

# Scaling/Approximation (Denn Chapter 11 and 14)

## LEARNING OBJECTIVES

1. Scale conservation equations. Analyze scaled equation.
2. Solve and analyze inviscid flow problems using stream functions and potential flows.

## MOTIVATION

Throughout this course we've encountered situations where an approximation has simplified our problem solving and analysis. Examples?

As a corollary, we should be able to rewrite our conservation equations (e.g. Navier-Stokes) in a form approximate to the situation. Hopefully, a solution to the approximate equations is an approximate solution.

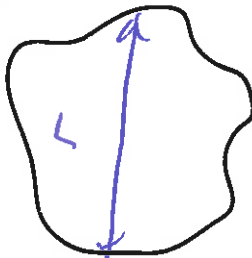
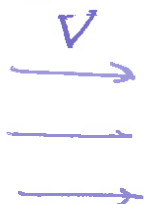
## REWRITING NAVIER-STOKES EQUATIONS (CHAPTER 11)

Consider Steady Navier-Stokes Equation:

$$\rho \underline{\mathbf{v}} \cdot \nabla \underline{\mathbf{v}} = -\nabla \mathcal{P} + \eta \nabla^2 \underline{\mathbf{v}}$$

family  $\mathcal{P}$  - bundle is gravity  
"modified"

And a general flow past an object problem:



$V$  = characteristic velocity

$L$  = characteristic length

Re-write the Navier Stokes problems in terms of the "Scaled Variables"

- dimensionless

• Scales are chosen such that new variables are the order of magnitude 1  
O(1)

## SCALING OUR VARIABLES

We can rescale our variables appropriately:

Scaled velocity  $\tilde{\mathbf{v}} = \mathbf{v}/V$ e.g.  $\tilde{v}_x = v_x/V$ ,  $\tilde{v}_y = v_y/V$ , etc.Scaled coordinate  $\tilde{\mathbf{x}} = \mathbf{x}/L$ e.g.  $\tilde{x} = x/L$ ,  $\tilde{y} = y/L$ , etc.What about pressure?  $\tilde{\mathcal{P}} = \mathcal{P}/\Pi$ characteristic pressure  
(will determine later)

Typical Inertial Term

$$\rho v_x \frac{\partial v_y}{\partial x} \quad v_x = \tilde{v}_x V \quad v_y = \tilde{v}_y V \quad x = \tilde{x} L$$

Plug in...

$$\rho (\tilde{v}_x V) \frac{\partial (\tilde{v}_y V)}{\partial (\tilde{x} L)} = \frac{\rho V^2}{L} \tilde{v}_x \frac{\partial \tilde{v}_y}{\partial \tilde{x}}$$

As a result we can rewrite the right side of N-S as

$$\text{inertial term} \quad \rho \underline{\mathbf{v}} \cdot \underline{\nabla} \underline{\mathbf{v}} \Rightarrow \frac{\rho V^2}{L} \underline{\tilde{\mathbf{v}}} \cdot \underline{\tilde{\nabla}} \underline{\tilde{\mathbf{v}}} \quad \text{inertial term}$$

$$(\underline{\tilde{\nabla}} = \hat{i} \partial / \partial \tilde{x} + \hat{j} \partial / \partial \tilde{y} + \hat{k} \partial / \partial \tilde{z})$$

Now for the viscous term:

$$\eta \frac{\partial^2 v_x}{\partial y^2} \quad v_x = \tilde{v}_x V \quad y = \tilde{y} L$$

Plug in...

$$= \eta \frac{\partial^2 (\tilde{v}_x V)}{\partial (\tilde{y} L)^2} = \frac{\eta V^2}{L^2} \frac{\partial^2 \tilde{v}_x}{\partial \tilde{y}^2}$$

And pressure:

$$\frac{\partial \mathcal{P}}{\partial x} \quad \mathcal{P} = \tilde{\mathcal{P}} \Pi \quad x = \tilde{x} L$$

Plug in...

$$\frac{\partial \mathcal{P}}{\partial x} = \Pi / L \frac{\partial \tilde{\mathcal{P}}}{\partial \tilde{x}} \quad \underline{\nabla} \mathcal{P} \rightarrow \frac{\Pi}{L} \underline{\tilde{\nabla}} \tilde{\mathcal{P}}$$

Rewrite our Navier-Stokes Equation:

$$\frac{\rho V^2}{L} \tilde{\mathbf{v}} \cdot \tilde{\nabla} \tilde{\mathbf{v}} = -\frac{\pi}{L} \tilde{\nabla} \tilde{p} + \frac{\mu V}{L^2} \tilde{\nabla}^2 \tilde{\mathbf{v}}$$

If variables are properly scaled, then all dimensionless terms are  $O(1)$  quantities.

⇒ relative importance of terms is revealed by what's out in front:

In particular, 
$$\frac{\text{inertial terms}}{\text{viscous terms}} = \frac{\rho V^2/L}{\mu V/L^2} = \frac{\rho V L}{\mu}$$

This provides basis for approximations.

