported Constants

None

### 10.3.2 Exported Access Programs

Name	In	Out	Exceptions
calc_lagrang	int, str	long, str	-
calc_hamil	long, str	long, str	-
mps_gui	GUI object	-	-

## 10.4 Semantics

### 10.4.1 State Variables

[the data structure doesn't have state variables? —SS]

### 10.4.2 Environment Variables

Plot\_TrajSim: GUI object

Plot\_Poincaré: GUI object

[Why does the data structure use gui objects? As mentioned previously, the GUI connects to too many modules. Most modules should be independent of the interface. —SS]

[This section is not necessary for all modules. Its purpose is to capture when the module has external interaction with the environment, such as for a device driver, screen interface, keyboard, file, etc. —SS]

### 10.4.3 Assumptions

[Try to minimize assumptions and anticipate programmer errors via exceptions, but for practical purposes assumptions are sometimes appropriate. —SS]

### 10.4.4 Access Routine Semantics

calc\_lagrang(mps\_input):

- transition: Utilizing the mps\_datastruct the mps\_input is calculated and passed to the gui\_trajsim and gui\_plot [if appropriate —SS]
- output: To gui\_trajsim and gui\_plot [if appropriate —SS]
- exception: WarnOutOfBounds (warn when mps\_input are invalid) [if appropriate —SS]

calc\_hamil(mps\_input):

- transition: Utilizing the mps\_datastruct the mps\_input is calculated and passed to the gui\_trajsim and gui\_plot [if appropriate —SS]
- output: To gui\_trajsim and gui\_plot [if appropriate —SS]
- exception: WarnOutOfBounds (warn when mps\_input are invalid) [if appropriate —SS]

mps\_gui(mps\_datastruct, gui\_trajsim, gui\_plot):

- transition: Utilizing the mps\_datastruct the mps\_input is calculated and passed to the gui\_trajsim and gui\_plot and thus the program gui\_trajsim will be prepared for the Lagrangian and Hamiltonian calculations done by their corresponding modules.
- output: To gui\_trajsim and gui\_plot [if appropriate —SS]
- exception: WarnOutOfBounds (warn when mps\_input are invalid) [if appropriate —SS]

[A module without environment variables or state variables is unlikely to have a state transition. In this case a state transition can only occur if the module is changing the state of another module. —SS]

[Modules rarely have both a transition and an output. In most cases you will have one or the other. —SS]

#### 10.4.5 Local Functions

[As appropriate —SS] [These functions are for the purpose of specification. They are not necessarily something that is going to be implemented explicitly. Even if they are implemented, they are not exported; they only have local scope. —SS]

## 11 MIS of Generic GUI/Plot Module (M8)

[Use labels for cross-referencing —SS]

[You can reference SRS labels, such as R??. —SS]

[It is also possible to use L<sup>A</sup>T<sub>E</sub>X for hyperlinks to external documents. —SS]

Generic methods to interact with the user. Provides the generic interface methods such as buttons, windows, plotting, entry fields to interact with a user.

### 11.1 Module

generic\_plot

## 11.2 Uses

Hardware-Hiding (M1)

## 11.3 Syntax

### 11.3.1 Exported Constants

None

### 11.3.2 Exported Access Programs

Name	In	Out	Exceptions
gui_trajsim	GUI object	GUI object	-
gui_plot	GUI object	GUI object	-

## 11.4 Semantics

### 11.4.1 State Variables

### 11.4.2 Environment Variables

Plot\_TrajSim: GUI object

[This section is not necessary for all modules. Its purpose is to capture when the module has external interaction with the environment, such as for a device driver, screen interface, keyboard, file, etc. —SS]

### 11.4.3 Assumptions

[Try to minimize assumptions and anticipate programmer errors via exceptions, but for practical purposes assumptions are sometimes appropriate. —SS]

### 11.4.4 Access Routine Semantics

gui\_trajsim():

- transition: [if appropriate —SS]
- output: To mps\_gui(mps\_datastruct, gui\_trajsim, gui\_plot) or the generic\_plot module [if appropriate —SS]
- exception: WarnOutOfBounds (warn when gui\_trajsim are invalid) [if appropriate —SS]

gui\_plot(mps\_datastruct, mps\_input):

- transition: `mps_datastruct` is a module that takes the `mps_input` and thus the program `gui_plot` will be prepared for the Lagrangian and Hamiltonian calculations done by their corresponding modules.
- output: [if appropriate —SS] [if it isn't appropriate, you should remove this field. —SS]
- exception: [if appropriate —SS]

[A module without environment variables or state variables is unlikely to have a state transition. In this case a state transition can only occur if the module is changing the state of another module. —SS]

[Modules rarely have both a transition and an output. In most cases you will have one or the other. —SS]

#### 11.4.5 Local Functions

[As appropriate —SS] [These functions are for the purpose of specification. They are not necessarily something that is going to be implemented explicitly. Even if they are implemented, they are not exported; they only have local scope. —SS]

## 12 MIS of Trajectory Simulation Module (M9)

[Use labels for cross-referencing —SS]

[You can reference SRS labels, such as R??. —SS]

[It is also possible to use  $\LaTeX$  for hyperlinks to external documents. —SS]

Algorithm to simulate the plot trajectory of the chain of pendula. Simulates the chain of pendula in space using the Lagrangian and the Hamiltonian.

### 12.1 Module

`mps_trajplotsim`

### 12.2 Uses

`mps_gui` (M3, Section 7)

`mps_input` (M4, Section 8)

Processing modules:

`mps_lagrang` (M5, Section 9), `mps_hamil` (M6, Section 10)

## 12.3 Syntax

### 12.3.1 Exported Constants

None

### 12.3.2 Exported Access Programs

Name	In	Out	Exceptions
MPS_trajsim	GUI object	GUI object	WarnOutOfBounds

## 12.4 Semantics

### 12.4.1 State Variables

data : object

### 12.4.2 Environment Variables

Plot\_TrajSim: GUI object

[This section is not necessary for all modules. Its purpose is to capture when the module has external interaction with the environment, such as for a device driver, screen interface, keyboard, file, etc. —SS]

### 12.4.3 Assumptions

[Try to minimize assumptions and anticipate programmer errors via exceptions, but for practical purposes assumptions are sometimes appropriate. —SS]

### 12.4.4 Access Routine Semantics

MPS\_trajsim():

- transition:
  1. Read in and verify mps\_input.
  2. Calculate Lagrangian module calc\_lagrang, iterate over the whole time frame (use data structure).
  3. Calculate Hamiltonian module calc\_hamil, iterate over the whole time frame (use data structure).
  4. Return the trajectory plot output as per the output/simulation module specifications.
- output: [if appropriate —SS]

- exception: WarnOutOfBounds (warn when mps\_input or calculations of the data structure are invalid) [if appropriate —SS]

[A module without environment variables or state variables is unlikely to have a state transition. In this case a state transition can only occur if the module is changing the state of another module. —SS]

[Modules rarely have both a transition and an output. In most cases you will have one or the other. —SS]

#### **12.4.5 Local Functions**

[As appropriate —SS] [These functions are for the purpose of specification. They are not necessarily something that is going to be implemented explicitly. Even if they are implemented, they are not exported; they only have local scope. —SS]

## References

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