

A decorative graphic on the left side of the slide. It consists of a blue parallelogram and a light green parallelogram, both tilted at an angle. The blue shape is in the foreground, and the green shape is partially behind it. They are set against a dark blue background with faint, lighter blue diagonal stripes.

# Data Structures & Algorithms



# Who Are We?

- Ben Banavige
- Karthik Garimella
- ESDIS -> 586 -> Jupyter Notebooks for Earth Science

## Karthenjamin

- <https://github.com/karthenjamin>



# Outline

- Big O notation
- Graph Theory
- Dijkstra's Shortest Paths Algorithm
  - Different implementation -> Effect on Big O

# Big O Notation

- Performance of an algorithm

1	5	12	32	67	82	93	109
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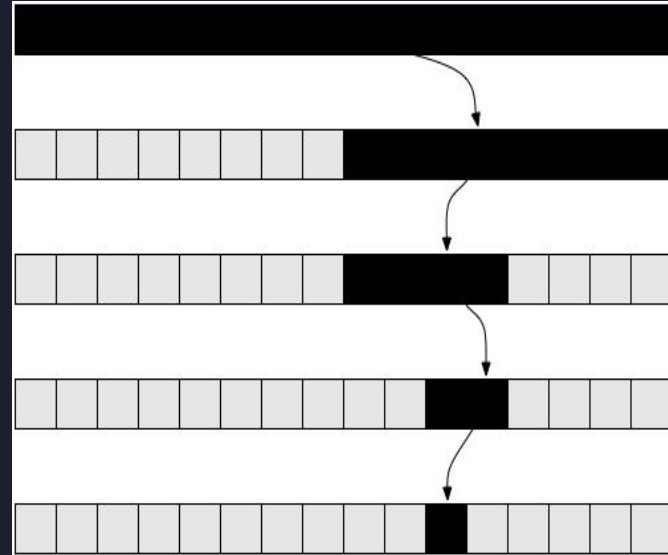
1	5	12	32	67	82	93	109
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1	5	12	32	67	82	93	109
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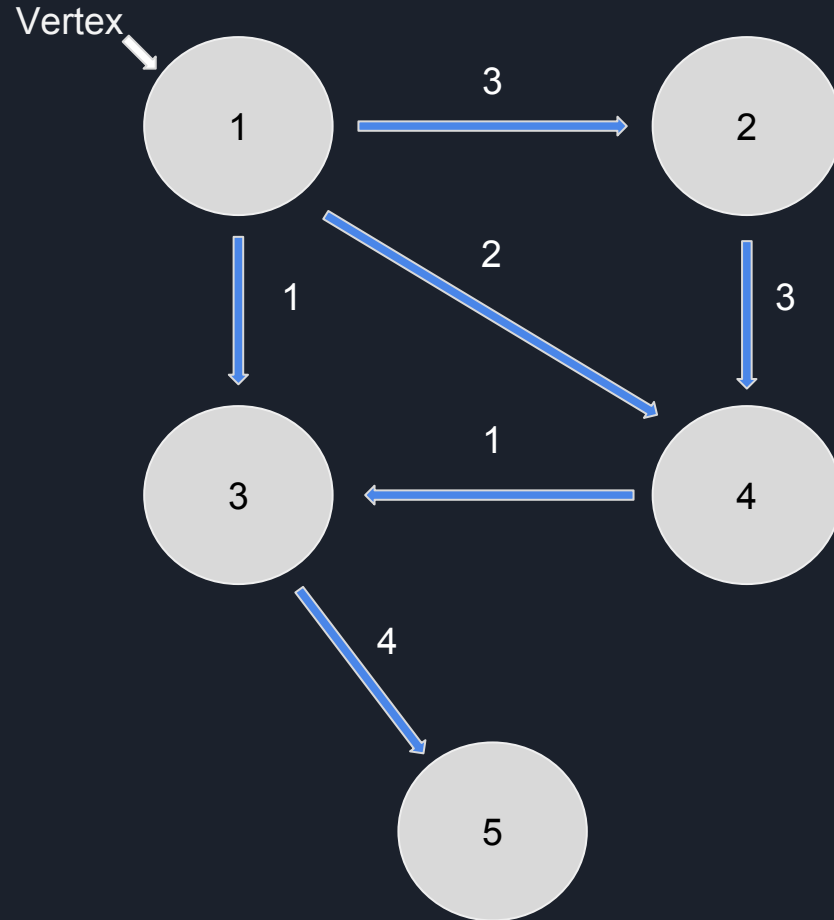
$O(n)$



