

Norkart - KartAI project

...

TDT4290 - Customer-driven development

Group 7

Introduction

- KartAI
- Norkart
 - Alexander Salveson Nossum
 - Håvard Watland
- Kristiansand Municipality
 - Eva Høksaas
 - Dagfinn Øksendal

Team

Group contract

- Align expectations
- Establish group norms

Group dynamics

- Inclusiveness, cohesion & collaboration

Teambuilding

- Initial group dinner
- AI workshop
- Trip to Kristiansand



Team Structure



Johanne Eide Omland
Team Leader



Magnus Andreas Giverin
Deputy Leader



Sverre Nystad
AI Lead



Andreas Lilleby Hjulstad
System Architect



Artemis Kjøllmoen Aarø
Team Product Owner



Maurice Wegerif
Report Lead

Project proposal

“The project goal is to **develop a full stack web based system** that **integrates** and **further develops the different “AI assistants”** in a **user friendly** application tailored to the work process and technical knowhow of both **case workers, citizens and companies** involved in the building permit application process.”

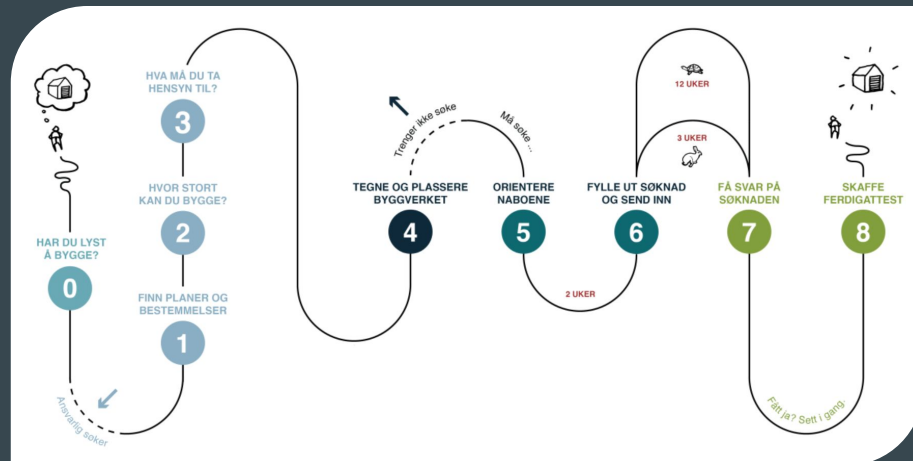
- Alexander Salveson Nossun, Norkart Project Proposal document for TDT4290

Project motivation

1. Reduce number of errors in building permit applications
 2. Make the building permit application handling more efficient with digital tools
 3. Bridge and test AI technologies in a human centric software system
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Problem Space

- Preliminary Research
- 6 interviews with municipal case workers
- Cataloguing **needs** vs. **wants**
 - Tools for applicants
 - Tools for municipal case workers
- **Before, during, and after** application



Solution Space

Explorative design

First proposal:

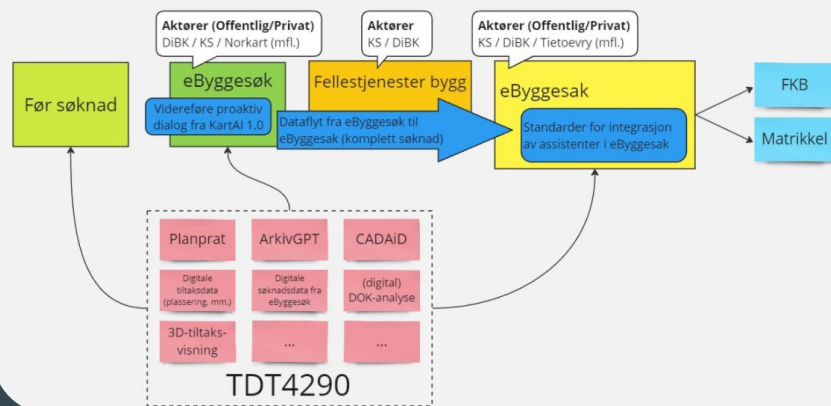
- Integrate into existing **eByggesøk** solution

