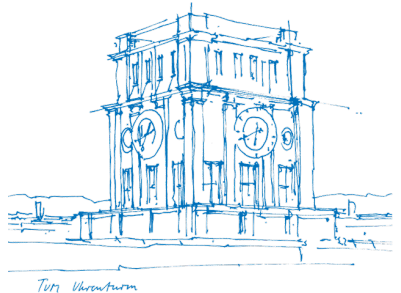


Experimental Evaluation of Machine Learning based Wireless Communication Algorithms

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07. Sep 2020



Introduction

- Channel Estimation is vital for any Wireless systems
- Required to revert the channel propagation effects

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- Required to revert the channel propagation effects
- For perfect Channel estimation, pilot symbols are to be placed on all sub carriers
- For massive MIMO \Rightarrow No. of Antennas \propto Pilot overhead
- Current research for potential solutions include
 - Model based channel estimation
 - Machine learning based algorithms to find the channel

- Setup a MIMO Test Jig

¹Jonas Maas. "Invertible Neural Networks for MIMO Detection". BA thesis. Technical University of Munich, 2020.

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- Collect real world experimental Tx-Rx data from the MIMO Setup

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- Setup a MIMO Test Jig
- Collect real world experimental Tx-Rx data from the MIMO Setup
- Use the data to train a Inverted Neural Network¹ as shown below



Figure: ML Model for learning the network

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- Software Defined Radio - USRP
- Possible Options for a MIMO Setup
- LTE Fundamentals
- Chosen Experimental Setup
- Results
- Conclusions and future work

Model	USRP2940
Baseband Bandwidth	40MHz
RF-Operating Frequency	50MHz-2200MHz
FPGA	Kintex-7 410T
No of Transmitters	2
No of Receivers	2
Connectivity	MXIe, Ethernet
Oscillator	Internal Crystal
ADC/DAC	14 (For Rx)/16 (For Tx) bit
Frequency Accuracy	2.5 ppm
Maximum Power Output	20dBm
Maximum I/Q Sample Rate	200MHz

Table: USRP2940 SDR Product details



Figure: Insides of USRP2940

Possible Options for a MIMO Setup

1. Standalone USRP

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- ✓ Minimum Hardware required
- ✓ Modular as long as we could use PCIe expanders
- ✗ Needs the Octoclock a Clock distribution accessory
- ✗ Transceivers not synchronised

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- ✓ supports upto 128 Antennas on the BS
- ✗ Expensive! >€100.000 for a minimum working setup
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- ✓ Only 2 USRPs and a Host are required
- ✗ Limited to 2x2 MIMO setup

Option 1 - Standalone USRP

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$$y(t) = \cos(\omega t) + j * \sin(\omega t)$$

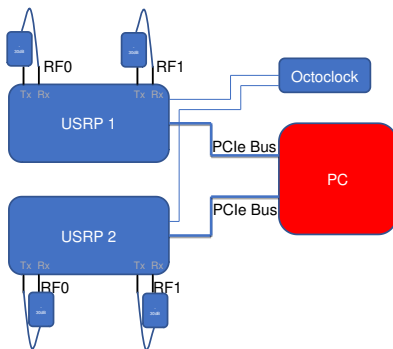


Figure: Setup of the USRPs in loopback Configuration

Option 1 - Standalone USRP

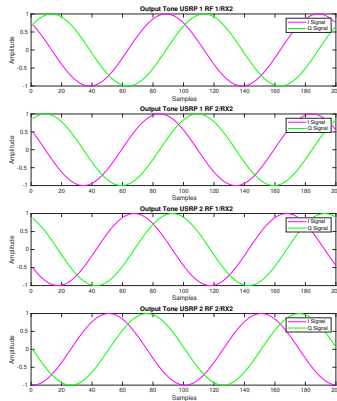
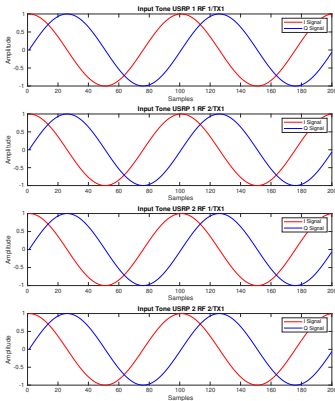