When  $Re \gg 1$ , expect inertia  $\gg$  viscous forces

⇒ Approximate by neglecting viscosity

⇒ Inviscid flow ←

When  $Re \ll 1$ , expect viscous  $\gg$  inertial forces

⇒ Approximate by neglecting inertia

⇒ Creeping flow

What about pressure? must keep it in equations to maintain eq/unknown balances

When inertial terms dominate (high  $Re$ ), pressure balances inertia term

$$\frac{\rho V^2}{L} \sim \frac{\pi}{L} \Rightarrow \Pi = \frac{\text{char. pressure}}{\rho V^2} = 1 \quad \text{Bernoulli's eq}$$

When viscous terms dominate (low  $Re$ ), pressure balances viscous term

$$\frac{\mu V}{L^2} \sim \frac{\pi}{L} \Rightarrow \Pi = \frac{\pi}{\mu V/L} = 1$$

Thus, for High Reynold's Number (inertial dominated) flow, we can write:

$$\tilde{\mathbf{v}} \cdot \tilde{\nabla} \tilde{\mathbf{v}} = -\tilde{\nabla} \tilde{\mathcal{P}} + \frac{1}{\text{Re}} \tilde{\nabla}^2 \tilde{\mathbf{v}} \Rightarrow \rho \frac{D\mathbf{v}}{Dt} = -\nabla p \quad \left( \begin{array}{l} \text{Euler's} \\ \text{eq} \end{array} \right)$$

Thus, for Low Reynold's Number (viscous dominated) flow, we can write:

$$\text{Re}(\tilde{\mathbf{v}} \cdot \tilde{\nabla} \tilde{\mathbf{v}}) = -\tilde{\nabla} \tilde{\mathcal{P}} + \tilde{\nabla}^2 \tilde{\mathbf{v}} \Rightarrow -\nabla p + \eta \nabla^2 \mathbf{v}$$

We hope that solutions of the approximation equations is an approximate solution to the problem. (Denn 11.6)

### High Re

"large"  $V, L$

"small"  $\nu$

- every day fluid mech.
- process  $\rightarrow$  pipes, pumps, flow meters
- planes, cars, boats...
- sports (golf, tennis, baseball)

### Low Re

- small  $V, L$

- large  $\nu$

- highly viscous materials (polymers, foods)
- microscop. phenomena (e.g. settling of particles)

## HIGH REYNOLD'S NUMBER (INVISCID FLOW)

*ignore viscosity*

$$Re = \frac{Dv\rho}{\eta} \Rightarrow \rho \frac{Dv}{Dt} = -\nabla p \quad (\text{Euler's eq. of motion})$$

However, we face some challenges with this equation. Need to define some other concepts before solving inviscid flow solutions. In particular, we seek Potential Flows (Denn Chp. 14).

## STREAM FUNCTION (CHAPTER 14)

Useful in 2-D flow (e.g.  $v_x(x, y)$ ,  $v_y(x, y)$ , and  $v_z = 0$ )

Case without a Stream function:

$$\left. \begin{array}{l} v_x(x, y) \\ v_y(x, y) \\ \mathcal{P}(x, y) \end{array} \right\} \begin{array}{l} 3 \text{ unknowns; } 3 \text{ eqs} - \text{continuity} \\ \text{continuity: } \partial v_x / \partial x + \partial v_y / \partial y = 0 \\ x, y \text{ components of } \mathbf{u} \end{array}$$

Define Stream Function,  $\Psi(x, y)$ :

$$\boxed{\begin{array}{l} v_x(x, y) = -\partial \Psi / \partial y \\ v_y(x, y) = \partial \Psi / \partial x \end{array}}$$

Plug into continuity:

$$\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} = \frac{\partial}{\partial x}(-\partial \Psi / \partial y) + \frac{\partial}{\partial y}(\partial \Psi / \partial x) = 0 \quad \text{continuity automatically satisfied}$$

Now we have

$$\left. \begin{array}{l} \Psi(x, y) \\ \mathcal{P}(x, y) \end{array} \right\} \begin{array}{l} 2 \text{ unknowns; } 2 \text{ eqs} \\ (N=5 \text{ to } x, y) \end{array}$$

In steady flow, the stream function doesn't change along the streamline. We can prove this by taking the substantial derivative:

$$\underbrace{\frac{D\Psi}{Dt}}_{\text{on 2-D, steady flow}} = v_x \frac{\partial \Psi}{\partial x} + v_y \frac{\partial \Psi}{\partial y} = -\frac{\partial \Psi}{\partial y} \frac{\partial \Psi}{\partial x} + \frac{\partial \Psi}{\partial x} \frac{\partial \Psi}{\partial y} = 0$$

For cylindrical coordinates:

$$v_r = -\frac{1}{r} \frac{\partial \Psi}{\partial \theta} \quad v_\theta = \frac{\partial \Psi}{\partial r} \\ (v_z = 0)$$