Final scope:

- Proof-of-concept
- Three stages
- **Figma** user tests

Expanded scope - AI summary assistant

KartAI 2.0 | Aktiviteter relatert byggesaker



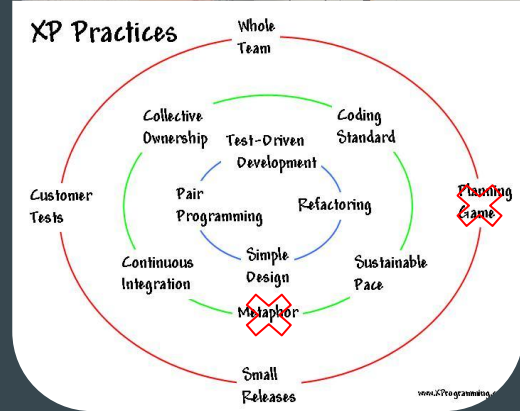
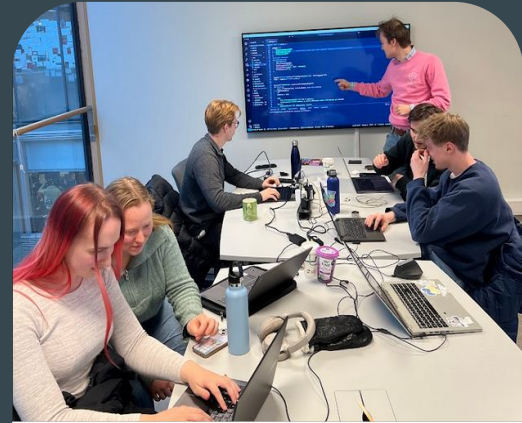
Development Methodology

Scrum

- Sprint planning
- Sprint retrospectives
- Daily standup

Extreme Programming (XP)

- Test-driven development
 - Continuous refactoring
- Pair programming



Final Product

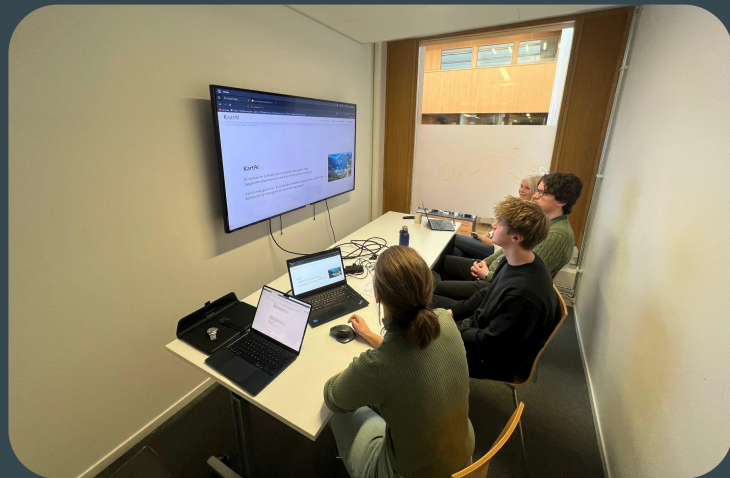
Two parts - **Web application** and **AI assistant API**

1. Web application

- **User tests** on **live demo** to ensure **usability**

2. AI Summary Assistant

- **Summarizes** applications
- **Validating** applications against official checklists, laws, and regulations
- **AI Innovation:** Combining new Agent architectures
 - CRAG and Reflexion



Demo



Kristiansand
kommune

Self-Evaluation

Solution

- Incomplete requirements
- Security

Sustainability

- Technical, social & environmental sustainability

Internal Processes

- Cohesion in the team was essential
- Proactive meeting scheduling needed improvement

User testing

- Last user testing came close to the delivery date
- Clearly specifying that it was a PoC
- Diversity - 5 women and 3 men aged 20-60+

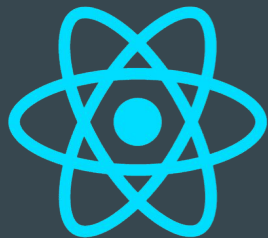


Q&A

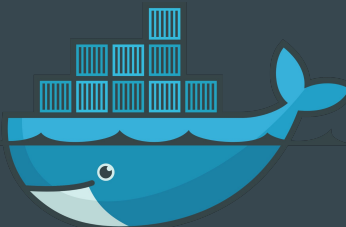
- **"Any questions?"**
- Discussion and feedback.