Figure: The left waveforms are the TX waveforms and the right waveforms are the RX waveforms. It can be seen that the received IQ waveforms are unsynchronised and clearly have a phase shift

Option 1 - Standalone USRP

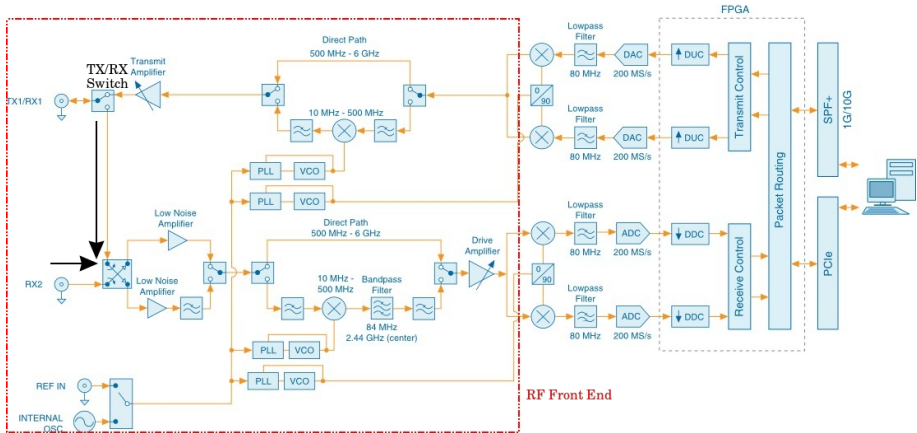


Figure: USRP 2940 Internal Components

- Multi-User MIMO **Single BS** with up to 128 Antennas and up to 12 single antenna Mobile Stations (MS)
- Single-user MIMO transmission between one BS with up to 128 antennas and one MS with up to 12 antennas
- Scalable number of antennas (multi-antenna MS: between 2 and 12; BS: between 2 and 128).
- Modulation Schemes - QPSK to 256 QAM
- Automatic gain control (AGC) at the BS and MS

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- Modulation Schemes - QPSK to 256 QAM
- Automatic gain control (AGC) at the BS and MS
- FPGA based real time signal processing such as
 - Modulation
 - Over-the-air synchronization
 - MIMO equalization
 - MIMO precoding
- Fully reconfigurable LTE like radio frame structure
- Bi Directional TDD and FDD functionality transmission of 20MHz bandwidth

Option 2 - MIMO Application Framework

Part Number	Description
USRP-2940	SDR
PXle-7976	FPGA Module for FlexRIO
CDA-2990	Clock Distribution Device
CPS-8910	Switch Device for PCI Express
PXle-6674T	Synchronization Module
PXle-1085	Chassis
PXle-8135	Controller

Table: Additional Hardware for required for MIMO AFW to function

	128-antenna BS 8 subsystems	64-antenna BS 4 subsystems	32-antenna BS 2 subsystems	16-antenna BS 1 subsystems	8-antenna BS 1 subsystems
USRP-29xx SDR Reconfigurable Device	64	32	16	8	6
PXle-1085 Chassis (18-Slot, 24 GB/s System Bandwidth (BW))	1	1	1	1	1
PXle-8135 Controller	1	1	1	1	1
PXle-7976 FPGA Module for FlexRIO	5	3	2	2	2
PXle-6674T Synchronization	1	1	1	1	1
CDA-2990 Clock Distribution Device	8	5	3	1	1
CPS-8910 Switch Device for PCI Express	8	4	2	1	1