$O(\log(n))$

# Graph Theory

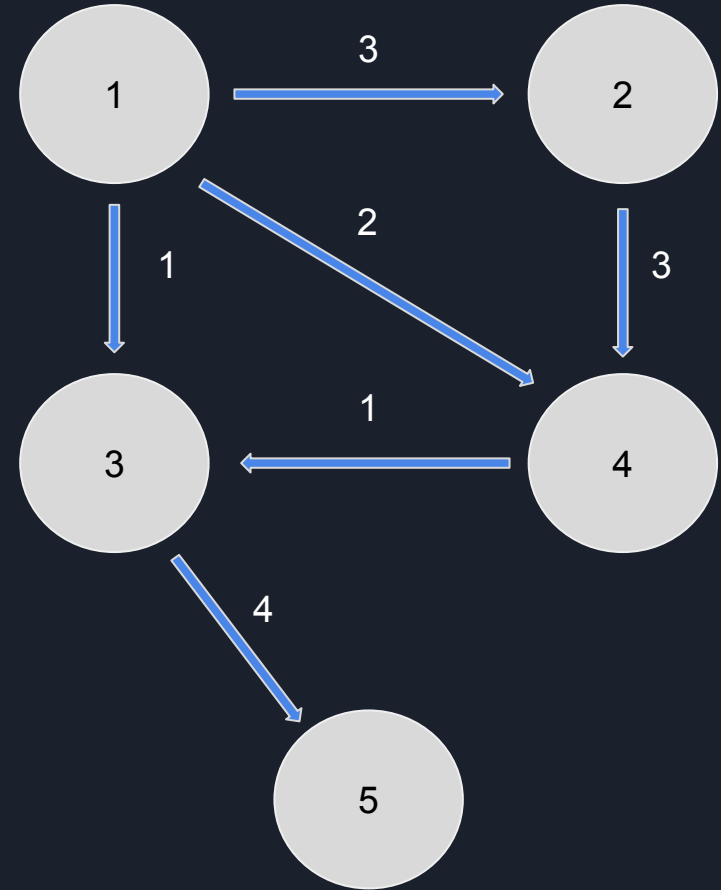
- Vertices
- Weighted Edges
- Representation
  - Adjacency Matrix
  - Adjacency List



# Adjacency Matrix

- $A$  is an adjacency matrix for graph  $G$
- $A[i,j]$  is weight of edge from vertex  $i$  to vertex  $j$