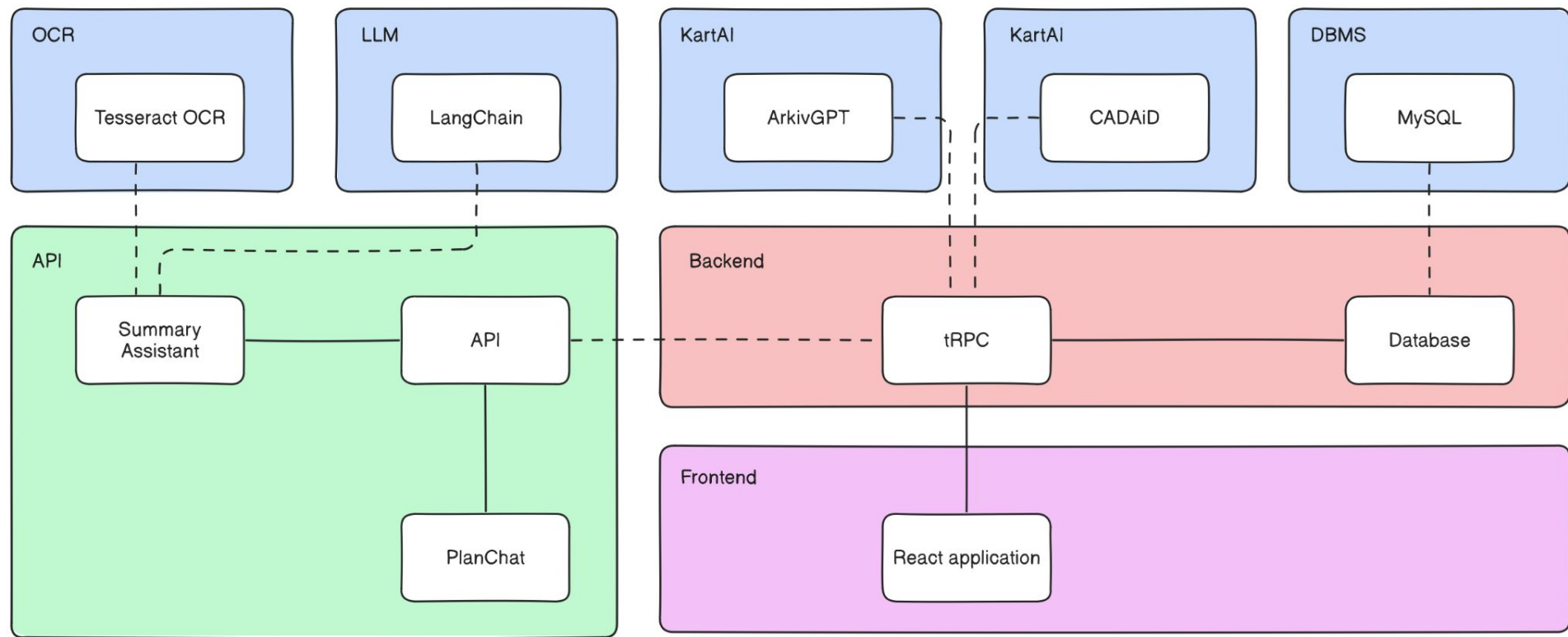
Technologies