Table: MIMO Configurations and HW requirements

Option 2 - MIMO Application Framework

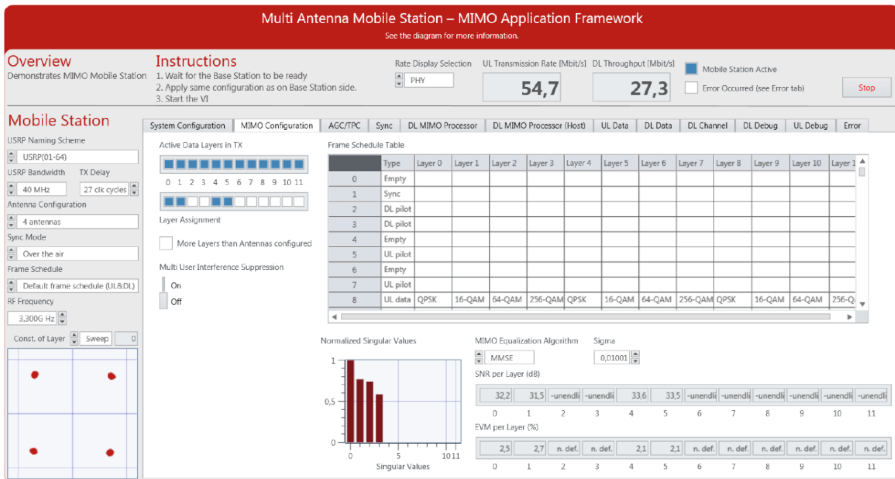


Figure: MIMO AFW

Option 3 - LTE Application Framework MIMO Extension

- Based on a LTE Application Framework, an LTE Release 10 implementation
- Developed by NI to demonstrate a functioning 2x2 MIMO System
- Provides a **Downlink ONLY** 2x2 LTE Setup
- Upto 64 QAM modulation
- FPGA based realtime signal processing
- 3 different Equalisation algorithms
 - Matched Filter
 - Zero Forcing
 - MMSE

- OFDMA based physical layer
- Frame based communication scheme of 10ms per Frame

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 - Secondary Synchronisation Signal (SSS) - **BPSK**
 - Cell Specific Reference Signal (CRS) - **QPSK**

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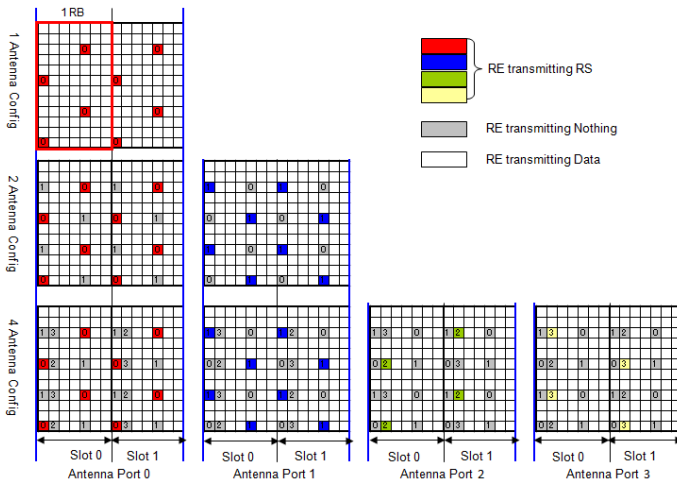
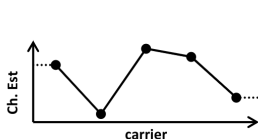
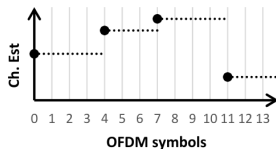


Figure: Cell Reference Signal layout for multi antenna configurations of 1,2 and 4 antenna systems in LTE