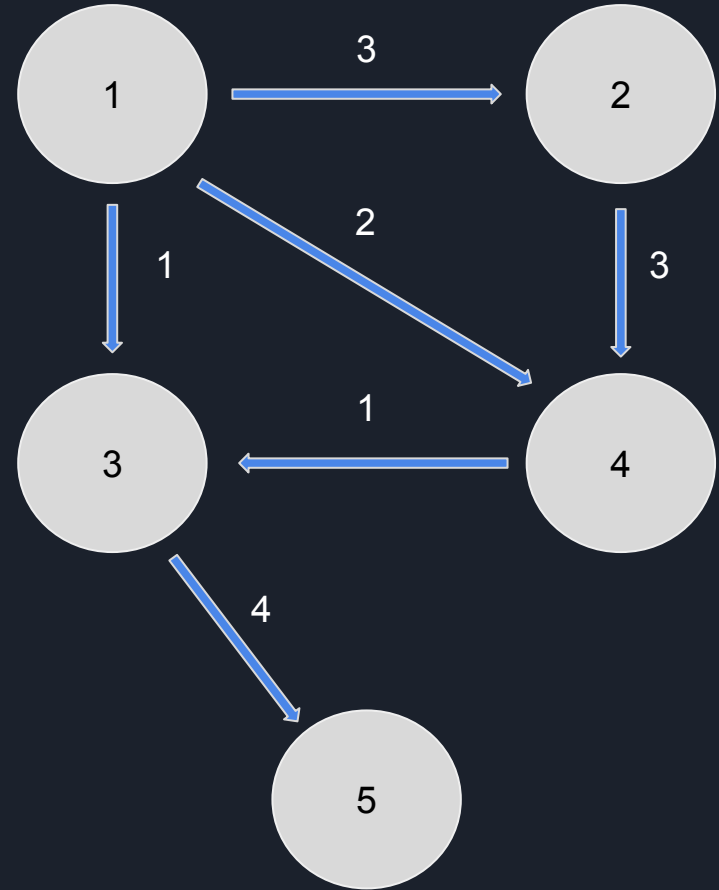
	1	2	3	4	5
1	$\infty$	3	1	2	$\infty$
2	$\infty$	$\infty$	$\infty$	3	$\infty$
3	$\infty$	$\infty$	$\infty$	$\infty$	4
4	$\infty$	$\infty$	1	$\infty$	$\infty$
5	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$



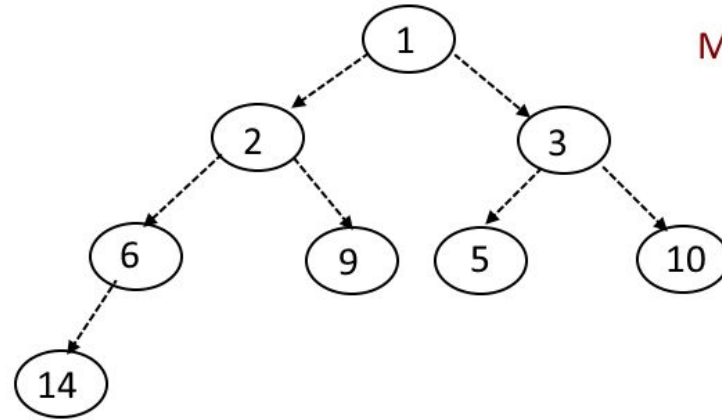
# Adjacency List

- $A$  is an adjacency list for graph  $G$
- $(c,j)$  is in  $A[i]$  if  $w_{i,j} = c$

1	→	(3, 2)	(1,3)	(2,4)
2	→	(3, 4)		
3	→	(4,5)		
4	→	(1,3)		
5	→			



# Heap



Min Heap

0	1	2	3	4	5	6	7	8
	1	2	3	6	9	5	10	14

for Node at  $i$  : Left child will be  $2i$  and right child will be at  $2i+1$  and parent node will be at  $[i/2]$ .



# Dijkstra's Algorithm - Shortest Path

Require: Weighted graph  $G = (V, E)$ , vertex  $s \in V$ , vertex  $t \in V$ .

```
1:  $Q \leftarrow \text{minHeap}$ 
2:  $Q.\text{insert}(0, s)$ 
3:  $\text{seen} \leftarrow []$ 
4:  $D[s] \leftarrow 0$ , all other  $D[v] \leftarrow \infty$ 
4: while  $Q$  is not empty do
    5:  $\text{cost}, u \leftarrow Q.\text{removeMin}$ 
    6: if  $u$  not in  $\text{seen}$   $\text{seen}.\text{append}(u)$ 
        7: If  $u == t$  then return  $\text{cost}$ 
        8: for each outgoing edge  $(u, v)$  from  $u$  do
            9. If  $\text{cost} > 0$  and  $D[v] > D[u] + c_{uv}$ 
                10.  $D[v] = D[u] + c_{uv}$ 
                11.  $Q.\text{append}(D[v], v)$ 
            12: end if
        13: end for
    14: end if
13: end while
14: return  $D[t]$ 
```