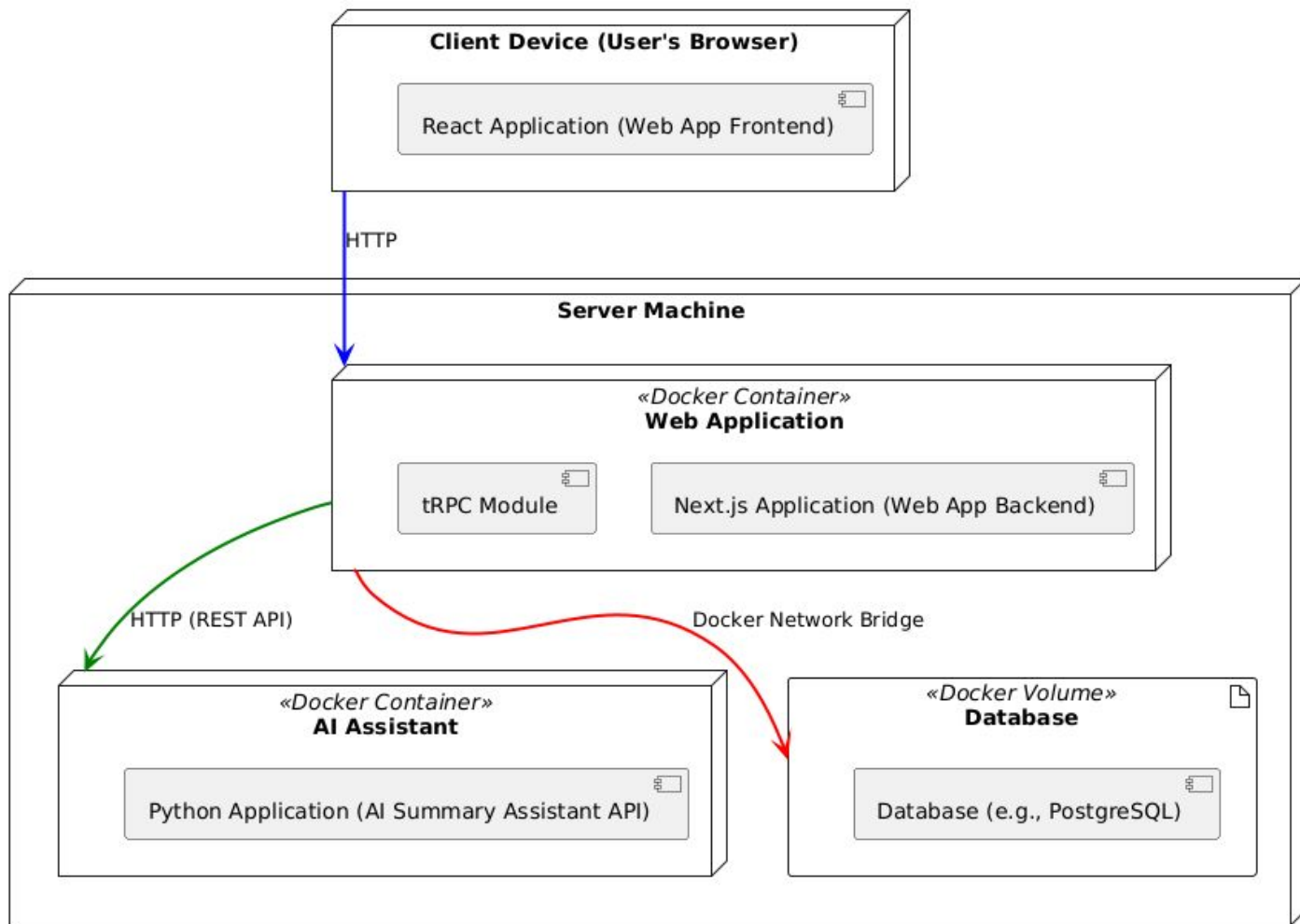
Web application:

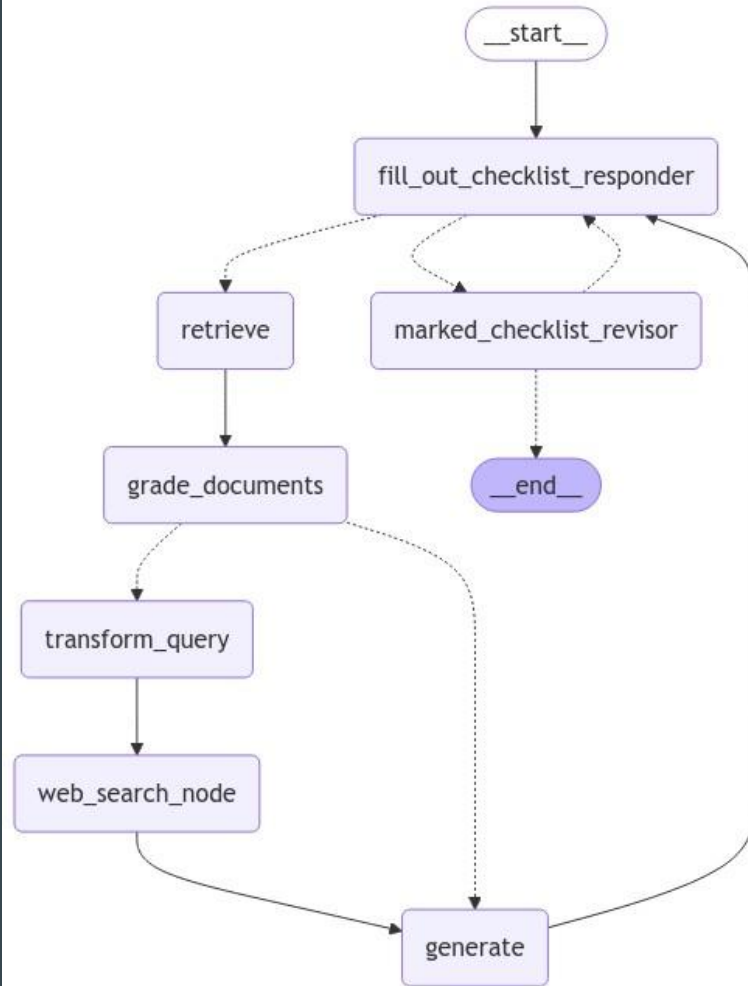


AI Summary Assistant:









Retrieval

x : Who was the screenwriter for *Death of a Batman*?

Retrieved Documents

d_1

d_2

Knowledge Correction

Retrieval Evaluator

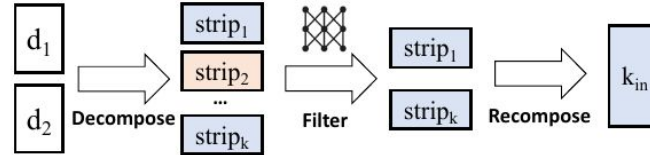
Ask: If retrieved documents are correct to x ?

Correct

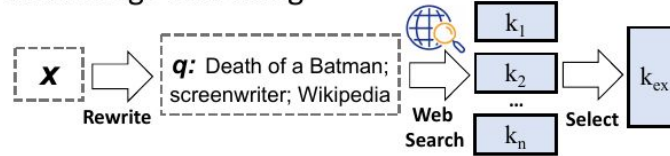
Ambiguous

Incorrect

Knowledge Refinement



Knowledge Searching



Generation

Correct

Ambiguous

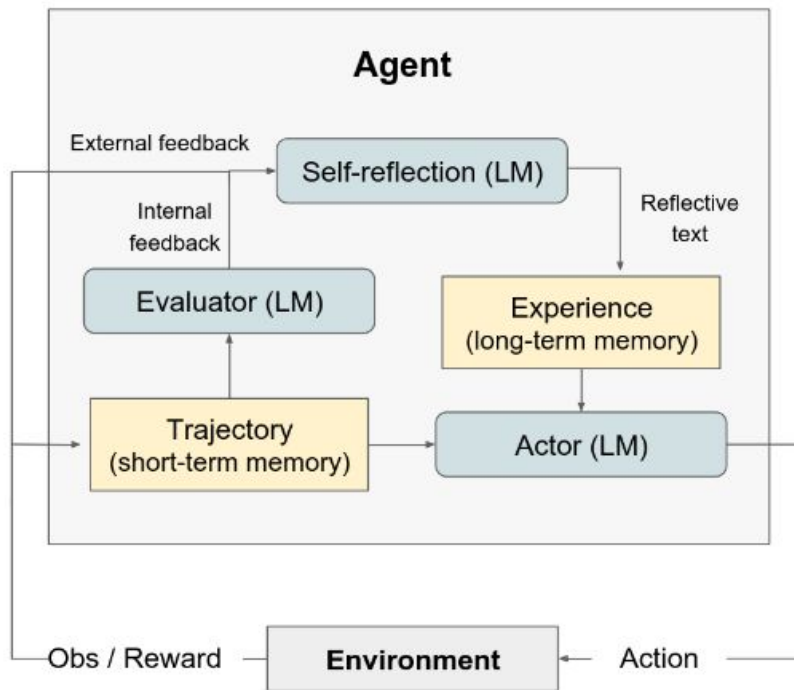
Incorrect

x + k_{in}

x + k_{in} + k_{ex}

x + k_{ex}

Generator



Algorithm 1 Reinforcement via self-reflection

Initialize Actor, Evaluator, Self-Reflection:

M_a, M_e, M_{sr}

Initialize policy $\pi_\theta(a_i|s_i), \theta = \{M_a, mem\}$

Generate initial trajectory using π_θ

Evaluate τ_0 using M_e

Generate initial self-reflection sr_0 using M_{sr}

Set $mem \leftarrow [sr_0]$

Set $t = 0$

while M_e not pass or $t < \text{max trials}$ **do**

 Generate $\tau_t = [a_0, o_0, \dots a_i, o_i]$ using π_θ

 Evaluate τ_t using M_e

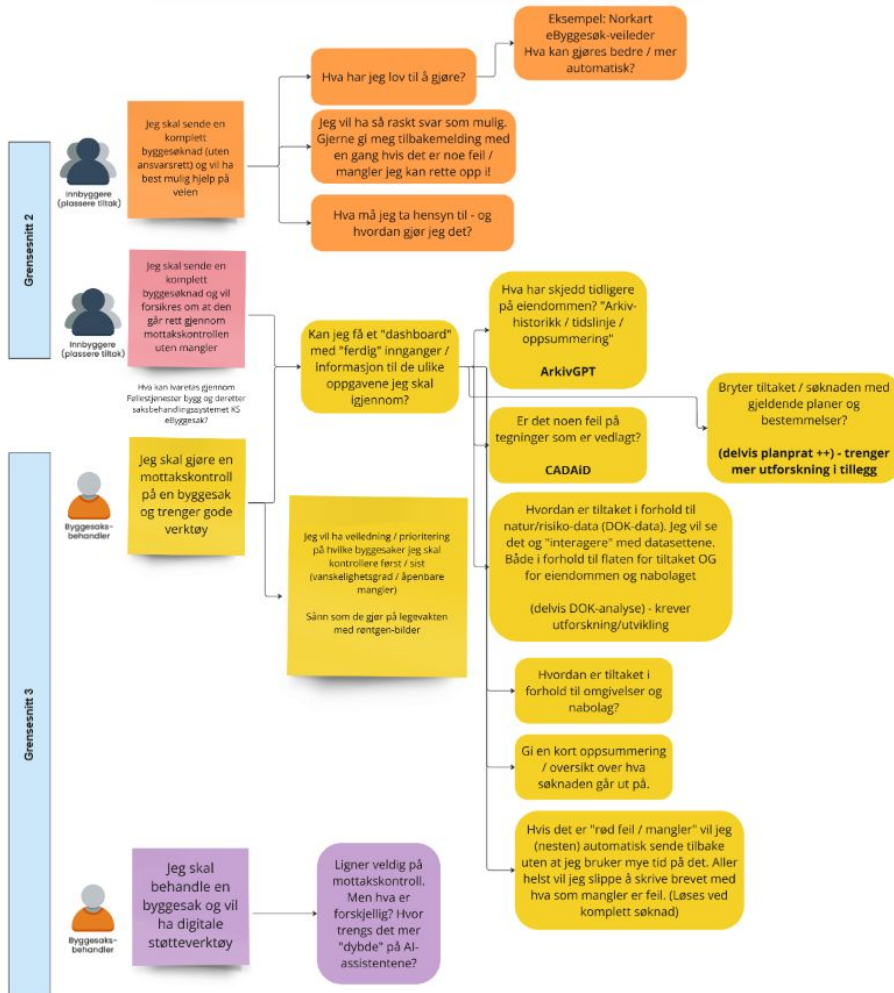
 Generate self-reflection sr_t using M_{sr}

 Append sr_t to mem

 Increment t

end while

return



Burndown Chart