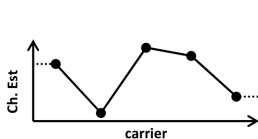


(a) Channel Estimation Interpolation over Frequency

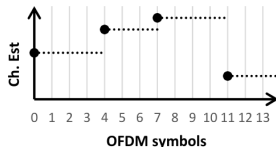


(b) Channel Estimation Zero order hold over time

Figure: Illustration of channel estimation interpolation over time and frequency



(a) Channel Estimation Interpolation over Frequency



(b) Channel Estimation Zero order hold over time

Figure: Illustration of channel estimation interpolation over time and frequency

- The RF Front end phase offset correction is applied to all the subcarriers and time symbols
- Fixed transmit pattern as defined by standard

Experimental Setup - Wideband Noise Calculation

Demo

Results - Data Loss

Microsoft Windows [Version 10.0.18363.1016]
(c) 2019 Microsoft Corporation. Alle Rechte vorbehalten.

C:\Users\ge69mog>cd Downloads\iperf-2.0.9-win64\iperf-2.0.9-win64

C:\Users\ge69mog\Downloads\iperf-2.0.9-win64\iperf-2.0.9-win64>iperf.exe -s -u
-B 127.0.0.1 -i 1 -p 60000

Server listening on UDP port 60000
Binding to local address 127.0.0.1
Receiving 1470 byte datagrams
UDP buffer size: 208 KByte (default)

```
[ 3] local 127.0.0.1 port 60000 connected with 127.0.0.1 port 49721
[ ID] Interval      Transfer      Bandwidth      Jitter      Lost/Total Datagrams
[ 3] 0.0- 1.0 sec    996 KBytes    8.16 Mbits/sec  2.017 ms    166/ 860 (19%)
[ 3] 0.00-1.00 sec  50 datagrams  received out-of-order
[ 3] 1.0- 2.0 sec    904 KBytes    7.41 Mbits/sec  2.426 ms    227/ 857 (26%)
[ 3] 1.00-2.00 sec  70 datagrams  received out-of-order
[ 3] 2.0- 3.0 sec    902 KBytes    7.39 Mbits/sec  2.148 ms    219/ 847 (26%)
[ 3] 2.00-3.00 sec  61 datagrams  received out-of-order
[ 3] 3.0- 4.0 sec    916 KBytes    7.50 Mbits/sec  1.904 ms    222/ 860 (26%)
[ 3] 3.00-4.00 sec  69 datagrams  received out-of-order
[ 3] 4.0- 5.0 sec    871 KBytes    7.14 Mbits/sec  4.137 ms    206/ 813 (25%)
[ 3] 4.00-5.00 sec  56 datagrams  received out-of-order
[ 3] 5.0- 6.0 sec    953 KBytes    7.81 Mbits/sec  4.710 ms    226/ 890 (25%)
[ 3] 5.00-6.00 sec  86 datagrams  received out-of-order
[ 3] 6.0- 7.0 sec    828 KBytes    6.79 Mbits/sec  2.786 ms    253/ 830 (30%)
[ 3] 6.00-7.00 sec  84 datagrams  received out-of-order
[ 3] 7.0- 8.0 sec    843 KBytes    6.90 Mbits/sec  4.467 ms    250/ 837 (30%)
[ 3] 7.00-8.00 sec  90 datagrams  received out-of-order
[ 3] 8.0- 9.0 sec    970 KBytes    7.95 Mbits/sec  1.648 ms    200/ 876 (23%)
[ 3] 8.00-9.00 sec  61 datagrams  received out-of-order
[ 3] 9.0-10.0 sec    8.86 MBytes   7.43 Mbits/sec  2.888 ms   2183/ 8505 (26%)
[ 3] 9.00-10.00 sec 689 datagrams received out-of-order
```