# Runtime

- $n$  = # of vertices
- $m$  = # of edges
- What takes time?
  - Popping from Queue
    - At most  $n$  times
  - Inserting into Queue
    - At most  $m$  times
- Runtime:  $O(n * T_{\text{pop}} + m * T_{\text{insert}}) = O(n \log n + m \log n) = O(m \log n)$  if  $m > n$

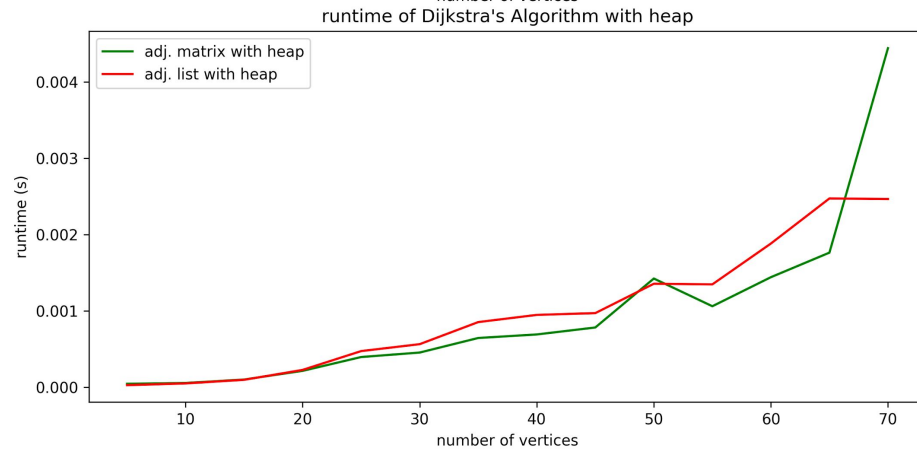
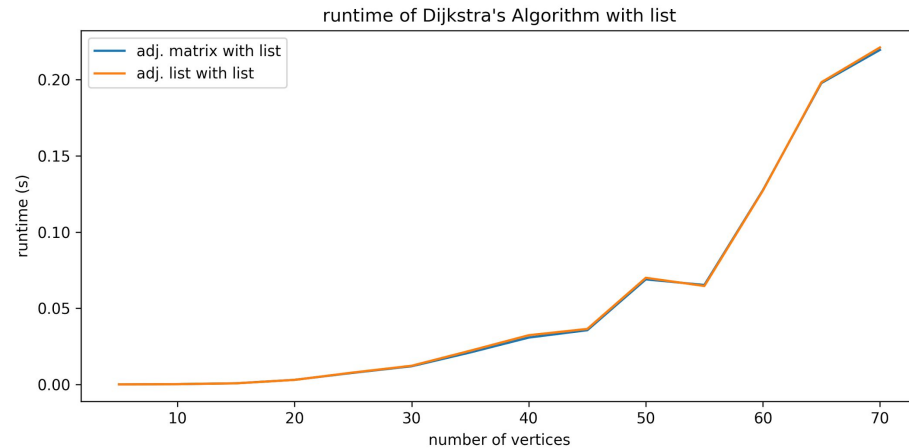


<https://www.cs.usfca.edu/~galles/visualization/Dijkstra.html>



# Analyzing Data Structures

- Data Structures change runtimes of algorithms
- Heap vs. List
- Adjacency Matrix vs. Adjacency List





# Takeaways

- Data structures change efficiency
- Algorithmic thinking helps solve complex problems



**Questions?**

# Negative Weights