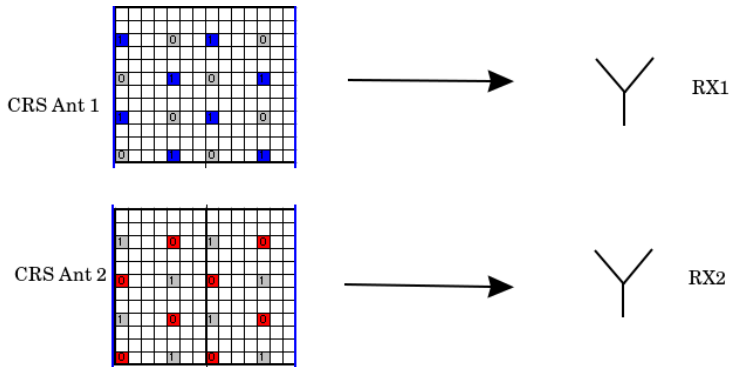
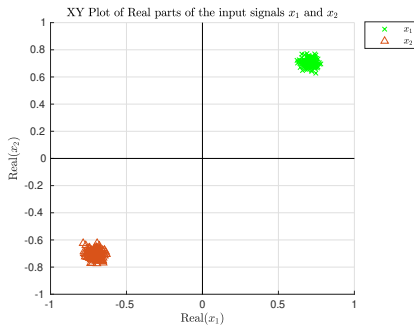


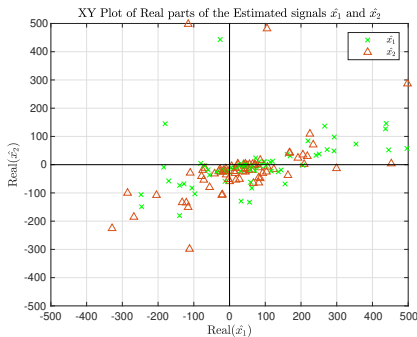
Figure: Illustration of the CRS signals and channel estimation coefficients used as the (x,y) pair

- A sequence of 8342 time symbols for the 200 CRS carriers were recorded
- Final matrix size of 200×8342

Results - INN Detection



(a) XY plot of the real parts of the input signals x_1 and x_2 with noise



(b) XY plot of the real parts of the INN Estimated signals \hat{x}_1 and \hat{x}_2

Figure: Detection accuracy of **22%** from the INN

Conclusion

A Slide with a different header

Some text, possibly **bold** or highlighted.

- Bullet points
- Second point
 - Sub-bullet

A Slide with a different header

Some text, possibly **bold** or highlighted.

- Bullet points
 - Second point
 - Sub-bullet
1. First
 2. Second
 3. Third

Frame with highlight boxes and alternative header

Important Result¹

The following holds:²

$$E = mc^2$$

¹ This is a footnote in a block title.

² This is a footnote in a block body.

Frame with highlight boxes and alternative header

Important Result¹

The following holds:²

$$E = mc^2$$



Can also be used without a title. Three color types are available: block (blue), alertblock (red), and exampleblock (green). Spacing may need some manual adjustment if formulas are included at the top or bottom of blocks.

¹ This is a footnote in a block title.

² This is a footnote in a block body.

- We consider some simple formulas, e.g. $\max(0, 1) = 1$
- Complicated formula: $h_J(y) = \sum_{K \subset N} \int_{\mathbb{R}} g_K(x, y) f_J(x) dx$
- This looks slightly weird since math fonts are smaller than text fonts.

However, this does not really affect equations.

$$h_J(y) = \sum_{K \subset N} \int_{\mathbb{R}} g_K(x, y) f_J(x) dx$$

No title on this frame.²

Example Block

Spacing around blocks is minimal (if option frameblock is used). Extra spaces, e.g. `vskip` or `vspace`, should be used.

Text below block.

²Smith et al., 2100: "Title of a paper that will be written in the future", *IEEE Trans Inf. Theory*

In diagrams and plots only use the following colors:

- Black, White
- Yellow, RGB 255/180/000
- Orange, RGB 255/128/000
- Red, RGB 229/052/024
- Dark Red, RGB 202/033/063
- Blue, RGB 000/153/255
- Light Blue, RGB 065/190/255
- Green, RGB 145/172/107
- Light Green, RGB 181/202/130

Final Slide

Add some vertical space.

Increase spacing between bullet points:

- More information can be found in the [beamer user guide](#)
- Use `pdflatex` to compile the source
- Have fun creating your slides!